

Multilevel Analysis

Techniques and Applications

QUANTITATIVE METHODOLOGY SERIES

Third Edition

Joop J. Hox
Mirjam Moerbeek
Rens van de Schoot



This an outstanding introduction to the topic of multilevel modeling. The new edition is even more detailed with key chapter revisions and additions, all combined with insightful computer-based examples and discussions. It is an excellent resource for anyone wanting to learn about multilevel analysis.

—**George A. Marcoulides**, University of California, Santa Barbara

This is a comprehensive book that takes the reader from the basics of multilevel modeling through to advanced extensions into models used for meta-analysis and survival analysis. It also describes the links with structural equation modeling and other latent models such as path models and factor analysis models. The book offers a great exposition of both the models and the estimation methods used to fit them and is accessible and links each chapter well to available software for the models described. The book also covers topics such as Bayesian estimation and power calculations in the multilevel setting. This edition is a valuable addition to the multilevel modeling literature.

—**William Browne**, Centre for Multilevel Modelling, University of Bristol

This book has been a staple in my research diet. The author team is at the developing edge of multilevel modeling and as they state about multilevel analysis in general, ‘both the statistical techniques and the software tools are evolving rapidly.’ Their book is the perfect melding of being an introduction to multilevel modeling as well as a researcher’s resource when it comes to the recent advances (e.g., Bayesian multilevel modeling, bootstrap estimation). It’s clearly written. With a light and unpretentious voice, the book narrative is not only accessible, it is also inviting.

—**Todd D. Little**, Director and Founder, Institute for Measurement, Methodology, Analysis, and Policy, Texas Tech University; Director and Founder of Stats Camp



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Multilevel Analysis

Applauded for its clarity, this accessible introduction helps readers apply multilevel techniques to their research. The book also includes advanced extensions, making it useful as both an introduction for students and as a reference for researchers. Basic models and examples are discussed in nontechnical terms with an emphasis on understanding the methodological and statistical issues involved in using these models. The estimation and interpretation of multilevel models is demonstrated using realistic examples from various disciplines including psychology, education, public health, and sociology. Readers are introduced to a general framework on multilevel modeling which covers both observed and latent variables in the same model, while most other books focus on observed variables. In addition, Bayesian estimation is introduced and applied using accessible software.

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Multilevel Analysis

Techniques and Applications

Third Edition

**Joop J. Hox, Mirjam Moerbeek,
Rens van de Schoot**

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Preface

*To err is human, to forgive divine;
but to include errors into your design is statistical.*

— Leslie Kish

This book is intended as an introduction to multilevel analysis for students and researchers. The term ‘multilevel’ refers to a hierarchical or nested data structure, usually subjects within organizational groups, but the nesting may also consist of repeated measures within subjects, or respondents within clusters, as in cluster sampling. The expression *multilevel model* is used as a generic term for all models for nested data. *Multilevel analysis* is used to examine relations between variables measured at different levels of the multilevel data structure. This book presents two types of multilevel model in detail: the multilevel regression model and the multilevel structural equation model. Although multilevel analysis is used in many research fields, the examples in this book are mainly from the social and behavioral sciences.

In the past decades, multilevel analysis software has become available that is both powerful and accessible, either as special packages or as part of a general software package. In addition, several handbooks have been published, including the earlier editions of this book. There is a continuing interest in multilevel analysis, as evidenced by the appearance of several reviews and monographs, applications in different fields ranging from psychology and sociology to education and medicine, a thriving Internet discussion list with more than 1400 subscribers, and a biennial International Multilevel Conference that has been running for more than 20 years. The view of ‘multilevel analysis’ applying to individuals nested within groups has changed to a view that multilevel models and analysis software offer a very flexible way to model complex data. Thus, multilevel modeling has contributed to the analysis of traditional individuals within groups data, repeated measures and longitudinal data, sociometric modeling, twin studies, meta-analysis and analysis of cluster randomized trials.

This book treats two classes of multilevel models: multilevel regression models, and multilevel structural equation models (MSEM).

Multilevel regression models are essentially a multilevel version of the familiar multiple regression model. As Cohen and Cohen (1983), Pedhazur (1997) and others have shown, the multiple regression model is very versatile. Using dummy coding for categorical variables, it can be used to analyze analysis of variance (ANOVA) type models, as well as the more

usual multiple regression models. Since the multilevel regression model is an extension of the classical multiple regression model, it too can be used in a wide variety of research problems.

Chapter 2 of this book contains a basic introduction to the multilevel regression model, also known as the hierarchical linear model, or the random coefficient model. Chapter 3 and Chapter 4 discuss estimation procedures, and a number of important methodological and statistical issues. They also discuss some technical issues that are not specific to multilevel regression analysis, such as centering of predictors and interpreting interactions.

Chapter 5 introduces the multilevel regression model for longitudinal data. The model is a straightforward extension of the standard multilevel regression model, but there are some specific complications, such as autocorrelated errors, which are discussed.

Chapter 6 treats the generalized linear model for dichotomous data and proportions. When the response (dependent) variable is dichotomous or a proportion, standard regression models should not be used. This chapter discusses the multilevel version of the logistic and the probit regression model.

Chapter 7 extends the generalized linear model introduced in Chapter 6 to analyze data that are ordered categorically and to data that are counts of events. In the context of counts, it presents models that take an overabundance of zeros into account.

Chapter 8 introduces multilevel modeling of survival or event history data. Survival models are for data where the outcome is the occurrence or non-occurrence of a certain event, in a certain observation period. If the event has not occurred when the observation period ends, the outcome is said to be censored, since we do not know whether or not the event has taken place after the observation period ended.

Chapter 9 discusses cross-classified models. Some data are multilevel in nature, but do not have a neat hierarchical structure. Examples are longitudinal school research data, where pupils are nested within schools, but may switch to a different school in later measurements, and sociometric choice data. Multilevel models for such cross-classified data can be formulated, and estimated with standard software provided that it can handle restrictions on estimated parameters.

Chapter 10 discusses multilevel regression models for multivariate outcomes. These can also be used to assess the reliability of multilevel measurements.

Chapter 11 describes a variant of the multilevel regression model that can be used in meta-analysis. It resembles the weighted regression model often recommended for meta-analysis. Using standard multilevel regression procedures, it is a flexible analysis tool, especially when the meta-analysis includes multivariate outcomes.

Chapter 12 deals with the sample size needed for multilevel modeling, and the problem of estimating the power of an analysis given a specific sample size. An obvious complication in multilevel power analysis is that there are different sample sizes at the distinct levels which should be taken into account.

Chapter 13 discusses the statistical assumptions made and presents some ways to check these. It also discusses more robust estimation methods, such as the profile likelihood method and robust standard errors for establishing confidence intervals, and multilevel bootstrap methods for estimating bias-corrected point-estimates and confidence intervals. This chapter also contains an introduction into Bayesian (MCMC) methods for estimation and inference.

Multilevel structural equation models (MSEM), are a powerful tool for the analysis of multilevel data. Recent versions of structural equation modeling software such as LISREL, and Mplus all include at least some multilevel features. The general statistical model for multilevel covariance structure analysis is quite complicated. Chapter 14 describes two different approaches to estimation in multilevel confirmatory factor analysis. In addition, it deals with issues of calculating standardized coefficients and goodness-of-fit indices in multilevel structural models. Chapter 15 extends this to multilevel path models.

Chapter 16 describes structural models for latent curve analysis. This is an SEM approach to analyzing longitudinal data, which is very similar to the multilevel regression models treated in Chapter 5.

This book is intended as an introduction to the world of multilevel analysis. Most of the chapters on multilevel regression analysis should be readable by social and behavioral scientists who have a good general knowledge of analysis of variance and classical multiple regression analysis. Some of these chapters contain material that is more difficult, but these are generally a discussion of specialized problems, which can be skipped at first reading. An example is the chapter on longitudinal models, which contains a long discussion of techniques to model specific structures for the covariances between adjacent time points. This discussion is not needed in understanding the essentials of multilevel analysis of longitudinal data, but it may become important when one is actually analyzing such data. The chapters on multilevel structure equation modeling obviously require a strong background in multivariate statistics and some background in structural equation modeling, equivalent to, for example, the material covered in Tabachnick and Fidell's (2013) book on multivariate analysis. On the other hand, in addition to an adequate background in structural equation modeling, the chapters on multilevel structural equation modeling do not require knowledge of advanced mathematical statistics. In all these cases, we have tried to keep the discussion of the more advanced statistical techniques theoretically sound, but non-technical.

In addition to its being an introduction, this book describes many extensions and special applications. As an introduction, it is useable in courses on multilevel modeling in a variety of social and behavioral fields, such as psychology, education, sociology, and business. The various extensions and special applications also make it useful to researchers who work in applied or theoretical research, and to methodologists who have to consult with these researchers. The basic models and examples are discussed in non-technical terms; the emphasis is on understanding the methodological and statistical issues involved in using

these models. Some of the extensions and special applications contain discussions that are more technical, either because that is necessary for understanding what the model does, or as a helpful introduction to more advanced treatments in other texts. Thus, in addition to its role as an introduction, the book should be useful as a standard reference for a large variety of applications. The chapters that discuss specialized problems, such as the chapter on cross-classified data, the meta-analysis chapter, and the chapter on advanced issues in estimation and testing, can be skipped entirely if preferred.

NEW TO THIS EDITION

One important change compared to the second edition is the introduction of two co-authors. This reflects the expansion of multilevel analysis; the field has become so broad that it is virtually impossible for a single author to keep up with the new developments, both in statistical theory and in software.

Compared to the second edition, some chapters have changed much, while other chapters have mostly been updated to reflect recent developments in statistical research and software development. One important development is increased use of Bayesian estimation and development of robust maximum likelihood estimation. We have chosen not to add a separate chapter on Bayesian estimation; instead, Bayesian estimation is discussed in those places where its use improves estimation. The chapters on multilevel logistic regression and on multilevel ordered regression have been expanded with a better treatment of the linked problems of latent scale and explained variance. In multilevel structural equation modeling (MSEM) the developments have been so fast that the chapters on multilevel confirmatory factor analysis and on multilevel path analysis have been significantly revised, in part by removing discussion of estimation methods that are now clearly outdated. The chapter on sample size and power and the chapter on multilevel survival analysis have been extensively rewritten.

An updated website at (<https://multilevel-analysis.sites.uu.nl/>) holds the data sets for all the text examples formatted using the latest versions of SPSS, HLM, MLwiN and Mplus, plus some software introductions with updated screen shots for each of these programs. Most analyses in this book can be carried out by any multilevel regression program, although the majority of the multilevel regression analyses were carried out in HLM and MLwiN. The multilevel SEM analyses all use Mplus. System files and setups using these packages are also available at the website.

Some of the example data are real, while others have been simulated especially for this book. The data sets are quite varied so as to appeal to those in several disciplines, including education, sociology, psychology, family studies, medicine, and nursing; Appendix E describes the various data sets used in this book in detail. Further example data will be added to the website for use in computer labs.

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We thank our colleagues at the Department of Methodology and Statistics of the Faculty of Social Sciences at Utrecht University for providing us with many discussions and a generally stimulating research environment. Our research has also benefited from the lively discussions by the denizens of the Internet *Multilevel Modeling* and the *Structural Equations Modeling (SEMNET)* discussion lists.

We also express our gratitude to the reviewers that reviewed our proposal for the new edition. They provided valuable feedback on the contents and the structure of the proposed book.

As always, any errors remaining in the book are entirely our own responsibility. We appreciate hearing about them, and will keep a list of errata on the homepage of this book.

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Mirjam Moerbeek
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Utrecht, August 2017



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1

Introduction to Multilevel Analysis

SUMMARY

Social research regularly involves problems that investigate the relationship between individuals and the social contexts in which they live, work, or learn. The general concept is that individuals interact with the social contexts to which they belong, that individual persons are influenced by the contexts or groups to which they belong, and that those groups are in turn influenced by the individuals who make up that group. The individuals and the social groups are conceptualized as a hierarchical system of individuals nested within groups, with individuals and groups defined at separate levels of this hierarchical system. Naturally, such systems can be observed at different hierarchical levels, and variables may be defined at each level. This leads to research into the relationships between variables characterizing individuals and variables characterizing groups, a kind of research that is generally referred to as '*multilevel research*'.

In multilevel research, the data structure in the population is hierarchical, and the sample data are a sample from this hierarchical population. For example, in educational research, the population typically consists of classes and pupils within these classes, with classes organized within schools. The sampling procedure often proceeds in successive stages: first, we take a sample of schools, next we take a sample of classes within each sampled school, and finally we take a sample of pupils within each sampled class. Of course, in real research one may have a convenience sample of schools, or one may decide not to sample pupils but to study all available pupils in each class. Nevertheless, one should keep firmly in mind that the central statistical model in multilevel analysis is one of successive sampling from each level of a hierarchical population.

In this example, pupils are *nested* within classes. Other examples are cross-national studies where the individuals are nested within their national units, organizational research with individuals nested within departments within organizations, family research with family members within families and methodological research into interviewer effects with respondents nested within interviewers. Less obvious applications of multilevel models are longitudinal research and growth curve research, where a series of several distinct observations are viewed as nested within individuals, and meta-analysis where the subjects are nested within different studies.

1.1 AGGREGATION AND DISAGGREGATION

In multilevel research, variables can be defined at any level of the hierarchy. Some of these variables may be measured directly at their 'own' natural level; for example, at the school level we may measure school size and denomination, at the class level we measure class size, and at the pupil level, intelligence and school success. In addition, we may move variables from one level to another by aggregation or disaggregation. Aggregation means that the variables at a lower level are moved to a higher level, for instance, by assigning to the classes the class mean of the pupils' intelligence scores. Disaggregation means moving variables to a lower level, for instance by assigning to all pupils in the schools a variable that indicates the denomination of the school they belong to.

The lowest level (level 1) is usually defined by the individuals. However, this is not always the case. For instance, in longitudinal designs, repeated measures within individuals are the lowest level. In such designs, the individuals are at level two, and groups are at level three. Most software allows for at least three levels, and some software has no formal limit to the number of levels. However, models with many levels can be difficult to estimate, and even if estimation is successful, they are unquestionably more difficult to interpret.

At each level in the hierarchy, we may have several types of variables. The distinctions made in the following are based on the typology offered by Lazarsfeld and Menzel (1961), with some simplifications. In our typology, we distinguish between *global*, *structural* and *contextual* variables.

Global variables are variables that refer only to the level at which they are defined, without reference to other units or levels. A pupil's intelligence or gender would be a global variable at the pupil level. School denomination and class size would be global variables at the school and class level. Simply put: a global variable is measured at the level at which that variable actually exists.

Structural variables are operationalized by referring to the sub-units at a lower level. They are constructed from variables at a lower level, for example, in defining the class variable 'mean intelligence' as the mean of the intelligence scores of the pupils in that class. Using the mean of a lower-level variable as an explanatory variable at a higher level is called aggregation, and it is a common procedure in multilevel analysis. Other functions of the lower-level variables are less common, but may also be valuable. For instance, using the standard deviation of a lower-level variable as an explanatory variable at a higher level could be used to test hypotheses about the effect of group heterogeneity on the outcome variable (cf. Klein and Kozlowski, 2000).

Contextual variables are the result from disaggregation; all units at the lower level receive the value of a global variable for the context to which they belong at the higher level. For instance, we can assign to all pupils in a school the school size, or the mean intelligence, as a pupil-level variable. Disaggregation is not needed in a proper multilevel analysis. For convenience, multilevel data are often stored in a single data file, in which the group-level variables are repeated for each individual within a group, but the statistical

model and the software will correctly recognize these as a single value at a higher level. The term *contextual variable*, however, is still used to denote a variable that models how the context influences an individual.

In order to analyze multilevel models, it is not important to assign each variable to its proper place in the typology. The benefit of the scheme is conceptual; it makes clear to which level a measurement properly belongs. Historically, multilevel problems have led to analysis approaches that moved all variables by aggregation or disaggregation to one single level of interest followed by an ordinary multiple regression, analysis of variance, or some other 'standard' analysis method. However, analyzing variables from different levels at one single common level is inadequate, and leads to two distinct types of problems.

The first problem is statistical. If data are aggregated, the result is that different data values from many sub-units are combined into fewer values for fewer higher-level units. As a result, much information is lost, and the statistical analysis loses power. On the other hand, if data are disaggregated, the result is that a few data values from a small number of super-units are 'blown up' into many more values for a much larger number of sub-units. Ordinary statistical tests treat all these disaggregated data values as independent information from the much larger sample of sub-units. The proper sample size for these variables is of course the number of higher-level units. Using the larger number of disaggregated cases for the sample size leads to significance tests that reject the null-hypothesis far more often than the nominal alpha level suggests. In other words, investigators come up with many 'significant' results that are totally spurious.

The second problem is conceptual. If the analyst is not very careful in the interpretation of the results, s/he may commit the fallacy of the wrong level, which consists of analyzing the data at one level, and formulating conclusions at another level. Probably the best-known fallacy is the *ecological fallacy*, which is interpreting aggregated data at the individual level. It is also known as the 'Robinson effect' after Robinson (1950). Robinson presents aggregated data describing the relationship between the percentage of blacks and the illiteracy level in nine geographic regions in 1930. The *ecological correlation*, that is, the correlation between the aggregated variables at the region level is 0.95. In contrast, the individual-level correlation between these global variables is 0.20. Robinson concludes that in practice an ecological correlation is almost certainly not equal to its corresponding individual-level correlation. For a statistical explanation, see Robinson (1950) or Kreft and de Leeuw (1987). Formulating inferences at a higher level based on analyses performed at a lower level is just as misleading. This fallacy is known as the *atomistic fallacy*.

A better way to look at multilevel data is to realize that there is not one 'proper' level at which the data should be analyzed. Rather, all levels present in the data are important in their own way. This becomes clear when we investigate cross-level hypotheses, or *multilevel* problems. A multilevel problem is a problem that concerns the relationships between variables that are measured at a number of different hierarchical levels. For example, a common question is how a number of individual and group variables influence

one single individual outcome variable. Typically, some of the higher-level explanatory variables may be structural variables, for example the aggregated group means of lower-level global (individual) variables. The goal of the analysis is to determine the direct effect of individual- and group-level explanatory variables, and to determine if the explanatory variables at the group level serve as moderators of individual-level relationships. If group-level variables moderate lower-level relationships, this shows up as a statistical interaction between explanatory variables from different levels. In the past, such data were analyzed using conventional multiple regression analysis with one dependent variable at the lowest (individual) level and a collection of disaggregated explanatory variables from all available levels (cf. Boyd & Iversen, 1979). This approach is completely outdated, since it analyzes all available data at one single level, it suffers from all of the conceptual and statistical problems mentioned above.

1.2 WHY DO WE NEED SPECIAL MULTILEVEL ANALYSIS TECHNIQUES?

Multilevel research concerns a population with a hierarchical structure. A sample from such a population can be described as a multistage sample: first, we take a sample of units from the higher level (e.g., schools), and next we sample the sub-units from the available units (e.g., we sample pupils from the schools). In such samples, the individual observations are in general not independent. For instance, pupils in the same school tend to be similar to each other, because of selection processes (for instance, some schools may attract pupils from higher social economic status (SES) levels, while others attract lower SES pupils) and because of the common history the pupils share by going to the same school. As a result, the average correlation (expressed as the so-called *intraclass correlation*) between variables measured on pupils from the same school will be higher than the average correlation between variables measured on pupils from different schools. Standard statistical tests lean heavily on the assumption of independence of the observations. If this assumption is violated (and with nested data this is almost always the case) the estimates of the standard errors of conventional statistical tests are much too small, and this results in many spuriously ‘significant’ results. The effect is generally *not* negligible, small dependencies in combination with medium to large group sizes still result in large biases in the standard errors. The strong biases that may be the effect of violation of the assumption of independent observations made in standard statistical tests has been known for a long time (Walsh, 1947) and are still a very important assumption to check in statistical analyses (Stevens, 2009).

The problem of dependencies between individual observations also occurs in survey research, if the sample is not taken at random but cluster sampling from geographical areas is used instead. For similar reasons as in the school example given above, respondents from the same geographical area will be more similar to each other than respondents from different geographical areas are. This leads again to estimates for standard errors that are too small and produce spurious ‘significant’ results. In survey research, this effect of cluster sampling

is well known (cf. Kish, 1965, 1987). It is called a ‘design effect’, and various methods are used to deal with it. A convenient correction procedure is to compute the standard errors by ordinary analysis methods, estimate the intraclass correlation between respondents within clusters, and finally employ a correction formula to the standard errors. For instance, Kish (1965, p. 259) corrects the sampling variance using $v_{eff} = v(1 + (n_{clus} - 1)\rho)$, where v_{eff} is the effective sampling variance, v is the sampling variance calculated by standard methods assuming simple random sampling, n_{clus} is the cluster size, and ρ is the intraclass correlation. The intraclass correlation is described in Chapter 2, together with its estimation. The following example makes clear how important the assumption of independence is. Suppose that we take a sample of 10 classes, each with 20 pupils. This comes to a total sample size of 200. We are interested in a variable with an intraclass correlation of 0.10, which is a rather low intraclass correlation. However, the effective sample size in this situation is $200 / [1 + (20 - 1)0.1] = 69.0$, which is far less than the apparent total sample size of 200. Clearly, using a sample size of 200 will lead to standard errors that are much too low.

Since the design effect depends on both the intraclass correlation and the cluster size, large intraclass correlations are partly compensated by small group sizes. Conversely, small intraclass correlations at the higher levels are offset by the usually large cluster sizes at these levels.

Some of the correction procedures developed for cluster and other complex samples are quite powerful (cf. Skinner et al., 1989). In principle such correction procedures could also be applied in analyzing multilevel data, by adjusting the standard errors of the statistical tests. However, multilevel models are multivariate models, and in general the intraclass correlation and hence the effective N is different for different variables. In addition, in most multilevel problems we have not only clustering of individuals within groups, but we also have variables measured at all available levels, and we are interested in the relationships between all of these variables. Combining variables from different levels in one statistical model is a different and more complicated problem than estimating and correcting for design effects. Multilevel models are designed to analyze variables from different levels simultaneously, using a statistical model that properly includes the dependencies.

To provide an example of a clearly multilevel problem, consider the ‘frog pond’ theory that has been utilized in educational and organizational research. The ‘frog pond’ theory refers to the notion that a specific individual frog may be a medium-sized frog in a pond otherwise filled with large frogs, or a medium-sized frog in a pond otherwise filled with small frogs. Applied to education, this metaphor points out that the effect of an explanatory variable such as ‘intelligence’ on school career may depend on the average intelligence of the other pupils in the school. A moderately intelligent pupil in a highly intelligent context may become demotivated and thus become an underachiever, while the same pupil in a considerably less intelligent context may gain confidence and become an overachiever. Thus, the effect of an individual pupil’s intelligence depends on the average intelligence of the other pupils in the class. A popular approach in educational research to investigate ‘frog pond’ effects has been to aggregate variables like the pupils’ IQ into group means, and

then to disaggregate these group means again to the individual level. As a result, the data file contains both individual-level (global) variables and higher-level (contextual) variables in the form of disaggregated group means. Already in 1976 the educational researcher Cronbach suggested to express the individual scores as deviations from their respective group means (Cronbach, 1976), a procedure that has become known as *centering on the group mean*, or *group mean centering*. Centering on the group means makes very explicit that the individual scores should be interpreted relative to their group's mean. The example of the 'frog pond' theory and the corresponding practice of centering the predictor variables makes clear that combining and analyzing information from different levels within one statistical model is central to multilevel modeling.

1.3 MULTILEVEL THEORIES

Multilevel data must be described by multilevel theories, an area that seems underdeveloped compared to the advances made in the modeling and computing machinery. Multilevel models in general require that the grouping criterion is clear, and that variables can be assigned unequivocally to their appropriate level. In reality, group boundaries are sometimes fuzzy and somewhat arbitrary, and the assignment of variables is not always obvious and simple. In multilevel research, decisions about group membership and operationalizations involve a range of theoretical assumptions (Klein & Kozlowski, 2000). If there are effects of the social context on individuals, these effects must be mediated by intervening processes that depend on characteristics of the social context. When the number of variables at the different levels is large, there is an enormous number of possible cross-level interactions (discussed in more detail in Chapter 2). Ideally, a multilevel theory should specify which direct effects and cross-level interaction effects can be expected. Theoretical interpretation of cross-level interaction effects between the individual and the context level require a specification of processes within individuals that cause those individuals to be differentially influenced by certain aspects of the context. Attempts to identify such processes have been made by, among others, Stinchcombe (1968), Erbring and Young (1979), and Chan (1998). The common core in these theories is that they all postulate processes that mediate between individual variables and group variables. Since a global explanation by 'group telepathy' is generally not acceptable, communication processes and the internal structure of groups become important concepts. These are often measured as a structural variable. In spite of their theoretical relevance, structural variables are infrequently used in multilevel research. Another theoretical area that has been largely neglected by multilevel researchers is the influence of individuals on the group. In multilevel modeling, the focus is on models where the outcome variable is at the lowest level. Models that investigate the influence of individual variables on group outcomes are scarce. For a review of this issue see DiPrete and Forristal (1994), an example is discussed by Alba and Logan (1992). Croon and van Veldhoven (2007) discuss analysis models for multilevel data where the outcome variable is at the highest level.

1.4 ESTIMATION AND SOFTWARE

A relatively new development in multilevel modeling is the use of Bayesian estimation methods. Bayesian estimation offers solutions to some estimation problems that are common in multilevel analysis, for example small sample sizes at the higher levels. Earlier editions of this book already introduced Bayesian estimation; in this edition the discussion of Bayesian estimation is expanded. We have chosen to do this by expanding the discussion of Bayesian methods where appropriate, rather than inserting a separate chapter on Bayesian methods. This book is not intended as a full introduction to Bayesian modeling. Our aim is to get the reader interested in Bayesian modeling by showing when and where it is helpful, and providing the necessary information to get started in this exciting field.

Many of the techniques and their specific software implementations discussed in this book are the subject of active statistical and methodological research. In other words: both the statistical techniques and the software tools are evolving rapidly. As a result, increasing numbers of researchers are applying increasingly advanced models to their data. Of course, researchers still need to understand the models and techniques that they use. Therefore, in addition to being an introduction to multilevel analysis, this book aims to let the reader become acquainted with some advanced modeling techniques that might be used, such as bootstrapping and Bayesian estimation methods. At the time of writing, these are specialist tools, and not part of the standard analysis toolkit. But they are developing rapidly, and are likely to become more popular in applied research as well.

2

The Basic Two-Level Regression Model

SUMMARY

The multilevel regression model has become known in the research literature under a variety of names, such as ‘random coefficient model’ (Kreft & de Leeuw, 1998), ‘variance component model’ (Searle et al., 1992; Longford, 1993), and ‘hierarchical linear model’ (Raudenbush & Bryk, 2002; Snijders & Bosker, 2012). Statistically oriented publications generally refer to the model as a ‘mixed-effects’ or ‘mixed linear model’ (Littell et al., 1996) and sociologists refer to it as ‘contextual analysis’ (Lazarsfeld & Menzel, 1961). The models described in these publications are not *exactly* the same, but they are highly similar, and we refer to them collectively as ‘multilevel regression models’. The multilevel regression model assumes that there is a hierarchical data set, often consisting of subjects nested within groups, with one single outcome or response variable that is measured at the lowest level, and explanatory variables at all existing levels. The multilevel regression model can be extended by adding an extra level for multiple outcome variables (see Chapter 10), while multilevel structural equation models are fully multivariate at all levels (see Chapter 14 and Chapter 15). Conceptually, it is useful to view the multilevel regression model as a hierarchical system of regression equations. In this chapter, we explain the multilevel regression model for two-level data, providing both the equations and an example, and later extend this model with a three-level example.

2.1 EXAMPLE

Assume that we have data from J classes, with a different number of pupils n_j in each class. On the pupil level, we have the outcome variable ‘popularity’ (Y), measured by a self-rating scale that ranges from 0 (very unpopular) to 10 (very popular). We have two explanatory variables on the pupil level: *pupil gender* (X_1 : 0 = boy, 1 = girl) and *pupil extraversion* (X_2 , measured on a self-rating scale ranging from 1–10), and one class-level explanatory variable *teacher experience* (Z : in years, ranging from 2–25). There are data on 2000 pupils in 100 classes, so the average class size is 20 pupils. The data are described in Appendix E. The data files and other support materials are also available online (at <https://multilevel-analysis.sites.uu.nl/>).

To analyze these data, we can set up separate regression equations in each class to predict the outcome variable Y using the explanatory variables X as follows:

$$Y_{ij} = \beta_{0j} + \beta_{1j}X_{1ij} + \beta_{2j}X_{2ij} + e_{ij} . \quad (2.1)$$

Using variable labels instead of algebraic symbols, the equation reads:

$$popularity_{ij} = \beta_{0j} + \beta_{1j}gender_{ij} + \beta_{2j}extraversion_{ij} + e_{ij} . \quad (2.2)$$

In this regression equation, β_{0j} is the intercept, β_{1j} is the regression coefficient (regression slope) for the dichotomous explanatory variable gender (i.e., the difference between boys and girls), β_{2j} is the regression coefficient (slope) for the continuous explanatory variable extraversion, and e_{ij} is the usual residual error term. The subscript j is for the classes ($j = 1 \dots J$) and the subscript i is for individual pupils ($i = 1 \dots n_j$). The difference with the usual regression model is that we assume that each class has a different intercept coefficient β_{0j} , and different slope coefficients β_{1j} and β_{2j} . This is indicated in Equations 2.1 and 2.2 by attaching a subscript j to the regression coefficients. The residual errors e_{ij} are assumed to have a mean of zero, and a variance to be estimated. Most multilevel software assumes that the variance of the residual errors is the same in all classes. Different authors (cf. Goldstein, 2011; Raudenbush & Bryk, 2002) use different systems of notation. This book uses σ_e^2 to denote the variance of the lowest level residual errors.

Figure 2.1 shows a single-level regression line for a dependent variable Y regressed on a single explanatory variable X . The regression line represents the predicted values \hat{y} for Y , the regression coefficient b_0 is the intercept, the predicted value for Y if $X = 0$. The regression slope b_1 indicates the predicted increase in Y if X increases by one unit.

Since in multilevel regression the intercept and slope coefficients vary across the classes, they are often referred to as *random* coefficients. Of course, we hope that this variation is not totally random, so we can explain at least some of the variation by introducing higher-level variables. Generally, we do not expect to explain all variation, so there will be some unexplained residual variation. In our example, the specific values for the intercept and the

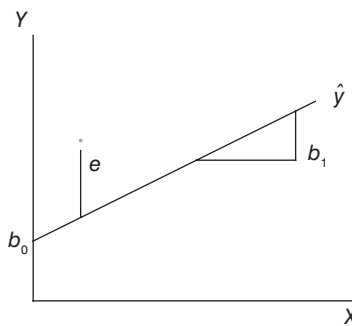


Figure 2.1 Example single-level regression line.

slope coefficients are a class characteristic. In general, a class with a high intercept is predicted to have more popular pupils than a class with a low value for the intercept. Since the model contains a dummy variable for gender, the value of the intercept reflects the predicted value for the boys (who are coded as zero). Varying intercepts shift the average value for the entire class, both boys and girls. Differences in the slope coefficient for gender or extraversion indicate that the relationship between the pupils' gender or extraversion and their predicted popularity is not the same in all classes. Some classes may have a high value for the slope coefficient of gender; in these classes, the difference between boys and girls is relatively large. Other classes may have a low value for the slope coefficient of gender; in these classes, gender has a small effect on the popularity, which means that the difference between boys and girls is small. Variance in the slope for pupil extraversion is interpreted in a similar way; in classes with a large coefficient for the extraversion slope, pupil extraversion has a large impact on their popularity, and vice versa.

Figure 2.2 presents an example with two groups. The panel on the left portrays two groups with no slope variation, and as a result the two slopes are parallel. The intercepts for both groups are different. The panel on the right portrays two groups with different slopes, or slope variation. Note that variation in slopes also has an effect on the difference between the intercepts!

Across all classes, the regression coefficients $\beta_{0j} \dots \beta_{2j}$ are assumed to have a multivariate normal distribution. The next step in the hierarchical regression model is to explain the variation of the regression coefficients $\beta_{0j} \dots \beta_{2j}$ by introducing explanatory variables at the class level, for the intercept

$$\beta_{0j} = \gamma_{00} + \gamma_{01}Z_j + u_{0j}, \quad (2.3)$$

and for the slopes

$$\begin{aligned} \beta_{1j} &= \gamma_{10} + \gamma_{11}Z_j + u_{1j} \\ \beta_{2j} &= \gamma_{20} + \gamma_{21}Z_j + u_{2j}. \end{aligned} \quad (2.4)$$

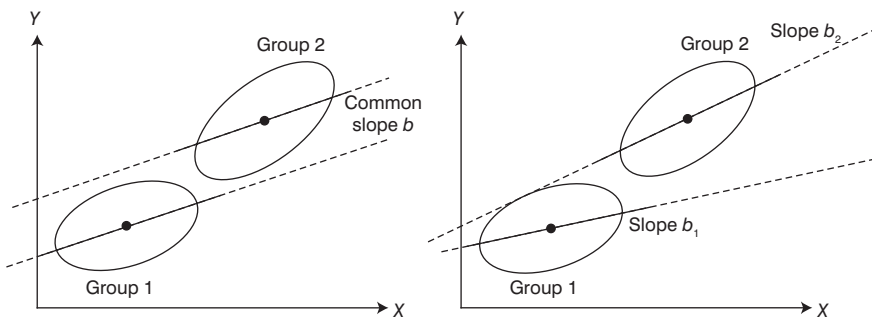


Figure 2.2 Two groups without (left) and with (right) random slopes.

Equation 2.3 predicts the average popularity in a class (the intercept β_{0j}) by the teacher's experience (Z). Thus, if γ_{01} is positive, the average popularity is higher in classes with a more experienced teacher. Conversely, if γ_{01} is negative, the average popularity is lower in classes with a more experienced teacher. The interpretation of the equations under 2.4 is a bit more complicated. The first equation under 2.4 states that the *relationship*, as expressed by the slope coefficient β_{1j} , between the popularity (Y) and the gender (X) of the pupil, depends upon the amount of experience of the teacher (Z). If γ_{11} is positive, the gender effect on popularity is larger with experienced teachers. Conversely, if γ_{11} is negative, the gender effect on popularity is smaller with more experienced teachers. Similarly, the second equation under 2.4 states, if γ_{21} is positive, that the effect of extraversion is larger in classes with an experienced teacher. Thus, the amount of experience of the teacher acts as a *moderator variable* for the relationship between popularity and gender or extraversion; this relationship varies according to the value of the moderator variable.

The u -terms u_{0j} , u_{1j} and u_{2j} in Equations 2.3 and 2.4 are (random) residual error terms at the class level. These residual errors u_j are assumed to have a mean of zero, and to be independent from the residual errors e_{ij} at the individual (pupil) level. The variance of the residual errors u_{0j} is specified as $\sigma_{u_0}^2$, and the variance of the residual errors u_{1j} and u_{2j} are specified as $\sigma_{u_1}^2$ and $\sigma_{u_2}^2$. The *covariances* between the residual error terms are denoted by $\sigma_{u_{01}}$, $\sigma_{u_{02}}$ and $\sigma_{u_{12}}$, which are generally *not* assumed to be zero.

Note that in Equations 2.3 and 2.4 the regression coefficients γ are not assumed to vary across classes. They therefore have no subscript j to indicate to which class they belong. Because they apply to *all* classes, they are referred to as *fixed* coefficients. All between-class variation left in the β coefficients, after predicting these with the class variable Z_j , is assumed to be residual error variation. This is captured by the residual error terms u_j , which do have subscripts j to indicate to which class they belong.

Our model with two pupil-level and one class-level explanatory variables can be written as a single complex regression equation by substituting Equations 2.3 and 2.4 into Equation 2.1. Substitution and rearranging terms gives:

$$Y_{ij} = \gamma_{00} + \gamma_{10}X_{1ij} + \gamma_{20}X_{2ij} + \gamma_{01}Z_j + \gamma_{11}X_{1ij}Z_j + \gamma_{21}X_{2ij}Z_j + u_{1j}X_{1ij} + u_{2j}X_{2ij} + u_{0j} + e_{ij} \quad (2.5)$$

Using variable labels instead of algebraic symbols, we have

$$\begin{aligned} \text{popularity}_{ij} = & \gamma_{00} + \gamma_{10} \text{gender}_{ij} + \gamma_{20} \text{extraversion}_{ij} + \gamma_{01} \text{experience}_j \\ & + \gamma_{11} \text{gender}_{ij} \cdot \text{experience}_j + \gamma_{21} \text{extraversion}_{ij} \times \text{experience}_j + u_{1j} \text{gender}_{ij} \\ & + u_{2j} \text{extraversion}_{ij} + u_{0j} + e_{ij} . \end{aligned}$$

The segment $[\gamma_{00} + \gamma_{10}X_{1ij} + \gamma_{20}X_{2ij} + \gamma_{01}Z_j + \gamma_{11}X_{1ij}Z_j + \gamma_{21}X_{2ij}Z_j]$ in Equation 2.5 contains the fixed coefficients. It is often called the fixed (or deterministic) part of the model. The segment $[u_{1j}X_{1ij} + u_{2j}X_{2ij} + u_{0j} + e_{ij}]$ in Equation 2.5 contains the random error terms, and it is often called

the random (or stochastic) part of the model. The terms X_{1j} and $X_{2j}Z_j$ are interaction terms that appear in the model as a consequence of modeling the varying regression slope β_j of a pupil-level variable X_{ij} with the class-level variable Z_j . Thus, the moderator effect of Z on the relationship between the dependent variable Y and the predictor X , is expressed in the single equation version of the model as a *cross-level interaction*. The interpretation of interaction terms in multiple regression analysis is complex, and this is treated in more detail in Chapter 4. In brief, the point made in Chapter 4 is that the substantive interpretation of the coefficients in models with interactions is much simpler if the variables making up the interaction are expressed as deviations from their respective means.

Note that the random error terms u_{ij} are connected to the X_{ij} . Since the explanatory variable X_{ij} and the corresponding error term u_{ij} are multiplied, the resulting error term will be different for different values of the explanatory variable X_{ij} , a situation that in ordinary multiple regression analysis is called ‘heteroscedasticity’. The usual multiple regression model assumes ‘homoscedasticity’, which means that the variance of the residual errors is independent of the values of the explanatory variables. If this assumption is not true, ordinary multiple regression does not perform very well. This is another reason why analyzing multilevel data with ordinary multiple regression techniques does not perform well.

As explained in the introduction in Chapter 1, multilevel models are needed because grouped data observations from the same group are generally more similar to each other than the observations from different groups, and this violates the assumption of independence of all observations. The amount of dependence can be expressed as a correlation coefficient: the intraclass correlation. The methodological literature contains a number of different formulas to estimate the intraclass correlation ρ . For example, if we use one-way analysis of variance with the grouping variable as independent variable to test the group effect on our outcome variable, the intraclass correlation is given by $\rho = [\text{MS(B)} - \text{MS(error)}] / [\text{MS(B)} + (n-1) \times \text{MS(error)}]$, where MS(B) is the between-groups mean square and n is the common group size. Shrout and Fleiss (1979) give an overview of formulas for the intraclass correlation for a variety of research designs.

The multilevel regression model can also be used to produce an estimate of the intraclass correlation. The model used for this purpose is a model that contains no explanatory variables at all, the so-called *intercept-only* or *empty* model (also referred to as baseline model). The intercept-only model is derived from Equations 2.1 and 2.3 as follows. If there are no explanatory variables X at the lowest level, Equation 2.1 reduces to

$$Y_{ij} = \beta_{0j} + e_{ij} . \quad (2.6)$$

Likewise, if there are no explanatory variables Z at the highest level, Equation 2.3 reduces to

$$\beta_{0j} = \gamma_{00} + u_{0j} . \quad (2.7)$$

We find the single equation model by substituting 2.7 into 2.6:

$$Y_{ij} = \gamma_{00} + u_{0j} + e_{ij}. \quad (2.8)$$

The intercept-only model of Equation 2.8 does not explain any variance in Y . It only decomposes the variance into two independent components: σ_e^2 , which is the variance of the lowest-level errors e_{ij} , and σ_{u0}^2 , which is the variance of the highest-level errors u_{0j} . These two variances sum up to the total variance, hence they are often referred to as variance components. Using this model, we can define the intraclass correlation ρ by the equation

$$\rho = \frac{\sigma_{u0}^2}{\sigma_{u0}^2 + \sigma_e^2}. \quad (2.9)$$

The intraclass correlation ρ indicates the proportion of the total variance explained by the grouping structure in the population. Equation 2.9 simply states that the intraclass correlation is the proportion of group-level variance compared to the total variance.¹ The intraclass correlation ρ can also be interpreted as the expected correlation between two randomly drawn units that are in the same group.

In the intercept-only model we defined variance of the lowest-level errors and variance of the highest-level errors. Both terms can be interpreted as unexplained variance on both levels since there are no predictors in the model specified yet. After adding predictors, just like in ordinary regression analyses, the R^2 , which is interpreted as the proportion of variance modeled by the explanatory variables, can be calculated. In the case of multilevel analyses, however, there is variance to be explained at every level (and also for random slope factors). The interpretation of these separate R^2 values are dependent on the ICC-values. For example, if the R^2 at the highest level appears to be 0.20 and the ICC is 0.40, then out of 40 percent of the total variance 20 percent is explained. This is further explained in Chapter 4.

2.2 AN EXTENDED EXAMPLE

The intercept-only model is useful as a null-model that serves as a benchmark with which other models are compared. For our pupil popularity example data, the intercept-only model is written as

$$popularity_{ij} = \gamma_{00} + u_{0j} + e_{ij}.$$

The model that includes pupil gender, pupil extraversion and teacher experience, but not the cross-level interactions, is written as

$$\begin{aligned} popularity_{ij} = & \gamma_{00} + \gamma_{10} gender_{ij} + \gamma_{20} extraversion_{ij} + \gamma_{01} experience_j + u_{1j} gender_{ij} \\ & + u_{2j} extraversion_{ij} + u_{0j} + e_{ij}. \end{aligned}$$

Table 2.1 Intercept-only model and model with explanatory variable

Model	Single-level model	M ₀ : intercept only	M ₁ : with predictors
Fixed part		Coefficient (s.e.)	Coefficient (s.e.)
Intercept	5.08 (.03)	5.08 (.09)	0.74 (.20)
Pupil gender			1.25 (.04)
Pupil extraversion			0.45 (.03)
Teacher experience			0.09 (.01)
Random part^a			
σ_e^2	1.91 (.06)	1.22 (.04)	0.55 (.02)
σ_{u0}^2		0.69 (.11)	1.28 (.47)
σ_{u1}^2			0.00 (–)
σ_{u2}^2			0.03 (.008)
Deviance	6970.4	6327.5	4812.8

a For simplicity the covariances are not included

Table 2.1 presents the parameter estimates and standard errors for both models.² For comparison, the first column presents the parameter estimates of a single-level model. The intercept is estimated correctly, but the variance term combines the level-one and level-two variances, and is for that reason not meaningful. M₀, the intercept-only two-level model, splits this variance term in a variance at the first and a variance at the second level. The intercept-only two-level model estimates the intercept as 5.08, which is simply the average popularity across all classes and pupils. The variance of the pupil-level residual errors, symbolized by σ_e^2 , is estimated as 1.22. The variance of the class-level residual errors, symbolized by σ_{u0}^2 , is estimated as 0.69. All parameter estimates are much larger than the corresponding standard errors, and calculation of the Z-test shows that they are all significant at $p < 0.005$.³ The intraclass correlation, calculated by equation 2.9 as $\rho = \sigma_{u0}^2 / (\sigma_{u0}^2 + \sigma_e^2)$, is 0.69 / 1.91, which equals 0.36. Thus, 36 percent of the variance of the popularity scores is at the group level, which is very high for social science data. Since the intercept-only model contains no explanatory variables, the residual variances represent unexplained error variance. The deviance reported in Table 2.1 is a measure of model misfit; when we add explanatory variables to the model, the deviance will go down.

The second model in Table 2.1 includes pupil gender and extraversion and teacher experience as explanatory variables. The regression coefficients for all three variables are significant. The regression coefficient for pupil gender is 1.25. Since pupil gender is coded 0 = boy, 1 = girl, this means that on average the girls score 1.25 points higher than boys on the popularity measure, when all other variables are kept constant. The regression coefficient for pupil extraversion is 0.45, which means that with each scale point higher on the extraversion

measure, the popularity is expected to increase with 0.45 scale points. The regression coefficient for teacher experience is 0.09, which means that for each year of experience of the teacher, the average popularity score of the class goes up by 0.09 points. This does not seem very much, but the teacher experience in our example data ranges from 2 to 25 years, so the predicted difference between the least experienced and the most experienced teacher is $(25 - 2) \times 0.09 = 2.07$ points on the popularity measure. The value of the intercept is generally not interpreted; it is the expected value of the dependent variable if all explanatory variables have the value zero. We can use the standard errors of the regression coefficients reported in Table 2.1 to construct a 95 percent confidence interval. For the regression coefficient of pupil gender, the 95 percent confidence interval runs from 1.17 to 1.33, the confidence interval for pupil extraversion runs from 0.39 to 0.51, and the 95 percent confidence interval for the regression coefficient of teacher experience runs from 0.07 to 0.11.⁴ Note that the interpretation of the regression coefficients in the fixed part is no different than in any other regression model (cf. Aiken & West, 1991).

The model with the explanatory variables includes variance components for the regression coefficients of pupil gender and pupil extraversion, symbolized by σ_{u1}^2 and σ_{u2}^2 in Table 2.1. The variance of the regression coefficients for pupil extraversion across classes is estimated as 0.03, with a standard error of 0.008. The variance of the regression coefficients for pupil gender is estimated as zero and not significant, so the hypothesis that the regression slopes for pupil gender vary across classes is not supported by the data. We should remove the residual variance term for the gender slopes from the model, and estimate the new model again. Table 2.2 presents the estimates for the model with a fixed slope for the effect of pupil gender. Table 2.2 also includes the covariance between the class-level errors for the intercept and the extraversion slope. These covariances are rarely interpreted (for an exception see Chapter 5

Table 2.2. Model with explanatory variables, extraversion slope random

Model	M_1 : with predictors
Fixed part	Coefficient (s.e.)
Intercept	0.74 (.20)
Pupil gender	1.25 (.04)
Pupil extraversion	0.45 (.02)
Teacher experience	0.09 (.01)
Random part	
σ_e^2	0.55 (.02)
σ_{u0}^2	1.28 (.28)
σ_{u2}^2	0.03 (.008)
σ_{u02}	-0.18 (.05)
Deviance	4812.8

and Chapter 16 where growth models are discussed), and for that reason they are often not included in the reported tables. However, as Table 2.2 demonstrates, they can be quite large and significant, so as a rule they are always included in the model.

The significant variance of the regression slopes for pupil extraversion implies that we should not interpret the estimated value of 0.45 without considering this variation. In an ordinary regression model, without multilevel structure, the value of 0.45 means that for each point difference on the extraversion scale, the pupil popularity goes up by 0.45, for all pupils in all classes. In our multilevel model, the regression coefficient for extraversion varies across the classes, and the value of 0.45 is just the expected value (the mean) across all classes. The varying regression slopes for pupil extraversion are assumed to follow a normal distribution. The variance of this distribution is in our example estimated as 0.034. Interpretation of this variation is easier when we consider the standard deviation, which is the square root of the variance and equal to 0.18 in our example data. A useful characteristic of the standard deviation is that with normally distributed observations, about 67 percent of the observations lie between one standard deviation below and above the mean, and about 95 percent of the observations lie between two standard deviations below and above the mean. If we apply this to the regression coefficients for pupil gender, we conclude that about 67 percent of the regression coefficients are expected to lie between $(0.45 - 0.18 =) 0.27$ and $(0.45 + 0.18 =) 0.63$, and about 95 percent are expected to lie between $(0.45 - 0.37 =) 0.08$ and $(0.45 + 0.37 =) 0.82$. The more precise value of $Z_{.975} = 1.96$ leads to the 95 percent predictive interval calculated as $0.09 - 0.81$. We can also use the standard normal distribution to estimate the percentage of regression coefficients that are negative. As it turns out, if the mean regression coefficient for pupil extraversion is 0.45, given the estimated slope variance, less than 1 percent of the classes are expected to have a regression coefficient that is actually negative. Note that the 95 percent interval computed here is totally different from the 95 percent confidence interval for the regression coefficient of pupil extraversion, which runs from 0.41 to 0.50. The 95 percent confidence interval applies to γ_{20} , the mean value of the regression coefficients across all the classes. The 95 percent interval calculated here is the 95 percent *predictive interval*, which expresses that 95 percent of the regression coefficients of the variable ‘pupil extraversion’ in the classes are predicted to lie between 0.09 and 0.81.

Given the significant variance of the regression coefficient of pupil extraversion across the classes, it is attractive to attempt to predict its variation using class-level variables. We have one class-level variable: teacher experience. The individual level regression equation for this example, using variable labels instead of symbols, is given by:

$$popularity_{ij} = \beta_{0j} + \beta_{1j}gender_{ij} + \beta_{2j}extraversion_{ij} + e_{ij} . \quad (2.10)$$

The regression coefficient β_1 for pupil gender does not have a subscript j , because it is not assumed to vary across classes. The regression equations predicting β_{0j} , the intercept in class j , and β_{2j} , the regression slope of pupil extraversion in class j , are given by Equation 2.3 and Equation 2.4, which are rewritten below using variable labels

$$\begin{aligned}\beta_{0j} &= \gamma_{00} + \gamma_{01}experience_j + u_{0j} \\ \beta_{2j} &= \gamma_{20} + \gamma_{21}experience_j + u_{2j}.\end{aligned}\quad (2.11)$$

By substituting 2.11 into 2.10 we get

$$\begin{aligned}popularity_{ij} &= \gamma_{00} + \gamma_{10}gender_{ij} + \gamma_{20}extraversion_{ij} + \gamma_{01}experience_j \\ &\quad + \gamma_{21}extraversion_{ij} \times experience_j + u_{2j}extraversion_{ij} + u_{0j} + e_{ij}\end{aligned}\quad (2.12)$$

The algebraic manipulations of the equations above make clear that to explain the variance of the regression slopes β_{2j} , we need to introduce an interaction term in the model. This interaction, between the variables pupil extraversion and teacher experience, is a cross-level interaction, because it involves explanatory variables from different levels. Table 2.3 presents the estimates from a model with this cross-level interaction. For comparison, the estimates for the model without this interaction are also included in Table 2.3.

Table 2.3 Model without and with cross-level interaction

Model	M _{1A} : main effects	M ₂ : with interaction
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	0.74 (.20)	-1.21 (.27)
Pupil gender	1.25 (.04)	1.24 (.04)
Pupil extraversion	0.45 (.02)	0.80 (.04)
Teacher experience	0.09 (.01)	0.23 (.02)
Extra*T.experience		-0.03 (.003)
Random part		
σ_e^2	0.55 (.02)	0.55 (.02)
σ_{u0}^2	1.28 (.28)	0.45 (.16)
σ_{u2}^2	0.03 (.008)	0.005 (.004)
$\sigma_{u_{02}}$	-0.18 (.05)	-0.03 (.02)
Deviance	4812.8	4747.6

The estimates for the fixed coefficients in Table 2.3 are similar for the effect of pupil gender, but the regression slopes for pupil extraversion and teacher experience are considerably larger in the cross-level model. The interpretation remains the same: extraverted pupils are more popular. The regression coefficient for the cross-level interaction is -0.03, which is small but significant. This interaction is formed by multiplying the scores for the variables 'pupil extraversion' and 'teacher experience', and the negative value means that with experienced teachers, the advantage of extraverted is smaller than expected from the direct effects only. Thus, the difference between extraverted and introverted pupils is smaller with more experienced teachers.

Comparison of the other results between the two models shows that the variance component for pupil extraversion goes down from 0.03 in the main effects model to 0.005 in the cross-level model. Apparently, the cross-level model explains some of the variation of the slopes for pupil extraversion. The deviance also goes down, which indicates that this model fits better than the previous model. The other differences in the random part are more difficult to interpret. Much of the difficulty in reconciling the estimates in the two models in Table 2.3 stems from adding an interaction effect. This issue is discussed in more detail in Chapter 4.

The coefficients in the tables are all unstandardized regression coefficients. To interpret them properly, we must take the scale of the explanatory variables into account. In multiple regression analysis, and structural equation models (SEM) for that matter, the regression coefficients are often standardized because that facilitates the interpretation when one wants to compare the effects of different variables within one sample. If the goal of the analysis is to compare parameter estimates from different samples to each other, one should always use unstandardized coefficients. To standardize the regression coefficients, as presented in Table 2.1 or Table 2.3, one could standardize all variables before putting them into the multilevel analysis. However, this would in general also change the estimates of the variance components, and their standard errors as well. Therefore, it is better to derive the standardized regression coefficients from the unstandardized coefficients:

$$\text{standardized coefficient} = \frac{\text{unstandardized coefficient} * \text{stand.dev.explanatory var.}}{\text{stand.dev.outcome var.}} \quad (2.13)$$

In our example data, the standard deviations are: 1.38 for popularity, 0.51 for gender, 1.26 for extraversion, and 6.55 for teacher experience. Table 2.4 presents the unstandardized and standardized coefficients for the second model in Table 2.2. It also presents the estimates that we obtain if we first standardize all variables, and then carry out the analysis.

Table 2.4 shows that the standardized regression coefficients are almost the same as the regression coefficients estimated for standardized variables. The small differences in Table 2.4 are simply due to rounding errors. However, if we use standardized variables in our analysis, we find very different variance components and a very different value for the deviance. This is not only the effect of scaling the variables differently; the covariance between the slope for pupil extraversion and the intercept is significant for the unstandardized variables, but not significant for the standardized variables. This kind of difference in results is general. The fixed part of the multilevel regression model is invariant for linear transformations, just as the regression coefficients in the ordinary single-level regression model. This means that if we change the scale of our explanatory variables, the regression coefficients and the corresponding standard errors change by the same multiplication factor, and all associated *p*-values remain exactly the same. However, the random part of the multilevel regression model is not invariant for linear transformations. The estimates of the variance components in the random part can and do change, sometimes dramatically. This is discussed in more detail in Section 4.2 in Chapter

Table 2.4 Comparing unstandardized and standardized estimates

Model	Standardization using 2.13		Standardized variables
Fixed part	Coefficient (s.e.)	Standardized	Coefficient (s.e.)
Intercept	0.74 (.20)	—	−0.03 (.04)
Pupil gender	1.25 (.04)	0.46	0.45 (.01)
Pupil extraversion	0.45 (.02)	0.41	0.41 (.02)
Teacher experience	0.09 (.01)	0.43	0.43 (.04)
Random part			
σ_e^2	0.55 (.02)		0.28 (.01)
σ_{u0}^2	1.28 (.28)		0.15 (.02)
σ_{u2}^2	0.03 (.01)		0.03 (.01)
$\sigma_{u_{02}}$	−0.18 (.01)		−0.01 (.01)
Deviance	4812.8		3517.2

4. The conclusion to be drawn here is that, if we have a complicated random part, including random components for regression slopes, we should think carefully about the scale of our explanatory variables. If our only goal is to present standardized coefficients in addition to the unstandardized coefficients, applying Equation 2.13 is safer than transforming our variables. On the other hand, we may estimate the unstandardized results, including the random part and the deviance, and then re-analyze the data using standardized variables, merely using this analysis as a computational trick to obtain the standardized regression coefficients without having to do hand calculations.

2.3 THREE- AND MORE LEVEL REGRESSION MODELS

2.3.1 Multiple-Level Models

In principle, the extension of the two-level regression model to three and more levels is straightforward. There is an outcome variable at the first, the lowest level. In addition, there may be explanatory variables at all available levels. The problem is that three- and more level models can become complicated very fast. In addition to the usual fixed regression coefficients, we must entertain the possibility that regression coefficients for first-level explanatory variables may vary across units of both the second and the third levels. Regression coefficients for second-level explanatory variables may vary across units of the third level. To explain such variation, we must include cross-level interactions in the model. Regression slopes for the cross-level interaction between first-level and second-

level variables may themselves vary across third-level units. To explain such variation, we need a three-way interaction involving variables at all three levels.

The equations for such models are complicated, especially when we do not use the more compact summation notation but write out the complete single equation-version of the model in an algebraic format (for a note on notation see Section 2.4).

The resulting models are not only difficult to follow from a conceptual point of view; they may also be difficult to estimate in practice. The number of estimated parameters is considerable, and at the same time the highest level sample size tends to become relatively smaller. As DiPrete and Forristal (1994, p. 349) put it, the imagination of the researchers "... can easily outrun the capacity of the data, the computer, and current optimization techniques to provide robust estimates."

Nevertheless, three- and more level models have their place in multilevel analysis. Intuitively, three-level structures such as pupils in classes in schools, or respondents nested within households, nested within regions, appear to be both conceptually and empirically manageable. If the lowest level is repeated measures over time, having repeated measures on pupils nested within schools again does not appear to be overly complicated. In such cases, the solution for the conceptual and statistical problems mentioned is to keep models reasonably small. Especially specification of the higher-level variances and covariances should be driven by theoretical considerations. A higher-level variance for a specific regression coefficient implies that this regression coefficient is assumed to vary across units at that level. A higher-level covariance between two specific regression coefficients implies that these regression coefficients are assumed to covary across units at that level. Especially when models become large and complicated, it is advisable to avoid higher-order interactions, and to include in the random part only those elements for which there is strong theoretical or empirical justification. This implies that an exhaustive search for second-order and higher-order interactions is not a good idea. In general, we should seek for higher-order interactions only if there is strong theoretical justification for their importance, or if an unusually large variance component for a regression slope calls for explanation. For the random part of the model, there are usually more convincing theoretical reasons for the higher-level variance components than for the covariance components. Especially if the covariances are small and non-significant, analysts sometimes do not include all possible covariances in the model. This is defensible, with some exceptions. First, it is recommended that the covariances between the intercept and the random slopes are always included. Second, it is recommended to include covariances corresponding to slopes of dummy variables belonging to the same categorical variable, and for variables that are involved in an interaction or belong to the same polynomial expression.

2.3.2 Intraclass Correlations in Three-Level Models

In a two-level model, the intraclass correlation is calculated in the intercept-only model using Equation 2.9, which is repeated below:

$$\rho = \frac{\sigma_{u_0}^2}{\sigma_{u_0}^2 + \sigma_e^2}. \quad (2.9, \text{repeated})$$

The intraclass correlation is an indication of the proportion of variance at the second level, and it can also be interpreted as the expected (population) correlation between two randomly chosen individuals within the same group.

If we have a three-level model, for instance pupils nested within classes, nested within schools, there are two ways to calculate the intraclass correlation. First, we estimate an intercept-only model for the three-level data, for which the single-equation model can be written as follows:

$$Y_{ijk} = \gamma_{000} + v_{0k} + u_{0jk} + e_{ijk}. \quad (2.15)$$

The variances at the first, second, and third level are respectively σ_e^2 , $\sigma_{u_0}^2$, and $\sigma_{v_0}^2$. The first method (cf. Davis & Scott, 1995) defines the intraclass correlations at the class and school level as

$$\rho_{class} = \frac{\sigma_{u_0}^2}{\sigma_{v_0}^2 + \sigma_{u_0}^2 + \sigma_e^2}, \quad (2.16)$$

and

$$\rho_{school} = \frac{\sigma_{v_0}^2}{\sigma_{v_0}^2 + \sigma_{u_0}^2 + \sigma_e^2}. \quad (2.17)$$

The second method (cf. Siddiqui et al., 1996) defines the intraclass correlations at the class and school level as

$$\rho_{class} = \frac{\sigma_{v_0}^2 + \sigma_{u_0}^2}{\sigma_{v_0}^2 + \sigma_{u_0}^2 + \sigma_e^2}, \quad (2.18)$$

and

$$\rho_{school} = \frac{\sigma_{v_0}^2}{\sigma_{v_0}^2 + \sigma_{u_0}^2 + \sigma_e^2}. \quad (2.19)$$

Actually, both methods are correct (Algina, 2000). The first method identifies the proportion of variance at the class and school level. This should be used if we are interested in a decomposition of the variance across the available levels, or if we are interested in how much variance is located at each level (a topic discussed in Section 4.5). The second method represents an estimate of the expected (population) correlation between two randomly chosen elements in the same group. So ρ_{class} as calculated in Equation 2.18 is the expected correlation between two pupils within the same class, and it correctly takes into account that two pupils who are in the same class must by definition also be in the same school. For this reason, the variance components for classes and schools must both be in the numerator of Equation 2.18. If the two sets of estimates are different, which may happen if the amount of variance at the

school level is large, there is no contradiction involved. Both sets of equations express two different aspects of the data, which happen to coincide when there are only two levels. The first method, which identifies the proportion of variance at each level, is the one most often used.

2.3.3 An Example of a Three-Level Model

The data in this example are from a hypothetical study on stress in hospitals. The data are from nurses working in wards nested within hospitals. In each of 25 hospitals, four wards are selected and randomly assigned to an experimental and control condition. In the experimental condition, a training program is offered to all nurses to cope with job-related stress. After the program is completed, a sample of about 10 nurses from each ward is given a test that measures job-related stress. Additional variables are: nurse age (years), nurse experience (years), nurse gender (0 = male, 1 = female), type of ward (0 = general care, 1 = special care), and hospital size (0 = small, 1 = medium, 2 = large).

This is an example of an experiment where the experimental intervention is carried out on a higher level, in this example the ward level. In biomedical research this design is known as a multisite cluster randomized trial. They are quite common also in educational and organizational research, where entire classes or schools are assigned to experimental and control conditions. Since the design variable Experimental versus Control group (ExpCon) is manipulated at the second (ward) level, we can study whether the experimental effect is different in different hospitals, by defining the regression coefficient for the ExpCon variable as random at the hospital level.

In this example, the variable ExpCon is of main interest, and the other variables are covariates. Their function is to control for differences between the groups, which can occur even if randomization is used, especially with small samples, and to explain variance in the outcome variable stress. To the extent that these variables successfully explain variance, the power of the test for the effect of ExpCon will be increased. Therefore, although logically we can test if explanatory variables at the first level have random coefficients at the second or third level, and if explanatory variables at the second level have random coefficients at the third level, these possibilities are not pursued. We do test a model with a random coefficient for ExpCon at the third level, where there turns out to be significant slope variation. This varying slope can be predicted by adding a cross-level interaction between the variables *expcon* and *hospsize*. In view of this interaction, the variables *expcon* and *hospsize* have been centered on their overall mean.⁵ Table 2.5 presents the results for a series of models.

The equation for the first model, the intercept-only model is

$$stress_{ijk} = \gamma_{000} + v_{0k} + u_{0jk} + e_{ijk} \quad (2.20)$$

This produces the variance estimates in the M_0 column of Table 2.5. The proportion of variance (ICC) is 0.52 at the ward level, and 0.17 at the hospital level, calculated following Equations 2.18 and 2.19. The nurse-level and the ward-level variances are evidently significant.

Table 2.5 Models for stress in hospitals and wards

Model	M ₀ : intercept only	M ₁ : with predictors	M ₂ : with random slope ExpCon	M ₃ : with cross-level interaction
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	5.00 (0.11)	5.50 (.12)	5.46 (.12)	5.50 (.11)
ExpCon ^a		−0.70 (.12)	−0.70 (.18)	−0.50 (.11)
Age		0.02 (.002)	0.02 (.002)	0.02 (.002)
Gender		−0.45 (.03)	−0.45 (.03)	−0.45 (.03)
Experience		−0.06 (.004)	−0.06 (.004)	−0.06 (.004)
Ward type		0.05 (.12)	0.05 (.07)	0.05 (.07)
Hospital size ^a		0.46 (.12)	0.29 (.12)	0.46 (.12)
Exp × HSize				1.00 (.16)
Random part				
$\sigma^2_{e\ ijk}$	0.30 (.01)	0.22 (.01)	0.22 (.01)	0.22 (.01)
$\sigma^2_{u0\ jk}$	0.49 (.09)	0.33 (.06)	0.11 (.03)	0.11 (.03)
σ^2_{v0k}	0.16 (.09)	0.10 (0.05)	0.166 (.06)	0.15 (.05)
σ^2_{u1k}			0.66 (.22)	0.18 (.09)
Deviance	1942.4	1604.4	1574.2	1550.8

^a Centered on grand mean

The test statistic for the hospital-level variance is $Z = 0.162 / 0.0852 = 1.901$, which produces a one-sided p -value of 0.029. The hospital-level variance is significant at the 5 percent level. The sequence of models in Table 2.5 shows that all predictor variables have a significant effect, except the ward type, and that the experimental intervention significantly lowers stress. The experimental effect varies across hospitals, and a large part of this variation can be explained by hospital size; in large hospitals the experimental effect is smaller.

2.4 NOTATION AND SOFTWARE

2.4.1 Notation

In general, there will be more than one explanatory variable at the lowest level and more than one explanatory variable at the highest level. Assume that we have P explanatory variables X at the lowest level, indicated by the subscript p ($p = 1 \dots P$). Likewise, we have Q explanatory variables Z at the highest level, indicated by the subscript q ($q = 1 \dots Q$). Then, Equation 2.5 becomes the more general equation:

$$Y_{ij} = \gamma_{00} + \gamma_{p0} X_{pij} + \gamma_{0q} Z_{qj} + \gamma_{pq} Z_{qj} X_{pij} + u_{pj} X_{pij} + u_{0j} + e_{ij}. \quad (2.21)$$

Using summation notation, we can express the same equation as

$$Y_{ij} = \gamma_{00} + \sum_p \gamma_{p0} X_{pij} + \sum_q \gamma_{0q} Z_{qj} + \sum_p \sum_q \gamma_{pq} X_{pij} Z_{qj} + \sum_p u_{pj} X_{pij} + u_{0j} + e_{ij}. \quad (2.22)$$

The errors at the lowest level e_{ij} are assumed to have a normal distribution with a mean of zero and a common variance σ_e^2 in all groups. The u -terms u_{0j} and u_{pj} are the residual error terms at the highest level. They are assumed to be independent from the errors e_{ij} at the individual level, and to have a multivariate normal distribution with means of zero. The variance of the residual errors u_{0j} is the variance of the intercepts between the groups, symbolized by $\sigma_{u_0}^2$. The variances of the residual errors u_{pj} are the variances of the slopes between the groups, symbolized by $\sigma_{u_p}^2$. The *covariances* between the residual error terms $\sigma_{u_{pp'}}$ are generally not assumed to be zero; they are collected in the higher-level variance/covariance matrix Ω .⁶

Note that in Equation 2.15, γ_{00} , the regression coefficient for the intercept, is not associated with an explanatory variable. We can expand the equation by providing an explanatory variable that is a constant equal to one for all observed units. This yields the equation

$$Y_{ij} = \gamma_{p0} X_{pij} + \gamma_{pq} Z_{qj} X_{pij} + u_{pj} X_{pij} + e_{ij} \quad (2.23)$$

where $X_{0ij} = 1$, and $p = 0 \dots P$. Equation 2.23 makes clear that the intercept is a regression coefficient, just like the other regression coefficients in the equation. Some multilevel software, for instance HLM (Raudenbush et al., 2011) puts the intercept variable $X_0 = 1$ in the regression equation by default. Other multilevel software, for instance MLwiN (Rasbash et al., 2015), requires that the analyst includes a variable in the data set that equals one in all cases, which must be added explicitly to the regression equation.

Equation 2.23 can be made very general if we let X be the matrix of all explanatory variables in the fixed part, symbolize the residual errors at all levels by $u^{(l)}$ with l denoting the level, and associate all error components with predictor variables Z , which may or may not be equal to the X . This produces the very general matrix formula $Y = X\beta + Z^{(l)}u^{(l)}$ (cf. Goldstein, 2011, Appendix 2.1). Since this book is more about applications than about mathematical statistics, it generally uses the algebraic notation, except when multivariate procedures such as structural equation modeling are discussed.

The notation used in this book is close to the notation used by Goldstein (2011) and Kreft and de Leeuw (1998). The most important difference is that these authors indicate the higher-level variance by σ_{00} instead of our $\sigma_{u_0}^2$. The logic is that, if σ_{01} indicates the covariance between variables 0 and 1, then σ_{00} is the covariance of variable 0 with itself, which is its variance. Raudenbush and Bryk (2002), and Snijders and Bosker (2012) use a different notation; they denote the lowest level error terms by r_{ij} , and the higher-level error terms by u_j .

The lowest-level variance is σ^2 in their notation. The higher-level variances and covariances are indicated by the Greek letter τ (tau); for instance, the intercept variance is given by τ_{00} . The τ_{pp} are collected in the matrix Tau, symbolized as T. The HLM program and manual in part use a different notation, for instance when discussing longitudinal and three-level models.

In models with more than two levels, two different notational systems are used. One approach is to use different Greek characters for the regression coefficients at different levels, and different (Greek or Latin) characters for the variance terms at different levels. With many levels, this becomes cumbersome, and it is simpler to use the same character, say β for the regression slopes and u for the residual variance terms, and let the number of subscripts indicate to which level these belong.

2.4.2 Software

Multilevel models can be formulated in two ways: (1) by presenting separate equations for each of the levels, and (2) by combining all equations by substitution into a single model-equation. The softwares HLM (Raudenbush et al., 2011) and Mplus (Muthén & Muthén, 1998–2015) require specification of the separate equations at each available level. Most other software, e.g., MLwiN (Rasbash et al., 2015), SAS Proc Mixed (Littell et al., 1996), SPSS command Mixed (Norusis, 2012), and the R package LME4 (Bates et al., 2015) use the single equation representation. Both representations have their advantages and disadvantages. The separate-equation representation has the advantage that it is always clear how the model is built up. The disadvantage is that it hides from view that modeling regression slopes by other variables is equivalent to adding a cross-level interaction to the model. As will be explained in Chapter 4, estimating and interpreting interactions correctly requires careful thinking. On the other hand, while the single-equation representation makes the existence of interactions obvious, it conceals the role of the complicated error components that are created by modeling varying slopes. In practice, to keep track of the model, it is recommended to start by writing the separate equations for the separate levels, and to use substitution to arrive at the single-equation representation.

To take a quote from Singer's excellent introduction to using SAS Proc Mixed for multilevel modeling (Singer, 1998, p. 350): 'Statistical software does not a statistician make. That said, without software, few statisticians and even fewer empirical researchers would fit the kinds of sophisticated models being promulgated today.' Indeed, software does not make a statistician, but the advent of powerful and user-friendly software for multilevel modeling has had a large impact in research fields as diverse as education, organizational research, demography, epidemiology, and medicine. This book focuses on the conceptual and statistical issues that arise in multilevel modeling of complex data structures. It assumes that researchers who apply these techniques have access to and familiarity with *some* software that can estimate these models. Specific software is mentioned in some places, but only if a technique is discussed that requires specific software features or is only available in a specific program.

Since statistical software evolves rapidly, with new versions of the software coming out much faster than new editions of general handbooks such as this, we do not discuss software setups or output in detail. As a result, this book is more about the possibilities offered by the various techniques than about how these things can be done in a specific software package. The techniques are explained using analyses on small but realistic data sets, with examples of how the results could be presented and discussed. At the same time, if the analysis requires that the software used have some specific capacities, these are pointed out. This should enable interested readers to determine whether their software meets these requirements, and assist them in working out the software setups for their favorite package.

In addition to the relevant program manuals, several software programs have been discussed in introductory articles. Using SAS Proc Mixed for multilevel and longitudinal data is discussed by Singer (1998). Peugh and Enders (2005) discuss SPSS Mixed using Singer's examples. Both Arnold (1992), and Heck and Thomas (2009) discuss multilevel modeling using HLM and Mplus as the software tool. Sullivan, Dukes and Losina (1999) discuss HLM and SAS Proc Mixed. West, Welch and Gatecki (2007) present a series of multilevel analyses using SAS, SPSS, R, Stata and HLM. Heck, Thomas and Tabata (2012, 2014) discuss SPSS. Finally, the multilevel modeling program at the University of Bristol maintains a multilevel homepage that contains a series of software reviews. The homepage for this book contains links to these and other multilevel resources (at <https://multilevel-analysis.sites.uu.nl/>).

The data sets used in the examples are described in the resources. In addition, it contains the data sets used in the examples and described in Appendix E (<https://multilevel-analysis.sites.uu.nl/>).

NOTES

- 1 The intraclass correlation is an estimate of the proportion of group-level variance *in the population*. The proportion of group-level variance in the *sample* is given by the correlation ratio η^2 (eta-squared, cf. Tabachnick & Fidell, 2013, p. 54): $\mu^2 = SS(B)/SS(\text{Total})$.
- 2 For reasons to be explained later, different options for the details of the maximum likelihood estimation procedure may result in slightly different estimates. So, if you re-analyze the example data from this book, the results may differ slightly from the results given here. However, these differences should never be so large that you would draw entirely different conclusions.
- 3 Testing variances is preferably done with a test based on the deviance, which is explained in Chapter 3.
- 4 Chapter 3 treats the interpretation of confidence intervals in more detail.
- 5 Chapter 4 discusses the interpretation of interactions and centering.
- 6 We may attach a subscript to Ω to indicate to which level it belongs. As long as there is no risk of confusion, the simpler notation without the subscript is used.

3

Estimation and Hypothesis Testing in Multilevel Regression

SUMMARY

The usual method to estimate the values of the regression coefficients and the intercept and slope variances is the maximum likelihood estimation method. This chapter gives a non-technical explanation of maximum likelihood estimation, to enable analysts to make informed decisions on the estimation options offered by current software. Some alternatives to maximum likelihood estimation are briefly discussed. Other estimation methods, such as Bayesian estimation methods and bootstrapping, are also briefly introduced in this chapter. Finally, this chapter describes some procedures that can be used to compare nested and non-nested models, which are especially useful when variance terms are tested.

3.1 WHICH ESTIMATION METHOD?

Estimation of parameters (regression coefficients and variance components) in multilevel modeling is mostly done by the maximum likelihood method. The maximum likelihood (ML) method is a general estimation procedure, which produces estimates for the population parameters that maximize the probability (produce the ‘maximum likelihood’) of observing the data that are actually observed, given the model (cf. Eliason, 1993). Other estimation methods that have been used in multilevel modeling are generalized least squares (GLS), generalized estimating equations (GEE), bootstrapping methods and Bayesian methods such as Markov chain Monte Carlo (MCMC). In this section, we will discuss these methods briefly.

3.1.1 Maximum Likelihood (ML): Full and Restricted ML Estimation

Maximum likelihood (ML) is the most commonly used estimation method in multilevel modeling. The results presented in Chapter 2 are all obtained using full ML estimation. An advantage of the maximum likelihood estimation method is that it is generally robust, and produces estimates that are asymptotically (i.e, when the sample size approximates infinity) efficient and consistent. With large samples, ML estimates are usually robust against mild violations of the assumptions, such as having non-normal errors. Maximum likelihood estimation proceeds by maximizing a function called the likelihood function.

Two different likelihood functions are used in multilevel regression modeling. One is full maximum likelihood (FML); in this method, both the regression coefficients and the variance components are included in the likelihood function. The other estimation method is restricted maximum likelihood (RML); here only the variance components are included in the likelihood function, and the regression coefficients are estimated in a second estimation step. Both methods produce parameter estimates with associated standard errors and an overall model *deviance*, which is a function of the likelihood. FML treats the regression coefficients as fixed but unknown quantities when the variance components are estimated, but does not take into account the degrees of freedom lost by estimating the fixed effects. RML estimates the variance components after removing the fixed effects from the model (cf. Searle et al., 1992, Chapter 6). As a result, FML estimates of the variance components are biased; they are generally too small. RML estimates have less bias (Longford, 1993). RML also has the property, that if the groups are balanced (have equal group sizes), the RML estimates are equivalent to ANOVA estimates, which are optimal (Searle et al., 1992, p. 254). Since RML is more realistic, it should, in theory, lead to better estimates, especially when the number of groups is small (Bryk & Raudenbush, 1992; Longford, 1993). In practice, the differences between the two methods are usually small (cf. Hox, 1998; Kreft & de Leeuw, 1998). For example, if we compare the FML estimates for the intercept-only model for the popularity data in Table 2.1 with the corresponding RML estimates, the only difference within two decimals is the intercept variance at level two. FML estimates this as 0.69, and RML as 0.70. The size of this difference is absolutely trivial. If nontrivial differences are found, the RML method is preferred (Browne, 1998). FML still continues to be used, because it has two advantages over RML. Firstly, the computations are generally easier, and secondly, since the regression coefficients are included in the likelihood function, an overall chi-square test based on the likelihood can be used to compare two models that differ in the fixed part (the regression coefficients). With RML, only differences in the random part (the variance components) can be compared with this test. Most tables in this book have been produced using FML estimation; if RML is used this is explicitly stated in the text.

Computing the maximum likelihood estimates requires an *iterative* procedure. At the start, the computer program generates reasonable starting values for the various parameters (for example based on single-level regression estimates). In the next step, an ingenious computation procedure tries to improve upon the starting values, to produce better estimates. This second step is repeated (iterated) many times. After each iteration, the program inspects how much the estimates actually changed compared to the previous step. If the changes are very small, the program concludes that the estimation procedure has *converged* and that it is finished. Using multilevel software, we generally take the computational details for granted. However, computational problems do sometimes occur. A problem common to programs using an iterative maximum likelihood procedure is that the iterative process is not always *guaranteed* to stop. There are models and data sets for which the program may go through an endless sequence of iterations, which can only be ended by stopping the program. Because of

this, most programs set a built-in limit to the maximum number of iterations. If convergence is not reached within this limit, the computations can be repeated with a higher limit. If the computations do not converge after an extremely large number of iterations, we suspect that they may never converge.¹ The problem is how one should interpret a model that does not converge. The usual interpretation is that a model for which convergence cannot be reached is a bad model, using the simple argument that if estimates cannot be found, this disqualifies the model. However, the problem may also lie with the data. Especially with small samples, the estimation procedure may fail even if the model is valid. In addition, it is even possible that, if only we had a better computer algorithm, or better starting values, we could find acceptable estimates. Still, experience shows that if a program does not converge with a data set of reasonable size, the problem often is a badly misspecified model. In multilevel analysis, non-convergence often occurs when we try to estimate too many random (variance) components that are actually close or equal to zero. The solution is to simplify the model by leaving out some random components; often the estimated values from the non-converged solution provide an indication which random components can be omitted. The strategy you apply to solve convergence issues should be reported in your logbook and/or paper.

3.1.2 Generalized Least Squares

Generalized least squares (GLS) is an extension of the standard estimation ordinary least squares (OLS) method that allows for heterogeneity and observations that differ in sampling variance. GLS estimation approximates ML estimates, and they are asymptotically equivalent. Asymptotic equivalence means that in very large samples they are in practice indistinguishable. ‘Expected GLS’ estimates can be obtained from a maximum likelihood procedure by restricting the number of iterations to one. Since GLS estimates are obviously faster to compute than full ML estimates, they can be used as a stand-in for ML estimates in computationally intensive procedures such as extremely large data sets. They can also be used when ML procedures fail to converge; inspecting the GLS results may help to diagnose the problem. Simulation research has shown that GLS estimates are less efficient, and that the GLS-derived standard errors are inaccurate (cf. Hox, 1998; van der Leeden et al., 2008; Kreft, 1996). Therefore, in general, ML estimation should be preferred.

3.1.3 Generalized Estimating Equations

The generalized estimating equations method (GEE, cf. Liang & Zeger, 1986) estimates the variances and covariances in the random part of the multilevel model directly from the residuals, which makes them faster to compute than full ML estimates. Typically, the dependences in the multilevel data are accounted for by a very simple model, represented by a *working correlation matrix*. For individuals within groups, the simplest assumption is that the respondents within the same group all have the same correlation. For repeated measures,

a simple autocorrelation structure is usually assumed. After the estimates for the variance components are obtained, GLS is used to estimate the fixed regression coefficients. Robust standard errors are generally used to counteract the approximate estimation of the random structure. For non-normal data this results in a *population average model*, where the emphasis is on estimating average population effects and not on modeling individual differences.

According to Goldstein (2011) and Raudenbush & Bryk (2002), GEE estimates are less efficient than full ML estimates, but they make weaker assumptions about the structure of the random part of the multilevel model. If the model for the random part is correctly specified, ML estimators are more efficient, and the model-based (ML) standard errors are generally smaller than the GEE-based robust standard errors. If the model for the random part is incorrect, the GEE-based estimates and robust standard errors are still consistent. So, provided the sample size is reasonably large, GEE estimators are robust against misspecification of the random part of the model, including violations of the normality assumption. A drawback of the GEE approach is that it only approximates the random effects structure, and therefore the random effects cannot be analyzed in detail. Most software will simply estimate a full unstructured covariance matrix for the random part, which makes it impossible to estimate random effects for the intercept or slopes. Given the general robustness of ML methods, it is preferable to use ML methods when these are available, and use robust estimators or bootstrap corrections when there is serious doubt about the assumptions of the ML method. Robust estimators, which are used with GEE estimators (Burton et al., 1998), are treated in more detail in Chapter 13 of this book.

3.2 BAYESIAN METHODS

In many different fields, including the field of multilevel analysis, Bayesian statistics is gaining popularity (van de Schoot et al., 2017), mainly because it can deal with all kinds of technical issues, for example multicollinearity (Can et al., 2014) or non-normality (see Chapter 13), or because it can deal with smaller sample sizes on the highest level (e.g., Baldwin & Fellingham, 2013). The scope of this paragraph is not to provide a full introduction to Bayesian multilevel modeling, for this we refer to Hamaker and Klugkist (2011). For a very gentle introduction to Bayesian modeling, we refer the novice reader to, among many others, Kaplan (2014), or van de Schoot et al. (2014). More detailed information about Bayesian multilevel modeling can be found in Gelman and Hill (2007). For a discussion in the context of MLwiN see Browne (2005). In the current chapter, and see also Section 13.5, we want to highlight some important characteristics of Bayesian estimation.

There are three essential ingredients underlying Bayesian statistics. The first ingredient is the background knowledge of the parameters in the model being tested. This first ingredient refers to all knowledge available before seeing the data and is captured in the so-called prior distribution. The prior is a probability distribution reflecting the researchers' beliefs about the value of the parameter in the population, and the amount of uncertainty the researcher has

regarding this belief. Researchers may have a great degree of certainty in their belief, and therefore specify an “informative prior”—that is, a prior with a low variance. In contrast, they may have very little certainty in this belief, and consequently specify a non-informative prior—that is, a prior with a large variance, also known as a diffuse or flat prior. The informativeness of a prior is governed by hyperparameters. For example, the hyperparameters for a normal distribution are the mean and variance terms that dictate the location and spread of the normal distribution. A normally distributed prior would be written $N(\mu, \sigma^2)$, where N denotes that the prior follows a normal distribution (other distributions can also be specified in a model), the mean of the prior is given by μ , and σ^2 is the prior variance. Consequently, μ can be based on background information about the model parameter value, and σ^2 can be used to specify how certain we are about the value of μ . The more informative a prior, the larger the impact it will have on final model results, especially if the prior is combined with small sample sizes. If a non-informative prior is desired, this is accomplished by specifying a very large variance for the prior. Many simulations studies have shown that the more information is captured via the prior distribution the smaller the sample size can become while maintaining power and precision.

The second ingredient in Bayesian estimation is the information in the data itself. It is the observed evidence expressed in terms of the likelihood function of the data given the parameters. In other words, the likelihood function asks: “given a set of parameters, such as the mean and/or the variance, what is the likelihood or probability of the data at hand?”

The third ingredient is based on combining the first two ingredients, which is called posterior inference. Both (1) and (2) are combined via Bayes Theorem and are summarized by the so-called posterior distribution, which is a combination of the prior knowledge and the observed evidence. The posterior distribution reflects one’s updated knowledge, balancing prior knowledge with observed data. Given that the posterior is a combination of information from the prior and the data, a more informative prior has a larger impact on the posterior (or final result).

The use of prior knowledge is one of the main elements that separate Bayesian and frequentist methods. However, the process of estimating a Bayesian model can also be quite different. Typically, Markov chain Monte Carlo (MCMC) methods are used, where estimation is conducted through the use of a Markov chain—or a chain that captures the nature of the posterior. Given that the posterior is a distribution (rather than a single, fixed number), we need to sample from it in order to obtain a “best guess” of what the posterior looks like. These samples from the posterior distribution form what we refer to as a chain. Every model parameter has a chain associated with it, and once that chain has converged (i.e., the mean—or horizontal middle of the chain—and the variance—or height of the chain—have stabilized), we use the information in the chain to derive the final model estimates. Often, the beginning portion of the chain is discarded because it represents an unstable part before convergence is reached; this portion of the chain is called the burn-in phase. The last portion of the chain, the post burn-in phase of the chain, is then used as the estimated posterior distribution where final model estimates are obtained.

The prior has the potential to have a rather large impact on final model results (even if it is non-informative). As a result, it is important to report all details surrounding the prior (see Depaoli & van de Schoot, 2017), which include: the distribution shape selected, the hyperparameters (i.e., the level of informativeness), and the source of the prior information. Equally important is to report a sensitivity analysis of priors to illustrate how robust final model results are when priors are slightly (or even greatly) modified; this provides a better understanding of the role of the prior in the analysis. Finally, it is also important to report all information surrounding the assessment of chain convergence. Final model estimates are only trustworthy if the Markov chain has successfully converged for every model parameter, and reporting how this was assessed is a key component to a Bayesian analysis.

Bayesian multilevel estimation methods are discussed in more detail in Chapter 13 where robust estimation methods are discussed to deal with non-normality, and in Chapter 12 where sample size issues are discussed.

3.3 BOOTSTRAPPING

Bootstrapping is not, by itself, a different estimation method. In its simplest form, the *bootstrap* (Efron, 1982; Efron & Tibshirani, 1993) is a method to estimate the parameters of a model and their standard errors strictly from the sample, without reference to a theoretical sampling distribution.² The bootstrap directly follows the logic of statistical inference. Statistical inference assumes that in repeated sampling, the statistics calculated in the sample will vary across samples. This sampling variation is modeled by a theoretical sampling distribution, for instance a normal distribution, and estimates of the expected value and the variability are taken from this distribution. In bootstrapping, we draw b times a sample (with replacement) from the observed sample at hand. In each sample, we estimate the statistic(s) of interest, and the observed distribution of the b statistics is used for the sampling distribution. Estimates of the expected value and the variability of the statistics are taken from this empirical sampling distribution (Stine, 1989; Mooney & Duval, 1993; Yung & Chan, 1999). Thus, in multilevel bootstrapping, in each bootstrap sample the parameters of the model must be estimated, which is usually done with ML.

Since bootstrapping takes the observed data as the sole information about the population, it needs a reasonable original sample size. Good (1999, p. 107) suggests a minimum sample size of 50 when the underlying distribution is not symmetric. Yung and Chan (1999) review the evidence on the use of bootstrapping with small samples. They conclude that it is not possible to give a simple recommendation for the minimal sample size for the bootstrap method. However, in general the bootstrap appears to compare favorably over asymptotic methods. A large simulation study involving complex structural equation models (Nevitt & Hancock, 2001) suggests that, for accurate results despite large violations of normality assumptions, the bootstrap needs an observed sample of more than 150. Given such results, the bootstrap is not the best approach when the major problem is a small sample size.

When the problem is violations of assumptions, or establishing bias-corrected estimates and valid confidence intervals for variance components, the bootstrap appears to be a viable alternative to asymptotic estimation methods.

The number of bootstrap iterations b is typically large, with b between 1000 and 2000 (Booth & Sarkar, 1998; Carpenter & Bithell, 2000). If the interest is in establishing very accurate confidence intervals, we need an accurate estimate of percentiles close to 0 or 100, which requires an even larger number of iterations, such as $b > 5000$.

The bootstrap is not without its own assumptions. A key assumption of the bootstrap is that the *resampling* properties of the statistic resemble its *sampling* properties (Stine, 1989). As a result bootstrapping does not work well for statistics that depend on a very “narrow feature of the original sampling process” (Stine, 1989, p. 286), such as the maximum value. Another key assumption is that the resampling scheme used in the bootstrap must reflect the actual sampling mechanism used to collect the data (Carpenter & Bithell, 2000). This assumption is very important in multilevel modeling, because in multilevel data we have a hierarchical sampling mechanism, which must be mimicked in the bootstrapping procedure.

If we carry out a bootstrap estimation for our example data introduced in Chapter 2, the results are almost identical to the asymptotic FML results reported in Table 2.2. The estimates differ by 0.01 at most, which is a completely trivial difference. Of course, the example data in Chapter 2 are simulated, and all assumptions are fully met. Bootstrap estimates are most attractive when we have reasons to suspect the asymptotic results, because we have non-normal data. Bootstrapping is described in more detail in Chapter 13 where robust estimation methods are discussed to deal with non-normality.

3.4 SIGNIFICANCE TESTING AND MODEL COMPARISON

This section discusses procedures for testing significance and model comparison for the regression coefficients and variance components.

3.4.1 Testing Regression Coefficients and Variance Components

Maximum likelihood estimation produces parameter estimates and corresponding standard errors. These can be used to carry out a significance test of the form $Z = (\text{estimate}) / (\text{standard error of estimate})$, where Z is referred to as the standard normal distribution. This test is known as the *Wald test* (Wald, 1943). The standard errors are asymptotic, which means that they are valid for large samples. As usual, it is not precisely known when a sample is large enough to be confident about the precision of the estimates. Simulation research suggests that for accurate standard errors for level-2 variances, a relatively large level-2 sample size is needed. For instance, simulations by van der Leeden, Busing and Meijer (1997) suggest that with fewer than 100 groups, ML estimates of variances and their standard errors are not very accurate. In ordinary regression analysis, a rule of thumb is to require $104 + p$

observations if the interest is in estimating and interpreting regression coefficients, where p is the number of explanatory variables (Green, 1991). If the interest is in interpreting (explained) variance, the rule of thumb is to require $50 + 8p$ observations. In multilevel regression, the relevant sample size for higher-level coefficients and variance components is the number of groups, which is often not very large. Green's rule of thumb and van der Leeden et al.'s simulation results agree on a preferred group-level sample size of at least 100. Additional simulation research (Maas & Hox, 2005) suggests that if the interest lies primarily in the fixed part of the model, far fewer groups are sufficient, especially for the lowest-level regression coefficients. The issue of the sample sizes needed to produce accurate estimates and standard errors is taken up in more detail in Chapter 12.

It should be noted that the p -values and confidence intervals produced by different software may not be exactly the same. Most multilevel analysis programs produce as part of their output parameter estimates and asymptotic standard errors for these estimates, all obtained from the maximum likelihood estimation procedure. The usual significance test is the Wald test, with Z evaluated against the standard normal distribution. Bryk and Raudenbush (1992, p. 50), referring to a simulation study by Fotiu (1989), argue that for the fixed effects it is better to refer this ratio to a t -distribution on $J - p - 1$ degrees of freedom, where J is the number of second-level units, and p is the total number of explanatory variables in the model. The p -values produced by the program HLM (Raudenbush et al., 2011) are based on these tests rather than the more common Wald tests. When the number of groups J is large, the difference between the asymptotic Wald test and the alternative Student's t -test is very small. However, when the number of groups is small, the differences may become important. Since referring the result of the Z -test on the regression coefficients to a Student's t -distribution is conservative, this procedure should provide a better protection against type I errors. A better choice for the degrees of freedom in multilevel models is provided by the Satterthwaite approximation (Satterthwaite, 1946) or the Kenward–Roger approximation (Kenward & Roger, 1997). Both approximations estimate the number of degrees of freedom using the values of the residual variances and their distribution across the available levels. Simulation research (Manor & Zucker, 2004) shows that these approximations work better than the Wald test when the sample size is small (e.g. smaller than 30). The Satterthwaite approximation is used in SAS, SPSS and Stata, the Kenward–Roger approximation is available in SAS.

Several authors (e.g. Raudenbush & Bryk, 2002; Berkhof & Snijders, 2001) argue that the Z -test is not appropriate for the variances, because it assumes a normal distribution, whereas the sampling distribution of variances is skewed, especially when the variance is small. Especially if we have both a small sample of groups and a variance component close to zero, the distribution of the Wald statistic is clearly non-normal. Raudenbush and Bryk propose to test variance components using a chi-square test on the residuals. This chi-square is computed by

$$\chi^2 = \sum (\hat{\beta}_j - \beta)^2 / \hat{V}_j, \quad (3.1)$$

where $\hat{\beta}_j$ is the OLS estimate of a regression coefficient computed separately in group j , β its overall estimate, and \hat{V}_j its estimated sampling variance in group j . The number of degrees of freedom is given by $df = J - p - 1$, where J is the number of second-level units, and p is the total number of explanatory variables in the model. Groups that have a small number of cases are passed over in this test, because their OLS estimates are not sufficiently accurate.

Simulation studies on the Wald test for a variance component (van der Leeden et al., 1997) and the alternative chi-square test (Harwell, 1997; Sánchez-Meca & Marín-Martínez, 1997) suggest that with small numbers of groups both tests suffer from a very low power. The test that compares a model with and without the parameters under consideration, using the chi-square model test described in the next section, is generally better (Goldstein, 2011; Berkhof & Snijders, 2001). Only if the likelihood is determined with a low precision, which is the case for some approaches to modeling non-normal data, the Wald test is preferred. Note that if the Wald test is used to test a variance component, a one-sided test is the appropriate one.

3.4.2 Testing Regression Coefficients and Variance Components Using Bayesian Estimation

In Bayesian estimation, instead of using p -values one can use credibility intervals or Bayes Factors (BF) for testing regression coefficients or variance components.

First, the Bayesian counterpart of the frequentist confidence interval is the Posterior Probability Interval, also referred to as the credibility interval or the higher posterior density. This interval is interpreted as the 95 percent probability that in the population the parameter lies between the upper and lower value of the interval. Note, however, that the Bayesian interval and the classical confidence interval may numerically be similar and might serve related inferential goals, but they are not mathematically equivalent and conceptually quite different. Many argue that the Bayesian 95 percent interval is easier to communicate because it is actually the probability that a certain parameter lies between two numbers, which is not the definition of a classical confidence interval. The Bayesian interval can be used to determine whether a specific value, for example zero, lies within or outside the 95 percent interval. Related to this, the region of practical equivalence has also been slowly gaining popularity in the literature to avoid testing so-called nil-hypotheses (Kruschke, 2011).

A second way of testing regression coefficients or variance components is to use Bayes Factors (Kass & Raftery, 1995; see also Morey & Rouder, 2011). Bayes Factors represent the amount of evidence favoring one hypothesis over another. When $BF = 1$, this result implies that both hypotheses are equally supported by the data, but when $BF = 10$, for example, the support for one hypothesis is ten times larger than the support for the alternative hypothesis. If $BF < 1$, the alternative hypothesis is supported by the data. Many researchers argue that BFs are to be preferred over p -values, for example, Sellke, Bayarri and Berger (2001) showed that the BF is preferable over a p -value when testing hypotheses because p -values tend to

overestimate the evidence against the null hypothesis. However, as stated by Konijn, van de Schoot, Winter and Ferguson (2015), potential pitfalls of a Bayesian approach include BF-hacking (cf., ‘Surely, God loves a Bayes Factor of 3.01 nearly as much as a BF of 2.99’). This can especially occur when BF values are small. The first way in which BFs can be applied, is to use them to test if variances are greater than zero (Verhagen & Fox, 2012), which is implemented in Mplus (TECH 16, Muthén & Muthén, 1998–2015). A second way in which BFs can be used is to test whether regression coefficients are smaller/larger than zero or to test for order constraints between regression coefficients (see van de Schoot et al., 2013; for an application see Johnson et al., 2015).

3.4.3 Comparing Nested Models

From the likelihood function we can calculate a statistic called the *deviance* that indicates how well the model fits the data. The deviance is defined as $-2 \times \text{LN}(\text{likelihood})$, where *likelihood* is the value of the likelihood function at convergence, and LN is the natural logarithm. In general, models with a lower deviance fit better than models with a higher deviance. If two models are *nested*, which means that a specific model can be derived from a more general model by removing parameters from the general model, we can compare them statistically using their deviances. The difference of the deviances for two nested models has a chi-square distribution, with degrees of freedom equal to the difference in the number of parameters estimated in the two models. This can be used to perform a formal chi-square test to test whether the more general model fits significantly better than the simpler model. The deviance difference test is also referred to as the likelihood ratio test, since the ratio of two likelihoods is compared by looking at the difference of their logarithms.

The chi-square test of the deviances can be used to good effect to explore the importance of random effects, by comparing a model that contains these effects with a model that excludes them.

Table 3.1 presents two models for the pupil popularity data used as an example in Chapter 2. The first model contains only an intercept. The second model adds two pupil-level variables and a teacher-level variable, with the pupil-level variable extraversion having random slopes at the second (class) level. To test the second-level variance component $\sigma_{u_0}^2$ using the deviance difference test, we remove it from model M0. The resulting model (not presented in Table 3.1) produces a deviance of 6970.4, and the deviance difference is 642.9. Since the modified model estimates one parameter less, this is referred to the chi-square distribution with one degree of freedom. The result is obviously significant.

The variance of the regression coefficient for pupil gender is estimated as zero, and therefore it is removed from the model. A formal test is not necessary. In model M₁ in Table 3.1 this variable is treated as fixed, no variance component is estimated. To test the significance of the variance of the extraversion slopes, we must remove the variance parameter from the model. This presents us with a problem, since there is also a covariance parameter $\sigma_{u_{02}}$ associated with

Table 3.1 Intercept-only model and model with explanatory variables

Model	M_0 : intercept only	M_1 : with predictors
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	5.08 (.09)	0.74 (.20)
Pupil gender		1.25 (.04)
Pupil extraversion		0.45 (.02)
Teacher experience		0.09 (.01)
Random part		
σ_e^2	1.22 (.04)	0.55 (.02)
σ_{u0}^2	0.69 (.11)	1.28 (.28)
σ_{u02}		−0.18 (.05)
σ_{u2}^2		0.03 (.008)
Deviance	6327.5	4812.8

the extraversion slopes. If we remove both the variance and the covariance parameter from the model, we are testing a combined hypothesis on two degrees of freedom. It is better to separate these tests. Some software (e.g. MLwiN) actually allows to remove the variance of the slopes from the model but to retain the covariance parameter. This is a strange model, but for testing purposes it allows us to carry out a separate test on the variance parameter only. Other software (e.g. MLwiN, SPSS, SAS) allows the removal of the covariance parameter, while keeping the variance in the model. If we modify model M_1 this way, the deviance increases to 4851.9. The difference is 39.1, which is a chi-square variate with one degree of freedom, and highly significant. If we modify the model further, by removing the slope variance as well, the deviance increases again to 4862.3. The difference with the previous model is 10.4, again with one degree of freedom, and it is highly significant.

Asymptotically, the Wald test and the test using the chi-square difference are equivalent. In practice, the Wald test and the chi-square difference test do not always lead to the same conclusion. If a variance component is tested, the chi-square difference test is clearly better, except when models are estimated where the likelihood function is only an approximation, as in the logistic models discussed in Chapter 6.

When the chi-square difference test is used to test a variance component, it should be noted that the standard application leads to a p -value that is too high. The reason is that the null-hypothesis of zero variance is on the boundary of the parameter space (all possible parameter values) since variances cannot be negative. If the null-hypothesis is true, there is a 50 percent chance of finding a positive variance, and a 50 percent chance of finding a negative variance. Negative variances are inadmissible, and the usual procedure is to change the negative estimate

to zero. Thus, under the null-hypothesis the chi-square statistic has a mixture distribution of 50 percent zero and 50 percent chi-square with one degree of freedom. Therefore, the p -value from the chi-square difference test must be divided by two if a variance component is tested (Berkhof & Snijders, 2001). If we test a slope variance, and remove both the slope variance and the covariance from the model, the mixture is more complicated, because we have a mixture of 50 percent chi-square with one degree of freedom for the unconstrained intercept-slope covariance and 50 percent chi-square with two degrees of freedom for the covariance and the variance that is constrained to be non-negative (Verbeke & Molenberghs, 2000). The p -value for this mixture is calculated using $p = 0.5P(\chi_1^2 > C^2) + 0.5P(\chi_2^2 > C^2)$ where C^2 is the difference in the deviances of the model with and without the slope variance and intercept-slope covariance. Stoel, Galindo, Dolan and van den Wittenboer (2006) discuss how to carry out such tests in general. If it is possible to remove the intercept-slope covariance from the model, it is possible to test the significance of the slope variance with a one degree of freedom test, and we can simply halve the p -value again. For the regression coefficients, the chi-square test (only in combination with FML estimation) is in general also superior. The reason is that the Wald test is to some degree sensitive to the parameterization of the model and the specific restrictions to be tested (Davidson & MacKinnon, 1993, Sections 13.5–13.6). The chi-square test is invariant across different parametrizations of the model. Since the Wald test is much more convenient, it is in practice used the most, especially for the fixed effects. Even so, if there is a discrepancy between the result of a chi-square difference test and the equivalent Wald test, the chi-square difference test is generally the preferred one.

LaHuis and Ferguson (2009) compare amongst others the chi-square deviance test and the chi-square residuals test described above. In their simulation, all tests controlled the type I error well, and the deviance difference test (dividing p by two for variances, as described above) generally performed best in terms of power.

3.4.4 Comparing Non-Nested Models

If the models to be compared are not nested models, the principle that models should be as simple as possible (theories and models should be parsimonious) indicates that we should generally keep the simpler model. A general fit index to compare the fit of statistical models is Akaike's Information Criterion—AIC (Akaike, 1987), which was developed to compare non-nested models, adjusting for the number of parameters estimated. The AIC for multilevel regression models is conveniently calculated from the deviance d , and the number of estimated parameters q :

$$AIC = d + 2q. \quad (3.2)$$

The AIC is a very general fit-index that assumes that we are comparing models that are fit to the same data set, using the same estimation method.

A fit index similar to the AIC is Schwarz's Bayesian Information Criterion—BIC (Schwarz, 1978), which is given by

$$\text{BIC} = d + q \ln(N). \quad (3.3)$$

In multilevel modeling, the general Equation 3.3 for the BIC is ambiguous, because it is unclear whether N refers to the first-level or the second-level sample size. What N means in Equation 3.3 is differently chosen by different software. Most software uses the number of units at the highest level for the N . This makes much sense when multilevel models are used for longitudinal data, where the highest level is often the subject level. Given the strong interest in multilevel modeling in contextual effects, choosing the highest-level sample size appears a sensible rule.

When the deviance goes down, indicating a better fit, both the AIC and the BIC also tend to go down. However, the AIC and the BIC both include a penalty function based on the number of estimated parameters q . As a result, when the number of estimated parameters goes up, the AIC and BIC tend to go up too. For most sample sizes, the BIC places a larger penalty on complex models, which leads to a preference for smaller models. Since multilevel data have a different sample size at different levels, the AIC is more straightforward than the BIC, and therefore the recommended choice. The AIC and BIC are typically used to compare a range of competing models, and the model(s) with the lowest AIC or BIC value are considered the most attractive. Both the AIC and the BIC have been shown to perform well, with a small advantage for the BIC (Haughton et al., 1997; Kieseppä, 2003). It should be noted that the AIC and BIC are based on the likelihood function. With FML estimation, the AIC and BIC can be used to compare models that differ either in the fixed part or in the random part. If RML estimation is used, it can only be used to compare models that differ in the random part. Since RML effectively partials out the fixed part, before the random part is estimated, the RML likelihood may still change if the fixed part is changed. Therefore, if likelihood based procedures are used to compare models using RML estimation, the fixed part of the model must be kept constant. Not all software reports the AIC or BIC, but they can be calculated using the formulas given earlier. For an introductory discussion of the background of the AIC and the BIC see McCoach and Black (2008).

Within the Bayesian framework the Deviance Information Criterion—DIC (Spiegelhalter et al., 2002) can be used similarly to the AIC and BIC. The posterior DIC is proposed in Spiegelhalter and colleagues (2002) as a Bayesian criterion for minimizing the posterior predictive loss. It can be seen as the error that is expected when a statistical model based on the observed data set \mathbf{y} is applied to a future data set \mathbf{x} . Let $f(\cdot)$ denote the likelihood, then the expected loss is given by

$$E_{f(\mathbf{x}|\theta^*)}[-2\log f(\mathbf{x}|\theta^*)],$$

where $-2 \log f()$ is the loss function of a future data set \mathbf{x} given the expected a-posteriori estimates of the model parameters based on the observed data set. If we would know the true parameter values, the expected loss could be computed. However, since these are unknown, the posterior DIC takes the posterior expectation leading to the DIC:

$$\text{DIC} = d + pD.$$

where the first term is (approximately) equal to d for the AIC and BIC. The second term is often interpreted as the “effective number of parameters”, but is formally interpreted as the posterior mean of the deviance minus the deviance of the posterior means. Just like with the AIC and BIC, models with a lower DIC-value should be preferred and indicates the model that would best predict a replicate dataset which has the same structure as that currently observed. For a detailed comparison of the three model selection tools, AIC BIC and DIC, we refer to Hamaker et al. (2011).

3.5 SOFTWARE

Most multilevel regression software uses maximum likelihood estimation and offers a choice between full maximum likelihood and restricted maximum likelihood estimation. Bayesian estimation is gaining in popularity, but a user-friendly software implementation is currently available only in MLwiN and Mplus. In most software, when maximum likelihood estimation is used, both regression coefficients and variance components are tested using the Wald test. The software HLM uses a chi-square test based on the residuals. The deviance difference test can be used only by calculating the difference of the two deviances manually. Bayesian estimation methods generally investigate the precision of the estimated regression coefficients and variances by calculating their 95 percent credibility interval. This is similar to the ML-based 95 percent confidence interval, but it has a simpler interpretation and is not necessarily symmetric, which is important for variance components.

NOTES

- 1 Some programs allow the analyst to monitor the iterations, to observe whether the computations are going somewhere, or are just moving back and forth without improving the likelihood function.
- 2 For a discussion of multilevel bootstrapping in the context of robust estimation see Hox and van de Schoot (2013), which explains bootstrapping in more detail.

4

Some Important Methodological and Statistical Issues

SUMMARY

This chapter treats a number of issues that often arise in modeling multilevel data. The multilevel regression model is more complicated than the standard single-level multiple regression model. One difference is the number of parameters, which is much larger in the multilevel model. This poses problems when models are fitted that have many parameters, and also in model exploration. This chapter outlines an analysis strategy that proceeds from a simple model with no predictors to more complex models. A second difference is that multilevel models often contain interaction effects in the form of cross-level interactions. Interaction effects are tricky, and analysts should deal with them carefully. Interactions are often estimated using predictors that have been centered on their grand mean. In multilevel data, there is also the option to center predictors on their group means. The implications of these choices are treated here.

The existence of different levels, and having residual variance terms on all levels, raises the issue of how much variance is explained at the separate levels. This chapter explains a simple method originally proposed by Bryk and Raudenbush (1992), and a more elaborate method originally proposed by Snijders and Bosker (1994).

The existence of several levels also raises issues with mediation models where mediation may span several levels. A related issue is multilevel modeling where the outcome variable is not on the lowest but on one of the higher levels. Simple aggregation to the level of the outcome variable is not the best way to deal with these analysis problems. This chapter discusses the issues involved, with reference to Chapter 15 on multilevel path models, which are the most attractive techniques for these analysis problems.

Finally, real data often contain missing values. In multilevel analysis, these can become very problematic if these missing values are on a higher level, because one single missing value for a group variable (e.g. teacher age) will result in deletion of the whole group (e.g. the entire class), although all individual variables may be completely observed. This is wasteful, but also statistically problematic because listwise deletion of incomplete cases (be they subjects or groups) makes strong assumptions. Two solutions are treated in this chapter: estimation methods that can include incomplete cases, and multilevel multiple imputation. Both turn out to work well under weaker assumptions than listwise deletion needs to make.

4.1 ANALYSIS STRATEGY

The number of parameters in a multilevel regression model can easily become very large. If there are p explanatory variables at the lowest level and q explanatory variables at the highest level, the multilevel regression model for two levels is given by Equation 4.1:

$$Y_{ij} = \gamma_{00} + \gamma_{p0} X_{pij} + \gamma_{0q} Z_{qj} + \gamma_{pq} Z_{qj} X_{pij} + u_{pj} X_{pij} + u_{0j} + e_{ij}. \quad (4.1)$$

The number of estimated parameters in the model described by Equation 4.1 is given in the list below.

<i>Parameters</i>	<i>Number</i>
Intercept	1
Lowest-level error variance	1
Fixed slopes for the lowest-level predictors	p
Highest-level error variance	1
Highest-level error variances for these slopes	p
Highest-level covariances of the intercept with all slopes	p
Highest-level covariances between all slopes	$p(p-1)/2$
Fixed slopes for the highest-level predictors	q
Fixed slopes for cross-level interactions	$p \times q$

An ordinary single-level regression model for the same data would estimate only the intercept, one error variance, and $p + q$ regression slopes. The superiority of the multilevel regression model is clear, if we consider that the data are clustered in groups. If we have 100 groups, estimating an ordinary multiple regression model would require adding 99 dummy variables to the model to accommodate the 100 groups, plus all interactions of the 99 dummies with the p individual level variables to accommodate possible varying slopes. At the cost of estimating many parameters, this model, called a fixed effects model (cf. Allison, 2009) incorporates all group effects in the model, without making assumptions about their distribution. It also makes no claims about generalization to a larger population of groups, it just describes the available groups. Multilevel regression, which is a random effects model, replaces estimating an intercept for the reference group plus 99 dummies for the group effects by estimating a mean intercept plus a residual variance term across groups, assuming a normal distribution for these residuals. Thus, multilevel regression analysis replaces estimating 100 separate coefficients by estimating two parameters: the mean and variance of the intercepts, plus a normality assumption. The same simplification is used for the regression slopes. Instead of estimating 100 slopes for the explanatory variable pupil extraversion, we estimate the mean slope along with its variance across groups, and assume

that the distribution of the slopes is normal. Nevertheless, even with a modest number of explanatory variables, multilevel regression analysis implies a complicated model.

If we have no strong theories, we can use an exploratory procedure to select a model. Model building strategies can be either top-down or bottom-up. The top-down approach starts with a model that includes the maximum number of fixed and random effects that are considered for the model. Typically, this is done in two steps. The first step starts with all the fixed effects and possible interactions in the model, followed by removing non-significant effects. The second step starts with a rich random structure, followed by removal of non-significant effects. This procedure is described by West, Welch and Gatecki (2007). In multilevel modeling, the top-down approach has the disadvantage that it starts with a large and complicated model, which leads to longer computation time and sometimes to convergence problems. In this book, the opposite strategy is mostly used, which is bottom-up: start with a simple model and proceed by adding parameters, which are tested for significance after they have been added. Typically, the procedure starts by building up the fixed part, and then the random part. The advantage of the bottom-up procedure is that it tends to keep the models simple.

It is attractive to start with the simplest possible model, the intercept-only model, and to add the various types of parameters step by step. At each step, we inspect the estimates and standard errors to see which parameters are significant, and how much residual error is left at the distinct levels. Since we have larger sample sizes at the lowest level, it makes sense to build up the model from there. In addition, since fixed parameters are typically estimated with much more precision than random parameters, we start with the fixed regression coefficients, and add variance components at a later stage. The different steps of such a selection procedure are given below.

Step 1

Analyze a model without explanatory variables. This model, the *intercept-only model*, is given by the model of Equation 2.8, which is repeated here:

$$Y_{ij} = \gamma_{00} + u_{0j} + e_{ij} . \quad (4.2)$$

In Equation 4.2, γ_{00} is the regression intercept, or simply the mean of Y in the sample, and u_{0j} and e_{ij} are the usual residuals at the group and the individual level. The intercept-only model is useful because it gives us an estimate of the intra-class correlation

$$\rho = \frac{\sigma_{u0}^2}{\sigma_{u0}^2 + \sigma_e^2} , \quad (4.3)$$

where σ_{u0}^2 is the variance of the group-level residuals u_{0j} , and σ_e^2 is the variance of the individual-level residuals e_{ij} . The intercept-only model also gives us a benchmark value of the deviance, which is a measure of the degree of misfit of the model, and which can be used to compare models as described in Chapter 3.

Step 2

Analyze a model with all lower-level explanatory variables fixed. This means that the corresponding variance components of the slopes are fixed at zero. This model is written as:

$$Y_{ij} = \gamma_{00} + \gamma_{p0} X_{pij} + u_{0j} + e_{ij}, \quad (4.4)$$

where the X_{pij} are the p explanatory variables at the individual level. In this step, we assess the contribution of each individual level explanatory variable. The significance of each predictor can be tested, and we can assess what changes occur in the first-level and second-level variance terms. Since Model 4.2 is nested in Model 4.4, and provided we use the FML estimation method, we can test the improvement of the final model chosen in this step by computing the difference of the deviance of this model and the previous model (the intercept-only model). This difference is distributed as a chi-square with as degrees of freedom the difference in the number of parameters of both models (cf. 3.1.1). In this case, the degrees of freedom are simply the number of explanatory variables added in Step 2. As discussed in Chapter 3, in addition to a formal significance test, we can also use the information criteria AIC, BIC, or in Bayesian estimation DIC.

Step 3

Add the higher-level explanatory variables:

$$Y_{ij} = \gamma_{00} + \gamma_{p0} X_{pij} + \gamma_{0q} Z_{qj} + u_{0j} + e_{ij} \quad (4.5)$$

where the Z_{qj} are the q explanatory variables at the group level. This model allows us to examine whether the group level explanatory variables explain between-group variation in the dependent variable. Again, if we use FML estimation, we can use the global chi-square test to formally test the improvement of fit. If there are more than two levels, this step is repeated on a level-by-level basis.

The models in Steps 2 and 3 are often denoted as *variance component* models, because they decompose the intercept variance into different variance components for each hierarchical level. In a variance component model, the regression intercept is assumed to vary across the groups, but the regression slopes are assumed fixed. If there are no higher-level explanatory variables, this model is equivalent to a random effects analysis of covariance (ANCOVA); the grouping variable is the usual ANCOVA factor, and the lowest-level explanatory variables are the covariates (cf. Kreft & de Leeuw, 1998, p. 30; Raudenbush & Bryk, 2002, p. 25). There is a difference in estimation method: ANCOVA uses OLS techniques and multilevel regression generally uses ML estimation. Nevertheless, both models are highly similar, and if the groups have all equal sizes, the multilevel model

is actually equivalent to analysis of covariance (ANCOVA). It is even possible to compute the usual ANCOVA statistics from the multilevel program output (Raudenbush, 1993a). The reason to start with models that include only fixed regression coefficients is that we generally have more information on these coefficients; they can be estimated with more precision than the variance components. When we are confident that we have a well-fitting model for the fixed part, we turn to modeling the random part.

Step 4

Assess whether any of the slopes of any of the explanatory variables at the individual level has a significant variance component between the groups. This model, the *random coefficient model*, is given by:

$$Y_{ij} = \gamma_{00} + \gamma_{p0} X_{pij} + \gamma_{0q} Z_{qj} + u_{pj} X_{pij} + u_{0j} + e_{ij} \quad (4.6)$$

where the u_{pj} are the group-level residuals of the slopes of the individual-level explanatory variables X_{pij} .

Testing for random slope variation is best done on a variable-by-variable basis. When we start by including all possible variance terms in a model (which involves also adding many covariance terms), the result is most likely an overparameterized model with serious estimation problems, such as convergence problems or extremely slow computations. Variables that were omitted in Step 2 may be analyzed again in this step; it is quite possible for an explanatory variable to have no significant average regression slope (as tested in Step 2), but to have a significant variance component for this slope.

After deciding which of the slopes have a significant variance between groups (see Chapter 3), we add all these variance components simultaneously in a final model, and use the chi-square test based on the deviances to test whether the final model of Step 4 fits better than the final model of Step 3. Since we are now introducing changes in the random part of the model, the chi-square test can also be used with RML estimation (cf. 3.1.1). When counting the number of parameters added, remember that adding slope variances in Step 4 also adds the covariances between the slopes! Again, in addition to the formal chi-square significance test, the information criteria AIC, BIC or DIC can also be used.

If there are more than two levels, this step is repeated on a level-by-level basis.

Step 5

Add cross-level interactions between explanatory group-level variables and those individual-level explanatory variables that had significant slope variation in Step 4. This leads to the full model:

$$Y_{ij} = \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{1j}X_{1ij} + u_{0j} + e_{ij}. \quad (4.7)$$

Again, provided we use FML estimation, we can use the global chi-square test to formally test the improvement of fit.

If we use an exploratory procedure to arrive at a ‘good’ model, there is always the possibility that some decisions that have led to this model are based on chance. We may end up overfitting the model by following peculiarities of our specific sample, rather than characteristics of the population. If the sample is large enough, a good strategy is to split it at random in two, use one half for our model exploration and the other half for cross-validation of the final model. See Camstra and Boomsma (1992) for a review of several cross-validation strategies. If the sample is not large enough to permit splitting it up in an exploration and validation sample, we can apply a Bonferroni correction to the individual tests performed in the fixed part at each step. The Bonferroni correction multiplies each p -value by the number of tests performed, and requires the inflated p -value to be significant at the usual level.¹

At each step, we decide which regression coefficients or (co)variances to keep on the basis of the significance tests, the change in the deviance, and changes in the variance components. Specifically, if we introduce explanatory variables in Step 2, we expect that the lowest-level variance σ_e^2 goes down. If the composition of the groups with respect to the explanatory variables is not exactly identical for all groups, we expect that the higher-level variance σ_{u0}^2 also goes down. Thus, the individual-level explanatory variables explain part of the individual and part of the group variance. The higher-level explanatory variables added in Step 3 can explain only group-level variance. It is tempting to compute the analogue of a multiple correlation coefficient to indicate how much variance is actually explained at each level (cf. Raudenbush & Bryk, 2002). However, this ‘multiple correlation’ is at best an approximation, and it is quite possible for it to become smaller when we add explanatory variables, which is impossible with a real multiple correlation. This problem is taken up in Section 4.5.

4.2 CENTERING AND STANDARDIZING EXPLANATORY VARIABLES

In ordinary multiple regression analysis, linear transformations of the explanatory variables do not change the essence of the regression estimates. If we divide an explanatory variable by two, its new regression slope equals the old one multiplied by two, the standard error is also multiplied by two, and a significance test for the regression slope gives exactly the same result. Most importantly, the proportion of unexplained residual variance and hence the multiple correlation does not change either. This is summed up in the statement that the multiple regression model is invariant under linear transformations; if we transform the variables, the estimated parameters change in a similar way, and it is always possible to recalculate the untransformed estimates.

In multilevel regression analysis, the model is only invariant for linear transformations if there are no random regression slopes, that is, if the slopes do not vary across the groups. To understand why this is the case, consider first a simple data set with only one explanatory variable and three groups. Figure 4.1 plots the three regression slopes when there is no slope variance across the groups. In this situation, the slopes are parallel lines. The variance of the intercept is the variance of the slopes at the point where the slopes cut through the Y -axis, which is at the point where the explanatory variable X is equal to zero. It is clear from Figure 4.1 that, if we shift the scale of X to X^* by adding or subtracting a certain amount, we merely shift the location of the Y -axis, without altering the spread of the intercepts. In this case, the variance of the slope is clearly invariant for shifts on the X -axis, which we produce by adding or subtracting a constant from X .

The variance of the regression slopes is not invariant for such a transformation if the regression slopes vary across the groups, which is the case if we have group-level slope variance. Figure 4.2 shows the situation with three different slope coefficients. This figure shows that with random regression slopes the variance of the intercept changes when we shift the scale of the explanatory variables. It also makes clear how the intercept variance should be interpreted: it is the variance of the intercepts at the point where the explanatory variable X is equal to zero.

It is clear from Figure 4.2 that, if we shift the scale of X to X^* or X^{**} by adding or subtracting a certain amount, the spread of the intercepts changes. If we shift the scale of the X -axis to X^* , the variation of the intercepts is considerable. If we shift the scale of the X -axis to X^{**} and extrapolate the regression slopes, the variation of the intercepts is very small and probably not statistically significant.

In multiple regression analysis, multilevel or single-level, the intercept is interpreted as the expected value of the outcome variable, when all explanatory variables have the value

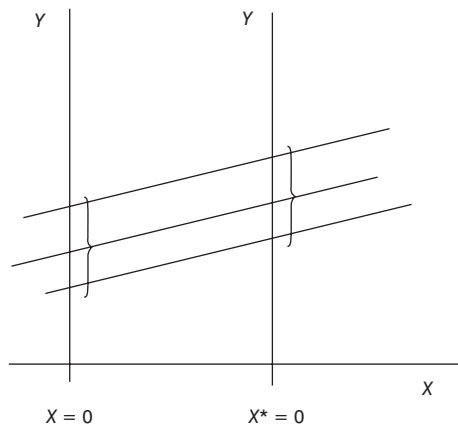


Figure 4.1 Parallel regression lines, with shift on X .

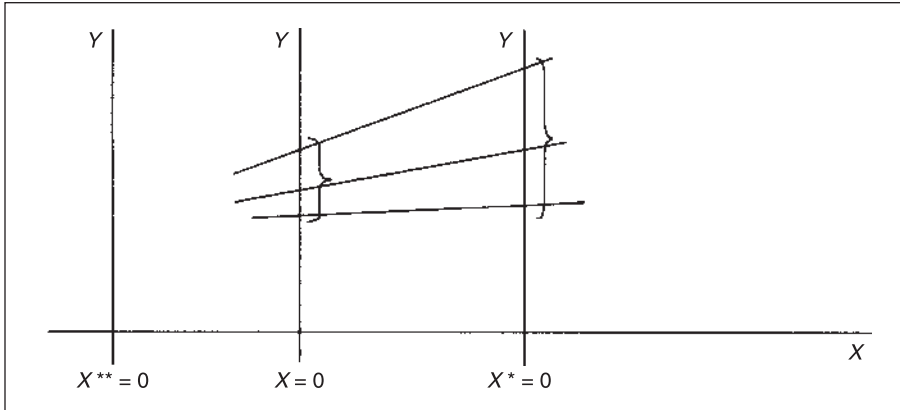


Figure 4.2 Varying regression lines, with shifts on X .

zero. The problem, illustrated in Figure 4.2 by the transformation of the X -scale to X^{**} , is that in many cases ‘zero’ may not even be a possible value. For instance, if we have an explanatory variable ‘gender’ coded as 1 = male, 2 = female, zero is not in the possible score range, and as a consequence the value of the intercept is meaningless. To handle this problem, it is useful to perform a transformation of the X -variables that make ‘zero’ a legitimate, observable value.

A linear transformation that is often applied to achieve this is *centering* the explanatory variables. The usual practice is that the overall or grand mean is subtracted from all values of a variable, which is called centering on the grand mean, or grand mean centering in short. If we apply grand mean centering, we solve the problem, because now the intercept in the regression equation is always interpretable as the expected value of the outcome variable, when all explanatory variables have their mean value. Grand mean centering is most often used, but it is also possible to center on a different value, e.g., on the median, or on a theoretically interesting value. For example, if we have an explanatory variable ‘gender’ coded as 1 = male, 2 = female, the value of the mean could be 1.6, reflecting that we have 60 percent females in our sample and 40 percent males. We can center on the sample mean of 1.6, but we may prefer to center on the mean of a theoretical population with 50 percent males and 50 percent females. To accomplish this, we would center on the population mean of 1.5, which effectively leads to a code of -0.5 for male and $+0.5$ for female. Although we center on a value that as such does not and even cannot exist in the population, the intercept is still interpretable as the expected outcome for the average person, disregarding gender.

In multilevel modeling, centering the explanatory variables has the additional advantage that variances of the intercept and the slopes now have a clear interpretation. They are the expected variances when all explanatory variables are equal to zero, in other words: the expected variances for the ‘average’ subject.

Centering is also important if the multiple regression model includes interactions. For each of the two explanatory variables involved in an interaction, the interpretation of its slope is that it is the expected value of the slope when the other variable has the value zero. Again, since ‘zero’ may not even be a possible value, the value of the slope for the interaction term may not be interpretable at all. Since multilevel regression models often include cross-level interactions, this is a serious interpretation problem. When both variables in the interaction are centered on their grand mean, the problem disappears. The problem of interpreting interactions in multilevel regression models is discussed in more detail in the next section.

We will consider the issue of centering in a simple example, using the data from our example in Chapter 2, and including only pupil extraversion as explanatory variable. We compare the estimates for pupil extraversion as a raw and as a grand mean centered variable, for a random coefficient model (varying slope for pupil extraversion). The table also shows the estimates that result when we standardize the variable pupil extraversion. Standardization is a linear transformation that implies grand mean centering, but adds a multiplicative transformation to achieve a standard deviation of one.

As Table 4.1 shows, grand mean centering of the variable pupil extraversion produces a different estimate for the intercept variance at the second level. The deviance remains the same, which indicates that all three random coefficient models fit the data equally well. In fact, all three models are equivalent. Equivalent models have the same fit, and produce the same residuals. The parameter estimates are not all identical, but the estimates for one model can be transformed to the estimates of the other model. Thus, grand mean centering and overall standardization do not really complicate the interpretation of the results. In addition, grand mean centering and standardization do have some advantages. One advantage is that the intercept becomes a meaningful value. The value of the higher-

Table 4.1 Popularity predicted by pupil extraversion, raw and centered predictor

Model:	Extraversion slope random		
Fixed part	Raw coefficient (s.e.)	Centered coefficient (s.e.)	Standardized coefficient (s.e.)
Intercept	2.46 (.20)	5.03 (.10)	5.03 (.10)
Extraversion	0.49 (.03)	0.49 (.03)	0.62 (.03)
Random part			
σ_e^2	0.90 (.03)	0.90 (.03)	0.90 (.03)
σ_{u0}^2	2.94 (.58)	0.88 (.13)	0.88 (.13)
σ_{u2}^2	0.03 (.009)	0.03 (.009)	0.04 (.01)
Deviance	5770.7	5770.7	5770.7

level intercept variance also becomes meaningful; it is the expected variance at the mean of all explanatory variables. A second advantage is that with centered explanatory variables the calculations tend to go faster, and encounter fewer convergence problems. Especially when explanatory variables vary widely in their means and variances, grand mean centering or standardization may be necessary to reach convergence, or even to be able to start the computations at all. Since grand mean centering only affects the intercept, which is often not interpreted anyway, it is preferred above standardization, which will also affect the interpretation of the regression slopes and the residual variances.

Some multilevel analysts advocate a totally different way of centering, called group mean centering. Group mean centering means that the group means are subtracted from the corresponding individual scores. This is sometimes done, because it can be used to represent a specific hypothesis. For instance, in educational research there is a hypothesis called the ‘frog pond effect’. This means that for a medium-sized frog the effect of being in a pond filled with big frogs is different than being in a pond filled with small frogs. In educational terms, pupils of average intelligence in a class with very smart pupils may find themselves unable to cope, and give up. Conversely, pupils of average intelligence in a class with very unintelligent pupils, are relatively smart, and may become stimulated to perform really well. The frog pond hypothesis states, that the effect of intelligence on school success depends on the relative standing of the pupils in their own class. A simple indicator of the pupils’ relative standing can be constructed by computing the individual deviation score, by subtracting from the pupil’s intelligence score the average intelligence in their class. Group mean centering is a direct translation of the frog pond mechanism in terms of the explanatory variables.

Group mean centering completely changes the meaning of the entire regression model. If we use grand mean centering, we get different regression slopes for variables that are involved in an interaction, and different variance components, but we have an equivalent model, with identical deviance and residual errors. A formal way to describe this situation is to state that we have a different *parameterization* for our model; the model is essentially the same, but transformed in a way that makes it easier to interpret. Using straightforward algebra, we can transform the grand mean centered estimates back to the values we would have found by analyzing the raw scores. Group mean centering, on the contrary, is *not* a simple reparameterization of our model, but a completely different model. We will find a different deviance, and transforming the estimated parameters back to the corresponding raw score estimates is not possible. The reason is that we have subtracted not one single value, but a collection of different values from the raw scores. The technical details that govern the relations between parameter estimates using raw scores, grand mean centered scores, and group mean scores, are complicated; they are discussed in detail in Kreft, de Leeuw and Aiken (1995) and in Enders and Tofighi (2007), and in more general terms in Hofman and Gavin (1998) and Paccagnella (2006).

Group mean centering of an explanatory variable discards all information concerning differences between groups. It would seem reasonable to restore this information by adding the aggregated group mean again as an additional group-level explanatory variable. But this adds extra information about the group structure, which is not present in the raw scores, and therefore we obtain a model that fits better than the raw score model.

The advantage of group mean centering is that the raw score is decomposed into a within-groups variable and a between-groups variable, which separates the lowest-level and second-level variation. By using two different variables as predictors, we analyze pure individual and group effects. In such a model, the regression coefficients for individual and group effects can be quite different. If a single raw score is used as predictor, inevitably only a single regression coefficient is estimated, and the model implicitly assumes that the individual-level and group-level effect are identical.

Group mean centering and adding the group mean as predictor variable is most useful when the research question requires a clear separation of individual and group effects. This is the case with frog pond theories, with research questions about contextual effects. In addition, Enders and Tofighi (2007) suggest that group mean centering (which they refer to as within cluster centering) is most valuable 1) when the research hypothesis is about the relationship between two or more level-1 variables (within-group centering removes confounding with between-group effects), and 2) when a hypothesis involves interactions among level-1 variables. This includes cross-level interactions, when the research hypothesis is that the second-level predictor moderates the strength of a first-level relationship.

Table 4.2 shows the effects of different choices for centering. The data are from 7185 pupils in 160 schools. A series of multilevel models for this dataset (High School & Beyond data) is discussed in detail by Raudenbush and Bryk (2002, Chapter 4). The dependent variable is mathematics achievement, and we restrict ourselves to the predictors SES and school mean SES.

The estimates for the first two models (M_1 and M_2) in Table 4.2 show that grand mean centering and group mean centering are indeed different. Compared to grand mean centering, group mean centering results in a much larger school-level residual variance, which is the result of removing school-level variation from the predictor variable. In model three (M_3), the school mean is added as a predictor. This predictor is clearly significant, and the school-level residual variance goes down as compared to model M_2 . It is obvious the residual variance at the individual level remains unchanged. The last model (M_4) shows what happens if we add the school means as a predictor to the grand mean centered SES variable. The residual variances and the deviance and AIC in model three and four are identical, which means that these models are equivalent. The regression coefficients, however, are not the same, and neither is their interpretation. In model M_3 , we have a clear separation: the school mean centered SES variable has only variance at the pupil level, and the school means have only variance at the school level. Since the school mean centered SES predictor can only explain variation within schools, the regression coefficient for school mean SES reflects the combined effects of school composition

Table 4.2 Mathematics achievement predicted by pupil SES and school means SES, differently centered predictors, adding group mean

Model	SES slope fixed			
	M ₁ : Grand mean	M ₂ : Group mean	M ₃ : Group mean plus school means	M ₄ : Grand mean plus school means
SES centered on				
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	12.66 (.19)	12.65 (.24)	12.66 (.15)	12.66 (.15)
SES	2.39 (.11)	2.19 (.11)	2.19 (.11)	2.19 (.11)
School SES	—	—	5.87 (.36)	3.67 (.38)
Random part				
σ_e^2	37.02 (.62)	37.01 (.62)	37.01 (.62)	37.01 (.62)
σ_{u0}^2	4.73 (.65)	8.61 (1.07)	2.64 (.40)	2.64 (.40)
Deviance	46641.0	46720.4	46563.8	46563.8
AIC	46649.0	46728.4	46573.8	46573.8

(due to differential selection of pupils in schools) and a real contextual effect of the school composition in SES. In model M₄, the grand mean SES has both within and between school variation, and explains both individual effects and school-level effects due to composition. Conditional on the grand mean centered predictor, the regression coefficient for school mean SES reflects only the contextual effect of being in a school with many high or low SES pupils.

Summarizing: grand mean centering of variables that have random slopes or that are involved in an interaction is always helpful. The choice between grand mean centering and group mean centering depends on the research problem at hand. For individuals within groups, we refer to Enders and Tofighi (2007). For longitudinal data, where group mean centering means centering the repeated measures on each individual's mean, we refer to Hoffman (2015, Chapter 9).

4.3 INTERPRETING INTERACTIONS

Whenever there are interactions in a multiple regression analysis (whether these are a cross-level interaction in a multilevel regression analysis or an interaction in an ordinary single-level regression analysis does not matter), there are two important technical points to be made. Both stem from the methodological principle that in the presence of a significant interaction the effect of the interaction variable and the direct effects of the explanatory variables that make up that interaction must be interpreted together as a system (Jaccard et al., 1990; Aiken & West, 1991).

The first point is that if the interaction is significant, it is best to include both direct effects in the regression too, even if they are not significant.

The second point is that in a model with an interaction effect, the regression coefficients of the simple or direct variables that make up that interaction carry a different meaning than in a model without this interaction effect. If there is an interaction, then the regression coefficient of one of the direct variables is the expected value of that regression slope when the other variable is equal to zero, and vice versa. If for one of the variables the value 'zero' is widely beyond the range of values that have been observed, as in age varying from 18 to 55, or if the value 'zero' is in fact impossible, as in gender coded male = 1, female = 2, the result is that the regression coefficient for the other variable has no substantive interpretation. In many such cases, if we compare different models, the regression coefficient for at least one of the variables making up the interaction will be very different from the corresponding coefficient in the model without interaction. *But this change does not mean anything.* One remedy is to take care that the value 'zero' is meaningful and actually occurs in the data. One can accomplish this by centering both explanatory variables on their grand mean.² After centering, the value 'zero' refers to the mean of the centered variable, and the regression coefficients change little when the interaction is added to the model. The regression coefficient of one of the variables in an interaction can now be interpreted as the regression coefficient for individuals with an 'average' score on the other variable. If all explanatory variables are centered, the intercept is equal to the grand mean of the dependent variable.

To interpret an interaction, it is helpful to write out the regression equation for one explanatory variable for various values of the other explanatory variable. The other explanatory variables can be disregarded or included at their mean value. When both explanatory variables are continuous, we write out the regression equation for the lower-level explanatory variable, for a choice of values for the explanatory variable at the higher level. Good choices are the mean and the mean plus/minus one standard deviation, or the median and the 25th and 75th percentile. A plot of these three regression lines clarifies the meaning of the interaction. If one of the explanatory variables is dichotomous, we write the regression equation for the continuous variable, for both values of the dichotomous variable.

In the example we have used so far, there is a cross-level interaction between pupil extraversion and teacher experience. In the corresponding data file, pupil extraversion is measured on a 10-point scale, the range is 1–10. Teacher experience is recorded in years, with the amount of experience ranging from 2 to 25 years. There are no pupils with a zero score on extraversion, and there are no teachers with zero experience, and this explains why adding the cross-level interaction between pupil extraversion and teacher experience to the model results in an appreciable change in the regression slope of pupil extraversion from 0.84 to 1.33. In the model without the interaction, the estimated value for the regression slope of pupil extraversion is independent from teacher experience. Therefore, it can be said to apply to the average class, with an average teacher having an amount of experience somewhere in the middle between 2 and 25 years. In the model with the interaction, the pupil extraversion

slope now refers to a class with a teacher who has zero years of experience. This is an extreme value, which is not even observed in the data. Following the same reasoning, we can conclude that the teacher experience slope refers to pupil extraversion = 0.

The example also includes a variable gender, coded 0 (boys) / 1 (girls). Since ‘zero’ is a value that does occur in the data, the interpretation of interaction effects with gender is straightforward; leaving the dummy uncentered implies that all slopes for variables interacting with gender refer to boys. This may be awkward in the interpretation, and therefore the dummy variable gender may also be centered around its grand mean or by using effect coding which codes boys = −0.5 and girls = +0.5. Centering issues do not differ for continuous and dichotomous variables (Enders & Tofighi, 2007). For a discussion of different coding schemes for categorical variables see Appendix C in this book.

The estimates for the centered explanatory variables in Table 4.3 are much more comparable across different models than the estimates for the uncentered variables (the small difference between 0.09 and 0.10 for teacher experience is due to rounding). To interpret the cross-level interaction, it helps to work out the regression equations for the effect of pupil extraversion for different values of teacher experience. Using the centered variables, the regression equation for the effect of pupil extraversion on popularity is:

$$\text{popularity} = 4.368 + 1.241 \times \text{gender} + 0.451 \times \text{extrav} + 0.097 \times t.\text{exp} - 0.025 \times t.\text{exp} \times \text{extrav}$$

Table 4.3 Model without and with cross-level interaction

Model:	M ₁ : main effects	M ₂ : with interaction	M ₁ : centered interaction variables	M ₂ : centered interaction variables
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	0.74 (.20)	−1.21 (.27)	4.39 (.06)	4.37 (.06)
Gender	1.25 (.04)	1.24 (.04)	1.25 (.04)	1.24 (.04)
Extraversion	0.45 (.02)	0.80 (.04)	0.45 (.02)	0.45 (.02)
T. exp.	0.09 (.01)	0.23 (.02)	0.09 (.01)	0.10 (.01)
Extra × T.exp		−0.03 (.003)		−0.025 (.002)
Random part				
σ _e ²	0.55 (.02)	0.55 (.02)	0.55 (.02)	0.55 (.02)
σ _{u0} ²	1.28 (.28)	0.45 (.16)	0.28 (.04)	0.28 (.04)
σ _{u2} ²	0.03 (.008)	0.005 (.004)	0.03 (.008)	0.005 (.004)
σ _{u02}	−0.18 (.05)	−0.03 (.02)	−0.01 (.02)	−0.00 (.01)
Deviance	4812.8	4747.6	4812.8	4747.6

The average effect of a change of one scale point in extraversion is to increase the popularity with 0.451. This is the predicted value for teachers of average experience (14.2 years in the raw data set, zero in the centered data). For each year more, the effect of extraversion decreases with 0.025. So for the teachers with the most experience, 25 years in our data, the expected effect of extraversion is $0.451 - 0.025 \times (25 - 14.2) = 0.18$. So, for these teachers the effect of extraversion is predicted to be much smaller.

Another way to make it easier to interpret an interaction is to plot the regression slopes for one of the explanatory variables for some values of the other. The mean of pupil gender is 0.51, so we can absorb that into the intercept giving:

$$\text{popularity} = 5.001 + 0.451 \times \text{extrav} + 0.097 \times \text{t.exp} - 0.025 \times \text{t.exp} \times \text{extrav}.$$

The centered variable pupil extraversion ranges from -4.22 to 4.79 . The centered variable teacher experience ranges from -12.26 to 10.74 , with a standard deviation of 6.552 . We can use Equation 2.12 to predict popularity, with extraversion ranging from -4.22 to 4.79 and teacher experience set at -6.552 , 0 , and 6.552 , which are the values of one standard deviation below the mean, the mean, and one standard deviation above the mean. Figure 4.3 presents a plot of the three regression lines.

It is clear that more extraverted pupils have a higher expected popularity score, and that the difference is smaller with more experienced teachers. In general, more experienced teachers have classes with a higher average popularity. At the maximum values of pupil extraversion, this relationship appears to reverse, but these differences are probably not significant. If we use the uncentered scores for the plot, the scale of the X -axis, which represents pupil extraversion, would change, but the picture would not. Centering explanatory variables is especially attractive when we want to interpret the meaning of an interaction by inspecting the regression coefficients in the table. As Figure 4.3 shows, plotting the interaction over the range of observed values of the explanatory variables is an effective way to convey its meaning, even if we work with raw variables.

Interactions are sometimes interpreted in terms of moderation or a moderator effect. In Figure 4.3, we can state that the effect of pupil extraversion is moderated by teacher experience, or that the effect of teacher experience is moderated by pupil extraversion. In multilevel analysis, where the interest often lies in contextual effects, the interpretation that the effect of pupil extraversion is moderated by teacher experience would in many cases be preferred. A more statistical approach is to examine for which range of values of teacher experience the effect of pupil extraversion is significant. A simple approach to probing interactions is to test simple slopes at specific levels of the predictors. In this approach, teacher experience is centered on a range of values, to find out by trial and error where the boundary lies between a significant and a nonsignificant effect for pupil extraversion. A more general method is the Johnson–Neyman (J–N) technique, which views interactions as conditional relations in which the effect of one predictor varies with the value of another. The values of the regression coefficients and their

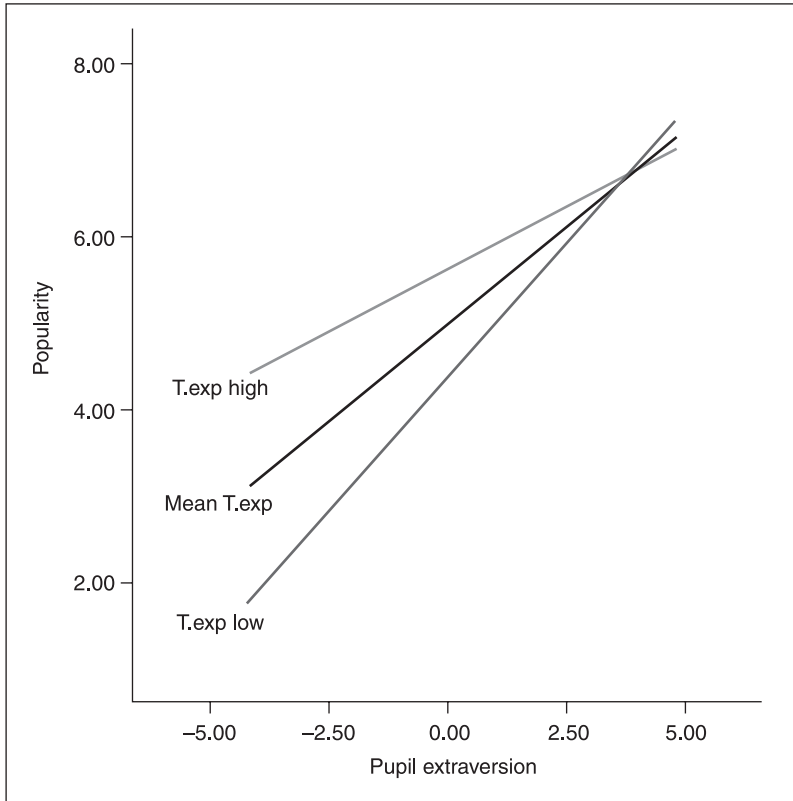


Figure 4.3 Regression lines for popularity by extraversion, for three levels of teacher experience.

standard errors are used to calculate the range of values on one explanatory variable for which the other variable in the interaction shows a significant effect. Bauer and Curran (2005) describe these techniques in the context of standard and multilevel regression analysis, and Preacher, Curran and Bauer (2006) describe analytic tools³ to evaluate interactions by establishing confidence bands for simple slopes across the range of the moderator variable.

A final note on interactions is that in general the power of the statistical test for interactions is lower than the power for direct effects. One reason is that random slopes are estimated less reliably than random intercepts, which means that predicting slopes (using interactions with second-level variables) is more difficult than predicting intercepts (using direct effects of second-level variables (Raudenbush & Bryk, 2002). In addition, if the variables that make up an interaction are measured with some amount of measurement error, the interaction term (which is a multiplication of the two direct variables) is less reliable than the direct variables (McLelland & Judd, 1993). For these two reasons modeling random slopes is less successful than modeling random intercepts.

4.4 HOW MUCH VARIANCE IS EXPLAINED?

An important statistic in ordinary multiple regression analysis is the multiple correlation R , or the squared multiple correlation R^2 , which is interpreted as the proportion of variance modeled by the explanatory variables. In multilevel regression analysis, the issue of modeled or explained variance is a complex one. First, there is unexplained variance at several levels to contend with. This alone makes the proportion of explained variance a more complicated concept than in single-level regression analysis. Second, if there are random slopes, the model is inherently more complex, and the concept of explained variance has no unique definition anymore. Various approaches have been proposed to indicate how well we are predicting the outcomes in a multilevel model.

A straightforward approach to examining the proportion of explained variance consists of examining the residual error variances in a sequence of models, such as the sequence proposed in Section 4.1 in this chapter. Table 4.4 presents for such a sequence of models the parameter estimates (regression coefficients and variance components) plus the deviance, using FML estimation. The first model is the intercept-only model. This is a useful baseline model, because it does not introduce any explanatory variables (except the constant intercept term) and decomposes the total variance of the outcome variable into two levels. Thus, the individual-level variance of the popularity scores is 1.22, the class-level variance is 0.69, and the total variance is the sum of the two: 1.91. Since there are no explanatory variables in the model, it is reasonable to interpret these variances as the error variances.

Table 4.4 Successive models for pupil popularity data

Model:	Intercept only	Level-1 predictors	Level-2 predictors	Random coefficient	Cross-level interaction
Fixed part					
Intercept	5.08	2.14	0.81	0.74	−1.21
Extraversion		0.44	0.45	0.45	0.80
Gender		1.25	1.25	1.25	1.24
T. exp.			0.09	0.09	0.23
Extra × t.exp.					−0.02
Random part					
σ_e^2	1.22	0.59	0.59	0.55	0.55
σ_{u0}^2	0.69	0.62	0.29	1.28	0.45
σ_{u2}^2				0.03	0.004
σ_{u02}				−0.18	−0.03
Deviance	6327.5	4934.0	4862.3	4812.8	4747.6

In the first ‘real’ model, the pupil-level explanatory variables extraversion and gender are introduced. As a result, the first-level residual error variance goes down to 0.59, and the second-level variance goes down to 0.62. Again, it is reasonable to interpret the difference as the amount of variance explained by introducing the variables pupil gender and pupil extraversion. To calculate a statistic analogous to the multiple R^2 , we must express this difference as a proportion of the total error variance. It appears most informative if we do this separately level-by-level. For the proportion of variance explained at the first level we use (cf. Raudenbush & Bryk, 2002):

$$R_1^2 = \left(\frac{\sigma_{elb}^2 - \sigma_{elm}^2}{\sigma_{elb}^2} \right), \quad (4.8)$$

where σ_{elb}^2 is the lowest-level residual variance for the baseline model, which is the intercept-only model, and σ_{elm}^2 is the lowest-level residual variance for the comparison model. For the pupil popularity data this calculates the proportion explained variance at the pupil level for the model with pupil gender and pupil extraversion as:

$$R_1^2 = \left(\frac{1.22 - 0.59}{1.22} \right) = 0.52.$$

For the proportion of variance explained at the second level (cf. Raudenbush & Bryk, 2002) we use:

$$R_2^2 = \left(\frac{\sigma_{u0b}^2 - \sigma_{u0m}^2}{\sigma_{u0b}^2} \right), \quad (4.9)$$

where σ_{u0b}^2 is the second-level residual variance for the baseline model, which is the intercept-only model, and σ_{u0m}^2 is the second-level residual variance for the comparison model. For the pupil popularity data this calculates the proportion explained variance at the class level as:

$$R_2^2 = \left(\frac{0.69 - 0.62}{0.69} \right) = 0.10.$$

It may come as a surprise that pupil-level variables are able to explain variance at the class level. The explanation is straightforward. If the distribution of extraversion or the proportion of girls is not exactly the same in all classes, the classes do differ in their composition, and this variation can explain some of the class-level variance in average popularity between classes. In our example, the amount of variance explained by pupil extraversion and gender at the class level is small, which reflects the fact that extraversion and gender are distributed almost equally across all classes. The results could have been different; explanatory variables that are divided very selectively across the groups can often explain a fair amount of group-level variance. The interpretation would generally be that this does not reflect a real contextual effect, but rather the unequal composition of the groups. This issue is discussed in Section 4.2 of this chapter.

Assessing the effect of adding the class-level explanatory variable ‘teacher experience’ to the model follows the same reasoning. The residual variance at the first level does not change at all. This is as it should be, because class-level variables cannot predict individual-level variation. The class-level residual variance goes down to 0.29, so the class-level R^2 becomes

$$R_2^2 = \left(\frac{0.69 - 0.29}{0.69} \right) = 0.58,$$

which means that 58 percent of the variance at the class level is explained by the pupil gender, pupil extraversion and teacher experience. A comparison with the previous $R_2^2 = 0.10$ makes clear that most of the predictive power stems from the teacher experience.

The next model is the random coefficient model, where the regression slope for pupil gender is assumed to vary across schools. In the random coefficient model, the variance of the slopes for pupil extraversion is estimated as 0.03. Since the model contains no cross-level interactions with pupil gender, the slope variance is not modeled, and can be interpreted as a residual error variance at the class level. The cross-level model includes the interaction of pupil extraversion with teacher experience, and estimates the variance for the pupil extraversion slopes as 0.004. Hence, the explained variance in these slopes is given by (cf. Raudenbush & Bryk, 2002):

$$R_{\beta_2}^2 = \left(\frac{\sigma_{u2/b}^2 - \sigma_{u2/m}^2}{\sigma_{u2/b}^2} \right), \quad (4.10)$$

where $\sigma_{u2/b}^2$ is the variance of the slopes for pupil extraversion in the baseline model, and $\sigma_{u2/m}^2$ is the variance of the slopes for pupil extraversion in the comparison model. For our example data, comparing the random coefficient model as a baseline model with the cross-level interaction model, we obtain (carrying one extra decimal for precision):

$$R_{extrav}^2 = \left(\frac{0.034 - 0.0047}{0.034} \right) = 0.86.$$

Using one explanatory variable at the school level, we can explain 86 percent of the variance of the pupil extraversion slopes.

All this appears straightforward, but there are two major problems. First, by using these formulas it is quite possible to arrive at the conclusion that a specific explanatory variable has a negative contribution to the explained variance. This will lead to a negative R^2 , which is an impossible value. This is unfortunate, to say the least. This will in fact always happen when a predictor variable is added to the model that has only lowest-level variation, such as a group mean centered predictor, or a measurement occasion in a longitudinal model with fixed occasions (cf. Snijders & Bosker, 2012). The reason is that the decomposition of the total variance into first-level and second-level variance in the empty model assumes random sampling at each level, and a variable with only lowest-level variance violates that assumption.

A second problem is that in models with random slopes, the estimated variances depend on the scale of the explanatory variables. This has been explained in Section 4.2 of this

chapter, in the discussion of the effects of centering and standardization. This means that the explained variance changes if we change the scale of the explanatory variables that have varying slopes. In Table 4.4 it is clear that the intercept variance changes wildly when a random slope is added to the model. Table 4.5 illustrates that using centered predictor variables produces a more stable succession of variance estimates. The regression coefficients are the same as before, except for the model with the interaction, and the deviances are all equal to the deviances using raw predictor variables.

Table 4.5 Successive models for pupil popularity data, all predictors centered

Model	Intercept only	Level-1 predictors	Level-2 predictors	Random coefficient	Cross-level interaction
Fixed part					
Intercept	5.08	5.07	5.07	5.02	4.98
Extraversion		0.44	0.45	0.45	0.45
Gender		1.25	1.25	1.25	1.24
T. exp.			0.09	0.09	0.09
Extra×t.exp.					−0.02
Random part					
σ_e^2	1.22	0.59	0.59	0.55	0.55
σ_{u0}^2	0.69	0.62	0.29	0.28	0.28
σ_{u2}^2				0.03	0.005
σ_{u02}				−0.01	−0.004
Deviance	6327.5	4934.0	4862.3	4812.8	4747.6

Centering the predictor variables produces more realistic and stable variance estimates, but does not solve the problem that using equations 4.8 to 4.10 can sometimes lead to negative estimates for the explained variance. To understand in more detail how variables can have a negative contribution to the explained variance, we must investigate the effect of including an explanatory variable on the variance components. The reasoning underlying Equations 4.8 to 4.10 assumes that the sample is obtained by simple random sampling at all levels. The underlying assumption is that the groups are sampled at random from a population of groups, and that the individuals are sampled at random within these groups.

Assume that we sample N individuals, and randomly assign them to J groups, all with equal group size n . For any variable X with mean μ and variance σ^2 , the distribution of the group means is approximately normal with mean μ and variance:

$$\sigma_{\mu}^2 = \sigma^2/n \quad (4.11)$$

This is a well-known statistical theorem, which is the basis of the familiar F -test in the Analysis of Variance. In analysis of variance, we estimate the population variance σ^2 using s_{pw}^2 , the pooled within-groups variance. A second estimate of σ^2 is given by ns_m^2 , using (4.11) and filling in the observed means m for the population means μ . This is used in the familiar F -test, $F = ns_m^2 / s_{pw}^2$, for the null-hypothesis that there are no real differences between the groups. If there are real group differences, there is a real group-level variance σ^2 in addition to the sampling variance σ_μ^2 , and ns_m^2 is an estimator of $(\sigma^2 + \sigma_\mu^2 / n)$. Thus, in general, in grouped data some of the information about the population within-groups variance is in the observed between-groups variance, and the between-groups variance calculated in the sample is an upwardly biased estimator of the population between-groups variance. This also means that, even if the between-groups variance in the population is zero, the observed between-groups variance is not expected to be exactly zero, but to be equal to σ^2/n .

As a result, for an individual-level variable sampled via a simple multilevel sampling process, we expect that it will show some between-group variability, even if there are no real group effects in the population. For such variables, the approximate R^2 formulas defined above should do reasonably well. But in some situations we have variables that have (almost) no variation at one of the levels. This occurs when we use as explanatory variable a group mean centered variable, from which all between-group information is removed, or the group averages, which have no variation at all at the individual level. In an implicit way this occurs when we have data with a strong selection process at one of the levels of sampling, or time series designs. For instance, if we carry out an educational experiment, we might assign pupils to classes to achieve an exactly equal gender ratio of 50 percent boys and 50 percent girls in each class. If we do this, we have no between class variation in average gender, which is *less* than expected by simple random sampling of boys and girls. In a similar way, in many studies where we have as the lowest level a series of repeated observations at different measurement occasions, all subjects have exactly the same series of time points, because they were measured at the same occasions. Here again we have no variation of time points across subjects. In these cases, using the simple formulas given above will generally produce the result that the explanatory variable ‘gender’ or ‘occasion’ appears to explain negative variance.

Snijders and Bosker (2012) explain the problem in detail. First, let us consider a model that contains no random effects for the slopes. We could base an estimate of σ_e^2 on the pooled within-groups variance. This would be inefficient, because it ignores the information we have about σ_e^2 in the between-groups variance. Furthermore, the observed between-groups variance must be corrected for the within-groups variance to produce an accurate estimator of σ_{u0}^2 . As a result, the maximum likelihood estimators of σ_e^2 and σ_{u0}^2 are a complex weighted function of the pooled within groups and the between-groups variances.

Assume that we start by estimating an intercept-only model, which gives us baseline estimates for the two variance components σ_e^2 and σ_{u0}^2 . First, we introduce a ‘normal’ first-level explanatory variable, like pupil gender in our example. As explained above, the expected between-groups variation for such a variable is not zero, but σ^2 / n . So, if

this variable correlates with the outcome variable, it will reduce both the within groups variance and the between-groups variance. The correction implicit in the ML estimators insures that both σ_e^2 and σ_{u0}^2 are reduced by the correct amount. Since σ_{u0}^2 is corrected for a ‘normal’ explanatory variable, it should not change, unless our explanatory variable explains some additional group-level variation as well. Now, consider what happens if we add an explanatory variable that is group mean centered, which means that all group-level information has been removed. This can reduce only the within-groups variance, and leaves the between-group variance unchanged. The correction implicit in the ML estimator of σ_{u0}^2 will now correct for the smaller amount of within-groups variance, and as a result the estimate of the apparent between-groups variance σ_{u0}^2 will increase. Using Equation 4.8, we get a negative estimate for the explained variance at the group level, which makes no sense. In ordinary multiple regression analysis such a thing cannot occur. When predictor variables are added that have more group-level variance than a random sampling process produces, the apparent within-groups variance σ_{u0}^2 can increase, which may produce a negative estimate for the explained variance at the lowest level.

With this knowledge in mind, let us look again at the formulas for explained variance. For the lowest level, we repeat the equation here:

$$R_1^2 = \left(\frac{\sigma_{e|b}^2 - \sigma_{e|m}^2}{\sigma_{e|b}^2} \right). \quad (4.8, \text{ repeated})$$

Provided that σ_e^2 is an unbiased estimator, this formula is correct. But, as we have seen, adding group-level variables to the model may lead to incorrect estimates, because the estimation procedure does not combine the information from the two levels correctly. Snijders and Bosker (2012) propose to remedy this by replacing σ_e^2 in (4.8) by the sum $\sigma_e^2 + \sigma_{u0}^2$. This will use all available information about the within-group variance in a consistent way.

The formula for the second-level explained variance is given by

$$R_2^2 = \left(\frac{\sigma_{u0|b}^2 - \sigma_{u0|m}^2}{\sigma_{u0|b}^2} \right). \quad (4.9, \text{ repeated})$$

Snijders and Bosker (1994) propose to replace σ_{u0}^2 in (4.9) by $\sigma_{u0}^2 + \sigma_e^2/n$. For unequal group sizes, the simplest solution is to replace the common group size n by the average group size. A more elaborate option proposed by Snijders and Bosker (1994) is to replace n by the harmonic group mean defined by $\left\{ (1/N) \sum_j (1/n_j) \right\}^{-1}$. The ad hoc estimator proposed by Muthén (1994), given by $c = [N^2 - \sum n_j^2] / [N(J-1)]$, is probably a better replacement for the average n , because it is designed for similar problems in analysis of variance. Except in the case of extreme unbalance, both these replacements for n are very close to the average group size n , so in most cases even the simple median of the group sizes n_j will suffice.

The various formulas given above assume that there are no random slopes in the model. If there are, the replacements are more complicated. Assume that there are q explanatory variables Z with a random slope, with means μ_z , between-groups covariance matrix Σ_B and pooled within-groups covariance matrix Σ_W . For the first-level residual error, we replace σ_e^2 in 4.8 by

$$\mu_z' \sigma_{u0}^2 \mu_z + \text{trace}(\sigma_{u0}^2 (\Sigma_B + \Sigma_W)) + \sigma_e^2, \quad (4.12)$$

and for the second-level residual error, we replace σ_{u0}^2 by

$$\mu_z' \sigma_{u0}^2 \mu_z + \text{trace} \left(\sigma_{u0}^2 \left(\Sigma_B + \frac{1}{n} \Sigma_W \right) \right) + \frac{1}{n} \sigma_e^2. \quad (4.13)$$

The computations are straightforward, but tedious. For the development of these equations and computational details see Snijders and Bosker (2012). Snijders and Bosker (2012) advise that if there are random slopes in the model, the explained variance can still be estimated using a simplified model with only fixed effects. With grand mean centered predictor variables, the μ -terms are zero, and Equations 4.12 and 4.13 are much simplified. If there is only one varying slope in the model, Equations 4.12 and 4.13 further simplify to

$$\sigma_{u0}^2 + \sigma_{u1}^2 (\sigma_B + \sigma_W) + \sigma_e^2, \quad (4.12a)$$

and

$$\sigma_{u0}^2 + \sigma_{u1}^2 \left(\sigma_B + \frac{1}{n} \sigma_W \right) + \frac{1}{n} \sigma_e^2. \quad (4.13a)$$

Table 4.6 lists the models presented in Table 4.5, with the explained variance as calculated using the approximations in (4.8) and (4.9), and with the explained variance as calculated using the Snijders and Bosker (1994) corrections.

The explained variance at the first level differs appreciably in the different approaches. There is a difference in interpretation as well. The approximate R^2 attempts to indicate the explained variance as a proportion of the first-level variance only. The Snijders and Bosker R^2 attempts to indicate the explained variance as a proportion of the total variance, because in principle first-level variables can explain all variation, including the variation at the second level. Note that the approximate R^2 appears to increase when a random effect is added to the model. This increase is spurious, because we cannot actually observe the random U terms. Thus, although the approximate approach can be used to compute an R^2 for models including random effects, the results must be interpreted with care. The Snijders and Bosker correction removes this spurious increase. Hence, for the approximate procedure, the explained intercept variance is based on a comparison of the null model and the model without random slopes.

Table 4.6. Explained variance for pupil popularity models in Table 4.5

Model	Intercept only	Level-1 predictors	Level-2 predictors	Random coefficient	Cross-level interaction
R_1^2 (approx.)	0.00	0.52	0.52	0.55	0.55
R_2^2 (approx.)	0.00	0.10	0.58	0.59	0.59
$R_{\text{extr.}}^2$ (approx.)	—	—	—	0.00	0.83 ^a
R_1^2 (S & B)	0.00	0.37	0.54	0.54	0.54
R_2^2 (S & B)	0.00	0.14	0.57	0.57	0.57

^a Calculated carrying only decimals reported in Table 4.5

Snijders and Bosker (2012) do not address the problem of defining explained variance in regression slopes, or explained variance in models with more than two levels. It is clear that the problems just described are also present at any higher levels, with more complex equations as the result. Since the intercept is simply the regression slope associated with a constant with value 1, the complications in interpreting the intercept variance will arise again when we consider the variance of the regression slopes. In addition, Snijders and Bosker’s approach does not solve the problem that with random slopes the residual variances depend on the scale of the explanatory variables. There is no current solution for this.

When the multilevel sampling process is close to two-stage simple random sampling, the formulas given as 4.8 to 4.10 should give reasonable approximations. As always, when the interest is in the size of variance components, it appears prudent to center all explanatory variables that have varying slopes on their grand mean. Given that the estimates of the variance components depend on the explanatory variables, this at least insures that we get variance estimates for values of the explanatory variables that actually exist, and reflect the average sampling unit. This would apply to both the approximate and the Snijders and Bosker approach to estimating explained variance.

4.5 MULTILEVEL MEDIATION AND HIGHER-LEVEL OUTCOMES

Mediation analysis is a causal model where the hypothesis is that the effect of an independent variable IV is assumed to have an effect on an outcome variable via a mediator variable M . Mediation is a popular research theme because it involves hypotheses about the process through which X influences Y . Figure 4.4 presents the essence of mediation analysis.

The left of Figure 4.4 shows the direct effect of variable X on Y . The right of Figure 4.4 shows the mediation model; X influences Y via M . In the mediation model, the direct effect c has changed to c' . If c' is essentially zero, we have full mediation; if c' is smaller than c but still significant, we have partial mediation. Traditionally mediation was investigated using a series of multiple regression analyses, the so-called Baron and Kenny steps. The current approach

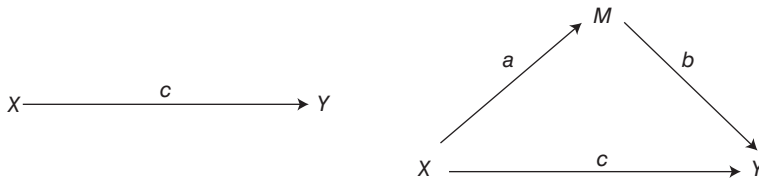


Figure 4.4 Basic elements of mediation analysis.

is to specify a mediation model as a structural equation model (SEM). This has the advantage that all coefficients are estimated simultaneously, and that the indirect effect $X \rightarrow M \rightarrow Y$ can be calculated from the coefficients a and b , and that more complex models can be specified including models with latent variables or models with multiple (parallel or serial) mediators.

If multilevel analysis finds effects of contextual predictors on an individual outcome variable, some process must mediate between the two, and an appropriate analysis would be multilevel mediation analysis. On the other hand, group-level outcomes could be affected by group processes that are measured at the individual level, which would also point towards multilevel mediation analysis, only here the final outcome variable would be at level two. Since SEM has such advantages above multiple regression analysis, for multilevel mediation analysis we prefer multilevel SEM. Some path models including mediation are presented in Chapter 15 in this book, a detailed exposition is in MacKinnon (2012). Multilevel models with group-level outcomes, including mediation models, are also best analyzed using multilevel SEM (Croon & van Veldhoven, 2007).

4.6 MISSING DATA IN MULTILEVEL ANALYSIS

Incomplete or missing data occur often in the analysis of real data. Most software deals with missing data in a very simple manner; incomplete cases are simply deleted from the analysis, a procedure known as listwise deletion. Not using the incomplete cases is wasting information and results in lower power, especially in a multilevel analysis where the missing value can be a group-level variable, and listwise deletion results in deleting the entire group. More important is the assumption that listwise deletion makes about the missingness mechanism. Any deletion scheme must assume that the remaining cases are representative for the original sample, which means that the missingness must be Missing Completely At Random (MCAR). This is in practice an unlikely assumption.

MCAR means that the missing values are not in any way related to the observed or unobserved values in the data. The missingness cannot be predicted by the observed variables, and also not by the unobserved (missing) values. The first assumption can be checked; if the observed variables predict missingness (e.g., in a logistic regression or cross table), the missingness mechanism is not MCAR. The last assumption cannot be checked, but it is an important assumption, and if it is violated the analysis results are likely to be biased.

Several techniques have been developed to analyze data that are not MCAR. Typically, these techniques assume that the missingness is Missing At Random (MAR). This means that, conditional on the observed variables, the missingness is not related to the unobserved (missing) values. If analysis techniques are used that assume MAR, correlations between missingness and other variables in the model are acceptable.

A third missingness mechanism is Missing Not At Random (MNAR). This assumes that conditional on the observed variables, the missingness is related to the values that we failed to observe. MNAR analysis is complicated and requires a good understanding of both missing data analysis and of the data at hand, and we will not treat it here.

MAR makes fewer assumptions than MCAR, and there are well-developed techniques to deal with MAR missingness. There are two main approaches to incomplete data assuming a MAR mechanism. The first approach is to use an estimation method that can include incomplete cases in the estimation procedure. This can be done in both ML and in Bayesian estimation, in a different manner, both assuming MAR. The second approach is to impute the missing values using multiple imputation, which allows incorporating the uncertainty in imputation in the analysis.

For a general introduction to missing data we refer to McKnight, McKnight, Sidani and Figueredo (2007). A more technical introduction is Enders (2010), who discusses all methods mentioned below. A review of missing data methods in the multilevel context is provided by Hox, van Buuren and Jolani (2016). What follows below is a brief introduction of the issues involved in analyzing incomplete multilevel data.

It should be noted that there is one case where multilevel analysis offers very simple solution to missing data, and that is multilevel analysis of longitudinal data with dropout or occasional wave nonresponse. Subjects that drop out of the study and therefore have missing data on later measurement occasions can easily be retained in the multilevel analysis. Provided ML or Bayesian estimation is used, the assumed missingness mechanism is MAR. This case is treated in Chapter 5 on longitudinal multilevel analysis. Here we discuss the general case of incomplete multilevel data.

4.6.1 Direct Estimation of Incomplete Data

Direct estimation of incomplete data using ML is based on rewriting the standard likelihood function in such a way that incomplete cases can be retained and therefore continue to play a role in the estimation procedure. In this case, generally called full information maximum likelihood (FIML), all available information is used, and the estimation is therefore efficient and assumes MAR. Structural equation modeling software generally has this capacity. Multilevel structural equation modeling includes multilevel regression, but also more general models like multilevel factor or path models, which we treat in Chapters 14 and 15. By specifying our multilevel regression model as particular multilevel structural equation model, we can solve the missing data problem.

There is one important problem with this approach. The likelihood function is specified for the dependent variables, independent variables must still be excluded by listwise deletion. The solution for this is to respecify the regression model in such a way, that the predictor variables still remain predictors, but technically become dependent variables. This is done by specifying for each predictor with missing values a corresponding latent variable that predicts the observed variable with a regression coefficient constrained equal to one, and constraining the prediction error variance as zero. The latent variable is identical to the observed variable, and is used in its stead as a predictor variable. Figure 4.5 illustrates the model.

The single disadvantage of this procedure is that the distribution of X becomes important. Ordinarily, there is no distributional assumption for predictor variables, but when it technically becomes a dependent variable it now needs to have a normal distribution, and this assumption must be checked. This also implies this approach cannot be used for categorical predictors, unless these are modeled correctly using procedures described in Chapters 6 and 7.

FIML works well with models that have only a random intercept. Varying slopes requires in Mplus an estimation method that uses numerical integration, which is very computer intensive. Bayesian estimation deals with missing data in a different way. In a Bayesian model, each missing data point simply becomes one more parameter to be estimated. This obviously leads to a very complex model, which ML estimation will not handle well, or not handle at all. One of the advantages of Bayesian estimation is that it deals well with complicated models. As we explained briefly in Chapter 3, Bayesian estimation is an entirely different framework for estimation. When applied to data with many missing values, convergence of the MCC chain can be slow, and should certainly be checked carefully using the methods outlined in Chapter 13. Bayesian estimation is most easily done in Mplus; unfortunately, at the time of writing, Bayesian estimation in Mplus cannot be used when an incomplete predictor has a random slope.

4.6.2 Multiple Imputation of Incomplete Data

A different approach to incomplete data is to fill in the missing values with plausible values, and then to proceed with the analysis, which is straightforward because there are no more missing values. This creates two problems: the imputed values are usually based on regression predictions, and therefore too precise, and the statistical software will use the

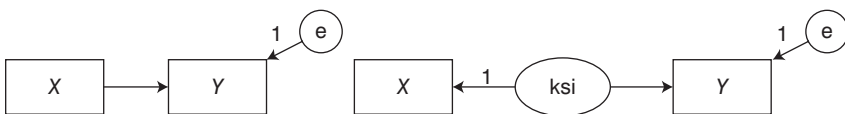


Figure 4.5 Specifying a predictor as a dependent variable.

imputed values as if they are real observations, and hence overestimate the sample size. Both problems are solved by using multiple imputation (Rubin, 1987): the imputations are repeated a number of times (say five times) and each time a random error is added to the imputed values, so the imputed datasets are different. Next, the analysis is carried out on each of the imputed datasets, and the analysis results are combined into a single final result.

The combination rules, often referred to as Rubin's rules (Rubin, 1987), are basically simple, and software that can deal with multiply-imputed data generally carries out the combination automatically. Generating the multiple imputations is difficult, because it is very important that the right amount of random error is added. A second requirement is that the model used to generate the multiple imputations is at least as complex as the analysis model. In multilevel data, this means that the imputation model must also be a multilevel model.

Imputations can be based on a model or on the data. A well-known data-driven imputation method is multivariate imputation by chained equations (MICE, van Buuren & Groothuis-Oudshoorn, 2011) using predictive mean matching (PMM). In MICE, a regression model is used to predict each incomplete variable in turn. Subjects with similar predicted values are grouped into a donor pool, and a randomly chosen subject from that pool who has an observed value for that variable donates that value to the incomplete case. An advantage of PMM is that the imputations are always values that have actually been observed in the data. As a result, PMM generally reproduces the observed data structure, including non-normality and multilevel structures (Vink et al., 2015). Multilevel imputation is available in the R package MICE (van Buuren & Groothuis-Oudshoorn, 2011) and in Mplus (Muthén & Muthén, 1998–2015).

4.6.3. An Example of Multilevel Incomplete Data

As an example of incomplete multilevel data, we take the popularity data used in Chapter 2, and create missingness in the variables extraversion and popularity, using a MAR procedure. The missingness mechanism is explained in Appendix E that contains a description of all data files used in this book. The model used is a main effects variance components model, not including the interaction between extraversion and teacher experience. The model is estimated using Mplus 7.4 with robust ML estimation. Multiple imputation estimates are based on 20 imputed datasets using Bayesian estimation of a full model for imputation and robust ML estimation for the model parameters. The results are shown in Table 4.7.

The column labeled Complete presents the results of the complete data. Since Mplus used a different specification for multilevel modeling than standard multilevel regression, the results differ a little from the results presented in Chapter 2. It is clear that Listwise deletion results in estimates that are different from the complete data. The intercept is severely underestimated, and the class-level residual variance is severely overestimated. The regression coefficients are actually estimated reasonably well.

Table 4.7 Model without and with cross-level interaction

Model main effects	Complete	Listwise	FIML	Bayes	Multiple Imputation
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.d.)	Coefficient (s.e.)
Intercept	0.81 (.21)	0.45 (.20)	0.74 (.15)	0.75 (.18)	0.73 (.19)
Pupil gender	1.25 (.04)	1.34 (.05)	1.29 (.04)	1.28 (.04)	1.27 (.04)
Pupil extraversion	0.45 (.03)	0.53 (.02)	0.50 (.02)	0.49 (.02)	0.50 (.02)
Teacher experience	0.09 (.01)	0.08 (.01)	0.08 (.01)	0.08 (.01)	0.08 (.01)
Random part					
σ_e^2	0.59 (.02)	0.53 (.02)	0.52 (.02)	0.52 (.02)	0.52 (.02)
σ_{u0}^2	0.29 (.05)	0.45 (.20)	0.28 (.05)	0.30 (.05)	0.28 (.05)
AIC/DIC	4874.3	2687.9	8674.5	8531.3	11249.4

The other three estimation methods produce estimates that are closer to the estimates of the complete data. They are closer to each other than to the complete data. This is to be expected; we have removed 25 percent of the data values for two variables, so we should find slightly different results. The three principled methods that all three assume MAR do not restore the lost information, all they do is allow us to use all available information, producing unbiased estimates if the missingness mechanism is MAR (or MCAR). Hox, van Buuren and Jolani (2016) include a simulation that compares several approaches to multilevel missing data, and conclude that multilevel FIML and multilevel multiple imputation produce the most accurate parameter estimates and standard errors, and work equally well.

4.7 SOFTWARE

Most specialist software for multilevel analysis contains options for creating grand mean or group mean centered predictor variables. In general statistical packages, these centered variables usually must be calculated manually. Proper analysis of mediation models is best performed using path analysis in structural equation modeling software, which is treated in Chapter 15. Missing data analysis using an estimation method that can include incomplete cases, using either ML or Bayesian estimation, is currently only available in Mplus. Multilevel multiple imputation can be performed in standard imputation software, but the most flexible tool is the R package MICE (van Buuren & Groothuis-Oudshoorn, 2011), which contains some automatic multilevel imputation tools.

NOTES

- 1 The usual Bonferroni correction is to keep the p -values, and divide the formal alpha level by the number of tests. However, if we have many tests in various steps, we end up with many different significance criteria. It is simpler to correct by appropriately inflating the p -values, and use one alpha criterion for all analysis steps. Both procedures are equivalent, but inflating the p -values makes for a simpler presentation of the results. Holm (1979) describes a more powerful variation of the Bonferroni. If k tests are performed, the Holm correction would multiply the smallest p -value by k , the next smallest p -value by $k-1$, and so on. The Benjamini-Hochberg correction (Benjamini & Hochberg, 1995) is even better, but more complicated.
- 2 Standardizing the explanatory variables has the same effect. In this case, it is recommended not to standardize the interaction variable because that makes it difficult to compute predictions or plot interactions. Standardized regression weights for the interaction term can always be determined using Equation 2.13.
- 3 Available at www.quantpsy.org.

5

Analyzing Longitudinal Data

5.1 INTRODUCTION

If the data are collected to analyze individual change over time, the constructs under study must be measured on a comparable scale at each occasion. When the time span is short, this does not pose complicated problems. For instance, Tate and Hokanson (1993) report on a longitudinal study where the scores of students on the Beck Depression Scale were collected at three occasions during the academic year. In such an application, especially when a well-validated measurement instrument is used, we may assume that the research instrument remains constant for the duration of the study. On the other hand, in a study that examines improvements in reading skill in school children from ages 5–12, it is clear that we cannot use the same instrument to measure reading skill at such different age levels. Here, we must make sure that the different measurement instruments are calibrated, meaning that a specific score has the same psychometric meaning at all age levels, independent of the actual reading test that is used. The issues are the same as the issues in cross-cultural comparison (cf. Vandenberg & Lance, 2000; van de Schoot et al., 2012), but the actual analysis models are different (cf. Little, 2013). Another requirement is that there is sufficient time between the measurements that memory effects are not a problem. In some applications, this may not be the case. For instance, if data are collected that are closely spaced in time, we may expect considerable correlation between measurements collected at occasions that are close together, partly because of memory effects. These effects should then be included in the model, which leads to models with correlated errors. Formulating multilevel models for such situations can be quite complex. Some multilevel software has built-in provisions for modeling correlated errors. These are discussed in the last part of this chapter.

The models discussed in this chapter are all models for data that have repeated measures on individuals over time. Within the framework of multilevel modeling, we can also analyze data where the repeated measures are on higher levels, e.g., data where we follow the same set of schools over a number of years, with of course in each year a different set of pupils. Models for such data are similar to the models discussed in this chapter, but the repeated measures are on the second level. Such repeated cross-sectional data are discussed by DiPrete and Grusky (1990) and Raudenbush and Chan (1993), for an example see Hox and Wijnngaards-de Meij (2014). Multilevel analysis models for longitudinal data are discussed in detail by Hedeker and Gibbons (2006) and by Singer and Willett (2003). Latent curve

analysis using structural equation modeling is discussed by Duncan, Duncan and Strycker (2006) and by Bollen and Curran (2006). The structural equation approach to latent curve analysis is treated in this book in Chapter 16.

Multilevel analysis of repeated measures is often applied to data from large-scale panel surveys. It can also be a valuable analysis tool in a variety of experimental designs. If we have a pretest–posttest design, the usual analysis is an analysis of covariance (ANCOVA) with the experimental and control groups as the factor and the pretest as the covariate. In the multilevel framework, we analyze the slopes of the change over time, using an experimental group/control group dummy variable to predict differences in the slopes. If we have just a pretest–posttest design this does not improve much on the usual analysis of covariance. However, in the multilevel framework it is simple to add more measurement occasions between the pretest and the posttest. Willett (1989) and Maxwell (1998) show that the power of the test for differences between the experimental and the control groups is increased dramatically by adding a few additional waves of data collection. Adding many more occasions again does not improve power; we refer to Chapter 12 for a discussion of power and sample size in multilevel modeling. There is a second and important advantage on ANCOVA if there is dropout, especially if this is not completely random. Multilevel analysis of repeated measures can include incomplete cases, which is a major advantage when there are missing data.

5.2 FIXED AND VARYING OCCASIONS

It is useful to distinguish between repeated measures that are collected at fixed or varying occasions. If the measurements are taken at fixed occasions, all individuals provide measurements at the same set of occasions, usually regularly spaced, such as once every year. When occasions are varying, we have a different set of measures taken at different points in time for different individuals. Such data occur, for instance, in growth studies, where physical or psychological characteristics are studied for a set of individuals at different moments in their development. The data collection could be at fixed moments in the year, but the individuals would have different ages at that moment. Alternatively, the original design is a fixed occasion design, but due to planning problems, the data collection does not take place at the intended moments. For a multilevel analysis of the resulting data, the difference between fixed and varying occasions is not very important. For fixed occasion designs, especially when the occasions are regularly spaced and when there are no missing data, repeated measures analysis of variance (ANOVA) is a viable alternative for multilevel analysis, although multilevel analysis tends to have larger power (Fan, 2003). A comparison of the ANOVA approach and multilevel analysis is given in Section 5.3. Another possibility in such designs is latent curve analysis, also known as latent growth curve analysis. This is a structural equation model (cf. Singer & Willett, 2003; Duncan et al., 2006) that models a repeated measures polynomial analysis of variance. Latent growth curve models are treated in Chapter 16.

5.3 EXAMPLE WITH FIXED OCCASIONS

The example data are a longitudinal data set from 200 college students. The students' Grade Point Average (GPA, theoretical range from 1 = lowest to 4 = highest) has been recorded for six successive semesters. At the same time, it was recorded whether the student held a job in that semester, and for how many hours. This is recorded in a variable 'job' (= hours worked). In this example, we also use the student-level variables high school GPA and gender (0 = male, 1 = female), which of course remain constant for each student across the six measurement occasions.

In a statistical package such as SPSS or SAS, such data are typically stored with the students defining the cases, and the repeated measurements as a multivariate set of variables, such as GPA1, GPA2, ..., GPA6, and JOB1, JOB2, ..., JOB6. For example, in SPSS the data structure would be as shown in Figure 5.1.

The data structure for a multilevel analysis of these data is generally different, depending on the specific program that is used. Multilevel software requires that the data is structured with the measurement occasions defining the lowest level, and student-level variables repeated over the cases. Figure 5.2 presents the GPA data in this format, where each row in the data set represents a separate occasion, with six repeated measurements resulting in six rows for each student. This data format is sometimes referred to as a 'long' (or 'stacked') data set, and the regular format in Figure 5.1 is referred to as a 'wide' (or 'multivariate') data set (cf. Chapter 10 on multivariate multilevel analysis). Although Figures 5.1 and 5.2 do not include missing data, missing occasions simply result in students with fewer than the full set of six occasions in the data file. As a result, missing occasions are very simple to handle in a multilevel model. [Note that the measurement occasions are numbered 0, ..., 5 instead of 1, ..., 6. This ensures that 'zero' is part of the range of possible values.] For the data in Figure 5.2, the intercept can be interpreted as the starting value at the first measurement occasion, and the second-level variance is the variance between subjects at the first measurement occasion. Other coding schemes for the measurement occasions are possible, and will be discussed later in this chapter.

The multilevel regression model for longitudinal data is a straightforward application of the multilevel regression model described in Chapter 2. It can also be written as a sequence of models for each level. At the lowest, the repeated measures level, we have:

$$Y_{it} = \pi_{0i} + \pi_{1i}T_{it} + \pi_{2i}X_{it} + e_{it}. \quad (5.1)$$

In repeated measures applications, the coefficients at the lowest level are often indicated by the Greek letter π . This has the advantage that the subject-level coefficients, which in repeated measures are at the second level, can be represented by the usual Greek letter β , and so on. In Equation 5.1, Y_{it} is the response variable of individual i measured at measurement occasion t , T is the time variable that indicates the measurement occasion, and X_{it} is a *time*

	student	sex	highgpa	gpa1	gpa2	gpa3	gpa4	gpa5	gpa6	job1	job2	job3	job4	job5	job6
1	1	1	2.8	2.3	2.1	3.0	3.0	3.0	3.3	2	2	2	2	2	2
2	2	0	2.5	2.2	2.5	2.6	2.6	3.0	2.8	2	3	2	2	2	2
3	3	1	2.5	2.4	2.9	3.0	2.8	3.3	3.4	2	2	2	3	2	2
4	4	0	3.8	2.5	2.7	2.4	2.7	2.9	2.7	3	2	2	2	2	2
5	5	0	3.1	2.8	2.8	2.8	3.0	2.9	3.1	2	2	2	2	2	2
6	6	1	2.9	2.5	2.4	2.4	2.3	2.7	2.8	2	3	3	2	3	3
7	7	0	2.3	2.4	2.4	2.8	2.6	3.0	3.0	3	2	3	2	2	2
8	8	1	3.9	2.8	2.8	3.1	3.3	3.3	3.4	2	2	2	2	2	2
9	9	0	2.0	2.8	2.7	2.7	3.1	3.1	3.5	2	2	3	2	2	2
10	10	0	2.8	2.8	2.8	3.0	2.7	3.0	3.0	2	2	2	3	2	2
11	11	1	3.9	2.6	2.9	3.2	3.6	3.6	3.8	2	3	2	2	2	2
12	12	1	2.9	2.6	3.0	2.3	2.9	3.1	3.3	3	2	2	2	2	2
13	13	0	3.7	2.8	3.1	3.5	3.6	3.9	3.9	2	2	2	2	2	2

Figure 5.1 Repeated measures data structure in SPSS.

	student	occas	gpa	job	sex	highgpa
1	1	0	2.3	2	1	2.8
2	1	1	2.1	2	1	2.8
3	1	2	3.0	2	1	2.8
4	1	3	3.0	2	1	2.8
5	1	4	3.0	2	1	2.8
6	1	5	3.3	2	1	2.8
7	2	0	2.2	2	0	2.5
8	2	1	2.5	3	0	2.5
9	2	2	2.6	2	0	2.5
10	2	3	2.6	2	0	2.5
11	2	4	3.0	2	0	2.5
12	2	5	2.8	2	0	2.5
13	3	0	2.4	2	1	2.5
14	3	1	2.9	2	1	2.5
15	3	2	3.0	2	1	2.5
16	3	3	2.8	3	1	2.5
17	3	4	3.3	2	1	2.5
18	3	5	3.4	2	1	2.5
19	4	0	2.5	3	0	3.8
20	4	1	2.7	2	0	3.8
21	4	2	2.4	2	0	3.8
22	4	3	2.7	2	0	3.8
23	4	4	2.9	2	0	3.8
24	4	5	2.7	2	0	3.8
25	5	0	2.8	2	0	3.1
26	5	1	2.8	2	0	3.1

Figure 5.2 Repeated measures data structure for multilevel analysis.

varying covariate. For example, Y_{it} could be the GPA of a student at measurement occasion t , T_{it} indicates the occasion at which the GPA is measured, and X_{it} the job status of the student at time t . Student characteristics, such as gender, are *time invariant covariates*, which enter the equation at the second level:

$$\begin{aligned}
 \pi_{0i} &= \beta_{00} + \beta_{01}Z_i + u_{0i} \\
 \pi_{1i} &= \beta_{10} + \beta_{11}Z_i + u_{1i} \\
 \pi_{2i} &= \beta_{20} + \beta_{21}Z_i + u_{2i}.
 \end{aligned}
 \tag{5.2}$$

By substitution, we get the single equation model:

$$\begin{aligned}
 Y_{it} &= \beta_{00} + \beta_{10}T_{it} + \beta_{20}X_{it} + \beta_{01}Z_i + \beta_{11}T_{it}Z_i + \beta_{21}X_{it}Z_i \\
 &\quad + u_{1i}T_{it} + u_{2i}X_{it} + u_{0i} + e_{it}.
 \end{aligned}
 \tag{5.3}$$

Using variable labels instead of letters, the equation for our GPA example becomes:

$$\begin{aligned}
 Y_{ii} = & \beta_{00} + \beta_{10}Occasion_{ii} + \beta_{20}Job_{ii} + \beta_{01}Sex_i \\
 & + \beta_{11}Occasion_{ii}Sex_i + \beta_{21}Job_{ii}Sex_i \\
 & + u_{1i}Occasion_{ii} + u_{2i}Job_{ii} + u_{0i} + e_{ii}.
 \end{aligned}
 \tag{5.4}$$

In longitudinal research, we sometimes have repeated measurements of individuals, who are all measured together on a small number of fixed occasions. This is typically the case with experimental designs involving repeated measures and panel research. If we simply want to test the null hypothesis that the means are equal for all occasions, we can use repeated measures analysis of variance. If we use repeated measures univariate analysis of variance (Stevens, 2009, p. 420), we must assume *sphericity*. Sphericity means that there are complex restrictions on the variances and covariances between the repeated measures, for details see Stevens (2009, Chapter 13. A specific form of sphericity, which is easily understood, is *compound symmetry*, sometimes referred to as *uniformity*. Compound symmetry requires that all population variances of the repeated measures are equal, and that all population covariances of the repeated measures are equal. If sphericity is not met, the *F*-ratio used in analysis of variance is positively biased, and we reject the null hypothesis too often. A different approach is to specify the repeated measures as observations on a multivariate response vector and use Multivariate Analysis of Variance (MANOVA). This does not require sphericity, and is considered the preferred approach if analysis of variance is used on repeated measures (O'Brien & Kaiser, 1985; Stevens, 2009). However, the multivariate test is more complicated, because it is based on a transformation of the repeated measures, and what is tested are actually contrasts among the repeated measures.

A MANOVA analysis of the example data using the General Linear Model in SPSS (IBM Corporation, 2012) cannot easily incorporate a time-varying covariate such as job status. But MANOVA can be used to test the trend over time of the repeated GPA measures by specifying polynomial contrasts for the measurement occasions, and to test the fixed effects of gender and high school GPA. Gender is a dichotomous variable, which is entered as a factor, and high school GPA is a continuous variable that is entered as a covariate. Table 5.1 presents the results of the traditional significance tests.

Table 5.1 MANOVA significance tests on GPA example data

Effect tested	F	df	P
Occasion	3.58	5/193	.004
Occasion (linear)	8.93	1/197	.003
Occasion \times HighGPA	0.87	5/193	.505
Occasion \times Gender	1.42	5/193	.220
HighGPA	9.16	1/197	.003
Gender	18.37	1/197	.000

Table 5.2 GPA means at six occasions, for male and female students

Occasion	1	2	3	4	5	6	Total
Male	2.6	2.7	2.7	2.8	2.9	3.0	2.8
Female	2.6	2.8	2.9	3.0	3.1	3.2	2.9
All students	2.6	2.7	2.8	2.9	3.0	3.1	2.9

The MANOVA results indicate that there is a significant linear trend for the GPA measures. Both gender and high school GPA have significant effects. The higher polynomial trends, which are not in the table, are not significant, and the interactions between measurement occasion and high school GPA and gender are not significant. Table 5.2 presents the GPA means at the different measurement occasions, rounded to one decimal, for all six occasions, for male and female students.

Table 5.2 makes clear that there is a linear upward trend of about 0.1 for each successive GPA measurement. Female students have a GPA that is consistently higher than the GPA of the male students. Finally, the SPSS output also contains the regression coefficients for the gender and high school GPA at the six occasions; these coefficients (not given in the table) are different for each predicted occasion, but both generally positive, indicating that female students do better than males on each occasion, and that students who have a high GPA in high school have a relatively high GPA in college at each measurement occasion.

In the multilevel regression model, the development over time is often modeled by a linear or polynomial regression equation, which may have different regression coefficients for different individuals. Thus, each individual can have their own regression curve, specified by the individual regression coefficients that in turn may depend on individual attributes. Quadratic and higher functions can be used to model nonlinear dependencies on time, and both time-varying and subject-level covariates can be added to the model. Although the measurement occasions will usually be thought of as occasion 1, 2, etc., it is useful to code the measurement occasions T as $t = 0, 1, 2, 3, 4, 5$. As a result, the intercept can be interpreted as the expected outcome on the first occasion. Using measurement occasions $t = 1, 2, 3, 4, 5, 6$ would be equivalent, but more difficult to interpret, because the value zero is not in the range of observed measurement occasions. If the explanatory variable is not successive measurement occasions but, for instance, calendar age, setting the first observation to zero is not the best solution. In that case, it is usual to center on the mean or median age, or on a rounded-off value close to the mean or median.¹

Before we start the analysis, we examine the distribution of the outcome variable GPA in the disaggregated data file with $200 \times 6 = 1200$ observations. The histogram with embedded best fitting normal curve is in Figure 5.3. The distribution appears quite normal, so we proceed with the analysis.

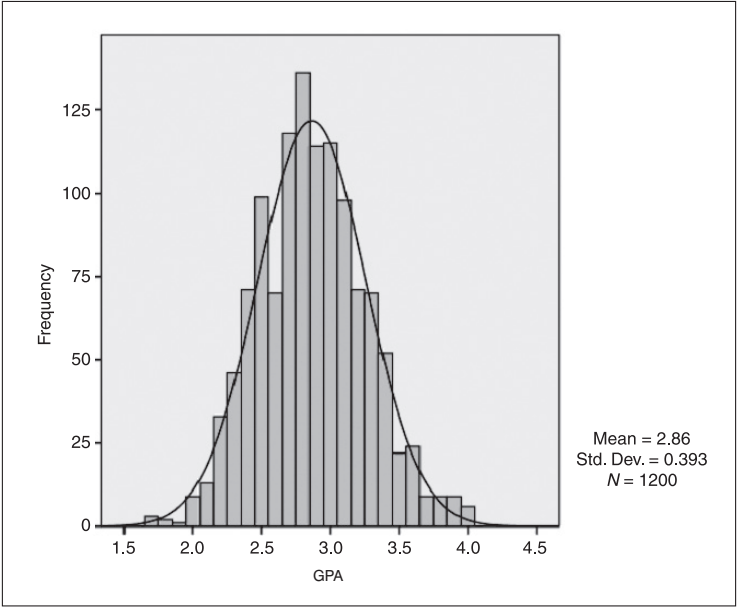


Figure 5.3 Histogram of GPA values in disaggregated data file.

Table 5.3 Results multilevel analysis of GPA, fixed effects

Model	M ₁ : null model	M ₂ : + occas.	M ₃ : + job stat	M ₄ : + high school GPA, gender
Fixed part				
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	2.87 (.02)	2.60 (.02)	2.97 (.04)	2.64 (.10)
Occasion		0.11 (.004)	0.10 (.003)	0.10 (.003)
Job status			−0.17 (.02)	−0.17 (.02)
GPA high school				0.08 (.03)
Gender				0.15 (.03)
Random part				
σ_e^2	0.098 (.004)	0.058 (.025)	0.055 (.002)	0.055 (.002)
σ_{u0}^2	0.057 (.007)	0.063 (.007)	0.052 (.006)	0.045 (.01)
Deviance	913.5	393.6	308.4	282.8
AIC	919.5	401.6	318.4	296.8
BIC	934.7	422.0	343.8	332.4

Table 5.3 presents the results of a multilevel analysis of these longitudinal data. Model 1 is a model that contains only an intercept term and variances at the occasion and the subject level. The intercept of 2.87 in this model is simply the average GPA across all individuals and occasions. The intercept-only model estimates the repeated measures (level 1) variance as 0.098, and the subject-level (level-2) variance as 0.057 (because these numbers are so small, they are given to three decimal places). This estimates the total GPA variance as 0.155. Using Equation 2.9, the intraclass correlation or the proportion variance at the subject level is estimated as $\rho = 0.057 / 0.155 = 0.37$. About one-third of the variance of the six GPA measures is variance between individuals, and about two-thirds is variance within individuals across time.

In Model 2, the time variable is added as a linear predictor with the same coefficient for all subjects. The model predicts a value of 2.60 at the first occasion, which increases by 0.11 on each succeeding occasion. Just as in the MANOVA analysis, adding higher order polynomial trends for time to the model does not improve prediction. Model 3 adds the time-varying covariate job status to the model. The effect of job status is clearly significant; the more hours are worked, the lower the GPA. Model 4 adds the subject-level (time invariant) predictors high school GPA and gender. Both effects are significant; high school GPA correlates with average GPA in college, and female students perform better than male students.

In all models in Table 5.3, the Wald test indicates that the subject-level (second-level) variance is significant. The more accurate test using the difference of the deviance in a model with and a model without the second-level variance term confirms this for all models in the table (results not reported here).

If we compare the variance components of Model 1 and Model 2, we see that entering the measurement occasion variable decreases the occasion-level variance considerably, while increasing the subject-level variance by as much as 11 percent. If the usual formula is used to estimate the second-level variance explained by the measurement occasion variable, we arrive at a negative value for the amount of explained variance. This is odd, but it is in fact typical for multilevel analysis of repeated measures. The occurrence of negative estimates for the explained variance makes it impossible to use the residual error variance of the intercept-only model as a benchmark, and to examine how much this goes down when explanatory variables are added to the model.

The reason for this apparent anomaly is, as is discussed in detail in Chapter 4, that the ‘amount of variance explained at a specific level’ is not a simple concept in multilevel models (cf. Snijders & Bosker, 2012). The problem arises because the statistical model behind multilevel models is a hierarchical sampling model: groups are sampled at the higher level, and at the lower level individuals are sampled within groups. This sampling process creates some variability in all variables between the groups, even if there are in fact no real group differences. In a time series design, the lowest level is a series of measurement occasions. In many cases, the data collection design is set up to make sure that the repeated measurements are evenly spaced and the data are collected at the same time for all individuals in the sample. Therefore, the variability between subjects in the measurement occasion variable is usually

much higher than the hierarchical sampling model assumes. Consequently, the intercept-only model overestimates the variance at the occasion level, and underestimates the variance at the subject level. Model 2 uses the measurement occasion variable to model the occasion level variance in the dependent variable GPA. Conditional upon this effect, the variances estimated at the measurement occasions and at the subject level are much more realistic.

Chapter 4 in this book describes procedures based on Snijders and Bosker (2012) to correct the problem. A simple approximation is to use as a baseline model for the ‘explained variance’ a model that includes the measurement occasion in an appropriate manner. Whether this is linear or needs to be some polynomial must be determined by preliminary analyses. In our example, a linear trend for measurement occasion suffices. Using M_2 in Table 5.3 as the baseline, we calculate that job status explains $(0.058 - 0.055) / 0.058 = 0.052$ or 5.2 percent of the variance, indicating that in semesters that they work more hours off campus, students tend to have a lower grade. The time-varying predictor job status explains a further $(0.063 - 0.052) / 0.063 = 0.175$ or 17.5 percent of the variance between students; apparently students differ in how many hours they work in an off campus job. Hence, although job status is a time-varying predictor, it explains more variation between different subjects in the same semester,

Table 5.4 Results multilevel analysis of GPA, varying effects for occasion

Model	M_5 : + occasion random	M_6 : + cross-level interaction	Standardized
Fixed part			
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	
Intercept	2.56 (.10)	2.58 (.09)	
Occasion	0.10 (.006)	0.09 (.01)	0.38
Job status	-0.13 (.02)	-0.13 (.02)	-0.14
GPA high school	0.09 (.03)	0.09 (.03)	0.13
Gender	0.12 (.03)	0.08 (.03)	0.10
Occasion*Gender		0.03 (.01)	0.13
Random part			
σ_e^2	0.042 (.002)	0.042 (.002)	
σ_{u0}^2	0.038 (.006)	0.038 (.01)	
σ_{u1}^2	0.004 (.001)	0.004 (.001)	
σ_{u01}	-0.002 (.002)	-0.002 (.001)	
r_{u01}	-0.21	-0.19	
Deviance	170.1	163.0	
AIC	188.1	183.0	
BIC	233.93	233.87	

than within the same subjects from one semester to the next. The pupil-level variables gender and high school GPA explain an additional 11.5 percent of the between students variance.

The models presented in Table 5.3 all assume that the rate of change is the same for all individuals. In the models presented in Table 5.4, the regression coefficient of the measurement occasion variable is assumed to vary across individuals.

In Model 5 in Table 5.4, the slope of the measurement occasion variable is allowed to vary across individuals. The Wald test for the variance of the slopes for occasion is significant, $Z = 6.02$ (calculated carrying more decimal values than reported in Table 5.4). The deviance difference test (comparing Model 5 to the same model without the subject-level variance) produces a chi-square of 109.62. With one degree of freedom, this translates to $Z = 10.47$, which demonstrates again that for variances the deviance difference test is generally more powerful than the Wald test.

The variance components for the intercept and the regression slope for the time variable are both significant. The significant intercept variance of 0.038 means that individuals have different initial states, and the significant slope variance of 0.004 means that individuals also have different rates of change. In Model 6, the interaction of the occasion variable with the subject-level predictor gender is added to the model. The interaction is significant, but including it does not decrease the slope variance for the time variable (actually, carrying all decimals in the output leads to a decrease in slope variance of 0.00022).

The variance component of 0.004 for the slopes of the occasion variable does not seem large. However, multilevel models assume a normal distribution for these slopes (or, equivalently, for the slope residuals u_1), for which the standard deviation is estimated in Models 5 and 6 as $\sqrt{0.004} = 0.063$. Compared to the value of 0.10 for the average time slope in Model 5, this is not very small. There is substantial variation among the time slopes, which is not modeled well by the available student variables.

In both Model 5 and Model 6 there is a small negative covariance σ_{u01} between the initial status and the growth rate; students who start with a relatively low value of their GPA, increase their GPA faster than the other students. It is easier to interpret this covariance if it is presented as a correlation between the intercept and slope residuals. Note that the correlation r_{u01} between the intercept and slope is slightly different in Models 5 and 6; the covariances seem equal because of rounding. In a model without other predictors except the time variable, this correlation can be interpreted as an ordinary correlation, but in Models 5 and 6 it is a partial correlation, conditional on the predictors in the model.

When the fit indices AIC and BIC are inspected, they both indicate Model 6 as the best model. Since the slope variation is small but not negligible, and since the cross-level interaction is also significant, we decide to keep Model 6.

To facilitate interpretation, standardized regression coefficients are calculated for the last model (Model 6) in Table 5.4 using Equation 2.13. The standardized regression coefficients indicate that the change over time is the largest effect. The standardized results also suggest that the interaction effect is more important than the unstandardized analyses indicate. To

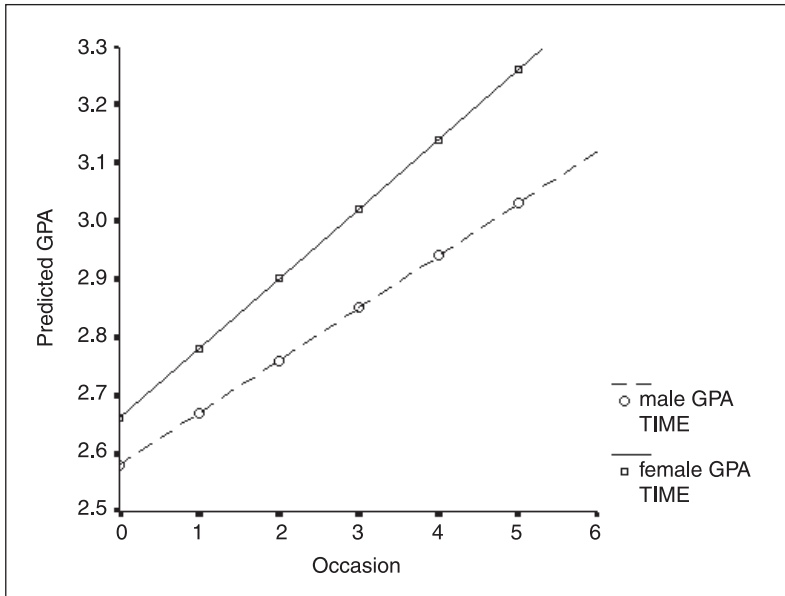


Figure 5.4 Regression lines for occasion, separate for male and female students.

investigate this further, we can construct the regression equation of the time variable separately for both male and female students. Since gender in this example is coded 0 (male) and 1 (female), including the interaction changes the value of the regression coefficient for the time trend. As discussed in Chapter 4, this regression coefficient now reflects the expected time effect for respondents with value zero on the gender variable. Thus, the regression coefficient of 0.09 for occasion in the final model refers to the male students. For female students the interaction term is added, so their regression coefficient equals $0.09 + 0.03 = 0.12$.

Figure 5.4 presents a plot of these regression lines. The expected difference between male and female students, which is 0.08 in the first semester, increases to 0.11 in the second semester. In the sixth semester, the difference has grown to 0.23.

Since the measurement occasion variable is coded in such a way that the first occasion is coded as zero, the negative correlation between the intercepts and slopes refers to the situation on the first measurement. As is explained in Section 4.2, the estimates of the variance components in the random part can change if the scale of the time variable is changed. In many models, this is not a real problem, because the interest is mostly in estimation and interpretation of the regression coefficients in the fixed part of the model. In repeated measures analysis, the correlation between the intercepts and the slopes of the time variable is often an interesting parameter, to be interpreted along with the regression coefficients. In this case, it is important to realize that this correlation is *not* invariant; it changes if the scale of the time variable is changed. In fact, one can show that by using extremely different scalings for the time variable,

Table 5.5 Results for Model 5 for different scalings of measurement occasion

Model	M_{5a} : first occasion=0	M_{5b} : last occasion=0	M_{5c} : occasions centered
Fixed part			
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	
Intercept	2.56 (.10)	3.07 (.09)	2.82 (.09)
Occasion	0.10 (.006)	0.10 (.006)	0.10 (.006)
Job status	−0.13 (.02)	−0.13 (.02)	−0.13 (.02)
GPA high school	0.09 (.03)	0.09 (.03)	0.09 (.03)
Gender	0.12 (.03)	0.12 (.03)	0.12 (.03)
Random part			
σ_e^2	0.042 (.002)	0.042 (.002)	0.042 (.002)
σ_{u0}^2	0.038 (.006)	0.109 (.014)	0.050 (.006)
σ_{u1}^2	0.004 (.001)	0.004 (.001)	0.004 (.001)
σ_{u01}	−0.002 (.002)	0.017 (.003)	0.007 (.001)
r_{u01}	−0.21	0.82	0.51
Deviance	170.1	170.1	170.1
AIC	188.1	188.1	188.1
BIC	233.9	233.9	233.9

we can give the correlation between the intercepts and slopes any desired value (Stoel & van den Wittenboer, 2001).

Table 5.5 illustrates this point. Table 5.5 shows the effect of different scalings of the time variable on the coefficients of Model 5. In Model 5a, the time variable is scaled as in all our analyses so far, with the first measurement occasion coded as zero. In Model 5b, the time variable is coded with the last measurement occasion coded as zero, and the earlier occasions with negative values −5, ..., −1. In Model 5c, the time variable is centered on its overall mean.

From the correlations between the intercepts and slopes for the time variable, we conclude in Model 5b that students who end with a relatively high GPA, on average have a steeper GPA increase over time. In the centered model, Model 5c, this correlation is lower, but still quite clear. If we inspect the first Model 5a, which codes the first occasion as zero, we see a negative correlation, meaning that subjects with a relatively low initial GPA have a steeper growth rate. It is clear that we cannot interpret the correlation between the intercept and slopes directly. This correlation can only be interpreted in combination with the scale on which the occasion variable is defined.²

Note that the three models in Table 5.5 have exactly identical estimates for all parameters that do not involve the measurement occasion, and exactly the same deviance and fit measures. The models are in fact equivalent. The different ways that the time variable is coded lead to what statisticians call a *re-parameterization* of the model. The three models all describe the data equally well, and are equally valid. Nevertheless, they are not identical. The situation is comparable to viewing a landscape from different angles. The landscape does not change, but some views are more interesting than others are. The important lesson here is that in repeated measures analysis, careful thought must be given to the coding of the time variable. As stated, by a judicious choice of scale, we can give the correlation between the intercept and slope residuals any value that we want. If the zero point is far outside the observed values, for instance if we code the occasions as 2004, 2005, 2006, 2007, 2008 and 2009, which does make some sense, we will get an extreme correlation. If we want to interpret the correlation between the intercepts and slopes, we must make sure that the zero point has a strong substantive meaning. Adding a graphical display of the slopes for different individuals may help to interpret the results.³

5.4 EXAMPLE WITH VARYING OCCASIONS

The data in the next example are a study of children's development in reading skill and antisocial behavior. The data are a sample of 405 children who were within the first two years of entry to elementary school. The data consist of four repeated measures of both the child's antisocial behavior and the child's reading recognition skills. In addition, at the first measurement occasion, measures were collected of emotional support and cognitive stimulation provided by the mother. Other variables are the child's gender and age and the mother's age at the first measurement occasion. The data were collected using face-to-face interviews of both the child and the mother at two-year intervals between 1986 and 1992. Between 1986 and 1992 there was an appreciable amount of panel dropout: all $N = 405$ children and mothers were interviewed at measurement occasion 1, but on the three subsequent occasions the sample sizes were 374, 297 and 294. Only 221 cases were interviewed at all four occasions. This data set was compiled by Curran (1997) from a large longitudinal data set. The predominant dropout pattern in this data set is panel dropout, meaning that if a subject was not measured at some measurement occasion, that subject is also not measured at subsequent measurement occasions. However, a small number of subjects were not measured at one of the measurement occasions, but did return at subsequent occasions.

These data are a good example of data with varying measurement occasions. Although the measurement occasions are the same for all children, their ages are all different. The children's ages at the first measurement occasion vary from 6 to 8 years. The children's ages were coded in months, and there are 25 different values for this variable. Since each child is measured at most four times, these 25 values are best treated as a time-varying predictor indicating varying measurement occasions. Figure 5.5 shows the frequency of different ages at the start of the data collection.

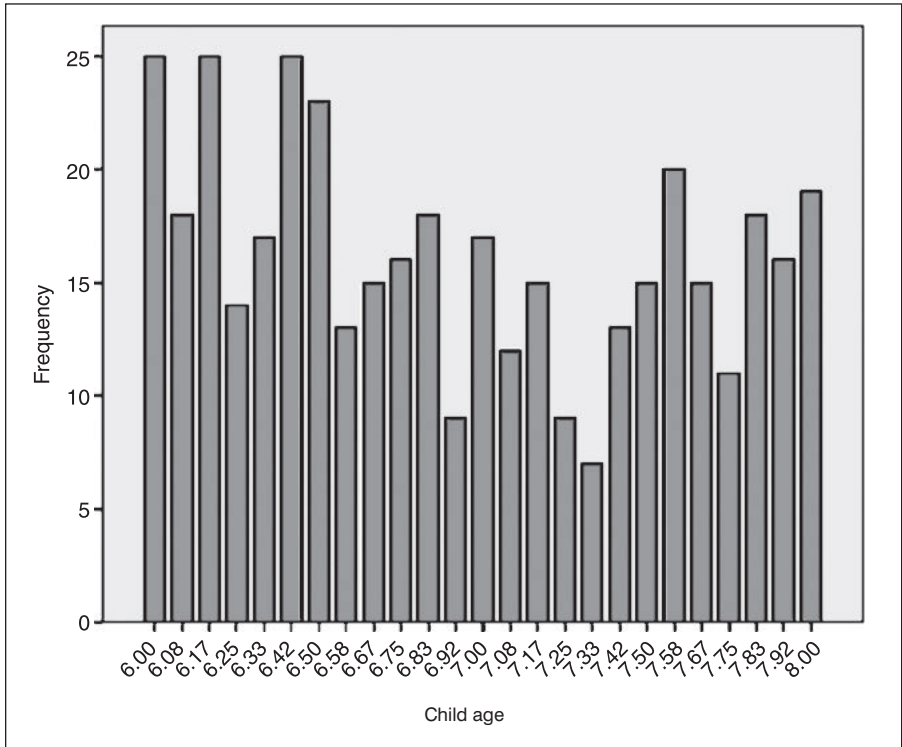


Figure 5.5 Child ages at the first measurement occasion.

It is clear that with 25 different ages and only four measurement occasions, using the real age in a MANOVA-type analysis is impossible, because using listwise deletion would leave no cases to analyze. Restructured in the ‘long’ or ‘stacked’ format, we have the children’s age varying from 6 to 14 years, and 1325 out of a possible 1620 observations for reading skill available for the analysis. Figure 5.6 shows a scatterplot for reading skill by child age, with the best fitting nonlinear fit line (the *LOESS* fit function) added. The relationship is mostly linear, reading skill increasing with age, but with some deceleration of the upwards trend at the higher ages. The variance of reading skills increases with age, which indicates that the regression coefficient for age is likely to vary across subjects.

Before the analysis, the time-varying variable child age is transformed by subtracting 6, which makes the lowest starting age zero. In addition a new variable is calculated which is the square of the new child age variable. It is important to obtain a good model for the trend over time, and therefore it is useful to evaluate adding nonlinear trends not only by the Wald significance test, but also by the deviance difference test (which is somewhat more accurate, also for regression coefficients) and fit indices. Since the deviance difference test is used to test regression coefficients, full maximum likelihood estimation must be used. Consistent with the

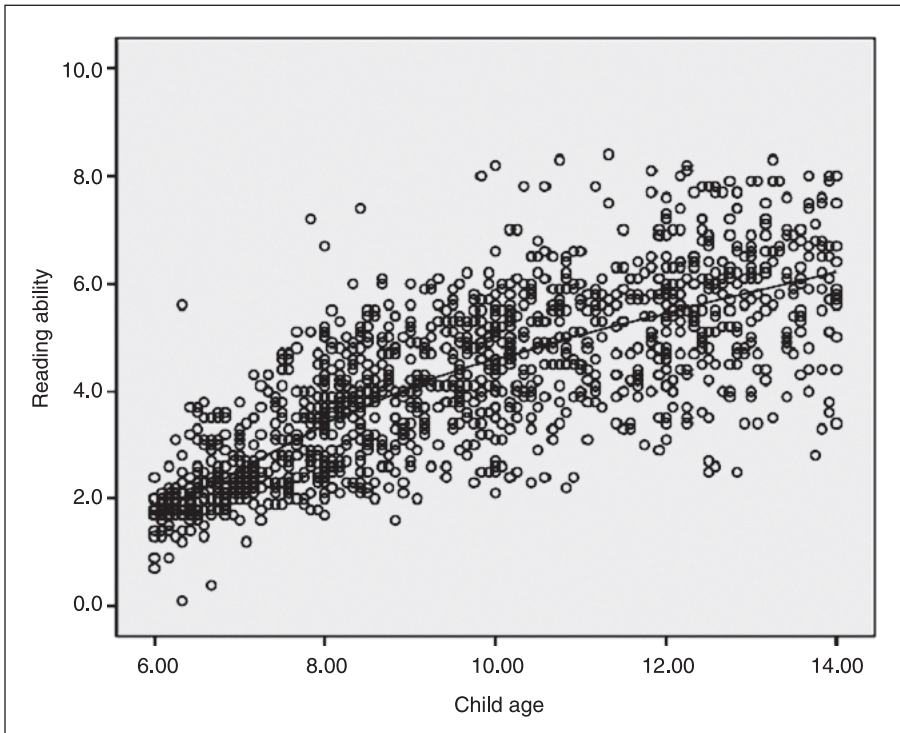


Figure 5.6 Scatterplot of reading skill by child age.

scatterplot, Model 1, the multilevel model for predicting reading skill by time-varying age and age squared looks promising. There is also a significant cubic trend (not reported in Table 5.6), but that is very small (regression coefficient 0.006 (s.e. 0.002)). For simplicity, this variable is not included in the model. Child age has a small, but significant variance across children, the squared age does not. A chi-square difference test between Models 2 and 3 in Table 5.6 also indicates that the added variance and covariance are significant ($\chi^2 = 200.8$, $df = 2$, $p < .001$). The correlation between the intercept and the age slope is 0.63. This indicates that children, who at the initial age of six read comparatively well, increase their reading skill faster than children who read worse at that age.

The time invariant variables mother age, cognitive stimulation, and emotional support, which were measured at the first measurement occasion, have significant effects in the fixed model, but two of these become nonsignificant when the effect of age is assumed to vary across the children, then only cognitive stimulation has a significant regression coefficient. The deviance difference between models M_2 and M_3 is 200.8. As explained in Chapter 3, given that we test both an unconstrained covariance and a variance that is constrained to be non-negative, the appropriate test is a mixture of 50 percent chi-square with one degree of freedom and 50 percent chi-square with two degrees of freedom. Given the large value of $\chi^2 = 200.8$,

Table 5.6 Multilevel models for reading skill

Model	M ₁	M ₂	M ₃	M ₄
Fixed part				
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	1.74 (.06)	0.71 (.48)	0.71 (.48)	1.06 (.49)
Child age	0.93 (.03)	0.92 (.03)	0.92 (.03)	0.49 (.14)
Child age sq	−0.05 (.003)	−0.05 (.003)	−0.05 (.003)	−0.05 (.003)
Mother age		0.05 (.02)	0.03 (.02) ^{ns}	0.02 (.02) ^{ns}
Cognitive stimulation		0.05 (.02)	0.04 (.01)	0.04 (.01)
Emotional support		0.04 (.02)	0.003 (.02) ^{ns}	−0.01 (.02) ^{ns}
Age*Momage				0.01 (.005)
Age*Emot				0.01 (.004)
Random part				
σ_e^2	0.39 (.02)	0.39 (.02)	0.27 (.02)	0.28 (.02)
σ_{u0}^2	0.66 (.06)	0.60 (.04)	0.21 (.04)	0.21 (.04)
σ_{u1}^2			0.02 (.003)	0.01 (.003)
σ_{u01}			0.04 (.001)	0.04 (.001)
r_{u01}				0.64
Deviance	3245.0	3216.2	3015.4	2995.3
AIC	3255.0	3232.2	3035.4	3019.3
BIC	3281.0	3273.7	3087.3	3081.6

a test at the conservative $df = 2$ produces a very small p -value $p < 0.001$. The decreasing AIC and BIC also suggest that Model 3 is preferable. Thus, the varying effect of age belongs in the model, and the significant effect of mother age and emotional support in the fixed model are interpreted as spurious.

To model the significant variance of the regression coefficient of child age, cross-level interactions of child age with the three time invariant variables are added to the model. In this model, the interactions between the child's age and mother's age and between the child's age and emotional support were significant. As a consequence, the direct effects of mother's age and emotional support are retained in the model, although these direct effects are not significant by themselves. The interaction between child's age and cognitive stimulation is not significant, and is dropped from the model. The last column of Table 5.6 presents the estimates for this final model. Both the deviance difference test ($\chi^2 = 20.1, df = 2, p < .001$) and the decrease

in AIC and BIC indicate that Model 4 is better than Model 3. However, the variance of the coefficients for child age is the same to two decimal places; when more decimal places are used it turns out that the two interaction effects explain only 0.9 percent of the slope variance.

The coefficients for the interactions are both 0.01. This means that when the mother's age is higher, or the emotional support is high, the reading skill increases faster with the child's age. Plots are useful to interpret such interactions; Figure 5.7 shows the estimated fit lines for mothers of different ages (the range in the data is 21–29) and low vs. high emotional support (the range in the data is 0–13). Figure 5.7 illustrates that for older mothers the increase in reading skill is steeper and the leveling off less sharp. The same holds for high emotional support; with high emotional support the increase in reading skill is steeper and the leveling off less sharp. Note that the curves in Figure 5.7 are the predicted outcomes disregarding all variables not involved in the cross-level interaction. It shows the theoretical effect of the interaction, not the trend in the actual data. The apparent downward trend at the higher ages is the result of extrapolating the quadratic trend.

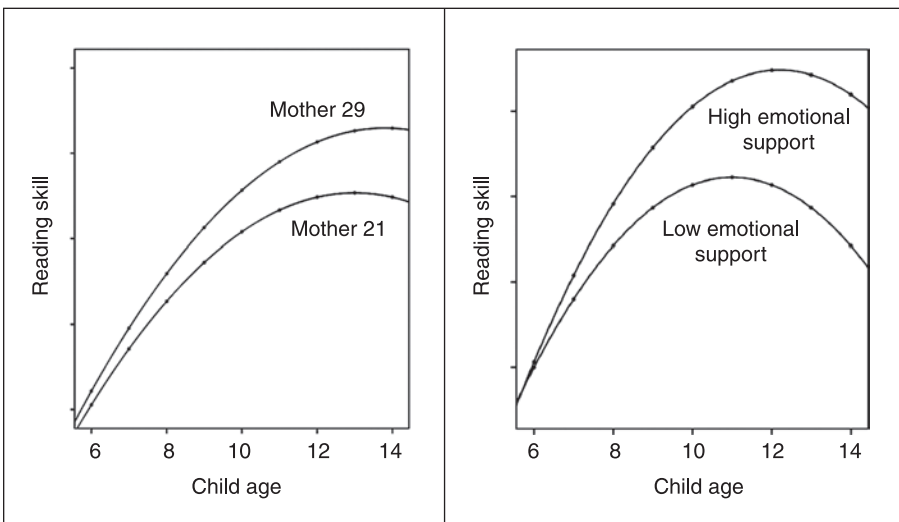


Figure 5.7 Estimated fit lines for reading by mothers of different ages and low vs. high emotional support.

5.5 ADVANTAGES OF MULTILEVEL ANALYSIS FOR LONGITUDINAL DATA

Using multilevel models to analyze repeated measures data has several advantages. Bryk and Raudenbush (1992) mention five key points. First, by modeling varying regression coefficients at the measurement occasion level, we have growth curves that are different for each subject. This fits in with the way individual development is generally conceptualized.

Second, the number of repeated measures and their spacing may differ across subjects. Other analysis methods for longitudinal data cannot handle such data well. Third, the covariances between the repeated measures can be modeled as well, by specifying a specific structure for the variances and covariances at either level. This approach will be discussed in Section 5.6. Fourth, if we have balanced data and use RML estimation, the usual analysis of variance based F -tests and t -tests can be derived from the multilevel regression results (cf. Raudenbush, 1993a). This shows that analysis of variance on repeated measures is a special case of the more general multilevel regression model. Fifth, in the multilevel model it is simple to add higher levels, to investigate the effect of family or social groups on individual development. A sixth advantage, not mentioned by Bryk and Raudenbush, is that it is straightforward to include time varying or time constant explanatory variables to the model, which allows us to model both the average group development and the development of different individuals over time. Finally, multilevel analysis tends to have a higher power than repeated measures ANOVA (Fan, 2003).

5.6 COMPLEX COVARIANCE STRUCTURES

If multilevel modeling is used to analyze longitudinal data, the variances and covariances between different occasions have a very specific structure. In a two-level model with only a random intercept at both levels, the variance at any measurement occasion has the value $\sigma_e^2 + \sigma_{u_0}^2$, and the covariance between any two measurement occasions has the value $\sigma_{u_0}^2$. Thus, for the GPA example data, a simple linear trend model as specified by Equation 5.1 is

$$GPA_{it} = \beta_{00} + \beta_{10} \text{Occasion}_{it} + u_{0i} + e_{it}, \quad (5.5)$$

where the residual variance on the occasion level is given by σ_e^2 , and the residual error on the subject level is given by $\sigma_{u_0}^2$. For this and similar models without additional random effects, the matrix of variances and covariances among the occasions is given by (Goldstein, 2011; Raudenbush & Bryk, 2002):

$$\Sigma(Y) = \begin{pmatrix} \sigma_e^2 + \sigma_{u_0}^2 & \sigma_{u_0}^2 & \sigma_{u_0}^2 & \dots & \sigma_{u_0}^2 \\ \sigma_{u_0}^2 & \sigma_e^2 + \sigma_{u_0}^2 & \sigma_{u_0}^2 & \dots & \sigma_{u_0}^2 \\ \sigma_{u_0}^2 & \sigma_{u_0}^2 & \sigma_e^2 + \sigma_{u_0}^2 & \dots & \sigma_{u_0}^2 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sigma_{u_0}^2 & \sigma_{u_0}^2 & \sigma_{u_0}^2 & \dots & \sigma_e^2 + \sigma_{u_0}^2 \end{pmatrix}. \quad (5.6)$$

In the covariance matrix (5.6), all variances are equal, and all covariances are equal. This shows that the standard multilevel model, with a single error term at the occasion and at the subject level, assumes *compound symmetry*, the same restrictive assumption that

is multivariate analysis of variance for repeated measures. According to Stevens (2009), if the assumption of compound symmetry is violated, the standard ANOVA significance tests are too lenient, and reject the null hypothesis more often than is warranted. Therefore, MANOVA is preferred, which estimates all variances and covariances among occasions without restrictions.

Bryk and Raudenbush (1992, p. 132) argue that uncorrelated errors may be appropriate in short time series. However, the assumption of uncorrelated errors is not essential, because the multilevel regression model can easily be extended to include an unconstrained covariance matrix at the lowest level (Goldstein, 2011). To model correlated errors, we use a multivariate response model (treated in more detail in Chapter 10 in this book) with a full set of dummy variables indicating the six consecutive measurement occasions. Thus, if we have p measurement occasions, we have p dummy variables, one for each occasion. The intercept term is removed from the model, so the lowest level is empty. The dummy variables are all allowed to have random slopes at the second level. Thus, for our grade point example with six occasions, we have six dummy variables O_1, O_2, \dots, O_6 , and the equation for a model without additional explanatory variables becomes:

$$GPA_{it} = \beta_{10}O_{1i} + \beta_{20}O_{2i} + \beta_{30}O_{3i} + \beta_{40}O_{4i} + \beta_{50}O_{5i} + \beta_{60}O_{6i} + u_{10i}O_{1i} + u_{20i}O_{2i} + u_{30i}O_{3i} + u_{40i}O_{4i} + u_{50i}O_{5i} + u_{60i}O_{6i} . \quad (5.7)$$

Having six random slopes at level two provides us with a 6×6 covariance matrix for the six occasions. This is often denoted as an unstructured model for residual errors across time; all possible variances and covariances are estimated. The unstructured model for the random part is also a saturated model; all possible parameters are estimated and it cannot fail to fit. The regression slopes β_{10} to β_{60} are simply the estimated means at the six occasions. Equation 5.7 defines a multilevel model that is equivalent to the MANOVA approach. Maas and Snijders (2003) discuss the model in Equation 5.7 at length, and show how the familiar F -ratios from the MANOVA approach can be calculated from the multilevel software output. An attractive property of the multilevel approach here is that it is not affected by missing data. Delucchi and Bostrom (1999) compare the MANOVA and the multilevel approach to longitudinal data using small samples with missing data. Using simulation, they conclude that the multilevel approach is more accurate than the MANOVA approach.

The model in Equation 5.7 is equivalent to a MANOVA model. Since the covariances between the occasions are estimated without restrictions, it does not assume compound symmetry. However, the fixed part is also fully saturated; it estimates the six means at the six measurement occasions. To model a linear trend over time, we must replace the fixed part of Equation 5.7 with the fixed part for the linear trend in Equation 5.5. This gives us the following model:

$$GPA_{it} = \beta_{00} + \beta_{10}T_{it} + u_{10i}O_{1i} + u_{20i}O_{2i} + u_{30i}O_{3i} + u_{40i}O_{4i} + u_{50i}O_{5i} + u_{60i}O_{6i} . \quad (5.8)$$

To specify the model in Equation 5.8 in standard multilevel software, we must specify an intercept term that has no second-level variance component and six dummy variables for the occasions that have no fixed coefficients. Some software has built-in facilities for modeling specific covariance structures over time. If there are no facilities for longitudinal modeling, the model in Equation 5.8 requires that the regression coefficients for the occasion dummies are restricted to zero, while their slopes are still allowed to vary across individuals. At the same time, an intercept and a linear time trend is added, which may not vary across individuals. The covariance matrix between the residual errors for the six occasions has no restrictions. If we impose the restriction that all variances are equal, and that all covariances are equal, we have again the compound symmetry model. This shows that the simple linear trend model in Equation 5.5 is one way to impose the compound symmetry structure on the random part of the model. Since the model in 5.5 is nested in the model in 5.7, we can use the overall chi-square test based on the deviance of the two models to test if the assumption of compound symmetry is tenable.

Models with a residual error structure over time as in the model in 5.6 are very complex, because they assume a saturated model for the error structure. If there are k measurement occasions, the number of elements in the covariance matrix for the occasions is $k(k + 1) / 2$. So, with six occasions, we have 21 elements to be estimated. If the assumption of compound symmetry is tenable, models based on this model (cf. Equation 5.5) are preferable, because they are more compact. Their random part requires only two elements (σ_e^2 and $\sigma_{u_0}^2$) to be estimated. The advantage is not only that smaller models are more parsimonious, but they are also easier to estimate. However, the compound symmetry model is very restrictive, because it assumes that there is one single value for all correlations between measurement occasions. This assumption is in many cases not very realistic, because the error term contains all omitted sources of variation (including measurement errors), which may be correlated over time. Different assumptions about the *autocorrelation* over time lead to different assumptions for the structure of the covariance matrix across the occasions. For instance, it is reasonable to assume that occasions that are close together in time have a higher correlation than occasions that are far apart. Accordingly, the elements in covariance matrix Σ should become smaller, the further away they are from the diagonal. Such a correlation structure is called a *simplex*. A more restricted version of the simplex is to assume that the autocorrelation between the occasions follow the model

$$e_t = \rho e_{t-1} + \varepsilon_t, \quad (5.9)$$

where e_t is the error term at occasion t , ρ is the autocorrelation, and ε_t is a residual error with variance σ_ε^2 . The error structure in Equation 5.9 is a first-order autoregressive process. This leads to a covariance matrix of the form:

$$\Sigma(Y) = \frac{\sigma_e^2}{(1-\rho^2)} \begin{pmatrix} 1 & \rho & \rho^2 & \cdots & \rho^{k-1} \\ \rho & 1 & \rho & \cdots & \rho^{k-2} \\ \rho^2 & \rho & 1 & \cdots & \rho^{k-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \rho^{k-1} & \rho^{k-2} & \rho^{k-3} & \cdots & 1 \end{pmatrix}. \quad (5.10)$$

The first term $\sigma_e^2 / (1-\rho^2)$ is a constant, and the autocorrelation coefficient ρ is between -1 and $+1$, but typically positive. It is possible to have second-order autoregressive processes, and other models for the error structure over time. The first-order autoregressive model that produces the simplex in Equation 5.10 estimates one variance plus an autocorrelation. This is just as parsimonious as the compound symmetry model, and it assumes constant variances but not constant covariances.

Another attractive and very general model for the covariances across time is to assume that each time lag has its own autocorrelation. So, all occasions that are separated by one measurement occasion share a specific autocorrelation, all occasions that are separated by two measurement occasions share a different autocorrelation, and so on. This leads to a banded covariance matrix for the occasions that is called a Toeplitz matrix:

$$\Sigma(Y)\sigma_e^2 \begin{pmatrix} 1 & \rho_1 & \rho_2 & \cdots & \rho_{k-1} \\ \rho_1 & 1 & \rho_1 & \cdots & \rho_{k-2} \\ \rho_2 & \rho_1 & 1 & \cdots & \rho_{k-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \rho_{k-1} & \rho_{k-2} & \rho_{k-3} & \cdots & 1 \end{pmatrix}. \quad (5.11)$$

The Toeplitz model poses $k-1$ unique autocorrelations. Typically, the autocorrelations with large lags are small, so they can be removed from the model.

It should be noted that allowing random slopes for the time trend variables (e.g., for the linear trend) also models a less restricted covariance matrix for the occasions. As a result, if the measurement occasion variable, or one of its polynomials, has a random slope, it is not possible to add a completely saturated MANOVA model for the covariances across measurement occasions, as in Equations 5.6 and 5.8. In fact, if we have k occasions, and use k polynomials with random slopes, we simply have used an alternative way to specify the saturated MANOVA model of Equation 5.6.

The implication is that the restrictive assumption of compound symmetry, which is implied in the straightforward multilevel analysis of repeated measures, is also diminished when random components are allowed for the trends over time. For instance, in a model with a randomly varying linear measurement occasion variable, the variance of any specific occasion at measurement occasion t is given by

$$\text{var}(Y_t) = \sigma_{u_0}^2 + \sigma_{u_{01}}(t-t_0) + \sigma_{u_1}^2(t-t_0) + \sigma_e^2, \quad (5.12)$$

and the covariance between any two specific occasions at measurement occasions t and s is given by

$$\text{cov}(Y_t, Y_s) = \sigma_{u_0}^2 + \sigma_{u_{01}} \left[(t - t_0) + (s - s_0) \right] + \sigma_{u_1}^2 (t - t_0)(s - s_0), \quad (5.13)$$

where s_0 and t_0 are the values on which the measurement occasions t and s are centered (if the measurement occasion variable is already centered, t_0 and s_0 may be omitted from the equation). Such models usually do not produce the simple structure of a simplex or other autoregressive model, but their random part can be more easily interpreted in terms of variations in developmental curves or growth trajectories. In contrast, complex random structures such as the autoregression or the Toeplitz are usually interpreted in terms of underlying but unknown disturbances.

The important point is that, in longitudinal data, there are many interesting models between the extremes of the very restricted compound symmetry model and the saturated MANOVA model. In general, if there are k measurement occasions, any model that estimates fewer than $k(k + 1) / 2$ (co)variances for the occasions represents a restriction on the saturated model. Thus, any such model can be tested against the saturated model using the chi-square deviance test. If the chi-square test is significant, there are correlations across occasions that are not modeled adequately. In general, if our interest is mostly on the regression coefficients in the fixed parts, the variances in the random part are not extremely important. A simulation study by Verbeke and Lesaffre (1997) shows that estimates of the fixed regression coefficients are not severely compromised when the random part is mildly misspecified.

Table 5.7 presents three different models using the GPA example data. The first model has a fixed slope for the measurement occasion. The second model has a random slope for the measurement occasion, and the third model has no random effects for the intercept or the measurement occasion, but models a saturated covariance matrix across the measurement occasions. For simplicity, the table only shows the variances at the six occasions, and not the covariances. Since the fixed part of the model remains unchanged, and the interest is only in modifications of the random part, REML (restricted maximum likelihood) estimation is used.

From a comparison of the deviances, it is clear that the saturated model fits better. The deviance difference test for the random coefficient model against the saturated model is significant ($\chi^2 = 180.1$, $df = 21$, $p < .001$), and the AIC and BIC are smaller. However, the random coefficient model estimates only four terms in the random part, and the saturated model estimates 21 terms. It would seem attractive to seek a more parsimonious model for the random part. We can also conclude that although the saturated model leads to slightly different estimates in the fixed part, the substantive conclusions are the same. Unless great precision is needed, we may decide to ignore the better fit of the saturated model, and present the model with the random slope for the measurement occasions instead.

Table 5.7 Results for Model 5 with different random parts

Model	Occasion fixed compound symmetry	Occasion random, compound symmetry	Occasion fixed, saturated
Fixed part			
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	2.64 (.10)	2.56 (.09)	2.50 (.09)
Occasion	0.10 (.004)	0.10 (.006)	0.10 (.004)
Job status	-0.17 (.02)	-0.13 (.02)	-0.10 (.01)
High GPA	0.08 (.03)	0.09 (.03)	0.08 (.03)
Gender	0.15 (.03)	0.12 (.03)	0.12 (.03)
Random part			
σ_e^2	0.05 (.002)	0.042 (.002)	
σ_{u0}^2	0.046 (.006)	0.039 (.006)	
σ_{u1}^2		0.004 (.001)	
σ_{u01}		-0.003 (.002)	
σ_{01}^2			0.090 (.009)
σ_{02}^2			0.103 (.010)
σ_{03}^2			0.110 (.011)
σ_{04}^2			0.108 (.011)
σ_{05}^2			0.104 (.011)
σ_{06}^2			0.117 (.012)
Deviance	314.8	201.9	21.8
AIC	318.8	209.9	63.8
BIC	329.0	230.3	170.6

5.7 STATISTICAL ISSUES IN LONGITUDINAL ANALYSIS

5.7.1 Investigating and Analyzing Patterns of Change

In the previous sections, polynomial curves were used to model the pattern of change over time. Polynomial curves are often used for estimating developmental curves. They are convenient, because they can be estimated using standard linear modeling procedures, and they are very flexible. If there are k measurement occasions, these can always be fitted exactly using a polynomial of degree $k - 1$. In general, in the interest of parsimony, a polynomial of a lower degree would be preferred. Another advantage of polynomial

approximation is that many inherently nonlinear functions can be approximated very well by a polynomial function. Nevertheless, modeling inherently nonlinear functions directly is sometimes preferable, because it may reflect some ‘true’ developmental process. For instance, Burchinal and Appelbaum (1991) consider the logistic growth curve and the exponential curve of special interest for developmental models. The logistic curve describes a developmental curve where the rate of development changes slowly in the beginning, accelerates in the middle, and slows again at the end. Burchinal and Appelbaum mention vocabulary growth in children as an example of logistic growth:

where children initially acquire new words slowly, beginning at about 1 year of age, then quickly increase the rate of acquisition until later in the preschool years when this rate begins to slow down again.

(Burchinal & Appelbaum, 1991, p. 29)

A logistic growth function is inherently nonlinear, because there is no transformation that makes it possible to model it as a linear model. It is harder to estimate than linear functions, because the solution must be found using iterative estimation methods. In multilevel modeling, this becomes even more difficult, because these iterations must be carried out nested within the normal iterations of the multilevel estimation method. Estimating the nonlinear function itself rather than a polynomial approximation is attractive from a theoretical point of view, because the estimated parameters have a direct interpretation in terms of the hypothesized growth process. An alternative is to use polynomial functions to approximate the true development function. Logistic and exponential functions can be well approximated by a cubic polynomial. However, the parameters of the polynomial model have no direct interpretation in terms of the growth process, and interpretation must be based on inspection of plots of the average or some typical individual growth curves. Burchinal and Appelbaum (1991) discuss these issues with examples from the field of child development. Since the available multilevel software does not support this kind of estimation, in practice polynomial approximations are commonly used.

A general problem with polynomial functions is that they often have very high correlations. The resulting collinearity problem may cause numerical problems in the estimation. If the occasions are evenly spaced and there are no missing data, transforming the polynomials to orthogonal polynomials offers a perfect solution. Tables for orthogonal polynomials are given in most handbooks on ANOVA procedures (e.g., Hays, 1994). Even if the data are not nicely balanced, using orthogonal polynomials usually reduces the collinearity problem. If the occasions are unevenly spaced, or we want to use continuous time measurements, it often helps to center the time measures in such a way that the zero point is well within the range of the observed data points. Appendix D in this book explains how to construct orthogonal polynomials for evenly spaced measurement occasions.

Although polynomial curves are very flexible, other ways of specifying the change over time may be preferable. Snijders and Bosker (2012) discuss the use of piecewise linear

functions and spline functions, which are functions that break up the development curve in different adjacent pieces, each with its own development model. Pan and Goldstein (1998) present an example of a multilevel analysis of repeated data using spline functions. Cudeck and Klebe (2002) discuss modeling developmental processes that involve phases. Using random coefficients, it is possible to model different transition ages for different subjects.

If there are k fixed occasions, and there is no hypothesis involving specific trends over time, we can model the differences between the occasions perfectly using $k - 1$ polynomial curves. However, in this case it is much more attractive to use simple dummy variables. The usual way to indicate k categories with dummy variables is to specify $k - 1$ dummy variables, with an arbitrary category as the reference category. In the case of fixed occasion data, it is often preferable to remove the intercept term from the regression, so all k dummy variables can be used to refer to the k occasions. This is taken up in more detail in Chapter 10.

5.7.2 Missing Data and Panel Dropout

An often-cited advantage of multilevel analysis of longitudinal data is the ability to handle missing data (Hedeker & Gibbons, 2006; Raudenbush & Bryk, 2002; Snijders, 1996). This includes the ability to handle models with varying measurement occasions. In a fixed occasions model, observations may be missing because at some measurement occasions respondents were not measured (occasional dropout or wave nonresponse) or subjects may cease to participate altogether (panel attrition or panel mortality) (de Leeuw, 2005). In MANOVA, the usual treatment of missing measurement occasions is to remove the case from the analysis, and analyze only the complete cases. Multilevel regression models do not assume equal numbers of observations, or fixed measurement occasions, so respondents with missing observations pose no special problems here, and all cases can remain in the analysis. This is an advantage because larger samples increase the precision of the estimates and the power of the statistical tests. However, this advantage of multilevel modeling does not extend to missing observations on the explanatory variables. If explanatory variables are missing, the usual treatment is again to remove the case completely from the analysis.

The capability to include incomplete cases in the analysis is a very important advantage. Little and Rubin (1987, 1989) distinguish between data that are missing completely at random (MCAR) and data that are missing at random (MAR). In both cases, the failure to observe a certain data point is assumed independent of the unobserved (missing) value. With MCAR data, the missingness must be completely independent of all other variables as well. With MAR data, the missingness may depend on other variables in the model, and through these be correlated with the unobserved values. For an accessible discussion of the differences between MAR and MCAR see McKnight, McKnight, Sidani and Figueredo (2007).

It is clear that MCAR is a much more restrictive assumption than MAR. In longitudinal research, a major problem is the occurrence of panel attrition: individuals who after one or more measurement occasions drop out of the study altogether. Panel attrition is generally not

random; some types of individuals are more prone to drop out than other individuals. In panel research, we typically have much information about the dropouts from earlier measurement occasions. In this case, it appears reasonable to assume that, conditional on these variables (which includes the score on the outcome variable on earlier occasions), the missingness is random (MAR). The complete cases method used in MANOVA assumes that data are missing completely at random (MCAR). Little (1995) shows that multilevel modeling of repeated measures with missing data assumes that the data are missing at random (MAR), provided that maximum likelihood estimation is used. Thus, MANOVA using listwise deletion leads to biased estimates when the missingness process is MAR, while multilevel analysis of data that are missing at random (MAR) leads to unbiased estimates.

Sometimes the issue arises what to do with cases that have many missing values. For example, assume we have an experiment with an experimental group and a control group and for these a pretest before the intervention, a posttest directly after the intervention, and a follow-up test three months after the intervention. Some participants drop out after the pretest, so for these we have only the pretest information. Do we keep these participants in the model? The answer is *yes*. One would definitively want to include the incomplete cases in the analysis, even these with only one measurement. Deleting these is a form of listwise deletion which assumes MCAR. Keeping all incomplete cases in a multilevel analysis of these data assumes MAR. The MAR assumption is justified here because if the incomplete cases have different means on the observed variables than the complete cases, the modeling process which is based on the pattern of (co)variances (in the multilevel case also at different levels) will correct for these differences. Obviously the individuals for which there is only one measurement will provide little information, but providing that information is crucial for the justification of the MAR assumption.

An example of the bias that can be the result of analyzing MAR incomplete data with a method that assumes MCAR is presented below. In the GPA data, a substantial fraction of subjects is assigned to a panel attrition process. This attrition process is not random: if the GPA at the previous measurement occasion is comparatively low, the probability of leaving the study is comparatively high. In the resulting data set, 55 percent of the students have complete data, and 45 percent have one or more missing values for the outcome variable GPA. Figure 5.8 illustrates the structure of the data file; for subjects with missing measurement occasions the data from the available occasions are retained in the data file, and the data from the missing occasions are left out. Subsequently, these data are analyzed employing the usual multilevel analysis methods.

Table 5.8 presents the means for the six consecutive GPA measures. The first row of numbers is the observed means in the complete data set. The second row is the observed means in the incomplete data set, as produced by MANOVA, using listwise deletion of incomplete cases. Compared to the complete data there is a clear upwards bias, especially in the last measurements. Using multilevel modeling results in less-biased estimates when the compound symmetry model is applied to the random part, and to perfect estimates (to two decimals) when

	student	sex	highgpa	admitted	occas	gpa	job
1	1	1	2.8	1	0	2.3	2
2	2	0	2.5	0	0	2.2	2
3	3	1	2.5	1	0	2.4	2
4	3	1	2.5	1	1	2.9	2
5	3	1	2.5	1	2	3.0	2
6	3	1	2.5	1	3	2.8	3
7	3	1	2.5	1	4	3.3	2
8	3	1	2.5	1	5	3.4	2
9	4	0	3.8	0	0	2.5	3
10	4	0	3.8	0	1	2.7	2
11	4	0	3.8	0	2	2.4	2
12	5	0	3.1	1	0	2.8	2
13	5	0	3.1	1	1	2.8	2
14	5	0	3.1	1	2	2.8	2
15	5	0	3.1	1	3	3.0	2
16	5	0	3.1	1	4	2.9	2
17	5	0	3.1	1	5	3.1	2

Figure 5.8 Example of a data set with panel attrition.

Table 5.8 Estimated means for complete and incomplete data, six occasions

GPA1	GPA2	GPA3	GPA4	GPA5	GPA6
Complete data					
2.59	2.72	2.81	2.92	3.02	3.13
Incomplete data, MANOVA (listwise $n = 109$)					
2.71	2.89	2.98	3.09	3.20	3.31
Incomplete data, multilevel model (compound symmetry)					
2.59	2.71	2.81	2.93	3.07	3.18
Incomplete data, multilevel model (saturated)					
2.59	2.72	2.81	2.92	3.02	3.13

the saturated model is applied to the random part. The difference between the outcomes of the two multilevel models emphasizes the importance of specifying a well-fitting model for the random part when there is panel attrition.

Hedeker and Gibbons (1997, 2006) present a more elaborate way to incorporate the missingness mechanism in the model. Using multilevel analysis for repeated measures, they first divide the data into groups according to their missingness pattern. Subsequently, variables that indicate these groups are included in the multilevel model as explanatory variables. The resulting *pattern mixture model* makes it possible to investigate if there is an effect of the different missing data patterns on the outcome, and to estimate an overall outcome across

the different missingness patterns. This is an example of an analysis that models a specific hypothesis about data that are assumed Missing Not At Random (MNAR).

5.7.3 Accelerated Designs

One obvious issue in longitudinal studies is that the data collection process takes a long time. Given that multilevel analysis of longitudinal data does not assume that all subjects are measured on the same occasions, it is possible to speed up the process. Different age cohorts of subjects are followed for a relatively short period of time, and then a curve is modeled across the entire age span in the data. This is called a cohort-sequential design, or an accelerated design. Figure 5.9 illustrates this design.

In the cohort-sequential design depicted in Figure 5.9, there are three age cohorts of children who at the beginning of the study are 6, 7 and 8 years old, respectively. The data collection takes two years, with data collected from the same children yearly. In the total sample, we have an age range of 6–10, and we can fit a growth curve across five years, although the actual data collection takes only two years. The reading skill data presented in the section on varying occasions is another example of accelerated design. Although the data collection used six years, the age range in the sample is 6–14 years.

In an accelerated design, the growth curve is estimated on a combination of cross-sectional and longitudinal information. Obviously, this assumes that the different cohorts are comparable, for example that in Figure 5.9 the 8-year-olds in cohort 1 are comparable to the 8-year-olds in cohort 3, who are in fact two years older than the children in cohort 1 and measured at a different measurement occasion. If the data collection contains a sufficient number of measurement occasions, this assumption can be tested, for example by fitting three separate linear growth curves and testing if these are equal in the three cohorts. Duncan, Duncan & Strycker (2006) provide a discussion of cohort-sequential designs and their analysis in the context of latent curve modeling, and Raudenbush and Chan (1993) discuss the analysis of cohort-sequential designs using multilevel regression models more closely. Miyazaki and Raudenbush (2000) discuss tests for age×cohort interactions in accelerated designs. Moerbeek (2011) studies power issues in accelerated designs.

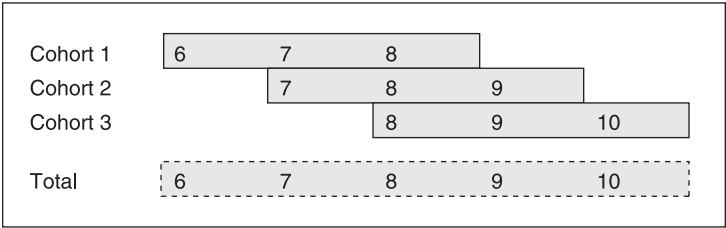


Figure 5.9 Example of an accelerated design.

5.7.4 The Metric of Time

In Section 5.2 the measurement occasions are numbered 0, ..., 5 to ensure that the intercept represents the starting point of the data collection. In Section 5.3 on varying occasions, there are four measurement occasions, but instead of 0, ..., 3 the real ages of the children at these occasions are used, transformed so that the youngest recorded age (six years) equals zero. This difference points toward a larger issue: what is the correct metric of time? Developmental models, for example growth curve models, are modeling a growth process that occurs in real time. The goal of such models is to estimate the overall growth pattern, and individual deviations from that pattern in the form of individual growth curves. Simply counting and indexing measurement occasions does not address these goals, using age-based models does. As discussed in the previous section on accelerated designs, age-based modeling is not unproblematic if subjects differ in age at the beginning of the data collection. On the one hand, this offers the means to analyze a wider age range than the number of years the data collection lasts, but on the other hand we must assume that there are no cohort effects. Especially when the initial age range is large, and the data collection period is short with respect to this age range, cohort effects can lead to misleading results. If there are cohort effects, it may be better to analyze the data ordered by data collection occasion, with differences in age at the first measurement occasion as predictors. A careful check of the assumption that there are no cohort effects is important in such cases.

Setting the first measurement occasion to zero, or using a transformed age measure as the measure of time, is not necessarily optimal. In the reading skill example in Section 5.3, the age is transformed by subtracting six. This is reasonable; most children have some reading ability at that age. Using raw age is not reasonable, because in this metric the intercept represents reading skill at age zero and the second-level variance represents the variation in reading skill at age zero. These estimates are clearly meaningless. A similar example is the multilevel model for the development of speech in young children in Raudenbush and Bryk (2002). Here the age is given in months, and Raudenbush and Bryk subtract 12 because the average child starts to use words at about 12 months of age. Deciding on the metric of time is not only a statistical problem; it is strongly connected to the topic of study. The major substantive problem is to establish a metric of time that fits the process. For example, in a study on the importance of a major life event, such as marriage or divorce, birth or death of a relative, the time of this event is often set to zero. This assumes that the event can be considered the start of the process that is examined. If the initial point is an event, age is often added as a subject-level variable. This assumes that the curve after the event may differ for different age cohorts. Again, deciding on the metric of time is a substantive and theoretical issue, which cannot be settled by statistical reasoning alone. We refer to Hoffman (2015) for an extended discussion of the metric of time.

To give an example of the importance of the metric of time, Table 5.9 presents the estimates of three models for the Curran reading data. Model 1 is the intercept-only model,

Table 5.9 Reading skill data comparing measurement occasion and real age as predictors

	Intercept only	Occasion predictor	Child age predictor
Intercept	4.11 (.05)	2.70 (.05)	2.16 (.04)
Occasion		1.10 (.02)	
Child age			0.56 (.01)
σ_e^2	2.39	0.46	0.46
σ_{u0}^2	0.30	0.78	0.65
Deviance	5055.9	3487.6	3426.0
AIC	5059.9	3491.6	3430.0
BIC	5070.3	3501.9	3440.3

which serves as the baseline model. Model 2 includes the measurement occasion as fixed predictor, and Model 3 includes the real age (6 years = 0) as fixed predictor.

The two models with occasion or age as predictor cannot be compared using the deviance difference test, since they are not nested. On the AIC and BIC criteria, the model with child age as predictor is clearly better. Age as predictor also predicts more variance. In both models we observe the familiar problem of explaining negative variance at the child level. If we simply compare the total unexplained variances, we have a total variance of (2.39 + 0.30 =) 2.69 in the intercept-only model, (0.46 + 0.78 =) 1.24 with occasion as predictor, and (0.46 + 0.65 =) 1.11 with child age as predictor. So the total explained variance with occasion is 53.9 percent and with child age it is 058.7 percent

5.7.5 Persons as Contexts

The GPA example presented above includes a time varying variable *job status* that explains both occasion-level variance and between students variance. Since there is only one regression coefficient estimated for this predictor, the model assumes that the regression coefficients within persons and between persons are the same. If this is not the case, the regression coefficient for this predictor becomes some weighted combination of the two regression coefficients, and its actual value is difficult to interpret.

To model the within person (occasion-level) and between persons (student-level) separately, we decompose the job status variable into the time invariant person mean score, and into the time varying deviation from the person mean score. This separates the two effects completely: the two new variables have a correlation of zero. The within-person component contains only the variation over time around each student’s typical value, and the between-person component contains only student-level variation. Since these components are defined at different levels, they can be included in the model simultaneously to assess

the occasion-level and student-level effects of job status. This decomposition is the same as the analysis of contextual effects in subjects within groups, by computing group means and deviations from the group means. Here, the persons are the contexts. We refer to Chapter 4 for a discussion of grand mean and group mean centering, and to Hoffman (2015) for a discussion of different centering methods in the context of longitudinal analysis.

5.8 SOFTWARE

The models that include complex covariance structures require multilevel software that allows restrictions on the random and fixed part. Some programs (HLM, SuperMix, PRELIS, and the general packages SAS, SPSS and STATA) recognize the structure of longitudinal data, and allow direct specification of various types of autocorrelation structures. For a discussion of some of these structures in the context of multilevel longitudinal models see Hedeker and Gibbons (2006). If there are many different and differently spaced occasions, MANOVA and related models become impractical. With varying occasions, it is still possible to specify an autocorrelation structure, but it is more difficult to interpret than with fixed occasions. The program MLwiN can model very general autocorrelation structures using macros available from the Multilevel Modelling Project at the University of Bristol. Examples of such analyses are given by Goldstein, Healy and Rasbash (1994) and Barbosa and Goldstein (2000). It should be noted that many of these programs, when the time structure is generated automatically, number the occasions starting at one. Since this makes ‘zero’ a non-existent value for the measurement occasion variable, this is an unfortunate choice. If this happens, software users should override it with a choice that makes better sense given their substantive question.

NOTES

- 1 The importance of centering explanatory variables on their overall mean or a similar value is discussed in Chapter 4.
- 2 The point on the t scale where the correlation flips from negative to positive is $t^* = t_0 - (u_{01}/u_{11})$, where t_0 is the current zero-point on the time axis. This is also the point where the intercept variance is the lowest (Mehta & West, 2000).
- 3 In large data sets this display will be confusing, and it is better to present a plot of a random or selected subsample of the individuals.

6

The Multilevel Generalized Linear Model for Dichotomous Data and Proportions

SUMMARY

The models discussed so far assume a continuous dependent variable and a normal error distribution. If the dependent variable is a scale in which the responses to a large number of questions are summated to one score, the data often approximate normality. However, there are situations in which the assumption of normality is always violated. For instance, in cases where the dependent variable is a single dichotomous variable, both the assumption of continuous scores and the normality assumption are obviously violated. If the dependent variable is a proportion, the problems are less severe, but the assumptions of continuous scores and normality are still violated. Also, in both cases, the assumption of homoscedastic errors is violated. This chapter treats multilevel regression models for these kinds of data.

6.1 GENERALIZED LINEAR MODELS

The classical approach to the problem of nonnormally distributed variables and heteroscedastic errors is to apply a transformation to achieve normality and reduce the heteroscedasticity, followed by a straightforward analysis with ANOVA or multiple regression. To distinguish this approach from the generalized linear modeling approach explained later in this chapter, where the transformation is part of the statistical model, it is often referred to as an empirical transformation. Some general guidelines for choosing a suitable transformation have been suggested for situations in which a specific transformation is often successful (e.g., Mosteller & Tukey, 1977). For instance, for the proportion p some recommended transformations are: the arcsin transformation $f(p) = 2\arcsin(\sqrt{p})$, the logit transformation $f(p) = \text{logit}(p) = \ln(p/(1-p))$, where 'ln' is the natural logarithm, and the probit or inverse normal transformation $f(p) = \Phi^{-1}(p)$, where Φ^{-1} is the inverse of the standard normal distribution. Thus, for proportions, we can use the logit transformation, and use standard regression procedures on the transformed variable:

$$\text{logit}(p) = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + e.$$

When the dependent variable is a frequency count of events with a small probability, such as the number of errors made in a school essay, the data tend to follow a Poisson distribution, which can often be normalized by taking the square root of the scores: $f(x) = \sqrt{x}$. When the data are highly skewed, which is usually the case if, for instance, reaction time is the dependent variable, a logarithmic transformation is often used: $f(x) = \ln(x)$, or the reciprocal transformation: $f(x) = 1/x$. For reaction times the reciprocal transformation has the nice property that it transforms a variable with an obvious interpretation (reaction time) into another variable with an equally obvious interpretation (reaction speed).

Empirical transformations have the disadvantage that they are ad hoc, and may encounter problems in specific situations. For instance, if we model dichotomous data, which are simply the observed proportions in a sample of size one, both the logistic and the probit transformations break down, because these functions are not defined for values 0 and 1. In fact, *no* empirical transformation can ever transform a dichotomous variable, which takes on only two values, into any resemblance of a normal distribution.

The modern approach to the problem of nonnormally distributed variables is to include the necessary transformation and the choice of the appropriate error distribution (not necessarily a normal distribution) explicitly in the statistical model. This class of statistical models is called *generalized linear models* (Gill, 2000; McCullagh & Nelder, 1989). Generalized linear models are defined by three components:

- 1 an outcome variable y with a specific error distribution that has mean μ and variance σ^2 ,
- 2 a linear additive regression equation that produces an unobserved (latent) predictor η of the outcome variable y ,
- 3 a *link function* that links the expected values of the outcome variable y to the predicted values for η : $\eta = f(\mu)$.

(McCullagh & Nelder, 1989, p. 27)

If the link function is the identity function ($f(x) = x$) and the error distribution is normal, the generalized linear model simplifies to standard multiple regression analysis. This means that the familiar multiple regression model can be expressed as a special case of the generalized linear model by stating that:

- 1 the probability distribution is Normal with mean μ and variance σ^2 , usually formulated as $y \sim N(\mu, \sigma^2)$,
- 2 the linear predictor is the multiple regression equation for η , e.g., $\eta = \beta_0 + \beta_1 X_1 + \beta_2 X_2$,
- 3 the link function is the identity function given by $\eta = \mu$.

The generalized linear model separates the error distribution from the link function. As a result, generalized linear models make it possible to extend standard regression models

in two different ways: by choosing a non-normal error distribution and by using nonlinear link functions. This is nearly the same as carrying out an empirical transformation on the response variable. However, if we carry out a standard regression analysis after transforming the outcome variable, we automatically assume that the error distribution is normal on the transformed scale. But the error distribution may not be simple, or the variance may depend on the mean, which introduces heteroscedasticity. Generalized linear models can deal with such situations. For instance, a commonly used generalized linear model for dichotomous data is the logistic regression model specified by:

- 1 the probability distribution is binomial (μ) with mean μ ,
- 2 the linear predictor is the multiple regression equation for η , e.g., $\eta = \beta_0 + \beta_1 X_1 + \beta_2 X_2$,
- 3 the link function is the logit function given by $\eta = \text{logit}(\mu)$.

Note that this specification does not include a term for the variance of the error distribution. In the binomial distribution, the variance is a function of the mean, and it cannot be estimated separately.

The estimation method in generalized linear models is a maximum likelihood procedure that uses the inverse of the link function to predict the response variable. The inverse function for the logit used above for binomial data is the logistic transformation given by $g(x) = e^x / (1 + e^x)$. The corresponding regression model is usually written as:

$$y = \frac{e^{(\beta_0 + \beta_1 X_1 + \beta_2 X_2)}}{1 + e^{(\beta_0 + \beta_1 X_1 + \beta_2 X_2)}}.$$

This regression equation is sometimes written as $y = \text{logistic}(\beta_0 + \beta_1 X_1 + \beta_2 X_2)$. This looks simpler, but does not show that the outcome has a binomial distribution. In reporting the results of an analysis with a generalized linear model, it is usual to list the three components of the generalized linear model explicitly. Using the regression equation $y = \text{logistic}(\beta_0 + \beta_1 X_1 + \beta_2 X_2)$ for estimation makes clear why modeling dichotomous data now works. Generalized linear modeling does not attempt to apply a logit transformation to the observed values 0 and 1, which is impossible, but applies the inverse logistic transformation to the predicted values, which does work.

In principle, many different error distributions can be used with any link function. Many distributions have a specific link function for which sufficient statistics exist, which is called the *canonical link* function. Table 6.1 presents some commonly used canonical link functions and the corresponding error distribution.

The canonical link has some desirable statistical properties, and McCullagh and Nelder (1989, Chapter 2) express a mild preference for using canonical links. However, there is no compelling reason to confine oneself to canonical link functions. Other link functions may even be better in some circumstances. For instance, although the logit link function is an appropriate choice for proportions and dichotomous data, we have the choice to specify other

Table 6.1 Some canonical link functions and corresponding error distributions

Response	Link function	Name	Distribution
Continuous	$\eta=\mu$	identity	normal
Proportion	$\eta=\ln(\mu/(1-\mu))$	logit	binomial
Count	$\eta=\ln(\mu)$	log	Poisson
Positive	$\eta=\mu^{-1}$	inverse	gamma

functions, such as the probit or the (complementary) log-log-function. Usually, when a link function is used, the transformation extends over the entire real line from minus to plus infinity, so there are no constraints on the values predicted by the linear regression equation. The link function is often the inverse of the error distribution, so we have the logit link for the logistic distribution, the probit link for the normal distribution, and the complementary log-log link for the extreme value (Weibull) distribution. For a discussion of error distributions and link functions in generalized linear models we refer to McCullagh and Nelder (1989).

Figure 6.1 shows the relation between the values of the proportion p and the transformed values using either a logit or a probit transformation. The left shows a plot of the standard normal and logit transformation against the proportion p . It shows that the logit and probit transformation have a similar shape, but the standard logit transformation results in a larger spread. The right shows a plot where the logit transformation is standardized to have a variance of one. It is clear from the right side of Figure 6.1 that the logit and the probit are extremely similar.

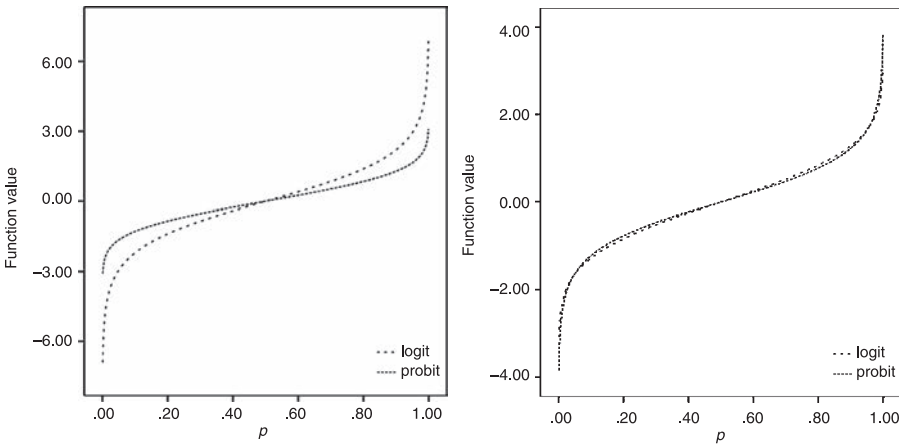


Figure 6.1 Plot of logit and probit transformed proportions.

Compared to the probit, the logit transformation has a higher peak and heavier tails, and spreads the proportions close to 0.00 or 1.00 over somewhat wider range of the transformed scale. The main point of Figure 6.1 is that the differences are extremely small. Therefore, logistic and probit regression produce results that are very similar. Logistic models are more commonly used than probit models, because the exponentiated logistic coefficients can be interpreted directly as odds ratios. Other transformations, such as the log-log transformation, which is given by $f(p) = -\log(-\log(p))$, and the complementary log-log transformation, which is given by $f(p) = \log(-\log(1-p))$, are sometimes used as well. These functions are asymmetric. For instance, if the proportions are larger than 0.5, the log-log function behaves much like the logit, while for proportions smaller than 0.5, it behaves more like the probit. The complementary log-log function behaves in the opposite way. McCullagh & Nelder (1989) discuss a broad range of link functions and error distributions for various modeling problems. McCullagh and Nelder (1989, pp. 108–110) express a mild preference for the canonical logit link function. Agresti (1984) discusses substantive reasons for preferring specific link functions and distributions.

Since the standard logit distribution has a standard deviation of $\sqrt{\pi^2/3} \approx 1.8$, and the standard normal distribution has a standard deviation of 1, the regression slopes in a probit model are generally close to the regression slopes in the corresponding logit model divided by 1.8 (Gelman & Hill, 2007). Since the standard errors are on the same probit or logit scale, the p -values for the significance tests of the probit and logit regression slopes are also very similar. In many cases, the choice for a specific transformation is in practice not important. When the modeled proportions are all between 0.1 and 0.9, the differences between the logit and the probit link functions are negligible. One would need many observations with proportions close to zero or one to detect a difference between these models.

6.2 MULTILEVEL GENERALIZED LINEAR MODELS

Goldstein (1991, 2011) and Raudenbush and Bryk (2002) describe the multilevel extension of generalized linear models. In generalized linear multilevel models, the multilevel structure appears in the linear regression equation of the generalized linear model. Thus, a two-level model for proportions is written as follows (cf. Equation 2.5):

- 1 the probability distribution for π_{ij} is binomial (μ_{ij}, n_{ij}) with overall mean μ ,
- 2 the linear predictor is the multilevel regression equation for η , e.g., $\eta_{ij} = \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{1j}X_{ij} + u_{0j}$,
- 3 the link function is the logit function given by $\eta = \text{logit}(\mu)$.

These equations state that our outcome variable is a proportion π_{ij} , that we use a logit link function, and that conditional on the predictor variables, we assume that π_{ij} has a binomial error distribution, with expected value μ_{ij} , and number of trials n_{ij} . If there is only one trial (all n_{ij} are equal to one), the only possible outcomes are 0 and 1, and we are modeling

dichotomous data. This specific case of the binomial distribution is called the *Bernoulli* distribution. Note that the usual lowest-level residual variance e_{ij} is not in the model equation, because it is part of the specification of the error distribution. If the error distribution is binomial, the variance is a function of the number of trials n_{ij} and the population proportion π_{ij} : $\sigma^2 = n \times \pi_{ij} \times (1 - \pi_{ij})$ and it does not have to be estimated separately. Some software allows the estimation of a scale factor for the lowest-level variance. If the scale factor is set to one, the assumption is made that the observed errors follow the theoretical binomial error distribution exactly. If the scale factor is significantly higher or lower than one, there is *overdispersion* or *underdispersion*. Under- and overdispersion can only be estimated if the number of trials is larger than one; in a Bernoulli distribution overdispersion cannot be estimated (McCullagh & Nelder, 1989, p. 125; Skrondal & Rabe-Hesketh, 2004, p. 127). The presence of underdispersion often indicates a misspecification of the model, such as the omission of large interaction effects. Overdispersion can occur if we omit important random effects or even an entire level in a multilevel model. Very small group sizes (around three or less) also lead to overdispersion (Wright, 1997).

When overdispersion or underdispersion is present, standard errors need to be adjusted (Gelman & Hill, 2007, p. 115). The inclusion of a scale factor for under- or overdispersion improves the model fit, and corrects the standard errors. Although this takes care of the problem, it does not identify the cause of the misfit. If the scale factor is very different from one, it is good practice to examine the problem, and to attempt to deal with it in a more explicit manner by modifying the model.

6.2.1 Estimation in Generalized Multilevel Models

The parameters of generalized linear models are estimated using maximum likelihood methods. Multilevel models are also generally estimated using maximum likelihood methods, and combining multilevel and generalized linear models leads to complex models and estimation procedures. Although implementation details in specific software vary, there are two different approaches to estimation: quasi-likelihood and numerical integration. Both approaches are described below.

The quasi-likelihood approach, implemented for example in MLwiN, HLM, and SPSS, is to approximate the nonlinear link by a nearly linear function, and to embed the multilevel estimation for that function in the generalized linear model. This approach is a quasi-likelihood approach, and it confronts us with two choices that must be made. The nonlinear function is linearized using an approximation known as Taylor series expansion. Taylor series expansion approximates a nonlinear function by an infinite series of terms. Often only the first term of the series is used, which is referred to as a first-order Taylor approximation. When the second term is also used, we have a second-order Taylor approximation, which is generally more accurate. So the first choice is whether to use a first-order or a second-order approximation. The second choice also involves the Taylor series expansion. Taylor

series linearization of a nonlinear function depends on the values of its parameters. And this presents us with the second choice: the Taylor series expansion can use the current estimated values of the fixed part only, which is referred to as marginal quasi-likelihood (MQL), or it can be improved by using the current values of the fixed part plus the residuals, which is referred to as penalized quasi-likelihood (PQL).

The quasi-likelihood estimation procedure in multilevel modeling proceeds iteratively, starting with approximate parameter values, which are improved in each successive iteration. Thus, the estimated parameter values change during the iterations. In consequence, the Taylor series expansion must be repeated after each run of the multilevel estimation procedure, using the current estimated values of the multilevel model parameters. This results in two sets of iterations. One set of iterations is the standard iterations carried out on the linearized outcomes, estimating the parameters (coefficients and variances) of the multilevel model. In HLM, these are called the micro-iterations (Raudenbush et al., 2004). The second set of iterations uses the currently converged estimates from the micro iterations to improve the Taylor series approximation. After each update of the linearized outcomes, the micro iterations are performed again. The successive improvements of the Taylor series approximation are called the macro iterations (Raudenbush et al., 2011). Thus, in the quasi-likelihood approach based on Taylor series approximation, there are two sets of iterations to check for convergence problems.

Estimation procedures for generalized multilevel models that are based on Taylor series expansion are discussed by Goldstein (2011), including procedures to model extra variation at the lowest level. In simulated data sets with a dichotomous response variable, Rodriguez and Goldman (1995) show that if the groups at the lowest level are small and the random effects are large, both the fixed and the random effects are severely underestimated by the first order MQL method. Goldstein and Rasbash (1996) demonstrate that using PQL and second-order estimates in such situations leads to much better estimates. Even with second-order expansion and PQL, the parameter estimates are still too small. Browne (1998) has repeated their analysis, using a much larger simulation setup. The amount of bias in the Taylor expansion approach can be judged from Table 6.2, which summarizes some of Browne’s findings.

Table 6.2 Simulation comparing MQL and PQL (Browne, 1998)

True value	MQL–1 estimates	PQL–2 estimates
$\beta_0=0.65$	0.47	0.61
$\beta_1=1.00$	0.74	0.95
$\beta_2=1.00$	0.75	0.96
$\beta_3=1.00$	0.73	0.94
$\sigma_e^2=1.00$	0.55	0.89
$\sigma_u^2=1.00$	0.03	0.57

From the results in Table 6.2, first-order MQL estimation appears almost worthless, especially regarding the second-level variance estimate. However, Goldstein and Rasbash (1996) point out that the data structure of this specific simulation is extreme, because there are very large variances in combination with very small groups. In less extreme data sets, the bias is much smaller, and then even first-order MQL produces acceptable estimates. Goldstein (1995) also mentions that using second-order PQL may encounter estimation problems. Moerbeek, van Breukelen and Berger (2003a) advise using second-order PQL for testing treatment effects in cluster randomized trials and multisite trials. This explains the choice problem. If second-order estimation and penalized quasi-likelihood are always better, then why not always use these? The reason is that complex models or small data sets may pose convergence problems, and we may be forced to use first-order MQL. Goldstein and Rasbash (1996) suggest using bootstrap methods to improve the quasi-likelihood estimates, and Browne (1998) explores bootstrap and Bayesian methods. These approaches will be treated extensively in Chapter 13. Jang and Lim (2009) show that the biases of PQL estimates of the variance components are systematically related to the biases in the PQL estimates of the regression coefficients. They also show that the biases of the PQL variance component estimates increase as the random effects become more heterogeneous. Rodriguez and Goldman (2001) compare MQL and PQL to an exact estimation approach, bootstrapping and Bayesian methods. They conclude that PQL is a considerable improvement on MQL, and that bootstrapping or Bayesian methods can further reduce the bias. However, these methods are computationally intensive, and they recommend continued use of PQL for exploratory purposes.

It is important to note that the Taylor series approach is a quasi-likelihood method. Since the likelihood that is maximized is an approximate likelihood function instead of the exact likelihood, the test statistics based on comparing the deviances of different models (which are minus two times the log likelihood) are not very accurate. The AIC and BIC indices are also based on the likelihood, and should also not be used. For testing parameter estimates when Taylor series linearization is used, the Wald test or procedures based on bootstrap or Bayesian methods are preferred.

The numerical integration approach does not use an approximate likelihood, but uses numerical integration of the exact likelihood function. Numerical integration maximizes the correct likelihood (Schall, 1991; Wolfinger, 1993). The estimation methods involve the numerical integration of a complex likelihood function, which becomes more complicated as the number of random effects increases. The actual calculations involve quadrature points, and the numerical approximation becomes better when the number of quadrature points in the numerical integration is increased. Unfortunately, increasing the number of quadrature points also increases the computing time, sometimes dramatically. Most software uses by default adaptive quadrature, which means that the user provided or default number of quadrature points are not spaced evenly, but their spacing is adapted to the shape of the likelihood function to improve estimation.

When full maximum likelihood estimation with numerical integration is used, the test procedures and goodness of fit indices based on the deviance are appropriate. Simulation research (Hartford & Davidian, 2000; Rodriguez & Goldman, 2001; Diaz, 2007) suggests that when both approaches are feasible, the numerical integration method achieves more precise estimates. Agresti, Booth, Hobert and Caffo (2000) also recommend using numerical integration rather than Taylor expansion when it is available.

Just like second-order PQL estimation, however, the numerical integration method may encounter convergence problems with certain data (Lesaffre & Spiessens, 2001). Convergence is improved when the explanatory variables have approximately the same range, and when predictor variables with a random slope are centered. If numerical integration is used, it helps if the user supplies good starting values, and it is recommended to check carefully if the algorithm has indeed converged (Lesaffre & Spiessens, 2001). A good check is to increase the number of integration points from its default value (which is often fairly low). If the estimates change when the number of quadrature points is increased, the smaller number was clearly not sufficient, and a new estimation run with a still larger number of quadrature points is needed to check whether the larger number was sufficient.

6.3 EXAMPLE: ANALYZING DICHOTOMOUS DATA

The program HLM (Raudenbush et al., 2011) includes an example data file with a dichotomous outcome variable. These ‘Thailand education data’ stem from a national survey of primary education in Thailand (Raudenbush & Bhumirat, 1992, cf. Raudenbush et al., 2004, p. 115). The outcome variable ‘repeat’ is a dichotomous variable indicating whether a pupil has repeated a grade during primary education. In this example, we use child gender (0 = female, 1 = male), having had preschool education (0 = no, 1 = yes) as predictor variable at the child level, and school mean SES as predictor variable at the school level. As outlined in the previous section, the generalized linear model has three distinct components: (1) a specific error distribution, (2) a linear regression equation, and (3) a link function. The customary link function for binomial data is the *logit* function: $\text{logit}(p) = \ln(p / (1 - p))$. The corresponding canonical error distribution is the binomial distribution. Following the logic of the generalized linear model, we write:

$$\text{Repeat}_{ij} = \pi_{ij} ; \pi \sim \text{Binomial}(\mu) \quad (6.1)$$

$$\pi_{ij} = \text{logistic}(\eta_{ij}) \quad (6.2)$$

$$\eta_{ij} = \gamma_{00} + \gamma_{10} \text{Sex}_{ij} + \text{Preschool Educ}_{ij} + \text{MeanSes}_j + u_{0j} \quad (6.3)$$

Or, more concisely

$$\pi_{ij} = \text{logistic} (\gamma_{00} + \gamma_{10} \text{Sex}_{ij} + \text{Preschool Educ}_{ij} + \text{MeanSes}_j + u_{0j}). \quad (6.4)$$

Equations 6.1 to 6.3 and Equation 6.4 describe a generalized linear model with an outcome *repeat*, which is assumed to have a binomial distribution with mean μ . Since the number of trials equals 1 in all cases, we have a dichotomous outcome variable and a Bernoulli distribution. We use a logit link function, which implies that the mean μ of this distribution is predicted using a logistic regression model. In our case, this logistic regression model includes a pupil-level variable *pupil gender* and a school-level residual variance term u_{0j} . The parameters of this model can be estimated using the quasi-likelihood procedure involving the Taylor series expansion approach outlined above, or using the full maximum likelihood procedure with numerical integration of the likelihood function. Table 6.3 presents the results of both approaches.

As Table 6.3 shows, the different methods produce estimates that are certainly not identical. First order MQL appears to underestimate both the frequency of repeats and the effect of being a male pupil, while second-order PQL estimation and the numerical estimation methods in HLM and SuperMix produce regression coefficients that are very similar. The estimates of the second-level variance are also quite different. First-order MQL appears to underestimate the second-level variance, while the second-order PQL and numerical integration estimates are closer. The Laplace method used in HLM improves only the estimates for the regression coefficients; the variances are still based on Taylor series expansion. Numerical integration of the exact likelihood produces the largest estimate for the school-level variance. Given the known tendency for the quasi-likelihood approach to underestimate regression coefficients and variance components, we assume that the full maximum likelihood estimates using numerical integration, which are presented in the last column in Table 6.3, are the most accurate.

Table 6.3 Thai educational data: predicting repeating a grade

Model	First-order MQL ^a	Secnd-order PQL ^a	Laplace ML ^b	Numerical ^c
Predictor	coefficient (s.e.)	coefficient (s.e.)	coefficient (s.e.)	coefficient (s.e.)
Intercept	−1.75 (.09)	−2.20 (.10)	−2.24 (.10)	−2.24 (.11)
Pupil gender	0.45 (.07)	0.53 (.08)	0.53 (.07)	0.54 (.08)
Preschool education	−0.54 (.09)	−0.63 (.10)	−0.63 (.10)	−0.63 (.10)
Mean SES school	−0.28 (.18)	−0.29 (.22)	−0.30 (.20)	−0.30 (.22)
σ^2_{u0}	1.16 (.12)	1.58 (.18)	1.28 (.22)	1.69 (.22)

a Using MLwiN

b Using HLM

c Using SuperMix

The data analyzed are dichotomous. They can also be aggregated to groups of male and female students in different schools. In that case the outcome variable is aggregated to a proportion. If the same analysis is carried out on these proportions, we get effectively the same results. Since the data file has become smaller, the analysis proceeds a little faster.

It is important to understand that the interpretation of the regression parameters reported in Table 6.3 is *not* in terms of the dichotomous outcome variable *repeat*. Instead, it is in terms of the underlying variate η defined by the logit transformation $\eta = \text{logit}(p) = \ln(p / (1 - p))$. The predicted values for η are on a scale that ranges from $-\infty$ to $+\infty$. The logistic function transforms these predictions into values between 0 and 1, which can be interpreted as the predicted probability that an individual pupil has repeated a class. For a quick examination of the analysis results we can simply inspect the regression parameters as calculated by the program. To understand the implications of the regression coefficients for the proportions we are modeling, it is helpful to transform the predicted logit values back to the proportion scale. For example, the results in the last column of Table 6.3 show that boys repeat grades more often than girls. But, what do the intercept of -2.24 and the regression slope of 0.54 actually mean? They predict a repeat score of -2.24 for the girls (coded zero) and $(-2.24 + 0.54) = -1.70$ for the boys. This is on the underlying continuous scale. Applying the logistic transformation $e^\eta / (1 + e^\eta)$ to these estimates produces an estimated repeat rate of 9.6 percent for the girls and 15.4 percent for the boys. These values are conditional on the other variables in the model (the predictors preschool education and school mean SES), so for these values to have meaning it is important to (grand mean) center these variables (as we did).

6.4 EXAMPLE: ANALYZING PROPORTIONS

The second example uses data from a meta-analysis of studies that compared face-to-face, telephone, and mail surveys on various indicators of data quality (de Leeuw, 1992; for a more thorough analysis see Hox & de Leeuw, 1994). One of these indicators is the response rate; the number of completed interviews divided by the total number of eligible sample units. Overall, the response rates differ between the three data collection methods. In addition, the response rates differ also across studies. This makes it interesting to analyze what study characteristics account for these differences.

The data of this meta-analysis have a multilevel structure. The lowest level is the 'condition level', and the higher level is the 'study level'. There are three variables at the condition level: the proportion of completed interviews in that specific condition, the number of potential respondents who are approached in that condition and a categorical variable indicating the data collection method used. The categorical data collection variable has three categories: 'face-to-face', 'telephone' and 'mail' survey. To use it in the regression equation, it is recoded into two dummy variables: a 'telephone dummy' and a 'mail dummy'. In the mail survey condition, the mail dummy equals one, and in the other two conditions it equals zero. In the telephone survey condition, the telephone dummy equals one, and in the other two conditions it equals

zero. The face-to-face survey condition is the reference category, indicated by a zero for both the telephone and the mail dummy. There are three variables at the study level: the year of publication (0 = 1947, the oldest study), the saliency of the questionnaire topic (0 = not salient, 2 = highly salient), and the way the response has been calculated. If the response is calculated by dividing the response by the total sample size, we have the completion rate. If the response rate is calculated by dividing by the sample size corrected for sampling frame errors, we have the response rate. Most studies compared only two of the three data collection methods; a few compared all three. Omitting studies with missing values, there are 47 studies, in which a total of 105 data collection methods are compared. The data set is described in Appendix E.

The dependent variable is the response. This variable is a proportion: the number of completed interviews divided by the number of potential respondents. If we had the original data sets at the individual respondent level, we would analyze them as dichotomous data, using full maximum likelihood analysis with numerical integration. However, the studies in the meta-analysis report the aggregated results, and we have only proportions to work with. If we would model these proportions directly by normal regression methods, we would encounter two critical problems. The first problem is that proportions do not have a normal distribution, but a binomial distribution, which (especially with extreme proportions and/or small samples) invalidates several assumptions of the normal regression method. The second problem is that a normal regression equation might easily predict values larger than 1 or smaller than 0 for the response, which are impossible values for proportions. Using the generalized linear (regression) model for the proportion p of potential respondents that are responding to a survey solves both problems, which makes it an appropriate model for these data.

The hierarchical generalized linear model for our response data can be described as follows. In each condition i of study j we have a number of individuals who may or may not respond. Each condition i of study j is viewed as a draw from a specific binomial distribution. So, for each individual r in each condition i of study j the probability of responding is the same, and the proportion of respondents in condition i of study j is π_{ij} . Note that we could have a model where each individual's probability of responding varies, with individual level covariates to model this variation. Then, we would model this as a three-level model, with binary outcomes at the lowest (individual) level. Since in this meta-analysis example we do not have access to the individual data, the lowest level is the condition level, with conditions (data collection methods) nested within studies.

Let p_{ij} be the observed proportion of respondents in condition i of study j . At the lowest level, we use a linear regression equation to predict $\text{logit}(\pi_{ij})$. The simplest model, corresponding to the intercept-only model in ordinary multilevel regression analysis is given by:

$$\pi_{ij} = \text{logistic}(\beta_{0j}), \quad (6.5)$$

which is sometimes written as

$$\text{logit}(\pi_{ij}) = \beta_{0j}. \quad (6.6)$$

As we explained earlier, Equation 6.6 is a bit misleading because it suggests that we are using an empirical logit transformation on the proportions, which is precisely what the generalized linear model avoids doing, so Equation 6.5 is a better representation of our model. Note again that the usual lowest-level error term e_{ij} is not included in Equation 6.5. In the binomial distribution the variance of the observed proportion depends only on the population proportion π_{ij} . As a consequence, in the model described by Equation 6.5, the lowest-level variance is determined completely by the estimated value for π_{ij} , and therefore it does not enter the model as a separate term. In most current software, the variance of π is modeled by

$$\text{VAR}(\pi_{ij}) = \sigma^2 (\pi_{ij} (1 - \pi_{ij})) / n_{ij}. \quad (6.7)$$

In Equation 6.7, σ^2 is not a variance, but a scale factor used to model under- or overdispersion. Choosing the binomial distribution fixes σ^2 to a default value of 1.00. This means that the binomial model is assumed to hold precisely, and the value 1.00 reported for σ^2 need not be interpreted. Given the specification of the variance in Equation 6.7, we have the option to estimate the scale factor σ^2 , which allows us to model under- or overdispersion.

The model in Equation 6.5 can be extended with an explanatory variable X_{ij} at the condition level (e.g., a variable describing the condition as a mail or as a face-to-face survey):

$$\pi_{ij} = \text{logistic} (\beta_{0j} + \beta_{1j} X_{ij}). \quad (6.8)$$

The regression coefficients β are assumed to vary across studies, and this variation is modeled by the study level variable Z_j in the usual second-level regression equations:

$$\beta_{0j} = \gamma_{00} + \gamma_{01} Z_j + u_{0j} \quad (6.9)$$

$$\beta_{1j} = \gamma_{10} + \gamma_{11} Z_j + u_{1j} \quad (6.10)$$

Substituting Equations 6.9 and 6.10 into Equation 6.8, we get the multilevel model:

$$\pi_{ij} = \text{logistic} (\gamma_{00} + \gamma_{01} X_{ij} + \gamma_{01} Z_j + \gamma_{11} X_{ij} Z_j + u_{0j} + u_{1j} X_{ij}). \quad (6.11)$$

Again, the interpretation of the regression parameters in Equation 6.11 is *not* in terms of the response proportions we want to analyze, but in terms of the underlying variate defined by the logit transformation $\text{logit}(p) = \ln(p / (1 - p))$. The logit link function transforms the proportions (between 0.00 and 1.00 by definition) into values on a logit scale ranging from $-\infty$ to $+\infty$. The logit link is nonlinear, and in effect it assumes that it becomes more difficult to produce a change in the outcome variable (the proportion) near the extremes of 0.00 and 1.00, as is illustrated in Figure 6.1. For a quick examination of the analysis results,

we can simply inspect the regression parameters calculated by the program. To understand the implications of the regression coefficients for the proportions we are modeling, the predicted logit values must be transformed back to the proportion scale.

In our meta-analysis, we analyze survey response rates when available, and if these are not available, the completion rate is used. Therefore, the appropriate null model for our example data is not the ‘intercept-only’ model, but a model with a dummy variable indicating whether the response proportion is a response rate (1) or a completion rate (0). The lowest-level regression model is therefore:

$$\pi_{ij} = \text{logistic}(\beta_{0j} + \beta_{1j} \text{resptype}), \quad (6.12)$$

where the random intercept coefficient β_{0j} is modeled by

$$\beta_{0j} = \gamma_{00} + u_{0j} \quad (6.13)$$

and the slope for the variable *resptype* by

$$\beta_{1j} = \gamma_{10}, \quad (6.14)$$

which leads by substitution to:

$$\pi_{ij} = \text{logistic}(\gamma_{00} + \gamma_{10} \text{resptype} + u_{0j}). \quad (6.15)$$

Since the accurate estimation of the variance terms is an important goal in meta-analysis, the estimation method uses the restricted maximum likelihood method with second-order PQL approximation. For the purpose of comparison, Table 6.4 presents for the model given by Equation 6.15 the first-order MQL parameter estimates and the preferred second-order PQL estimates. (Numerical integration estimation using HLM encountered convergence problems.)

The MQL-1 method estimates the expected response rate (RR) as $(0.45 + 0.68 =) 1.13$, and the PQL-2 method as $(0.59 + 0.71 =) 1.30$. As noted before, this refers to the underlying distribution established by the logit link function, and *not* to the proportions themselves. To determine the expected proportion, we must use the inverse transformation, the logistic function, given by $g(x) = e^x / (1 + e^x)$. Using this transformation, we find an expected response rate of 0.79 for PQL-2 estimation, and 0.76 for MQL-1 estimation. This is not exactly equal to the value of 0.78 that we obtain when we calculate the mean of the response rates, weighted by sample size. However, this is as it should be, for we are using a nonlinear link function, and the value of the intercept refers to the intercept of the underlying variate. Transforming that value back to a proportion is *not* the same as computing the intercept for the proportions themselves. Nevertheless, the difference is usually rather small when the proportions are not very close to 1 or 0.

Table 6.4 Null model for response rates

Fixed part Predictor	MQL-1 Coefficient (s.e.)	PQL-2 Coefficient (s.e.)
Intercept	0.45 (.16)	0.59 (.15)
Resptype is RR	0.68 (.18)	0.71 (.06)
Random part		
σ_{u0}^2	0.67 (.14)	0.93 (.19)

It is tempting to use the value of 1.00 as a variance estimate to calculate the intraclass correlation for the null model in Table 6.4. However, the value of 1.00 is just a scale factor. The variance of the standard logistic distribution with scale factor 1 is $\pi^2 / 3 \approx 3.29$ (with $\pi \approx 3.14$, cf. Evans et al., 1993). So the intraclass correlation for the null-model is $r = 0.93 / (0.93 + 3.29) = 0.22$.

The next model adds the condition-level dummy variables for the telephone and the mail condition, assuming fixed regression slopes. The equation at the lowest (condition) level is:

$$\pi_{ij} = \text{logistic} (\beta_{0j} + \beta_{1j} \text{resptype}_{ij} + \beta_{2j} \text{tel}_{ij} + \beta_{3j} \text{mail}_{ij}), \quad (6.16)$$

and at the study level:

$$\beta_{0j} = \gamma_{00} + u_{0j} \quad (6.17)$$

$$\beta_{1j} = \gamma_{10} \quad (6.18)$$

$$\beta_{2j} = \gamma_{20} \quad (6.19)$$

$$\beta_{3j} = \gamma_{30} . \quad (6.20)$$

Substituting Equations 6.17 to 6.20 into Equation 6.16 we obtain:

$$\pi_{ij} = \text{logistic} (\gamma_{00} + \gamma_{10} \text{resptype}_{ij} + \gamma_{20} \text{tel}_{ij} + \gamma_{30} \text{mail}_{ij} + u_{0j}) . \quad (6.21)$$

Until now, the two dummy variables are treated as fixed. One even could argue that it does not make sense to model them as random, since the dummy variables are simple dichotomies that code for our three experimental conditions. The experimental conditions

are under control of the investigator, and there is no reason to expect their effect to vary from one experiment to another. But some more thought leads to the conclusion that the situation is more complex. If we conduct a series of experiments, we would expect identical results only if the research subjects were all sampled from exactly the same population, and if the operations defining the experimental conditions were all carried out in exactly the same way. In the present case, both assumptions are questionable. In fact, some studies have sampled from the general population, while others sample from special populations such as college students. Similarly, although most articles give only a short description of the procedures that were actually used to implement the data collection methods, it is highly likely that they were not all identical. Even if we do not know all the details about the populations sampled and the procedures used, we may expect a lot of variation between the conditions as they were actually implemented. This would result in varying regression coefficients in our model. Thus, we analyze a model in which the slope coefficients of the dummy variables for the telephone and the mail condition are assumed to vary across studies. This model is given by

$$\beta_{0j} = \gamma_{00} + u_{0j}$$

$$\beta_{1j} = \gamma_{10}$$

$$\beta_{2j} = \gamma_{20} + u_{2j}$$

$$\beta_{3j} = \gamma_{30} + u_{3j}$$

which gives

$$\pi_{ij} = \text{logistic} (\gamma_{00} + \gamma_{10} \text{resptype}_{ij} + \gamma_{20} \text{tel}_{ij} + \gamma_{30} \text{mail}_{ij} + u_{0j} + u_{2j} \text{tel}_{ij} + u_{3j} \text{mail}_{ij}) . \quad (6.22)$$

Results for the models specified by Equatons 6.21 and 6.22, estimated by numerical integration in HLM, are given in Table 6.5.

The intercept represents the condition in which all explanatory variables are zero. When the telephone dummy and the mail dummy are both zero, we have the face-to-face condition. Thus, the values for the intercept in Table 6.5 estimate the expected completion rate (CR) in the face-to-face condition, 0.90 in the fixed model. The variable *resptype* indicates whether the response is a completion rate (*resptype* = 0) or a response rate (*resptype* = 1). The intercept plus the slope for *resptype* equals 1.36 in the random slopes model. These values on the logit scale translate to an expected completion rate of 0.76 and an expected response rate of 0.80 for

Table 6.5 Models for response rates in different conditions

Fixed part Predictor	Conditions fixed coefficient (s.e.)	Conditions random coefficient (s.e.)
Intercept	0.90 (.14)	1.16 (.21)
Resptype is RR	0.53 (.06)	0.20 (.23)
Telephone	−0.16 (.02)	−0.20 (.09)
Mail	−0.49 (.03)	−0.57 (.15)
Random part		
σ_{u0}^2	0.86 (.18)	0.87 (.19)
$\sigma_{u(rel)}^2$		0.26 (.07)
$\sigma_{u(mail)}^2$		0.57 (.19)

the average face-to-face survey. The negative values of the slope coefficients for the telephone and mail dummy variables indicate that the expected response is lower in these conditions. To find out how much lower, we must use the regression equation to predict the response in the three conditions, and transform these values (which refer to the underlying logit-variate) back to proportions. For the telephone conditions, we expect a response rate of 1.16, and for the mail condition 0.79. These values on the logit scale translate to an expected response rate of 0.76 for the telephone survey and 0.69 for the mail survey.

The variances of the intercept and the conditions are significant, and we may attempt to explain these using the known differences between the studies. In the example data, we have two study-level explanatory variables: year of publication, and the salience of the questionnaire topic. Since not all studies compare all three data collection methods, it is quite possible that study-level variables also explain between condition variance. For instance, if older studies tend to have a higher response rate, and the telephone method is included only in the more recent studies (telephone interviewing is, after all, a relatively new method), the telephone condition may seem characterized by low response rates. After correcting for the year of publication, in that case the telephone response rates should look better. We cannot inspect the condition-level variance to investigate whether the higher-level variables explain condition-level variability. In the logistic regression model used here, the lowest-level (condition-level) variance term is automatically constrained to $\pi^2 / 3 \approx 3.29$ in each model, and it remains the same in all analyses. Therefore, it is also not reported in the tables.

Both study-level variables make a significant contribution to the regression equation, but only the year of publication interacts with the two conditions. Thus, the final model for these data is given by

$$\pi_{ij} = \text{logistic} (\beta_{0j} + \beta_{1j} \text{resptype}_{ij} + \beta_{2j} \text{tel}_{ij} + \beta_{3j} \text{mail}_{ij})$$

at the lowest (condition) level, and at the study level:

$$\beta_{0i} = \gamma_{00} + \gamma_{01} year_j + \gamma_{02} saliency_j + u_{0j}$$

$$\beta_{1j} = \gamma_{10}$$

$$\beta_{2j} = \gamma_{20} + \gamma_{21} year_j + u_{2j}$$

$$\beta_{3j} = \gamma_{30} + \gamma_{31} year_j + u_{3j} ,$$

which produces the combined equation

$$\begin{aligned} \pi_{ij} = \text{logistic} & (\gamma_{00} + \gamma_{10} resptype_{ij} + \gamma_{20} tel_{ij} + \gamma_{30} mail_{ij} + \gamma_{01} year_j + \gamma_{02} saliency_j \\ & + \gamma_{21} tel_{ij} year_j + \gamma_{31} mail_{ij} year_j + u_{0j} + u_{2j} tel_{ij} + u_{3j} mail_{ij}) . \end{aligned} \quad (6.23)$$

Results for the model specified by Equation 6.23 are given in Table 6.6. Since interactions are involved, the explanatory variable year has been centered on its overall mean value of 29.74.

Compared to the earlier results, the regression coefficients are about the same in the model without the interactions. The variances for the telephone and mail slopes in the interaction model are lower than in the model without interactions, so the cross-level interactions explain some of the slope variation. The regression coefficients in Table 6.6 must be interpreted in terms of the underlying logit scale. Moreover, the logit transformation implies that raising the response becomes more difficult as we approach the limit of 1.00. To show what this means, the predicted response for the three methods is presented in Table 6.7 as logits (in parentheses) and proportions, both for a very salient (*saliency* = 2) and a nonsalient (*saliency* = 0) questionnaire topic. To compute these numbers we must construct the regression equation implied by the last column of Table 6.6, and then use the inverse logistic transformation given earlier to transform the predicted logits back to proportions. The year 1947 was coded in the data-file as zero, after centering the year zero refers to 1977. As the expected response rates in Table 6.6 show, in 1977 the expected differences between the three data collection modes are small, while the effect of the saliency of the topic is much larger. To calculate the results in Table 6.7, the rounded values for the regression coefficients given in Table 6.6 were used.

To gain a better understanding of the development of the response rates over the years, it is useful to predict the response rates from the model and to plot these predictions over the years. This is done by filling in the regression equation implied by the final model for the three survey conditions, for the year varying from 1947 to 1998 (followed by centering on the overall mean of 25), with saliency fixed at the intermediate value of one.

Table 6.6 Models for response rates in different conditions, with random slopes and cross-level interactions

Fixed part Predictor	No interactions coefficient (s.e.)	With interactions coefficient (s.e.)
Intercept	0.33 (.25)	0.36 (.25)
Resptype	0.32 (.20)	0.28 (.20)
Telephone	−0.17 (.09)	−0.21 (.09)
Mail	−0.58 (.14)	−.54 (.13)
Year	−0.02 (.01)	−0.03 (.01)
Saliency	0.69 (.17)	0.69 (.16)
Tel * year		0.02 (.01)
Mail * year		0.03 (.01)
Random part		
σ^2_{u0}	0.57 (.13)	0.57 (.14)
σ^2_{u2}	0.25 (.07)	0.22 (.07)
σ^2_{u3}	0.53 (.17)	0.39 (.15)

Table 6.7 Predicted response rates (plus logits), cross-level interaction model. Year centered on 1977

Topic	Face-to-face	Telephone	Mail
Not salient	0.65 (.63)	0.61 (.44)	0.53 (.11)
Salient	0.88 (2.01)	0.86 (1.82)	0.82 (1.49)

Figure 6.2 presents the predictions for the response rates, based on the cross-level interaction model, with the saliency variable set to intermediate. The oldest study was published in 1947, the latest in 1992. At the beginning, in 1947, the cross-level model implies that the differences between the three data collection modes were large. After that, the response rates for face-to-face and telephone surveys declined, with face-to-face interviews declining the fastest, while the response rates for mail surveys remained stable. As a result, the response rates for the three data collection modes have become more similar in recent years. Note that the response rate scale has been cut off at 65 percent, which exaggerates the difference in trends.

6.5 THE EVER-CHANGING LATENT SCALE: COMPARING
COEFFICIENTS AND EXPLAINED VARIANCES

In many generalized linear models, for example in logistic and probit regression, the scale of the unobserved latent variable η is arbitrary, and to identify the model it needs to be

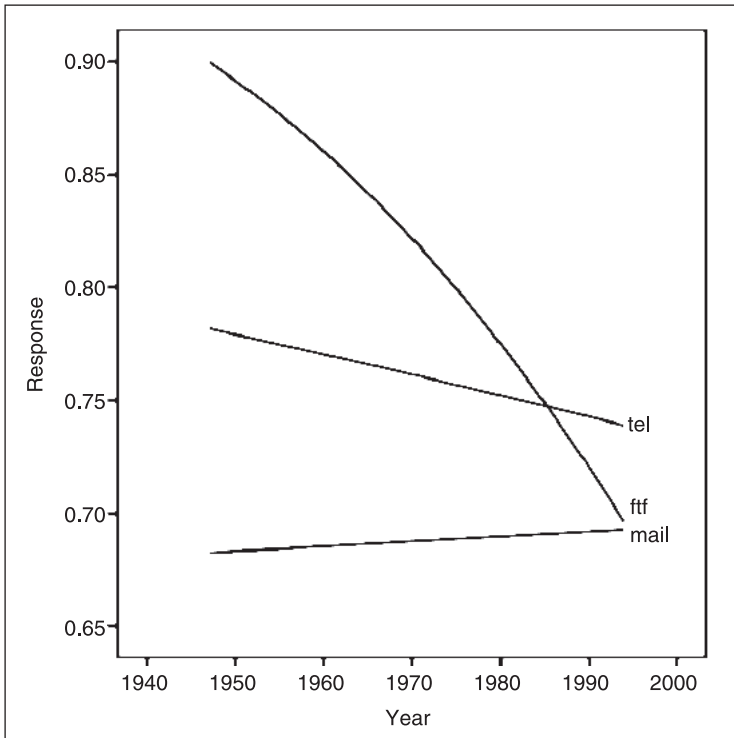


Figure 6.2 Predicted response rates over the years.

standardized. Probit regression uses the standard normal distribution, with mean zero and variance one. Logistic regression uses the standard logistic distribution (scale parameter equal to one) which has a mean of zero and a variance of $\pi^2 / 3 \approx 3.29$. The assumption of an underlying latent variable is convenient for interpretation, but not crucial.

An important issue in these models is that the underlying scale is standardized to the same standard distribution in each of the analyzed models. If we start with an intercept-only model, and then estimate a second model where we add a number of explanatory variables that explain part of the variance, we normally expect that the estimated variance components become smaller. However, in logistic and probit regression (and in many other generalized linear models), the underlying latent variable is rescaled, so the lowest-level residual variance is again $\pi^2 / 3$ (or unity in probit regression). Consequently, the values of the regression coefficients and higher-level variances are also rescaled, in addition to any real changes due to the changes in the model. These implicit scale changes make it impossible to compare regression coefficients across models, or to investigate how variance components change. Snijders and Bosker (2011) discuss this phenomenon briefly; a more detailed discussion is given by Fielding (2002, 2004).

The phenomenon of the change in scale is not specific to multilevel generalized linear modeling, it also occurs in single-level logistic and probit models (Long, 1997). For the single-level logistic model, several pseudo- R^2 formulas have been proposed to provide an indication of the explained variance. These are all based on the log-likelihood. They can be applied in multilevel logistic and probit regression, provided that a good estimate of the log-likelihood is available.

A statistic that indicates the importance of each individual predictor is the partial correlation, also called Atkinson's R , between the outcome variable and the predictor. In logistic regression this partial correlation can be estimated using the Wald statistic and the deviance (which equals -2 times the log-likelihood). When a single predictor is assessed, the Wald test is most conveniently described as $Z_w = \beta / \text{s.e.}(\beta)$, the estimated parameter divided by its standard error. The partial correlation is then estimated as

$$R = \sqrt{\frac{Z_w^2 - 2}{|Deviance_{\text{null}}|}}. \quad (6.24)$$

Menard (1995) warns that when the absolute value of the regression coefficient is large, the standard error of the parameters tend to be overestimated, which makes the Wald test conservative, and in that case Equation 6.24 will provide an underestimate of the partial correlation. The deviance difference test, which compares the model with and without each predictor, is more accurate than the Wald test. If an accurate value of the deviance is available, the Z^2 in Equation 6.24 can be replaced by the chi-square value produced by the difference of the deviances. Since the importance of predictor variables is assessed, full maximum likelihood estimation must be used here.

A simple analogue to the squared multiple correlation in logistic regression is McFadden's R_{MF}^2 , given by

$$R_{MF}^2 = 1 - \frac{Deviance_{\text{model}}}{Deviance_{\text{null}}}. \quad (6.25)$$

Other pseudo- R^2 s also take the sample size into account. A common approach to the squared multiple correlation in logistic regression are the Cox and Snell R_{CS}^2 and the Nagelkerke R_N^2 . The Cox and Snell R^2 is calculated as

$$R_{CS}^2 = 1 - \exp\left(\frac{Deviance_{\text{model}} - Deviance_{\text{null}}}{n}\right), \quad (6.26)$$

where $\exp(x)$ means e^x . A problem with the Cox and Snell R^2 is that it cannot reach the maximum value of 1. The Nagelkerke adjustment produces Nagelkerkes R_N^2 which can be 1:

$$R_N^2 = \frac{R_{CS}^2}{1 - \exp\left(\frac{-Deviance_{\text{null}}}{n}\right)}. \quad (6.27)$$

Tabachnick and Fidell (2013) warn that these pseudo- R^2 s cannot be interpreted as explained variance; they are similar in the sense that they indicate how much of the deviance is explained, and can be used to gauge the substantive worth of the model. Although pseudo- R^2 s cannot be interpreted independently or compared across different datasets, they are useful in comparing and evaluating various models predicting the same outcome on the same dataset. In general, the pseudo- R^2 s tend to be much lower than real R^2 s, with values between 0.2 and 0.4 indicating good prediction. The statistical literature indicates no clear preference for any of these pseudo- R^2 s. However, in multilevel logistic regression, the McFadden pseudo- R^2 can be decomposed into an R^2 value for each level separately, which is an advantage. The extension is straightforward:

$$R^2_{MFw} = 1 - \frac{Deviance_{within-model}}{Deviance_{null}} \quad (6.28)$$

$$R^2_{MFb} = 1 - \frac{Deviance_{between-model}}{Deviance_{null}} \quad (6.29)$$

In Equations 6.28 and 6.29 the decrease in deviance is calculated respectively using only the within part (lowest level) and the between part (highest level) predictors. To achieve good separation of the within and between part, we recommend using group mean centering, and adding group means at the second level as predictors.

The approaches discussed above can only be used if there is an accurate estimate of the likelihood. If Taylor expansion is used, the likelihood is not accurate enough for these approaches. Snijders and Bosker (2011) propose a general solution for the explained variance in multilevel logistic regression that does not rely on the likelihood. It is a multilevel extension of a method proposed by McKelvey and Zavoina (1975) that is based on the explained variance of the latent outcome η in the generalized linear model. The variance of η is decomposed into the lowest-level residual variance σ_R^2 , which is fixed to $\pi^2 / 3$ in the logistic and to 1 in the probit model, the second-level intercept variance σ_{u0}^2 , and the variance σ_F^2 of the linear predictor from the fixed part of the model. The variance of the linear predictor is the systematic variance in the model; the other two variances are the residual errors at the two levels. The proportion of explained variance is then given by:

$$R^2_{MZ} = \frac{\sigma_F^2}{\sigma_F^2 + \sigma_{u0}^2 + \sigma_R^2} \quad (6.30)$$

The variance of the linear predictor is sometimes given by the software, but it can easily be determined by calculating the predictions from the regression equation. These predictions are on the unobserved latent variable. Because McKelvey and Zavoina's approach is very similar to OLS R-squares, we can interpret the McKelvey and Zavoina R^2 as a multiple- R^2 for the latent continuous variable. The accuracy of various pseudo- R^2 s has been assessed in simulation studies by predicting a continuous variable through OLS regression and a

dichotomized version by logistic regression and then comparing the pseudo- R^2 's to the OLS R^2 . In these simulations, McKelvey and Zavoina's pseudo- R^2 (R_{MZ}^2) was the closest to the OLS R^2 , which the other pseudo- R^2 's tended to underestimate (Long, 1997; DeMaris, 2002).

Calculating the total variance of the latent outcome is in itself useful. The square root of the total variance $\sigma_F^2 + \sigma_{u0}^2 + \sigma_R^2$ is after all the standard deviation of the latent variable. This can be used to compute standardized regression coefficients.

Following McKelvey and Zavoina's approach, we can calculate the total variance of the latent variable as $\sigma_F^2 + \sigma_{u0}^2 + \sigma_R^2$. Since rescaling takes place only when lowest-level variance is explained, only first-level predictors are used here. For the null model, the total variance is $\sigma_0^2 = \sigma_{u0}^2 + \sigma_R^2$, with $\sigma_R^2 \approx 3.29$. For the model m including the first-level predictor variables, the total variance is $\sigma_m^2 = \sigma_F^2 + \sigma_{u0}^2 + \sigma_R^2$. Hence, we can calculate a scale correction factor (SCF) which rescales the model m to the same underlying scale as the null model. The scale correction factor equals σ_0/σ_m for the regression coefficients and σ_0^2/σ_m^2 for the variance components. Next, we can rescale both the regression coefficients and the variance estimates σ_{u0}^2 and σ_R^2 by the appropriate scale correction factor, which makes them comparable across models. The scale corrected variance estimates are useful for assessing the amount of variance explained separately at the different levels, using the procedures outlined in Chapter 4. Given all these prospects made possible by rescaling to the scale of the intercept-only model, the McKelvey and Zavoina method is the most appealing.

There is one final method to assess the importance of predictor variables and indicate the explained variance, which does not need numerical integration. Regression is about prediction, and we can use the linear predictor to classify the predicted values into predicted values classes in the dichotomous outcomes. We simply recode the continuous linear predictor into '0' and '1,' splitting these values on the percentile equal to the percentage of '1's in the observed data. Next, we can calculate the crosstable for predicted outcomes versus observed outcomes. The percentage correct predictions, or the phi correlation coefficient, provide a simple assessment of the explained variation. This can be extended further by comparing several linear predictors, for instance one based only on the level-one predictors, and one based on all predictors.

We use the Thai educational data to illustrate these procedures. The sample consists of 8582 pupils in 357 schools. The first three columns in Table 6.8 present the null model M_0 and the estimates of the model M_1 that include pupil gender and preschool education, and model M_2 that adds school mean SES as predictor. The estimation method is full numerical integration (SuperMix with 20 adaptive quadrature points), and we report three decimals for a more precise calculation. For clarity, calculations are based on the values in Table 6.8 in a real application we would carry all decimals reported by the software. The last column in Table 6.8 shows the partial r for the predictors in the model M_2 . The largest partial r is 0.09 for pupil gender, which Cohen (1988) classifies as a small correlation. If the deviance difference is used instead of the square of the Wald Z , the partial correlation is estimated as 0.10. We can take the square root of a pseudo- R^2 and obtain the analogue to the multiple correlation. For M_2 the McFadden R is 0.13, the Cox & Snell R is 0.11, and the Nagelkerke R is 0.15. All these

estimates are rather similar and all lead to the same conclusion that the explanatory power of the model on repeating a class is low.

The variance of the linear predictor for M_2 (calculated in the raw data file, using the coefficients for the three predictors in the fixed part of the regression equation) s_F^2 is 0.201. Thus, the explained variance using the McKelvey and Zavoina method is $0.201 / (0.201 + 1.686 + 3.290 = 5.177) = 0.039$, and the corresponding multiple correlation is 0.20. Consistent with the existing simulation studies it is the highest of the pseudo- R^2 estimates, but we still conclude that we explain only a small amount of variance.

When we dichotomize the linear predictor on its 85.49th percentile, which reflects having 14.51 percent repeats in the data, we can form the 2×2 crosstable of predicted versus observed repeats. Of the 1067 pupils that repeated a class, 230 (21.6%) are classified correctly, and the phi correlation coefficient is 0.09. Again, we conclude that we have low explanatory power.

The square root of the total variance of the latent variable, which is its standard deviation, is 2.275. This value is used, together with the standard deviations of the predictors in the sample, to calculate the standardized regression coefficients for M_2 in the last column, using the equation $b_s = b \times s_x / s_y$. The standardized regression coefficients are all low, indicating low explanatory power.

To calculate estimates of explained variance at separate levels we need to bring the models to the same scale. The total variance of the latent outcome variable in the intercept-only model is $1.726 + 3.290 = 5.016$ and the corresponding standard deviation is 2.240. The variance of the linear predictor, using only the level-one variables in model M_1 , is 0.171. Therefore, the total variance in the model with only the first-level predictor variables is $5.016 + 0.171 = 5.187$, and the corresponding standard deviation is 2.277. The difference is tiny, and reflects the small effects of the explanatory variables on the outcome variable. The scale-correction factor is $2.240 / 2.277 = 0.984$. The variances must be scaled with the square of the scaling factor, which is 0.967. The rescaled regression coefficients are on the

Table 6.8 Thai educational data: logistic regression estimates with partial r

Model	M_0	M_1	M_2	M_2 partial r	M_2 standardized
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)		
Intercept	-2.234 (.088)	-2.237 (.107)	-2.242 (.106)	—	—
Pupil gender		0.536 (.076)	0.535 (.076)	0.009	0.12
Pre education		-0.642 (.100)	-0.627 (.100)	0.007	-0.14
Mean SES			-0.296 (.217)	0.000	-0.05
σ_{u0}^2	1.726 (.213)	1.697 (.211)	1.686 (.210)		
Deviance	5537.444	5443.518	5441.660		

same scale as the intercept-only model. If we build up the model in steps, as suggested in Chapter 4, we can use this method to rescale all results to the scale of the null-model, thus retaining comparability across different models. When changes are made to the fixed part at the lowest level, the scaling factor has to be calculated again. When changes are made to the higher levels, as in M_2 in Table 6.9, the scale factor remains the same, because such changes do not alter the explained variance at the lowest level. Table 6.9 presents the estimates for the models in Table 6.6 in both the raw and the rescaled version. The lowest level variance σ_R^2 is added to the table. In the null-model this has the distributional value of 3.29; in the subsequent models it is rescaled, just as the higher-level variances.

In Table 6.9, the columns SC M1 and SC M2 contain the scale-corrected values of the regression coefficients and variances, including the residual variance at the lowest level. Using procedures described in Chapter 4, we can estimate the explained variance in M_1 and M_2 . In the empty model, the lowest-level variance has its distributional value 3.290. In the scale-corrected M_1 , this variance decreases to 3.184, which leads to a level-one explained variance in M_1 of 0.032. At the second level, the variance drops from 1.726 in the intercept-only model to 1.670 in the scaled model 1; this leads to a level-two explained variance in M_1 of 0.032. In the scale-corrected M_2 , the second-level variance goes down to 1.632, and the explained variance at the school level increases to 0.054. In terms of explained variance, the school variation in repeat rates is explained better by the differences in pupil composition, and less by the contextual effect of school mean SES. The partial correlations in the last column of Table 6.9 indicate also that school mean SES is relatively unimportant. If we calculate the total explained variance by calculating the proportional difference between the total variance in M_0 and in M_2 scaled, we obtain 0.04, a value close to the value calculated earlier (the difference is due to rounding errors).

Table 6.9 Thai educational data: logistic regression estimates with rescaling

Model	M_0	M_1	SC M_1	M_2	SC M_2
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	
Intercept	−2.234 (.088)	−2.237 (.107)	−2.20 (.11)	−2.242 (.106)	2.21 (.10)
Pupil gender		0.536 (.076)	0.53 (.08)	0.535 (.076)	0.53 (.08)
Pre education		−0.642 (.100)	−0.63 (.10)	−0.627 (.100)	−0.62 (.10)
Mean SES				−0.296 (.217)	0.29 (.21)
σ_R^2	3.290	n/a	3.184	n/a	3.184
σ_{u0}^2	1.726 (.213)	1.697 (.211)	1.670 (.20)	1.686 (.210)	1.632 (.20)
Deviance	5537.444	5443.518	–	5441.660	–

We note again that using the McKelvey and Zavoina method provides explained variance in the latent variable η . In multilevel structural equation modeling with non-normal dependent variables, the explained variance reported in the output is also for the latent variable underlying the observations.

The examples in this chapter refer to logistic and probit regression, because these are the most commonly used distributions. However, almost any continuous function that maps probability onto the real line from minus infinity to plus infinity can be used to form a generalized linear model. When it is desirable to rescale such models, one needs to know the variance of the standard distribution. For example, the log-log and complementary log-log distributions which were mentioned earlier have variance $\pi^2/6$. Here the variance also depends on the fixed predictions, and also changes between one model and the next. For details for a large number of distributions we refer to Evans, Hastings and Peacock (2000).

6.6 INTERPRETATION

The models and parameter estimates described earlier are the so-called ‘unit specific’ models. Unit specific models predict the outcome of individuals and groups conditional on all random effects included in the model. The interpretation of such models is equivalent to the interpretation of effects in standard multilevel regression models; the regression coefficients for all explanatory variables reflect the predicted change in outcome when a predictor is changed by one unit. With nonlinear models, one can also estimate a population average model. This model does not condition on the random effects, but averages over all random effects. This approach is a form of estimation termed generalized estimating equations (GEE), discussed in more detail in Chapter 13. In scientific research where the variation in behavior of individuals within groups are studied, and the focus is on explaining how individual- and group-level variables affect that behavior, unit-specific models are appropriate. Population average models have their place in policy research, when the research problem concerns estimating the expected change in an entire population when one of the group-level variables is manipulated. For a technical discussion of the difference between unit specific and population average models we refer to Raudenbush and Bryk (2002); an accessible discussion in the context of epidemiological research is given by Hu, Goldberg, Hedeker, Flay and Pentz (1998).

6.7 SOFTWARE

For estimating nonlinear models, there is an increasing availability of software that uses numerical integration. The precise choices available depend on the software. As the example analyses in this chapter show, in many cases the difference between PQL and numerical integration is small, especially for the regression coefficients in the fixed part. However, this is not always the case. Simulations by Rodriguez and Goldman (1995) show that the

combination of small groups and a high intraclass correlation can produce a severe bias, even when PQL is used. This combination is not unusual in some kinds of research. For instance, when families or couples are studied, the groups will be small and the intraclass correlation is often high. The smallest group sizes occur when we analyze dyadic data (couples). Given some amount of spouse nonresponse, the average group size can be well under two for such data; and if the model is nonlinear, PQL can be expected to produce biased results. Longitudinal data also tend to have small 'group' sizes and high intraclass correlations. If numerical integration is not available, bootstrap or Bayesian methods should be used to improve the estimates (cf. Chapter 13).

As mentioned earlier, with dichotomous data the overdispersion parameter cannot be estimated. Nevertheless, some software in fact allows estimating overdispersion with dichotomous data, especially when quasi-likelihood estimation methods are used. With dichotomous data, the overdispersion parameter is superfluous, and should in general not be included in the model (Skron dal & Rabe-Hesketh, 2007).

The program MLwiN does not use numerical integration, but bootstrapping and Bayesian methods are available. The multilevel software developed by Hedeker and Gibbons use numerical integration, and are available in a package called SuperMix (Hedeker et al., 2008). HLM has the option of using numerical integration for dichotomous and count data only (Raudenbush et al., 2011), using an approach called Laplace approximation. This is equivalent to using numerical integration with only one integration point (Rabe-Hesketh & Skron dal, 2008, p. 251). The Mplus software (Muthén & Muthén, 1998–2015) includes several options for numerical integration. Several large software packages, such as SAS, STATA but also the freely available package R have numerical integration for multilevel generalized linear models, as does the free STATA add-in GLLAMM (Rabe-Hesketh et al., 2004).

7

The Multilevel Generalized Linear Model for Categorical and Count Data

SUMMARY

When outcome variables are severely non-normal, the usual remedy is to try to normalize the data using a non-linear transformation, to use robust estimation methods, or a combination of these (see Chapter 4 for details). Then again, just like dichotomous outcomes, some types of data will always violate the normality assumption. Examples are ordered (ordinal) and unordered (nominal) categorical data, which have a uniform distribution, or counts of rare events. These outcomes can sometimes also be transformed, but they are preferably analyzed in a more principled manner, using the generalized linear model introduced in Chapter 6. This chapter describes the use of the generalized linear mixed model for multilevel ordered categorical data and for count data.

7.1 ORDERED CATEGORICAL DATA

There is a long tradition, especially in the social sciences, of treating ordered categorical data as if they were continuous and measured on an interval scale. A prime example is the analysis of Likert-scale data, where responses are collected on ordered response categories, for example ranging from 1 = totally disagree to 5 = totally agree. Another example is a physician's prognosis for a patient categorized as 'good', 'fair' and 'bad'.

The consequences of treating ordered categorical data as continuous are well known, both through analytical work (Olsson, 1979) and through simulations (e.g., Dolan, 1994; Muthén & Kaplan, 1985; Rhemtulla et al., 2012). The general conclusion is that if there are at least five categories, and the observations have a symmetric distribution, the bias introduced by treating categorical data as continuous is small (Bollen & Barb, 1981; Johnson & Creech, 1983). With seven or more categories, the bias is very small. If there are four or fewer categories, or the distribution is markedly skewed, both the parameter estimates and their standard errors have a downward bias. When this is the case, a statistical method designed specifically for ordered data is needed. Such models are discussed by, among others, McCullagh and Nelder (1989) and Long (1997). Multilevel extensions of these models are discussed by Goldstein (2011), Raudenbush and Bryk (2002), and Hedeker and Gibbons (1994, 2006). This chapter treats the cumulative regression model, which is frequently used in practice; see Hedeker (2008) for a discussion of other multilevel models for ordered data.

7.1.1 Cumulative Regression Models for Ordered Data

A useful model for ordered categorical data is the cumulative ordered logit or probit model. It is common to start by assigning simple consecutive values to the ordered categories, such as $1 \dots C$ or $0 \dots C - 1$. For example, for a response variable Y with three categories such as ‘never’, ‘sometimes’ and ‘always’ we have three response probabilities:

$$\text{Prob}(Y = 1) = p_1$$

$$\text{Prob}(Y = 2) = p_2$$

$$\text{Prob}(Y = 3) = p_3.$$

The cumulative probabilities are given by

$$p_1^* = p_1$$

$$p_2^* = p_1 + p_2$$

$$p_3^* = p_1 + p_2 + p_3 = 1$$

where p_3^* is redundant. With C categories, only $C - 1$ cumulative probabilities are needed. Since p_1 and p_2 are probabilities, generalized linear regression can be used to model the cumulative probabilities. As stated in Chapter 6, a generalized linear regression model consists of three components:

- 1 an outcome variable y with a specific error distribution that has mean μ and variance σ^2 ,
- 2 a linear additive regression equation that produces a predictor η of the outcome variable y ,
- 3 a *link function* that links the expected values of the outcome variable y to the predicted values for η : $\eta = f(\mu)$.

For a logistic ordinal regression we have the logit link function

$$\eta_c = \text{logit}(p_c^*) = \ln \left(\frac{p_c^*}{1 - p_c^*} \right), \quad (7.1)$$

and for probit ordinal regression the inverse normal link

$$\eta_c = \Phi(p_c^*)^{-1}, \quad (7.2)$$

for $c = 1 \dots C - 1$. A two-level intercept-only model for the cumulative probabilities is then written as

$$\eta_{ijc} = \theta_c + u_{0j}. \quad (7.3)$$

Equation 7.3 specifies a different intercept θ_c for each of the estimated probabilities. These intercepts are called thresholds, because they specify the relationship between the latent variable η and the observed categorical outcome. The position on the latent variable determines which categorical response is observed. Specifically,

$$y_i = \begin{cases} 1, & \text{if } \eta_i \leq \theta_1 \\ 2, & \text{if } \theta_1 < \eta_i \leq \theta_2 \\ 3, & \text{if } \eta_i > \theta_2 \end{cases}$$

where y_i is the observed categorical variable, η_i is the latent continuous variable, and θ_1 and θ_2 are the thresholds. Note that a dichotomous variable only has one threshold, which becomes the intercept in a regression equation.

Figure 7.1 illustrates the relations between the thresholds q , the unobserved response variable η , and the observed responses. As noted by McCullagh and Nelder (1989), assuming a continuous latent distribution underlying the categorical responses is not strictly necessary for use of generalized linear regression models like the kind presented here, but it does help interpretation. Figure 7.1 shows that the standard logistic distribution

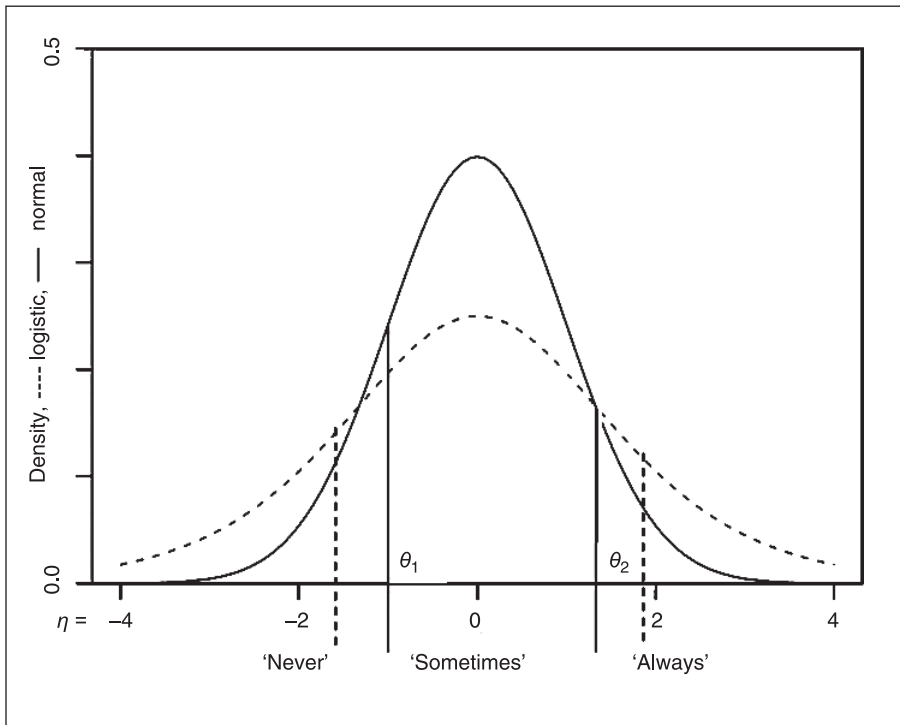


Figure 7.1 Thresholds and observed responses for logit and probit model.

has a larger variance ($\pi^2 / 3 \approx 3.29$) than the standard normal distribution, something that was discussed earlier in the chapter on dichotomous data (Chapter 6). So in the logistic regression model the regression coefficients tend to be larger than in the probit model, but this reflects just a difference in the scaling of the latent outcome variable. The standard errors are also larger in the logistic model, and as Figure 7.1 clearly shows the thresholds are also scaled. Since the relative shape of the two distributions is extremely similar (see Figure 6.1 for an illustration), when the results are standardized or expressed as predicted response probabilities, the results are also very similar.

The model in Figure 7.1 assumes that the effect of the predictor variables is the same for all thresholds. This assumption is called the assumption of *parallel regression* lines. In the logit model this translates to the proportional odds model, which assumes that the predictors have the same effect on the odds for each category c . The assumption of proportional odds is equivalent to the assumption of parallel regression lines; when the structure is shifted the slope of the regression lines do not change. The same assumption is also made in the probit model.

7.1.2 Cumulative Multilevel Regression Models for Ordered Data

Just as in multilevel generalized linear models for dichotomous data, the linear regression model is constructed on the underlying logit or probit scale. Both have a mean of zero, the variance of the logistic distribution is $\pi^2 / 3$ (≈ 3.29 , standard deviation 1.81), and the standard normal distribution for the probit has a variance of 1. As a consequence, there is no lowest-level error term e_{ij} , similar to its absence in generalized linear models for dichotomous data. In fact, dichotomous data can be viewed as ordered data with only two categories. Since the standard logit distribution has a standard deviation of $\sqrt{\pi^2/3} \approx 1.8$, and the standard normal distribution has a standard deviation of 1, the regression slopes in a probit model are generally close to the regression slopes in the corresponding logit model divided by 1.6–1.8 (Gelman & Hill, 2007). Assuming individuals i nested in groups j , and distinguishing between the different cumulative proportions, we write the model for the lowest level as follows:

$$\begin{aligned} \eta_{1ij} &= \theta_{1j} + \beta_{1j} X_{ij} \\ \eta_{2ij} &= \theta_{2j} + \beta_{1j} X_{ij} \\ &\vdots \quad \quad \quad \vdots \\ \eta_{cij} &= \theta_{cj} + \beta_{1j} X_{ij} \end{aligned} \quad (7.4)$$

where the thresholds $\theta_1 \dots \theta_c$ are the intercepts for the response outcomes. The model given by Equation 7.4 is problematic, because we have a collection of intercepts or thresholds that can all vary across groups. The interpretation of such variation is that the groups differ in how the values of the underlying η variable are translated into response categories. If this is the case, there is no measurement equivalence between different groups, and it is impossible to make meaningful comparisons. Therefore the model is rewritten by subtracting the value

from the first threshold from all thresholds. Thus, the first threshold becomes zero, and is thereby effectively removed from the model. It is replaced by an overall intercept β_{0j} , which is allowed to vary across groups. Thus, the lowest-level model becomes

$$\begin{aligned}\eta_{1ij} &= \beta_{0j} + \beta_{1j}X_{ij} \\ \eta_{2ij} &= \theta_2 + \beta_{0j} + \beta_{1j}X_{ij} \\ &\vdots \quad \vdots \quad \vdots \quad \vdots \\ \eta_{cij} &= \theta_c + \beta_{0j} + \beta_{1j}X_{ij}\end{aligned}\quad (7.5)$$

where in Equation 7.5 the thresholds θ_c is equal to $\theta_c - \theta_1$ in Equation 7.4. Obviously, the value for the intercept β_{0j} in Equation 7.5 will be equal to $-\theta_1$ in Equation 7.4. The transformed thresholds θ_c do not have a subscript for groups; they are assumed to be fixed to maintain measurement invariance across the groups. To keep the notation simple, we will continue to use $\theta_2 \dots \theta_c$ to refer to the thresholds in the Equation 7.5 parameterization, where the first threshold is constrained to zero to allow an intercept in the model, and the other thresholds are all shifted by the same value θ_1 .

From this point, the multilevel generalized model for ordinal observations is constructed following the accustomed procedures. Thus, the intercept β_{0j} and the slope β_{1j} are modeled using a set of second-level regression equations

$$\begin{aligned}\beta_{0j} &= \gamma_{00} + \gamma_{01}Z_j + u_{0j} \\ \beta_{1j} &= \gamma_{10} + \gamma_{11}Z_j + u_{1j}.\end{aligned}\quad (7.6)$$

The single equation version of the model is

$$\begin{aligned}\eta_{1ij} &= \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{0j} + u_{1j}X_{ij} \\ \eta_{2ij} &= \theta_2 + \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{0j} + u_{1j}X_{ij} \\ &\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ \eta_{cij} &= \theta_c + \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{0j} + u_{1j}X_{ij}\end{aligned}\quad (7.7)$$

or, in a simpler notation

$$\eta_{cij} = \theta_c + \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{0j} + u_{1j}X_{ij}, \quad (7.8)$$

with the condition that θ_1 is zero. Using the empty model

$$\eta_{cij} = \theta_c + \gamma_{00} + u_{0j}, \quad (7.9)$$

we obtain estimates of the variance of the residual errors u_0 that can be used to calculate the intraclass correlation. The residual first-level variance is equal to $\pi^2 / 3 \approx 3.29$ for the logit and 1 for the probit scale. Note that the IntraClass correlation (ICC) is defined on the underlying continuous scale, and not on the observed categorical response scale. Just as in

the dichotomous case, the underlying continuous scale is rescaled when first-level predictors are added, and the regression coefficients from different models cannot be compared directly.

Modeling the cumulative probabilities $p_1, p_1 + p_2, \dots, p_1 + p_2 + \dots + p_{C-1}$ makes the last response category the reference category. As a result, the regression coefficients in the cumulative regression model will have a sign that is the opposite of the sign given by an ordinary linear regression. This is confusing, and most model and software writers solve this effectively by writing the regression equation e.g. for Equation 7.8 as

$$\eta_{cij} = -1(\theta_c + \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{0j} + u_{1j}X_{ij}), \quad (7.10)$$

which restores the signs to the direction they would have in a standard linear regression. However, this is not universally done, and software users should understand what their particular software does.

The estimation issues discussed in modeling dichotomous outcomes and proportions also apply to estimating ordered categorical models. One approach is to use Taylor series linearization, using either the marginal quasi-likelihood (MQL) or the penalized quasi-likelihood (PQL). PQL is generally considered more accurate, but in either case the approximation to the likelihood is not accurate enough to permit deviance difference tests. The other approach is to use numerical integration, which is more accurate but also computer-intensive and more vulnerable to failure. In contrast to dichotomous outcomes, PQL often performs as well as numerical integration when the outcome is ordinal (Bauer & Sterba, 2011). When numerical integration is used, its performance can be improved by paying careful attention to the explanatory variables. Outliers and using variables that differ widely in scale increase the risk of nonconvergence. In addition, centering explanatory variables with random slopes to make sure that zero is an interpretable value is important. The next section presents an example where these issues are present.

It should be noted that the proportional odds assumption is often violated in practice. An informal test of the assumption of parallel regression lines is made by transforming the ordered categorical variable into a set of dummy variables, following the cumulative probability structure. Thus, for an outcome variable with C categories, $C - 1$ dummies are created. The first dummy variable equals 1 if the response is in category 1, and 0 otherwise. The second dummy variable equals 1 if the response is in category 2 or 1, and 0 otherwise. And so on until the last dummy variable which equals 1 if the response is in category $C - 1$ or lower, and 0 if the response is in category C . Finally, independent regressions are carried out on all dummies, and the null-hypothesis of equal regression coefficients is informally assessed by inspecting the estimated regression coefficients and their standard errors. Long (1997) gives an example of this procedure and describes a number of formal statistical tests.

There are a number of alternatives for the proportional odds model. Hedeker and Mermelstein (1998) describe a multilevel model that relaxes the proportional odds assumption, by modeling the thresholds separately. This allows predictors to have varying

effects across different cut points. Other approaches include adding interactions with the thresholds to the model, or analyzing the ordinal data with a multinomial model, using only the categorical nominal information. Adjacent category or continuation-ratio logits are other options. These are well-known in the single-level regression literature, but their extension to the multilevel case and implementation in software is limited. If there are only a few predictors that fail to satisfy the proportional odds assumption, it may be possible to use a partial proportional odds model, where most predictors do meet that assumption, but a few do not (Hedeker & Mermelstein, 1998).

7.1.3 Example of Ordered Categorical Data

Assume that we undertake a survey to determine how characteristics of streets affect feelings of being unsafe in people walking these streets. A sample of 100 streets is selected, and on each street a random sample of 10 persons is asked how often they feel unsafe while walking that street. The safety is asked using three answer categories: 1 = never, 2 = sometimes, 3 = often. Predictor variables are age and gender, street characteristics are an economic index (standardized Z-score) and a rating of the crowdedness of the street (7-point scale). The data have a multilevel structure with people nested in streets.

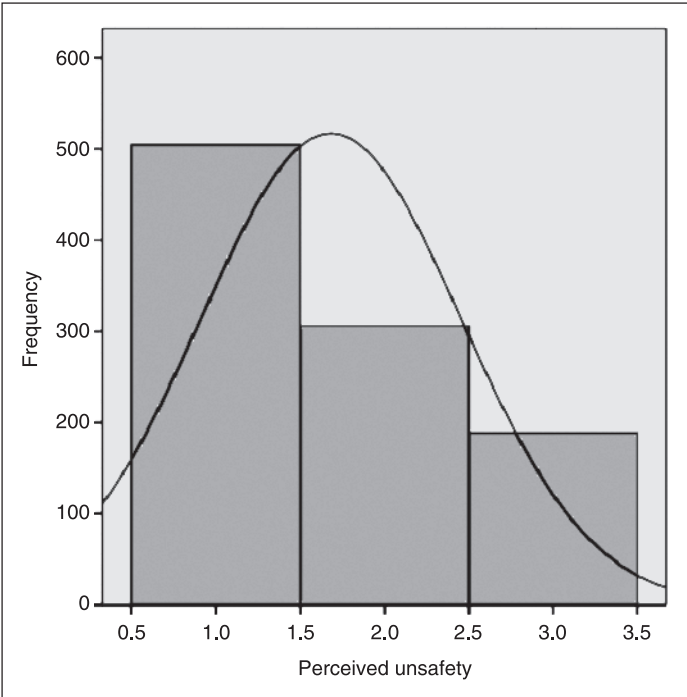


Figure 7.2 Histogram of outcome variable Feeling Unsafe.

Figure 7.2 shows the distribution of the outcome variable. In addition to having only three categories, it is clear that the distribution is not symmetric. Treating this outcome as continuous is not proper.

These data have some characteristics that make estimation unnecessarily difficult. The respondents' age is recorded in years, and ranges from 18–72. This range is much different from the range of the other variables. In addition, zero is not a possible value in age and crowdedness. To deal with these issues, the variable age is divided by 10, and all explanatory variables (including sex and age) are centered. Using the exploration strategy proposed earlier (Chapter 4), it turns out that all explanatory variables are significant, and that age has significant slope variation across streets. However, this variation cannot be explained by economic status or crowdedness. Table 7.1 presents the results of the final model, once for the logit and once for the probit model. Estimates were made with full ML, using numerical integration in SuperMix.

Table 7.1 Results logit and probit model for unsafety data

Model	Logit	Probit
Fixed part		
Predictor	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	−0.02 (.09)	−0.02 (.06)
Threshold 2	2.02 (.11)	1.18 (.06)
Age/10	0.46 (.07)	0.27 (.04)
Sex	1.23 (.15)	0.72 (.09)
Economic	−0.72 (.09)	−0.42 (.05)
Crowded	−0.47 (.05)	−0.27 (.03)
Random part		
Intercept	0.26 (.12)	0.10 (.04)
Age/10	0.20 (.07)	0.07 (.02)
Int/age	−0.01 (.07)	−0.00 (.02)
Deviance	1718.58	1718.08

In terms of interpretation the two models are equivalent. The coefficients and the standard errors are on average 1.7 times larger in the logit model than in the probit model. The variances and their standard errors are 2.73 times larger, which is approximately 1.65 squared. The probit model is simple to interpret, since the underlying scale has a standard deviation of 1. So, an increase in age by 10 years increases the feelings of being unsafe by approximate one-fourth of a standard deviation, which is a relatively small effect. On the other hand, the difference between men and women on the underlying scale is about 0.7

standard deviation, which is a large effect. On the logit scale, the interpretation is often in terms of the odds. Thus, the odds ratio corresponding to the regression coefficient of 0.46 for age / 10 is $e^{0.46} = 1.59$. Thus, an increase of 10 years results in the odds for being in response category c and higher compared to $c-1$ and lower are 1.59 times larger. So with every 10 years, the odds of being in the ‘often’ category versus the ‘never’ or ‘sometimes’ categories are 1.59 times higher. Note that the change in odds is independent of the specific response category, which follows from the proportional odds assumption.

To gain some insight in the effect of different estimation strategies, Table 7.2 presents the same results for the logit model only, where the estimation methods are varied. The first column contains the estimates produced using Taylor series expansion (using HLM, first order PQL). The second column contains the estimates using numerical integration with SuperMix, the third column contains the estimates using numerical integration with Mplus, which uses a different estimation algorithm.

All estimates in Table 7.2 are close. The Taylor series linearization in HLM produces estimates that are a bit smaller than the numerical integration methods do. For dichotomous data it has been shown that the Taylor series approach tends to have a small negative bias (Breslow & Lin, 1995; Raudenbush et al., 2000; Rodriguez & Goldman, 1995). The estimates in Table 7.2 suggest that the same bias occurs in modeling ordered data. Nevertheless, the estimates produced by Taylor series approximation for the unsafety data are very close to the

Table 7.2 Results unsafety data with different estimation methods

Estimation	Taylor series (HLM)	Numerical (SuperMix)	Numerical (Mplus)
Fixed part			
Predictor	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept/threshold	−0.01 (.09)	−0.02 (.09)	0.02 (.09)
Threshold 2	1.96 (.10)	2.02 (.11)	2.04 (.12)
Age/10	−0.42 (.06)	0.46 (.07)	0.46 (.07)
Sex	−1.15 (.14)	1.23 (.15)	1.22 (.14)
Economic	0.68 (.09)	−0.72 (.09)	−0.72 (.09)
Crowded	0.44 (.05)	−0.47 (.05)	−0.47 (.05)
Random part			
Intercept	0.21 (.26)	.12 (.26)	.07
Age/10	0.16 (.20)	.07 (.20)	.07
Int/age	−0.01 (−.01)	.07 (−.01)	.07
Deviance		1718.58	1718.59
AIC		1736.58	1736.59
BIC		1780.75	1780.76

other estimates, and the differences would not lead to a different interpretation. The estimates produced by the numerical integration in SuperMix and Mplus are essentially identical. HLM does not give standard errors for the random part, but the chi-square test on the residuals (see Chapter 3 for details) shows that both the intercept and the slope variance are significant.

Table 7.2 also illustrates the effect of different choices for the model parameterization. HLM uses the proportional odds model as presented in Equation 7.8. This models the probability of being in category c or lower against being in the last category $c = C$. Thus, the regression coefficients have a sign that is opposite to the sign in an ordinary regression model. SuperMix and Mplus use the model as presented in Equation 7.10, where the linear predictor in the generalized regression model is multiplied by -1 to restore the signs of the regression coefficients. A small difference between SuperMix and Mplus is that SuperMix transforms the thresholds as described above, and Mplus does not. So the first row in the fixed part shows the intercept for SuperMix, and threshold 1 for Mplus. If we subtract 0.02 from both thresholds in the Mplus column, the first becomes 0 and the second becomes identical to threshold 2 in the SuperMix column. All these model parameterizations are equivalent, but the opposite signs of the regression coefficients in Table 7.2 show the importance of knowing exactly what the software at hand actually does.

7.2 COUNT DATA

Frequently the outcome variable of interest is a count of events. In most cases count data do not have a nice normal distribution. A count cannot be lower than zero, so count data always have a lower bound at zero. In addition, there may be a number of extreme values, which often results in a long tail at the right and hence skewness. When the outcome is a count of events that occur frequently, these problems can be addressed by taking the square root or in more extreme cases the logarithm. However, such nonlinear transformations change the interpretation of the underlying scale, so analyzing counts directly may be preferable. Count data can be analyzed directly using a generalized linear model. When the counted events are relatively rare they are often analyzed using a Poisson model. Examples of such events are frequency of depressive symptoms in a normal population, traffic accidents on specific road stretches, or conflicts in stable relationships. More frequent counts are often analyzed using a negative binomial model. Both models will be presented in the next section.

7.2.1 The Poisson Model for Count Data

In the Poisson distribution, the probability of observing y events ($y = 0, 1, 2, 3, \dots$) is

$$\Pr(y) = \frac{\exp(-\lambda)\lambda^y}{y!}, \quad (7.11)$$

where \exp is the inverse of the natural logarithm. Just like the binomial distribution, the Poisson distribution has only one parameter, the event rate l (lambda). The mean and variance of the Poisson distribution are both equal to l . As a result, with an increasing event rate, the frequency of the higher counts increases, and the variance of the counts also increases, which introduces heteroscedasticity. An important assumption in the Poisson distribution is that the events are independent and have a constant mean rate (l). For example, counting how many days a pupil has missed school is probably not a Poisson variate, because one may miss school because of an illness, and if this lasts several days these counts are not independent. The number of typing errors on randomly chosen book pages is probably a Poisson variate.

The Poisson model for count data is a generalized linear regression model that consists of three components:

- 1 an outcome variable y with a specific error distribution that has mean μ and variance σ^2 ,
- 2 a linear additive regression equation that produces a predictor η of the outcome variable y ,
- 3 a *link function* that links the expected values of the outcome variable y to the predicted values for η : $\eta = f(\mu)$.

For counts, the outcome variable is often assumed to follow a Poisson distribution with event rate l . The Poisson model assumes that the length of the observation period is fixed in advance (constant exposure), that the events occur at a constant rate, and that the number of events in disjoint intervals are statistically independent. The multilevel Poisson model deals with certain kinds of dependence. The model can be further extended by including a varying exposure rate m . For instance, if book pages have different numbers of words, the distribution of typing errors would be Poisson with exposure rate the number of words on a page. In some software the exposure variable just needs to be specified. If this is not possible, the exposure variable is added as a predictor variable to the model, including a log transformation $\ln(m)$ to put it on the same scale as the latent outcome variable η . Such a term is called the *offset* in the linear model, and usually its coefficient is constrained equal to one (McCullagh & Nelder, 1989).

The multilevel Poisson regression model for a count Y_{ij} for person i in group j can be written as:

$$Y_{ij} | \lambda_{ij} = \text{Poisson}(m_{ij}, \lambda_{ij}). \quad (7.12)$$

The standard link function for the Poisson distribution is the logarithm, and

$$\eta_{ij} = \ln(\lambda_{ij}). \quad (7.13)$$

The first-level and second-level model is constructed as usual, so

$$\eta_{ij} = \beta_{0j} + \beta_{1j}X_{ij}, \quad (7.14)$$

and

$$\begin{aligned} \beta_{0j} &= \gamma_{00} + \gamma_{01}Z_j + u_{0j} \\ \beta_{1j} &= \gamma_{10} + \gamma_{11}Z_j + u_{1j}, \end{aligned} \quad (7.15)$$

giving

$$\eta_{cij} = \gamma_{00} + \gamma_{10}X_{ij} + \gamma_{01}Z_j + \gamma_{11}X_{ij}Z_j + u_{0j} + u_{1j}X_{ij}. \quad (7.16)$$

Since the Poisson distribution has only one parameter, its variance is equal to the mean. Estimating an expected count implies a specific variance. Therefore, just as in logistic regression, the first-level equations do not have a lowest-level error term. In actual practice, we often find that the variance exceeds its expected value. In this case we have overdispersion. In more rare cases we may have underdispersion. Underdispersion often indicates a misspecification of the model, such as the omission of large interaction effects. Overdispersion can occur if there are extreme outliers, or if we omit an entire level in a multilevel model. In binomial models, very small group sizes (around three or fewer) also lead to overdispersion (Wright, 1997); this is likely to be also the case in Poisson models. A different issue is the problem of having many more zero counts than expected. This problem is dealt with later in this chapter. If the variance is clearly larger than the mean, the negative binomial model can be used, which estimates a separate variance parameter.

Example of count data

Skrondal and Rabe-Hesketh (2004) discuss an example where 59 patients who suffer from epileptic seizures are followed on four consecutive visits to the clinic. There is a baseline count of the number of epileptic seizures in the two weeks before the treatment starts. After the baseline count, the patients are randomly assigned to a treatment (drug) and a control (placebo) condition. One additional variable is the patients' age. Because the link function is the logarithm, the baseline seizure count and age are log-transformed, and subsequently centered around their grand mean.

Figure 7.3 shows the frequency distribution of the seizures, which is evidently not normally distributed. The mean number of seizures is 8.3 and the variance is 152.7, which casts serious doubt on the applicability of the Poisson model. However, the histogram also shows some extreme outliers. Skrondal and Rabe-Hesketh (2004) discuss these data in more detail, pointing out how inspection of residuals and related procedures provide information about the model fit.

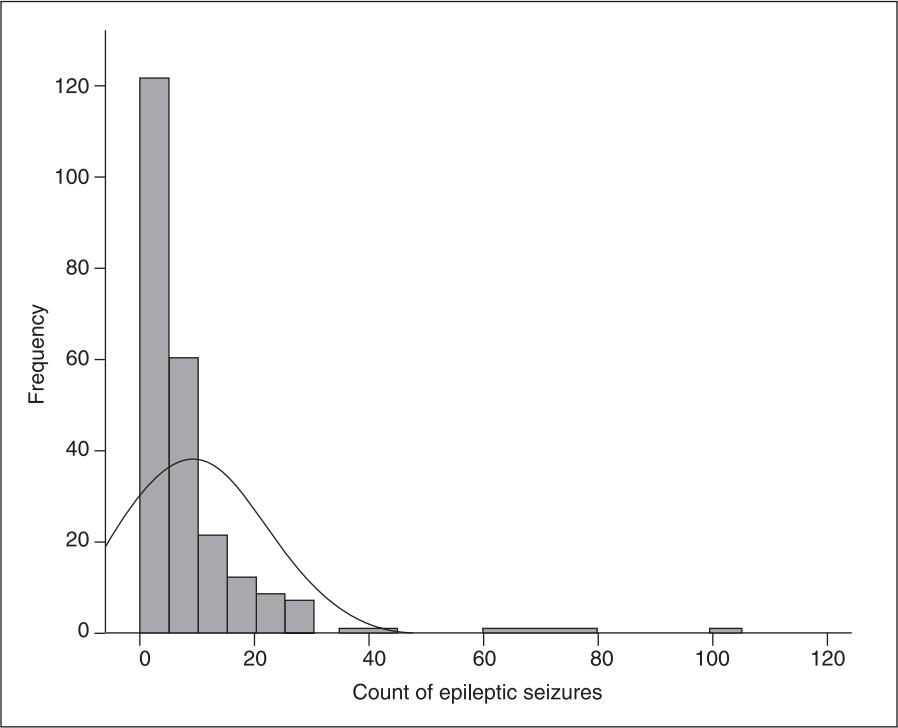


Figure 7.3 Frequency distribution of epileptic seizures.

Table 7.3 Results of epilepsy data with different estimation methods

Estimation	Taylor series (HLM)	Taylor series (HLM)	Numerical (HLM)
Fixed part			
Predictor	Coefficient (s.e.) ^r	Coefficient (s.e.) ^r	Coefficient (s.e.) ^r
Intercept	1.82 (.09)	1.83 (.09)	1.80 (.13)
Log baseline	1.00 (.10)	1.00 (.11)	1.01 (.10)
Treatment	−0.33 (.15)	−0.30 (.15)	−0.34 (.16)
Random part			
Intercept	0.28	0.26	0.27
Overdispersion		1.42	

r indicates robust standard error used

Table 7.3 presents the results of a multilevel Poisson regression analysis of the epilepsy data. We omit the age variable, which is not significant. Given the heterogeneity in the data, robust standard errors are used where available. HLM does not give standard errors for the random part, but the chi-square test on the residuals (see Chapter 3 for details) shows that the intercept variance is significant. The three different analyses result in very similar estimates. A fourth analysis with SuperMix (not presented here), which uses a different type of numerical approximation than HLM, results in virtually the same estimates as the HLM numerical approach presented in the last column. Note that HLM does not allow overdispersion with the numerical approximation. SuperMix also does not allow an overdispersion parameter in the model, but it can also estimate models for count data using a negative binomial model. This is an extension of the Poisson model that allows extra variance in the counts.

With all estimation methods the baseline measurement has a strong effect, and the treatment effect is significant at the 0.05 level. To interpret the results in Table 7.3, we need to translate the estimates on the log scale to the observed events. The log baseline is centered, and the control group is coded 0, so the intercept refers to the expected event rate for the control group. Using the estimates in the last column, we take $Y = e^{1.8} = 6.05$ as the event rate in the control group. In the experimental group we take $Y = e^{(1.8-0.34)} = 4.31$ as the event rate. On average, the drug lowers the event rate by 28.8 percent of the event rate in the untreated control group.

7.2.2 The Negative Binomial Model for Count Data

In the Poisson model, the variance of the outcome is equal to the mean. When the observed variance is much larger than expected under the Poisson model, we have overdispersion. One way to model overdispersion is to add an explicit error term to the model. Thus, for the Poisson model we have the link function (see Equation 7.13 $\eta_{ij} = \text{Ln}(\lambda_{ij})$), and the inverse is $\lambda_{ij} = \exp(\eta_{ij})$, where η_{ij} is the outcome predicted by the linear regression model. The negative binomial adds an explicit error term ε to the model, as follows:

$$\lambda_{ij} = \exp(\eta_{ij} + \varepsilon_{ij}) = \exp(\eta_{ij})\exp(\varepsilon_{ij}). \quad (7.17)$$

The error term in the model increases the variance compared to the variance implied by the Poisson model. This is similar to adding a dispersion parameter in a Poisson model; a detailed description of the single-level negative binomial model is given by Long (1997). When the epilepsy data are analyzed with the negative binomial model, the estimates are very close to the results in the last column of Table 7.3. The variance parameter is 0.14 (s.e. = 0.04, $p = 0.001$). The subject-level variance is a bit lower at 0.24, which is reasonable given that in the negative binomial model there is more variance at the event-level than in the Poisson model presented in Table 7.3. Given that the negative binomial model is

a Poisson model with an added variance term, the test on the deviance can be used to assess whether the negative binomial model fits better. The negative binomial model cannot directly be compared to the Poisson model with overdispersion parameter, because these models are not nested. However, the AIC and BIC can be used to compare these models. Both the AIC and the BIC are smaller for the Poisson model with overdispersion than for the negative binomial model.

7.2.4 Too Many Zeros: The Zero-Inflated Model

When the data show an excess of zeros compared to the expected number under the Poisson distribution, it is sometimes assumed that there are two processes that produce the data. Some of the zeros are part of the event count, and are assumed to follow a Poisson model (or a negative binomial). Other zeros are part of the event taking place or not, a binary process modeled by a binomial model. These zeros are not part of the count, they are structural zeros, indicating that the event *never* takes place. Thus, the assumption is that our data actually include two populations, one that always produces zeros and a second that produces counts following a Poisson model. For example, assume that we study risky behavior, such as using drugs or having unsafe sex. One population never shows this behavior, it is simply not part of their behavior repertoire. These individuals will always report a zero. The other population consists of individuals who do have this behavior in their repertoire. These individuals can report on their behavior, and these reports can also contain zeros. An individual may sometimes use drugs, but just did not do this in the time period surveyed. Models for such mixtures are referred to as zero-inflated Poisson or ZIP models. For the count part of the model we use a standard regression model, for instance assuming a Poisson or a negative binomial distribution; and for the probability of being in the population that can produce only zeros we use a standard logistic regression model. Both models are estimated simultaneously. Table 7.4 presents the results for a multilevel Poisson and a multilevel zero-inflated Poisson model for the epilepsy data (estimation using Mplus).

Both the AIC and the BIC indicate that the ZIP model is better, although the parameter estimates for the Poisson model change very little. There is an extra parameter: the intercept of the inflation part. In the ZIP model reported in Table 7.4, there are no explanatory variables that predict the probability of being in the always zero class. As a result, the intercept indicates the average probability of being in that class. A large value of the intercept indicates a large fraction of ‘always zero’. The model for the inflation part is a logistic model, so the intercept value of -3.08 is on the underlying logit scale. Translating it to a proportion using the inverse of the logit transformation (introduced in Chapter 6), we find

$$\hat{p} = \frac{e^{3.08}}{1 + e^{3.08}} = 0.044, \quad (7.18)$$

Table 7.4 Results for epilepsy data: Poisson and zero inflated Poisson

Estimation	Poisson	ZIP
Fixed part		
Predictor	Coefficient (s.e.) ^r	Coefficient (s.e.) ^r
Intercept	1.80 (.09)	1.87 (.09)
Log baseline	1.01 (.11)	0.99 (.11)
Treatment	−0.34 (.15)	−0.35 (.15)
Inflation intercept		−3.08 (.49)
Random part		
Intercept	0.28 (.07)	0.25 (.06)
Deviance	1343.20	1320.29
AIC	1351.20	1330.29
BIC	1365.05	1347.61

r indicates robust standard error used

which shows that the fraction of ‘always zero’ in the epilepsy data is very small. In the epilepsy data set, 9.7 percent of the subjects reports zero seizures. Using Equation 7.18, we can now estimate that 4.4 percent have zero seizures, meaning that their epilepsy is totally suppressed, and 5.3 percent of the subjects merely happen to have no seizures in the period surveyed.

The ZIP model reported in Table 7.4 does not include predictors for the inflation part. It is possible to expand the inflation model, which is a logistic model similar to the models discussed in Chapter 6, by including predictors. In this particular data set, the available predictors do not predict the zero inflation, and the AIC and BIC indicate that the ZIP model without predictors for the inflation part is preferable.

Empirical data often exhibit either overdispersion or an excess of zeros, and choosing the best distributional model is an important part of the modeling process (cf. Gray, 2005 for an example).

Just like the Poisson model, the negative binomial model can also be extended to include an inflated numbers of zeros. Lee, Wang, Scott, Yau and McLachlan (2006) provide a discussion of the multilevel Poisson model for data with an excess of zeros, and Moghimbeigi, Esraghian, Mohammad and McArdle (2008) discusses negative binomial models for such data. In the epilepsy example data, adding a zero-inflation part to the negative binomial model turns out to be superfluous, the latent class of extra zeros is estimated as very small, and the AIC and BIC indicate that the negative binomial model without zero inflation is preferable.

7.3 EXPLAINED VARIANCE IN ORDERED CATEGORICAL AND COUNT DATA

In generalized linear models, there is no real equivalent to the multiple correlation in linear regression. If numerical integration is used, we can use the pseudo- R^2 s based on the deviance, as discussed for logistic regression in Chapter 6. In Chapter 6 we expressed a preference for McFadden's pseudo- R^2 which is easily calculated as

$$R_{MF}^2 = 1 - \frac{Deviance_{model}}{Deviance_{null}}, \quad (6.25, \text{repeated})$$

because it is simple to calculate and can be expanded to distinguish between different levels. The method proposed by McKelvey and Zavoina (1975) is superior, but it requires some follow-up analyses and calculations. For details we refer to Chapter 6. In the McKelvey and Zavoina approach the explained variance is given by

$$R_{MZ}^2 = \frac{\sigma_F^2}{\sigma_F^2 + \sigma_{u0}^2 + \sigma_R^2}, \quad (6.26, \text{repeated})$$

where σ_F^2 is the variance of the linear predictor, σ_{u0}^2 is the second-level estimated variance, and σ_R^2 is the variance implied by the error distribution. Ordered categorical regression uses the logit or the probit distribution, with distributional variance of 3.29 and 1.00 respectively. In count models, the Poisson distribution has a distributional variance equal to the mean, which can be estimated in the intercept-only model. The negative-binomial also has a variance equal to the mean, plus an extra lowest-level variance that is estimated.

In Chapter 6 we describe methods to assess explanatory power using the linear predictor to predict the observed outcomes. In the unsafety data, which are ordinal categorical (three categories), we can calculate the linear predictor, and categorize it into three categories according to the percentages '1', '2' and '3' in the observed data. Of the 189 respondents in category 3 (very often), 84 (44.4 percent) were correctly classified. The (ordinal) Spearman correlation between the observed and predicted categories is 0.45, and the Spearman correlation between the observed categories and the linear predictor is 0.51. The explanatory power of the final model is quite high.

In the epilepsy data, there is no need to categorize the linear predictor (the observed counts can be viewed as continuous). The Spearman correlation between the linear predictor and the epilepsy counts is 0.69. Unfortunately, this is almost entirely due to the baseline count; the correlation between the baseline count and the observed counts is 0.67, and the correlation between the treatment and the observed counts is -0.12 . This indicates a weak relationship between treatment and epilepsy rate. At the end of section 7.2.1, using estimates from the Poisson model, we estimated the average event rate in the control group as 6.05, and in the treatment group as 4.31, which is 28 percent lower. Although in terms of explained variance this effect is dwarfed by the effect of the baseline count, this difference may well be clinically important or have a large effect on the well-being of the patients (remember these are real data).

7.4 THE EVER-CHANGING LATENT SCALE, AGAIN

Just as in logistic and probit regression, also in ordered categorical and count models the scale of the latent outcome variable implicitly changes when the model is changed. The lowest-level residuals are in each separate model scaled to the variance of the standard distribution, as described in Section 7.3 earlier. Thus, with some changes in calculating the lowest-level residual variance, all procedures discussed in Section 6.5 for standardizing regression coefficients also apply to the ordered and count data discussed in this chapter.

7.5 SOFTWARE

The software issues are similar to the issues with the multilevel logistic or probit models for dichotomous data and proportions, discussed in Chapter 6 (Section 6.7). If available, numeric estimation methods are generally more accurate than the MQL or PQL linearization methods. This is especially the case if group sizes are small and the interclass correlation is high. For multilevel generalized linear regression methods, analysis should check what estimation choices are available in their software of choice.

8

Multilevel Survival Analysis

SUMMARY

Survival analysis or event history analysis is a set of methods for modeling the length of time until the occurrence of some event. The term ‘survival analysis’ is used most often in biomedical applications where the event of interest is not repeatable, such as studies where the length of time until relapse or loss of life is modeled as a function of some independent variables, often including a treatment indicator. Failure analysis and hazard modeling are related terms. In social research, more neutral terms like event history analysis or duration analysis are commonly used. This chapter uses the term survival analysis to refer to all of these methods. An important feature of survival data is that for some cases the final event is not yet observed by the end of the study, and such observations are said to be censored. Censoring can also occur during the course of the study when subjects leave for other reasons than event occurrence. This chapter provides a brief introduction to survival analysis, and shows how standard survival analysis can be extended to include multilevel data structures. The discussion of survival analysis here is limited to models for discrete time.

8.1 SURVIVAL ANALYSIS

Survival analysis concerns the analysis of the occurrence of events over time and of the length of time it takes for their occurrence. Examples of events are marriage, entry into parenthood, getting a job, or dropping out of school. The time of event occurrence can be measured either continuously or discretely. With the continuous-time approach the exact time of event occurrence can be measured, or at least very thin and precise time units can be used. The discrete-time approach discretizes the time scale using multiple consecutive coarse time intervals, such as weeks, months or years, and at the end of each time interval it is recorded whether a respondent experienced the event within that time interval. This implies it is known the event occurred within a certain time interval but the exact time is unknown. This results in a loss of information, and a careful justification for measuring time discretely rather than continuously should be given. In retrospective studies memory failure may play a role and respondents may not be able to remember the exact time of event occurrence, while in prospective studies measuring too often is not always feasible from an ethical, financial or cost-effective point of view. The approach that treats time discretely is

analogous to longitudinal data with fixed occasions and the one that treats time continuously is analogous to longitudinal data with varying occasions.

Unless the duration data are actually collected at regular fixed occasions, treating time as a discrete fixed variable appears to be an inferior approach, although the effect on statistical power is small (Moerbeek & Schormans, 2015). Several approaches to continuous duration data have been developed, of which the Kaplan–Meier method (1958) and the Cox method (Cox, 1972) are most widely used. The Kaplan–Meier method uses the grouped time method, but extends this by putting each observed duration value into its own interval. Discrete-time survival data can simply be analyzed by means of generalized linear models for dichotomous or ordinal data and the appropriate techniques are treated in detail in Singer and Willett (2003). The focus of this chapter is on discrete-time (or grouped-time) survival analysis and the survival data are said to be interval censored.

A central issue in survival or event history data is that observations may arise where the occurrence of an event has not yet been observed, because the subject left the study prematurely or because the study ended at a point in time before the event could be observed. For these subjects, the survival time is unknown; these observations are said to be censored. More precisely, these observations are right-censored: the event has not yet occurred at the end of the observation period. Simply excluding these observations is not an acceptable solution. Imagine that in a longitudinal study of marriage duration we exclude all respondents that are still married at the end of the data collection period. Estimates of average marriage duration would obviously be biased downward, and we would have discarded a large fraction of our sample. Thus, the goal of survival analysis is to obtain unbiased estimates of expected duration, including relevant predictor variables, and incorporating censored observations. This can only be achieved when the censoring mechanism is non-informative, which implies subjects only leave the study for other reasons than event occurrence. In that case those subjects who remain in the study until its end are representative of those who would have remained in the study had censoring been absent.

The grouped time approach categorizes the time variable into a relatively small number of time intervals. In the approach in this section the intervals are assumed to be of equal length. For each time interval, the hazard and survival probabilities are determined. These probabilities can be summarized in life tables, and various statistics are available to summarize the survival and hazard probability function for the entire group or for subgroups. The hazard probability $h(t_{ij})$ for subject i is the probability of experiencing the event within time interval t conditional on not having experienced the event before this time interval:

$$h(t_i) = P(T_i = t | T_i \geq t). \quad (8.1)$$

Here, T_i is a discrete random variable for time whose value indicates the time interval in which subject i experiences the event. It is a conditional probability since it is conditional on not having experienced the event before time interval t . This implicitly implies the focus is on single events and not on recurring events (such as remarriage after divorce or relapse to alcohol abuse after a period of abstinence). The hazard probability is estimated from the data as follows

$$\hat{h}(t) = \frac{\text{number of events in time interval } t}{\text{number at risk in time interval } t}. \quad (8.2)$$

The hazard probability can vary widely across the time intervals and later in this section various approaches to model time in a statistical model are discussed.

The survival probability is the probability of surviving past time period t :

$$S(t) = P(T_i > t). \quad (8.3)$$

At the beginning of a study it is equal to 1, which implies all subjects are at risk of experiencing the event. In other words, they are in a certain state (e.g. never having smoked) and are at risk of transitioning to another state (e.g. ever having smoked). The focus is on two non-overlapping states. In other words: we do not focus on competing risk events where three or more states are considered. An example of competing risks can be found in education, where a student can either graduate from college or drop-out (without graduation).

The survival probability is estimated from the data as

$$\hat{S}(t) = \frac{\text{number at risk in the study} - \text{number of events by the end of time interval } t}{\text{number at risk in the study}}. \quad (8.4)$$

During the course of the study subjects experience the event, which implies the survival probability function declines across time. The decline is largest in those time intervals with highest hazard probability. The survival and hazard probability are related as follows

$$S(t) = S(t-1) \times (1 - h(t)). \quad (8.5)$$

The survival probability at the end of time period t is the survival probability at the end of time period $t-1$ (i.e. at the beginning of time period t) multiplied by the probability of event non-occurrence during time period t . The hazard probability function assesses the unique risk within each time period, while the survival probability function cumulates the risk of event non-occurrence across time.

The survival model is basically a model for the hazard probability function. The hazard probability is modeled by covariates X_{it} which can be time-invariant or time-varying. Since it is a probability, the hazard probability function is bounded between

zero and one. Therefore, a linear model is not suitable, and a generalized linear model is used, with an appropriate link function to transform the hazard probability. For a given link function g we have:

$$g(h(t | X_{it})) = \alpha_t + \beta_1 X_{it}, \quad (8.6)$$

where α_t are time-specific intercepts that represent the baseline hazard probability. Thus, each interval has its own intercept α_t . Inspection of the baseline hazard probability reveals in which time period(s) the risk of event occurrence is largest and how it develops across time. This can serve as a basis to identify those time periods in which the need for interventions to prevent or delay unwanted behavior (such as smoking initiation) is most needed.

If the link function g is the logit function, the corresponding model is the proportional odds model:

$$\ln\left(\frac{h(t|x_{it})}{1-h(t|x_{it})}\right) = \alpha_t + \beta_1 X_{it}. \quad (8.7)$$

Another link function used in survival modeling is the complementary log-log function given by $g = -\ln(-\ln(1 - h(t)))$. The complementary log-log link is suggested for studies where the underlying survival process is continuous but observations are made in discrete time periods, while the logit link is more suitable for studies that are truly discrete in time and in which events can only occur at some pre-set points in time, such as graduation at the end of each term (Singer & Willett, 2003).

In the proportional odds model given by Equation 8.7, a unit change in covariate X_{it} produces a β_1 change in the logit of the hazard probability, and this effect is independent of the time interval. In other words, there is no interaction between time and the effect of the covariate X_{it} . This is a strong assumption and it may be worthwhile to verify if a non-proportional odds model, with time-varying effects of the covariate, has a better fit. In addition to that, the model may be extended by including more covariates and their interactions.

If there are a large number of distinct time points, there are as many time-specific intercepts α_t , which leads to a large model with many parameters. To make the model more parsimonious, in such cases the time-specific intercepts are approximated by a function of the time variable t , for instance a high-degree polynomial. Since T distinct time points can be fitted perfectly by a polynomial of degree $T - 1$, the model with a polynomial of degree $R < T - 1$ is nested in the model with T time-specific intercepts, and the chi-square difference test on the deviance can be used to test whether a polynomial of degree R is sufficient. Thus, the T time-specific intercepts are replaced by a regression equation of the form:

$$\alpha_t = \gamma_0 + \gamma_1 t + \dots + \gamma_{T-1} t^{T-1}. \quad (8.8)$$

As an example we use a data set collected by Capaldi, Crosby and Stoolmiller (1996) and discussed in depth by Singer and Willett (2003). This example shows how a survival model can be viewed as a special multilevel model, after which the extension to more levels is straightforward. The data were a sample of 180 boys who were tracked from the 7th grade (approximate age 12 years) until the 12th grade (approximate age 17) and measurements were taken once each year. The event of interest was time to first heterosexual sexual intercourse; in the 12th grade 30 percent of the boys were still virgins, meaning that these observations are censored. None of the boys left the study for other reasons than event occurrence prior to the end of the study.

In our example, we used one time-invariant predictor, a dummy variable indicating whether before the 7th grade the boys had experienced a parental transition (coded 1) or had lived with both parents during these years (coded 0). The interest was in the question of whether the time to first sexual intercourse was the same for both groups.

Figure 8.1 shows the data file in a standard ‘normal’ format, with one line of data for each subject. The variable *grade* records the grade in which the event occurs, after which observation stops. If the event has not occurred by the 12th grade, the grade recorded is 12, and the observation is coded as censored. The variable *partrans* indicates whether a parental transition had occurred before grade 7 or not. To analyze these data in standard logistic regression software, the data must be restructured to the ‘person–period’ format shown in Figure 8.2. In Figure 8.2, each row in the data corresponds to a specific person and grade combination, and there are as many rows as there are times (grades) to either the event or censoring. There are several data lines for each subject, similar to the ‘long’ data format used in longitudinal modeling (Chapter 5). To model the baseline hazard probability in each grade, six dummies have been added to indicate each of the six grades.

person	grade	censor	partrans
1	9	0	0
2	12	1	1
3	12	1	0
5	12	0	1
6	11	0	0
7	9	0	1
9	12	1	0
10	11	0	0
11	12	1	1
12	11	0	1

Figure 8.1 Normal data file for survival data.

person	period	event	grade7	grade8	grade9	grade10	grade11	grade12	partrans
1	7	0	1	0	0	0	0	0	0
1	8	0	0	1	0	0	0	0	0
1	9	1	0	0	1	0	0	0	0
2	7	0	1	0	0	0	0	0	1
2	8	0	0	1	0	0	0	0	1
2	9	0	0	0	1	0	0	0	1
2	10	0	0	0	0	1	0	0	1
2	11	0	0	0	0	0	1	0	1
2	12	0	0	0	0	0	0	1	1
3	7	0	1	0	0	0	0	0	0
3	8	0	0	1	0	0	0	0	0
3	9	0	0	0	1	0	0	0	0
3	10	0	0	0	0	1	0	0	0
3	11	0	0	0	0	0	1	0	0
3	12	0	0	0	0	0	0	1	0
5	7	0	1	0	0	0	0	0	1
5	8	0	0	1	0	0	0	0	1
5	9	0	0	0	1	0	0	0	1
5	10	0	0	0	0	1	0	0	1
5	11	0	0	0	0	0	1	0	1

Figure 8.2 Person–period format of survival data.

Both Equation 8.5 and the structure of the data in Figure 8.2 suggest a multilevel approach to these longitudinal data. However, multilevel modeling of within-person variation that consists of a long series of zeros followed (sometimes) by a single *one* leads to estimation problems. The data as given in Figure 8.1 can be modeled using special survival analysis software. It is also possible to use standard logistic regression software, where the dependencies in the data are dealt with by adding the period dummies to the model (Figure 8.2). If there are many periods, there will be many dummies. In that case, the baseline hazard probabilities (the period-specific intercepts) are approximated by a smooth function of time, such as a polynomial function of time.

8.2 MULTILEVEL SURVIVAL ANALYSIS

The discrete or grouped survival model extends readily to multilevel models (see Barber et al., 2000; Reardon et al., 2002; Grilli, 2005), and this chapter restricts itself to an exposition of this model. As an example, we use a data set about divorce risk, which was analyzed earlier by Dronkers and Hox (2006). The data are described in more detail in Appendix A. The data set consists of longitudinal data where respondents were asked repeatedly about live events, such as marriages, divorces, and child births. In addition to their own history,

	famid	respid	lengthm	lengthc	divorce	status	educlev	gender	birthyr	famsize	kid
1	1	2	35	4	0	50.6	10.1	1	38	5	1
2	1	3	29	4	0	100.0	12.0	0	36	5	1
3	1	4	41	4	0	50.6	10.1	1	32	5	1
4	4	5	16	3	0	18.0	8.9	1	56	3	1
5	5	9	39	4	0	14.0	0.0	1	28	5	1
6	5	10	41	4	0	14.0	8.9	1	25	5	1
7	5	11	32	4	1	37.0	8.9	0	28	5	1
8	13	13	49	4	0	50.6	3.9	0	18	10	1
9	27	21	29	4	0	60.0	10.1	1	43	3	1
10	32	29	34	4	0	18.0	8.9	0	30	2	1
11	33	33	23	3	0	37.0	8.9	0	44	3	1
12	33	34	24	4	0	50.6	8.9	0	46	3	1
13	33	35	16	3	0	50.6	12.0	1	50	3	1
14	34	37	43	4	0	14.0	12.0	1	24	5	1

Figure 8.3 Divorce example data (partial)

respondents were also asked to provide information on up to three siblings. The data set analyzed here includes only data on the first marriage.

Figure 8.3 shows part of the data. There are respondents nested within families. There is a duration variable *lengthm* (length of marriage in years), which indicates the time when the last observation is made, and a variable indicating if the subject has divorced. If the last observed value for divorced equals zero, that observation is censored. Other variables indicate the respondent's occupational status, educational level, gender (female = 1), parental family size, whether the respondent has kids, educational level of mother and father, and the proportion of siblings that are divorced. The research problem involved the question whether divorce risks are similar for children from the same family (siblings) and whether parental characteristics can explain the similarity of divorce risk.

To analyze these data using the discrete time survival model, the data must be restructured to a format resembling the stacked or 'long' format used to analyze longitudinal data with multilevel models. The result is a person-period data set with one row for each person-period combination. Figure 8.4 shows part of the person-period data for some of the respondents shown in Figure 8.3. Note that in both data sets a column with the family identifier is included.

In Figure 8.4 we see part of the restructured data set; the last four observations for respondent 2 (who was married for 35 years at the interview time, and had not divorced) and the first six observations for respondent 3. So the last value of the variable 'divorce' for each respondent indicates either the event (scored 1) or censoring (scored 0).

To estimate the t time-specific intercepts we need to add t dummy variables as period indicators to the model. The time indicator *lengthm* for marriage length ranges in value from 0 to 67. If there are many periods, the time-specific intercepts α_i are usually replaced

	famid	respid	lengthm	divorce	status	educlev	gender	birthyr	famsize	kid	fastat	moedysr	faedysr	sibdivpr
33	1	2	32	0	50.6	10.1	1	38	5	1	37.2	8.7	8.9	.00
34	1	2	33	0	50.6	10.1	1	38	5	1	37.2	8.7	8.9	.00
35	1	2	34	0	50.6	10.1	1	38	5	1	37.2	8.7	8.9	.00
36	1	2	35	0	50.6	10.1	1	38	5	1	37.2	8.7	8.9	.00
37	1	3	0	0	100.0	12.0	0	36	5	0	37.2	8.7	8.9	.00
38	1	3	1	0	100.0	12.0	0	36	5	0	37.2	8.7	8.9	.00
39	1	3	2	0	100.0	12.0	0	36	5	1	37.2	8.7	8.9	.00
40	1	3	3	0	100.0	12.0	0	36	5	1	37.2	8.7	8.9	.00
41	1	3	4	0	100.0	12.0	0	36	5	1	37.2	8.7	8.9	.00
42	1	3	5	0	100.0	12.0	0	36	5	1	37.2	8.7	8.9	.00

Figure 8.4 Divorce example data (partial)

by a smooth function, for instance a polynomial function of the time variable. Time-varying effects can be entered by allowing interactions of covariates with the time variable. It is clear that if the data structure in Figure 8.4 is analyzed using a multilevel model, adding time-varying covariates is straightforward. Furthermore, if respondents are grouped, as we have here, adding a third level for the groups is also straightforward. Note that in the logistic regression model used, there is no lowest-level error term (see Chapter 6 for details). This implies there is no error term at the individual level and, as already explained by the end of the previous section, there is no error term at the repeated measures level either.

The hazard probability function $h(t)$ is the probability of the event occurring in time interval t , conditional on no earlier occurrence. In our case, the time variable is the marriage length at time t . The hazard probability is generally modeled with a logistic regression, in our case a multilevel regression of the following form:

$$\text{logit}(h_{ij}(t)) = \alpha(t) + \beta_2 x_{ij} + \beta_3 z_j, \quad (8.9)$$

where α_t is the baseline hazard probability at marriage year t , x_{ij} is a sibling-level predictor for sibling i in family j , and z_j is a family-level predictor for family j . The regression coefficient of x_{ij} varies at the family level. There is no intercept in the model, since the α_t are a full set of dummy variables that model the baseline hazard probability. When there are a large number of periods, the model can be made more parsimonious by modeling the baseline hazard probability as a smooth function of t . If a linear function of time suffices, we have:

$$\text{logit}(h_{ij}(t)) = \beta_{0ij} + \beta_1 t_{ijt} + \beta_2 x_{ij} + \beta_3 z_j, \quad (8.10)$$

which becomes:

$$\text{logit}(h_{ij}(t)) = \gamma_0 + \gamma_1 t_{ijt} + \gamma_2 x_{ij} + \gamma_3 z_j + u_{0j} + u_{2j}, \quad (8.11)$$

where u_{0j} is the family-level variation in the baseline risk, and u_{2j} implies family-level variation in the slope of the sibling-level predictor variable. The regression coefficient of the period indicator t may or may not vary across families, but family-level-varying baseline hazard probabilities are difficult to interpret, so the preference is to model the period indicator as fixed.

In our divorce data, the marriage length ranges from 0 to 67. Including 67 dummy variables in the model is not an attractive approach, and therefore we include a polynomial for the marriage length. The polynomial approximation must be accurate, and in addition to the linear function presented in Equation 8.11 we examine polynomials up to the fifth-degree polynomial. Whether these are all needed can be checked by examining their significance using the Wald test, or by a deviance difference test using full maximum likelihood and numerical approximation for the estimation.

To prevent estimation problems caused by large differences in the scale of the explanatory variables, the marriage length is transformed into a Z-score, and the higher-degree polynomials are derived from this Z-score. For the divorce data, a cubic polynomial turns out to be sufficient. To evaluate how well the polynomial describes the baseline hazard probability, we can plot the predicted and observed proportions of divorce at each marriage length. This plot (not shown here) reveals that there is an outlier; at a marriage length of 53 years there is an unexpectedly high proportion of divorces. The number of cases with such long marriages is small (11 subjects, 0.6 percent of the sample), and this high divorce rate may well be chance. Still, it is best to add to the baseline hazard probability model a dummy that indicates period 53.

Table 8.1 shows the results for both models, with and without the dummy for marriage length equal to 53. When the period = 53 dummy is added to the model, the third order polynomial is no longer significant, and it is removed from the model. The differences between both models are not large. We have used full maximum likelihood and numerical integration (HLM Laplace method), so the deviance statistic can be used to compare the models. The models are not nested, but we can use the AIC or the BIC to compare the models. The model that treats period 53 as an outlier performs slightly better, so that will be the basis for further modeling.

The regression coefficients for time period in Table 8.1 show that the risk of divorce decreases when the marriage length is larger. The negative regression coefficient for t^2 indicates a faster decreasing trend for longer marriage durations. The variance of 0.58 can be compared to the lowest-level variance, which is the variance of the standard logistic distribution: $\pi^2 / 3 \approx 3.29$. The intraclass correlation for the family-level variance in divorce risk is therefore $0.58 / (3.29 + 0.58) = .15$. This is not very large, but it clearly shows a family effect on divorce.

Table 8.1 Survival model for marriage length (M_1)

Predictor	Time third order	Time second order + p53
	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	−5.71 (.16)	−5.70 (.16)
t	−0.44 (.16)	−0.24 (.10)
t_2	−0.46 (.13)	−0.40 (.11)
t_3	0.15 (.07)	—
Period 53	—	5.12 (1.34)
Variance σ^2_{u0}	$0.58(\chi^2_{(952)} = 1394.8, p < .001)$	$0.58(\chi^2_{(952)} = 1354.5, p < .001)$
Deviance	82347.6	82343.9
AIC / BIC	82357.6 / 82381.9	82353.9 / 82378.2

Table 8.2 Survival model for marriage length (M_2)

Predictor	Time second order + p53	+ first level explanatory vars
	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	-5.70 (.16)	-5.72 (.16)
t	-0.24 (.10)	-0.21 (.10)
t_2	-0.40 (.11)	-0.40 (.11)
Period 53	5.12 (1.34)	5.10 (1.34)
EducLev		0.11 (.03)
Gender		0.38 (.15)
Variance σ_{u0}^2	$0.58(\chi^2_{(952)} = 1354.5, p < .001)$	$0.52(\chi^2_{(952)} = 1520.7, p < .001)$
Deviance	82343.9	82320.4
AIC/BIC	82353.9 / 82378.2	82334.4 / 82368.4

The results in Table 8.1 are best regarded as the equivalent of the intercept-only null model. Only after the person-year trend is represented well can other predictor variables be added to the model. These variables can be both time-varying and time-invariant. In our case, there are no time-varying predictors. As it turns out, none of the family-level predictors has a significant effect.

Table 8.2 presents the final model for divorce, which contains only individual-level predictors. Divorce risk still decreases with marriage length, and women and respondents with a high educational level have a higher risk of divorce.

8.3 MULTILEVEL ORDINAL SURVIVAL ANALYSIS

Hedeker and Gibbons (2006) describe multilevel survival analysis models where the data are grouped in a small number of ordinal coded time intervals. The model assumes that there are a small number of measurement periods, coded $t = 1, 2, \dots, T$. For each level-1 unit, observations are made until either the event occurs or censoring takes place (meaning the event had not occurred by the last observed period). As a result, we do not know the exact time point when an event has taken place, we just know in which time interval (observed period) it has taken place. The model is similar to the one in 8.10:

$$\text{logit}(h_{ij}(t)) = \alpha_t + \beta_{2j}x_{ij} + \beta_{3j}z_j, \quad (8.12)$$

but in Equation 8.12 there are only a small number of period-specific intercepts, which are modeled with an ordinal threshold model, similar to the ordinal models discussed in

Chapter 7. Hedeker and Gibbons (2006) express a preference for the complementary log-log function instead of the logit, which gives:

$$\ln[-\ln(1 - h_{ij}(t))] = \alpha_i + \beta_2 x_{ij} + \beta_3 z_j. \tag{8.13}$$

When the complementary log-log function is used, the regression coefficients in the ordinal grouped-time model are invariant to the length of the interval, and equivalent to the coefficients in the underlying continuous-time proportional hazards model. This does not hold when the logit function is used.

The advantage of the ordinal survival model is that we do not need a long series of person–period records in the data file: it suffices to have a single record for each individual, including the last observed interval and an indicator variable that specifies if the event occurred in this interval or not. In the latter case, the last observation is censored. A disadvantage of the ordinal survival model is that it cannot accommodate time-varying predictors. If time-varying predictors are present, the person–period approach discussed earlier must be used.

Figure 8.3 in the previous section shows the data file for the multilevel ordered survival model, for the divorce example data analyzed earlier. Each individual respondent is present in the data file only once. In addition to the continuous variable *lengthm*, which codes the marriage length in years, there is a categorical variable *lengthc* that codes the marriage length in four categories (originally five quintiles, but the fourth and fifth quintile are combined because the fifth quintile contained only five divorces). There are up to three respondents in each family.

Table 8.3 shows the parameter estimates for the null model and for the model with the same explanatory variables used earlier, applying a logistic model estimated with SuperMix. The null model estimates the family-level variance at 0.88. The residual variance on the standard logistic distribution is fixed at $\pi^2 / 3 \approx 3.29$, so the intraclass correlation is .21. This estimate is somewhat higher than the estimate in the continuous

Table 8.3 Survival model for marriage length (M_3)

Predictor	Null model	+ first level explanatory vars
	Coefficient (s.e.)	Coefficient (s.e.)
Intercept	−3.12 (.17)	−4.33 (.37)
EducLev		0.09 (.03)
Gender		0.39 (.15)
Variance σ_{u0}^2	0.88 (.34)	0.82 (.33)
Deviance	1998.8	1980.4
AIC/BIC	2008.8 / 2036.4	1994.4 / 2033.1

grouped-time model, where the intraclass correlation was estimated as .15. It confirms the evidence for a family effect on risk of divorce.

In the null model, the thresholds are estimated as -3.12 , -2.42 , -2.06 , and -1.84 . These are the baseline logit hazard probabilities for the four time periods. These can be transformed to probabilities using the inverse of the logit transformation, which is:

$$P(y) = e^y / (1 + e^y). \quad (8.14)$$

Using Equation 8.14 we calculate the baseline hazard probabilities as 0.04, 0.08, 0.11, and 0.14. The cumulative probability of experiencing a divorce increases with increasing marriage length, but it remains relatively low. As in the earlier analysis, educational level and being female increase the risk of divorce.

8.4 SOFTWARE

In survival analysis, the outcome variable is dichotomous: an event either occurred or did not occur during the time period of observation. The data are structured as a person–period file, which is a multilevel structure. Consequently, all software that estimates multilevel generalized linear models can be used for such data, following procedures explained in this chapter. The estimation choices are the same as in Chapter 6, where the generalized linear model for multilevel dichotomous data is introduced. Estimation methods that use numerical integration are to be preferred to estimation methods based in MQL or PQL linearization. The ordinal survival model described in section 8.3 is available in software such as Supermix, Mplus, MLwiN and HLM.

9

Cross-Classified Multilevel Models

SUMMARY

Not all multilevel data are purely hierarchical. For example, pupils can be nested within the schools they attend, and within the neighborhoods in which they live. However, the nesting structure may be less clear when we consider the schools and neighborhoods. It is likely that there is a tendency for pupils to attend schools in their own neighborhood, but there will be exceptions. Some pupils will attend schools in other neighborhoods than the one they live in, and especially schools that are located close to the border of two neighborhoods may be expected to draw pupils from several neighborhoods. As a result, it is not possible to set up an unambiguous hierarchy of pupils within schools within neighborhoods. We could, of course, arbitrarily set up such a model structure, but to do so we would have to include several schools more than once, because they appear in different neighborhoods.

Whenever we encounter this kind of problem, chances are that we are dealing with a cross-classified data structure. In the schools and neighborhoods example, pupils are nested within schools, and also within neighborhoods, but schools and neighborhoods are *crossed* with each other. If we study educational achievement, we may assume that achievement can be influenced by both schools and neighborhoods. Therefore, the model has to incorporate both schools and neighborhoods as sources of variation in achievement, but in such a manner that pupils are nested in the cross-classification of both schools and neighborhoods. This chapter describes cross-classified analysis techniques, and discusses the requirements this poses for the software.

9.1 INTRODUCTION

Cross-classified data structures can occur at any level of a hierarchical data set. If we have pupils nested within the cross-classification of schools and neighborhoods, the cross-classification of schools and neighborhoods is the second level, and the pupils are the lowest (first) level. However, it is also possible to have a cross-classification at the lowest level. Consider the example of students who have to carry out a set of complicated analysis tasks in a computer class. There are several parallel classes, taught by different teachers. To keep the grading policy equivalent for all students, all computer exercises are graded by all available teachers. As a result, at the student level we would have grades for several different exercises, given by several different teachers. One way to view this is to distinguish the class level as the

highest level, with students below this level, with the teachers at the next lower level, and the exercises as the lowest level below the teachers. This constitutes a nicely hierarchical four-level data structure. On the other hand, we could also distinguish the class level as the highest level, with students below this level, the exercises at the next lower level, and the teachers as the lowest level below the exercises. This also constitutes a nicely four-level hierarchical data structure. It appears that we can model this data using two contradictory data structures. Again, whenever we have this kind of problem, it indicates that we are probably dealing with a cross-classified data structure. In the grading example, we have pupils nested within classes, with a cross-classification of teachers (graders) and exercises nested within the classes. It is important that such cross-classified data are modeled correctly and that crossed factors are not ignored. The consequences of ignoring crossed factors have been studied by Gilbert, Petscher, Compton and Schatschneider (2016), Luo and Kwok (2009, 2012), Luo, Cappaert and Ning (2015) and Meyers and Beretvas (2006).

Since we may expect differences between classes and pupils, the cross-classification of exercises and teachers would be defined at the lowest level, nested within pupils within classes. The reliability of the combined grade of the student in such situations can be modeled using generalizability theory (Cronbach, Gleser, Nanda & Rajaratnam, 1972). To assess the generalizability of the students' combined grade across exercises and teachers using generalizability theory, we must partition the total variation of the assigned grades as the sum of contributions from classes, students, exercises and teachers. Cross-classified multilevel analysis is a good way to obtain the required estimates for the various variance components in such a partition (cf. Hox & Maas, 2006).

Cross-classified multilevel models are applicable to a variety of situations. The examples given so far are from the field of education. Other applications are models for nonresponse in longitudinal research, where respondents are visited repeatedly, sometimes by the same interviewer, sometimes by a different interviewer. Interviewer characteristics may affect the respondents' cooperation, which is analyzed with a multi-level model with respondents nested within interviewers (Hox et al., 1991). In longitudinal studies, the previous interviewer may also be relevant, and as a result, we have a cross-classified structure, with respondents nested within the cross-classification of the current and the previous interviewer. Examples of multilevel cross-classified analyses in panel interview studies are the studies by Pickery and Loosveldt (1998), O'Muircheartaigh and Campanelli (1999) and Pickery, Loosveldt and Carton (2001). Cross-classified multilevel models have also been applied to sociometric choice data, where members of groups both give popularity ratings to and receive ratings from other group members (van Duijn, van Bussbach & Snijders, 1999). For other examples see Raudenbush (1993b) and Rasbash and Goldstein (1994).

Considering multilevel analysis of longitudinal data, the usual approach is to specify this as a hierarchical structure with measurement occasions nested within individual subjects. However, if all subjects are measured in the same time period (for example yearly periods all starting in the same year), it makes sense to treat the data as a cross-classification

of measurement occasions with individual subjects, with both factors ‘subjects’ and ‘measurement occasions’ treated as random. Such a specification still allows missing data, in the form of panel dropout or occasionally missing a measurement occasion.

9.2 EXAMPLE OF CROSS-CLASSIFIED DATA: PUPILS NESTED WITHIN (PRIMARY AND SECONDARY SCHOOLS)

Assume that we have data from 1000 pupils who have attended 50 different primary schools, and subsequently went on to 30 secondary schools. Similar to the situation where we have pupils within schools and neighborhoods, we have a cross-classified structure. Pupils are nested within primary and within secondary schools, with primary and secondary schools crossed. In other words: pupils are nested within the cross-classification of primary and secondary schools. Goldstein (1994, 2011) uses a formal description of these models, which will be followed here. In our example, we have a response variable *achievement* which is measured in secondary school. We have two explanatory variables at the pupil level: *pupil gender* (0 = male, 1 = female) and a six-point scale for pupil social-economic status, *pupil ses*. We have at the school level a dichotomous variable that indicates if the school is public (denom = 0) or denominational (denom = 1). Since we have both primary and secondary schools, we have two such variables (named *pdenom* for the primary school and *sdenom* for the secondary school).

At the pupil level, we can write an intercept-only model as

$$Y_{i(jk)} = \beta_{0(jk)} + e_{i(jk)}, \quad (9.1)$$

where the achievement score of pupil $Y_{i(jk)}$ of pupil i , nested within the cross-classification of primary school j and secondary school k , is modeled by the intercept (the overall mean) $\beta_{0(jk)}$ and a residual error term $e_{i(jk)}$. The subscripts (jk) are written within parentheses to indicate that they are conceptually at the same level: the (jk) th primary school/secondary school combination in the cross-classification of primary and secondary schools.

The subscripts (jk) indicate that we assume that the intercept $\beta_{0(jk)}$ varies independently across both primary and secondary schools. Thus, we can model the intercept using the second-level equation

$$\beta_{0(jk)} = \gamma_{00} + u_{0j} + v_{0k}. \quad (9.2)$$

In Equation 9.2, u_{0j} is the residual error term for the primary schools, and v_{0k} is the residual error term for the secondary schools. After substitution, this produces the intercept-only model:

$$Y_{i(jk)} = \gamma_{00} + u_{0j} + v_{0k} + e_{i(jk)} \quad (9.3)$$

where the outcome variable is modeled with an overall intercept γ_{00} , with a residual error term u_{0j} for primary school j and a residual error term v_{0k} for secondary school k , and the individual residual error term $e_{i(jk)}$ for pupil i in the cross-classification of primary school j and secondary school k .

Individual-level explanatory variables can be added to the equation, and their regression slopes may be allowed to vary across primary and/or secondary schools. School-level variables can also be added, and used to explain variation in the slopes of individual-level variables across schools, in a manner similar to ordinary multilevel regression models.

Cross-classified models can be set up in all multilevel analysis software that allows equality constraints on the variance components. Raudenbush (1993b) and Rasbash and Goldstein (1994) show how a cross-classified model can be formulated and estimated as a hierarchical model. The details of setting up a cross-classified model depend strongly on the software; some software (e.g. MLwiN) requires that users use a macro or set up the model by hand, other software (e.g. HLM, SPSS, SAS, Stata) include cross-classified models as part of the standard setup. Recent multilevel software hides the complications of cross-classified models from the user. Some comments on software use are given in the last section of this chapter.

Table 9.1 presents the parameter estimates for a sequence of models, using ML estimation.

Table 9.1 Cross-classified model for achievement in primary and secondary schools

Model	Intercept-only	+ pupil vars)	+ school vars	+ ses random
	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Fixed part				
Predictor				
Intercept	6.35 (.08)	5.76 (.11)	5.52 (.19)	5.52 (.14)
Pupil gender		0.26 (.05)	0.26 (.05)	0.25 (.05)
Pupil SES		0.11 (.02)	0.11 (.02)	0.12 (.02)
Primary denomination			0.20 (.12)	0.20 (.12)
Secondary denomination			0.18 (.10)	0.17 (.10)
Random part				
$\sigma^2_{\text{int/pupil}}$	0.51 (.02)	0.47 (.02)	0.47 (.02)	0.46 (.02)
$\sigma^2_{\text{int/primary}}$	0.17 (.04)	0.17 (.04)	0.16 (.04)	0.15 (.08)
$\sigma^2_{\text{int/secondary}}$	0.07 (.02)	0.06 (.02)	0.06 (.02)	0.05 (.02)
$\sigma^2_{\text{ses/primary}}$				0.008 (.004)
Deviance	2317.8	2243.5	2238.0	2224.7
AIC	2325.8	2255.5	2253.9	2244.7

The results of a series of models on the cross-classified data set are presented in Table 9.1 in a more conventional form. The first column in Table 9.1 presents the results for the intercept-only model. Since cross-classified models usually contain more than two levels, which are not all unambiguously nested, the table does not use the usual sigma-terms (σ_e^2 , σ_{u0}^2 , and so on) for the variance components, but names that correspond to the proper variable and level. Therefore, the term $\sigma_{\text{int/pupil}}^2$ corresponds to the usual lowest-level error term for the intercept σ_e^2 in the model equation and $\sigma_{\text{int/primary}}^2$ to the usual second-level error term for the intercept σ_{u0}^2 . The term $\sigma_{\text{ses/primary}}^2$ refers to variance for the *ses* slope at the primary school level. When a model contains many variance components, indicating these in the results tables by proper names instead of symbols often makes interpretation easier.

Since the levels of the primary and secondary school are independent, we can add the estimated variances in the intercept-only model (the first column in Table 9.1) for a total variance of 0.75. The intraclass correlation for the primary school level is $0.17 / 0.75 = 0.23$, and the intraclass correlation for the secondary school level is $0.07 / 0.75 = 0.09$. So, 23 percent of the total variance is accounted for by the primary schools, and 9 percent by the secondary schools. Taken together, the schools account for $(0.17 + 0.07) / 0.75 = 0.32$ of the total variance.

The pupil-level variables pupil gender and pupil SES have a significant contribution. The effect of either the primary or the secondary school being denominational is of borderline significance. The difference between the deviances of the second and the third model is 5.85, with two more parameters estimated in the third model. A chi-square test for this difference is also of borderline significance ($\chi^2 = 5.85$, $df = 2$, $p = 0.054$). The AIC indicates that we should prefer model three. The conclusion is that, although there is apparently an effect of both school levels, the denomination of the school does not explain the school-level variance very well. The fourth column in Table 9.1 shows the estimates for the model where we allow for variation in the slope for pupil SES across primary schools. This is indicated by the term $\sigma_{\text{ses/primary}}^2$. There is a small but significant slope variance for *ses* at the primary school level. The deviance difference between the third and the fourth model is 13.3, ($df = 2$, $p < 0.01$). The *ses* slope variance at the secondary school level (not shown in the table) is negligible.

9.3 EXAMPLE OF CROSS-CLASSIFIED DATA: (SOCIOMETRIC RATINGS) IN SMALL GROUPS

In the previous example, the cross-classification is at the higher levels, with pupils nested within the cross-classification of primary and secondary schools. The cross-classification can also be at lower levels. An example is the following model for sociometric ratings. Sociometric ratings can be collected by asking all members of a group to rate all other members, typically on a seven- or nine-point scale that indicates how much they would like to share some activity with the rated person. Figure 9.1 presents an example of a sociometric rating data set for three small groups, as it would look in standard statistical software.

	group	child	age	sex	grsize	rating1	rating2	rating3	rating4	rating5	rating6	rating7	rating8	rating9
1	1	1	8	1	7	.	3	6	4	4	7	6	.	.
2	1	2	10	1	7	5	.	6	4	5	7	5	.	.
3	1	3	11	1	7	4	6	.	4	5	7	6	.	.
4	1	4	9	0	7	4	4	6	.	5	7	5	.	.
5	1	5	11	0	7	5	5	6	5	.	7	6	.	.
6	1	6	10	1	7	4	5	6	3	4	.	6	.	.
7	1	7	10	1	7	3	5	6	5	3	6	.	.	.
8	2	1	9	0	9	.	3	5	3	4	6	6	4	5
9	2	2	9	0	9	2	.	4	5	6	5	4	4	5
10	2	3	9	0	9	5	3	.	4	3	6	5	4	6
11	2	4	8	1	9	3	2	5	.	6	6	5	3	4
12	2	5	9	1	9	4	4	5	5	.	5	7	4	5
13	2	6	9	0	9	3	4	4	4	4	.	5	4	5
14	2	7	9	1	9	4	4	6	5	6	5	.	4	5
15	2	8	11	0	9	3	4	5	4	5	6	6	.	5
16	2	9	8	1	9	3	4	5	5	4	6	7	5	.
17	3	1	11	0	5	.	5	7	5	6
18	3	2	11	0	5	5	.	7	6	6
19	3	3	13	1	5	5	5	.	6	8
20	3	4	12	1	5	4	4	6	.	6

Figure 9.1. Sociometric rating data for three small groups.

In Figure 9.1, we see the sociometric ratings for a group of seven and a group of nine children, and part of the data of a third group of five children. High numbers indicate a positive rating. One way to collect such data is to give each child a questionnaire with a list of names for all children, and ask them to write their rating after each name. Therefore, each row in the table in Figure 9.1 consists of the sociometric ratings given by a specific child. The columns (variables) labeled *rating1*, *rating2* ... *rating11* are the ratings given for child number 1, 2 ... 11. Figure 9.1 makes clear that network data, of which these sociometric ratings are an example, have a complicated structure that does not fit well in the rectangular data matrix assumed by most statistical software. The groups do not have the same size, so *rating6* to *rating11* have all missing values for group three, which has only five children. The children do not rate themselves, so these ratings also have missing values in the data matrix. The data also include the pupil characteristic *age* and *gender* and the group characteristic *group size*.

Special models have been proposed for network data (for an extensive introduction see Wasserman & Faust, 1994), and specialized software is available for the analysis of network data. Van Duijn, Busschbach and Snijders (1999) show that one can also use multilevel regression models to analyze network data. In the example of the sociometric ratings, we would view the ratings as an outcome variable that is nested within the cross-classification of the *senders* and the *receivers* of sociometric ratings. At the lowest level we have the separate ratings that belong to specific sender-receiver pairs. This is nested within the cross-classification of senders and receivers at the second level, which in turn can be nested, for example within a sample of groups.

To analyze sociometric choice data using multilevel techniques, the data must be arranged in a different format than the one shown in Figure 9.1. In the new data file, the individual rows must refer to the separate ratings, with associated child identification codes to identify the sender and receiver in that particular rating, and the variables that characterize the sender and receiver of information. Such a data set looks like the one depicted in Figure 9.2. This figure illustrates clearly how the distinct ratings are nested below both senders and receivers, who in turn are nested below the sociometric groups.

As the data set in Figure 9.2 illustrates, the cross-classification is here at the second level. We have ratings of senders and receiver pairs, which form a cross-classification nested within the groups. At the lowest level are the separate ratings. At the second level, we have the explanatory variables *age* and *gender* for the senders and receivers of ratings, and at the group level, we have the group characteristic *group size*.

The data in Figures 9.1 and 9.2 are part of a data set that contains sociometric data from 20 groups of children, with group sizes varying between 4 and 11. At the lowest level, we can write the intercept-only model as follows:

$$Y_{i(jk)l} = \beta_{0(jk)l} + e_{i(jk)l} \quad (9.4)$$

In Equation (9.4), rating *i* of sender *j* and receiver *k* is modeled by an intercept $\beta_{0(jk)l}$. At the lowest level, the ratings level, we have residual random errors $e_{i(jk)l}$ which indicates that

	group	sender	receiver	rating	agesend	sexsend	agerec	sexrec	grsize
1	1	1	2	3	8	1	10	1	7
2	1	1	3	6	8	1	11	1	7
3	1	1	4	4	8	1	9	0	7
4	1	1	5	4	8	1	11	0	7
5	1	1	6	7	8	1	10	1	7
6	1	1	7	6	8	1	10	1	7
7	1	2	1	5	10	1	8	1	7
8	1	2	3	6	10	1	11	1	7
9	1	2	4	4	10	1	9	0	7
10	1	2	5	5	10	1	11	0	7
11	1	2	6	7	10	1	10	1	7
12	1	2	7	5	10	1	10	1	7
13	1	3	1	4	11	1	8	1	7
14	1	3	2	6	11	1	10	1	7
15	1	3	4	4	11	1	9	0	7
16	1	3	5	5	11	1	11	0	7
17	1	3	6	7	11	1	10	1	7
18	1	3	7	6	11	1	10	1	7
19	1	4	1	4	9	0	8	1	7
20	1	4	2	4	9	0	10	1	7

Figure 9.2. Sociometric data rearranged for multilevel analysis, first four senders.

we do not assume that all variation between ratings can be explained by differences between senders and receivers. These residual errors could be the result of random measurement errors, but they could also reflect unmodeled interactions between senders and receivers. The cross-classification of senders and receivers is nested within the groups, indicated by l . Again, parentheses are used to indicate a cross-classification of factors that are conceptually at the same level: the (jk) th sender/receiver combination, which is nested within group l .

Note that we use subscripts on the intercept term β_0 to indicate that we assume that the intercept varies across both senders and receivers. Models involving cross-classified levels tend to have many distinct levels, and the practice of assigning a different Greek letter to regression coefficients at each level leads in such cases to a confusing array of Greek letters. In this chapter, the Greek letter β is used for regression coefficients that are assumed to vary across some level(s), with subscripts indicating these levels, and the Greek letter γ is used to denote fixed regression coefficients. So, the subscripts j, k and l on the regression coefficient $\beta_{0(jk)l}$ indicate that we assume that the intercept $\beta_{0(jk)l}$ varies across the cross-classification of senders and receivers nested within groups. Thus, we can model this intercept variance using the second-level equation

$$\beta_{0(jk)l} = \beta_{0l} + u_{0j} + v_{0kl}. \quad (9.5)$$

The subscript l on the regression coefficient β_{0l} indicates that we assume that the intercept β_{0l} varies across groups. We can further model the intercept variance using the third-level equation

$$\beta_{0l} = \gamma_{00} + f_{0l} \quad (9.6)$$

After substitution, this produces

$$Y_{i(jk)l} = \gamma_{00} + f_{0l} + u_{0jl} + v_{0kl} + e_{i(jk)l} \quad (9.7)$$

where the outcome variable is modeled with an overall intercept γ_{00} , together with a residual error term f_l for group l , the individual-level residual error terms u_{jl} for sender j in group l , and v_{kl} for receiver k in group l , and the measurement-level error term $e_{i(jk)l}$.

Both sender and receiver characteristics like *age* and *gender* and group characteristics like *group size* can be added to the model as predictors, and child characteristics may be allowed to have random slopes at the group level. The analysis proceeds along exactly the same lines as outlined for the cross-classification of primary and secondary schools.

The first model is the intercept-only model of 9.7 written with variable names rather than symbols.

$$Rating_{i(jk)l} = \gamma_{00} + f_{0l} + u_{0jl} + v_{0kl} + e_{i(jk)l} \quad (9.8)$$

This produces an estimate for the overall intercept, and the variance components σ_e^2 for the variance of the ratings, $\sigma_{u_0}^2$ and $\sigma_{v_0}^2$ for the senders and the receivers, plus $\sigma_{f_0}^2$ for the variance at the group level. Since the group sizes here are small at all levels, we use REML (restricted maximum likelihood) estimation. The estimates are in the first column of Table 9.2.

For the sake of readability, the variance components in the random part are indicated by proper variable and level names instead of the usual symbols. From the intercept-only model in the first column, it appears that 20 percent of the total variance is at the lowest (ratings) level, only 7 percent of the total variance is variance between the senders, 32 percent of the total variance is variance between the receivers, and 41 percent is variance between groups. Apparently, there are strong group effects.

The model in the second column of Table 9.2 adds all available explanatory variables as fixed predictors. Using abbreviated variable names, it can be written as:

$$\begin{aligned} rating_{i(jk)l} = & \gamma_{00} + \gamma_{10} send.age_{jl} + \gamma_{20} send.gender_{jl} + \gamma_{30} rec.age_{kl} \\ & + \gamma_{40} rec.gender_{kl} + \gamma_{01} groupsize_l + f_{0l} + u_{0jl} + v_{0kl} + e_{i(jk)l} \end{aligned} \quad (9.9)$$

Table 9.2 Results for cross-classified model sociometric ratings in groups

Model	Intercept-only	+ all fixed	+ sender gender random	+ interaction gender/gender
	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Fixed part				
Intercept	5.02 (.22)	1.56 (1.17)	1.00 (1.00)	1.00 (1.00)
Sender age		0.23 (.03)	0.22 (.03)	0.22 (.03)
Sender gender		-0.16 (.07)	-0.12 (.13)	-0.37 (.14)
Receiver age		0.21 (.06)	0.21 (.06)	0.22 (.06)
Receiver gender		0.74 (.13)	0.73 (.13)	0.49 (.13)
Group size		-0.17 (.10)	-0.09 (.07)	-0.08 (.07)
Interaction gender/gender				0.51 (.09)
Random part				
$\sigma^2_{\text{int/ratings}}$	0.42 (.02)	0.42 (.02)	0.42 (.02)	0.40 (.02)
$\sigma^2_{\text{int/senders}}$	0.15 (.03)	0.09 (.02)	0.02 (.01)	0.02 (.01)
$\sigma^2_{\text{int/receivers}}$	0.65 (.09)	0.48 (.07)	0.49 (.07)	0.48 (.07)
$\sigma^2_{\text{int/groups}}$	0.84 (.31)	0.42 (.17)	0.23 (.11)	0.23 (.11)
$\sigma^2_{\text{send.gender/groups}}$			0.28 (.11)	0.30 (.11)
$\sigma_{\text{send.gender-int/groups}}$			0.17 (.09)	0.18 (.09)
Deviance	2773.6	2696.2	2633.5	2603.2
AIC	2781.6	2704.2	2645.5	2615.2

From the regression coefficients estimated in the second column of Table 9.2 we conclude that age of sender and receiver have a small positive effect on the ratings. In larger groups, the ratings are a bit lower, but this effect is not significant. The effect of the children's gender is more complicated. *Gender* is coded 0 for male, 1 for female, and Table 9.2 shows that female senders give lower ratings, while female receivers get higher ratings.

Only one explanatory variable, *sender gender*, has a significant slope variation on the group level. This model can be written as:

$$\begin{aligned}
 \text{rating}_{i(jk)l} = & \gamma_{00} + \gamma_{10} \text{send.age}_{jl} + \gamma_{20} \text{send.gender}_{jl} + \gamma_{30} \text{rec.age}_{kl} + \gamma_{40} \text{rec.gender}_{kl} \\
 & + \gamma_{01} \text{groupsize}_l + f_{1l} \text{send.gender}_{jl} + f_{0l} + u_{0jl} + v_{0kl} + e_{i(jk)l}
 \end{aligned} \quad (9.10)$$

Apart from having two residual error terms at the second level, one for the senders and one for the receivers, Equation 9.10 represents an ordinary multilevel regression model with one varying slope at the group level, and no cross-level interactions. The estimates for this model are in the third column of Table 9.2. The variance of the slopes for sender gender is substantial, which indicates that the effect of the gender of the senders differs considerably across groups.

The only group level variable available to explain the variation of the *sender gender* slopes is group size. However, if we enter that in the model by forming the cross-level interaction between the variables *sender gender* and *group size*, it turns out to be nonsignificant.

The different effects of sender and receiver gender suggest looking in more detail at the effect of the explanatory variable *gender*. The last model in Table 9.2 includes an interaction effect for sender gender and receiver gender. This interaction, which is an ordinary interaction and not a cross-level interaction, is indeed significant. To interpret this interaction, it is useful to graph it. Figure 9.3 shows the interaction. It is clear that, in addition to the direct effects of sender gender (girls give on average lower ratings than boys), and receiver gender (girls receive on average higher ratings than boys), there is an interaction effect: both boys and girls give higher ratings to other children from their own gender.

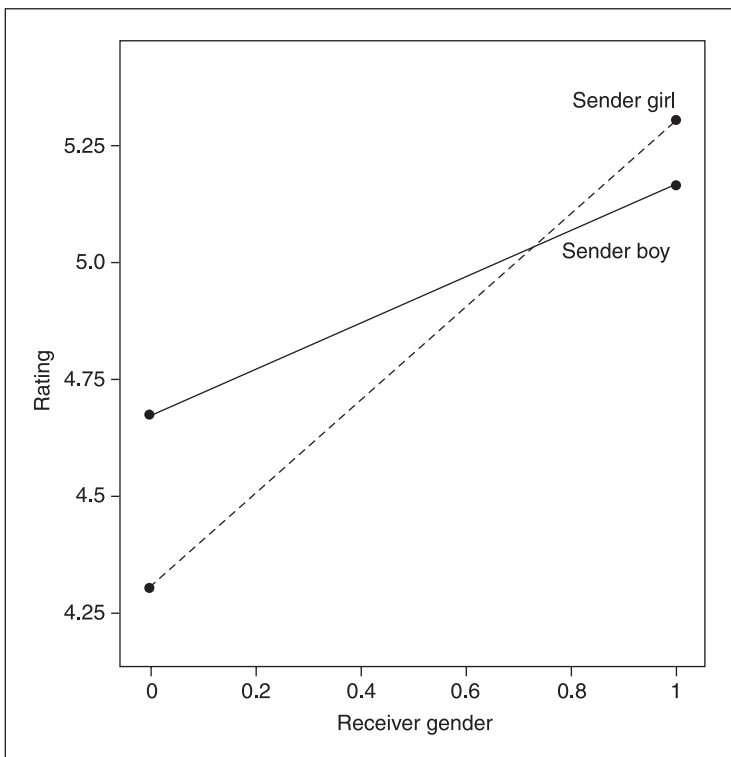


Figure 9.3 Graph of interaction between sender gender and receiver gender.

Snijders and Bosker (2012, Chapter 11) discuss a number of extensions of multilevel models for sociometric data. For instance, it may be useful to insert a second level that defines the *dyads*, the sender-receiver pairs. For each pair there are two ratings. The amount of variance at the dyad level indicates the degree of reciprocity in the ratings. For other extensions to the multilevel analysis of network data see Snijders and Kenny (1999) and van Duijn, van Busschbach and Snijders (1999). The analysis of so-called ego-centered network data, which have a simple nesting structure, is discussed by Snijders, Spreeen and Zwaagstra (1994), Spreeen and Zwaagstra (1994) and by Kef, Habekothé and Hox (2000). Models for dyadic data are discussed extensively by Kenny, Kashy and Cook (2006).

9.4 SOFTWARE

Although cross-classified models may look deceptively simple in recent multilevel software, cross-classified data often result in large and complicated models. For instance, if we have 50 primary and 30 secondary schools, the result is a crosstable with $50 \times 30 = 1500$ cells. If we have a perfect hierarchy, each secondary school is nested within one specific primary school, and most of the cells of the crosstable are empty. Multilevel software uses this structure to achieve efficient estimation. In a cross-classified model, each combination of primary and secondary school can occur, and estimation proceeds more slowly and consumes more computer memory.

Cross-classified models can be fitted in most statistical packages like SPSS, SAS and STATA, simply by declaring several random levels. In specialized multilevel software, such as HLM, MLwiN and Mplus, the setups are more complicated. In packages like SPSS, cross-classified models can be set up in the syntax window. However, in SPSS and similar packages the *random* command behaves differently depending on the coding of the lowest-level units. Unique identification numbers have different effects than restarting the count in each group. SPSS users are referred to the review by Leyland (2004). Different model specifications may lead to the same estimates, but different computational demands. So, HLM distinguishes between ‘row’ and ‘column’ classifications, and directs the user to define the identification variable with the smallest number of groups as the ‘column’ variable, to speed up computations. In SPSS, different specifications of the same model lead to the same estimates, but very different computation times (Leyland, 2004).

A model related to the cross-classified model is the multiple membership model. Assume that we use dummies to refer to groups. Standard multilevel analyses use 0 / 1 dummies to indicate group membership. If an individual is a member of more than one group, or if group membership is unknown for some individuals, it is possible to ‘spread’ the dummy-value of 1.0 over several groups, for instance giving each of two possible groups a dummy value of 0.5. This model, which is useful for multiple memberships, or if group membership is fuzzy, is discussed by Hill and Goldstein (1998). The consequences of ignoring multiple membership structures have been studied by Chung and Beretvas (2011).

10

Multivariate Multilevel Regression Models

SUMMARY

Multivariate multilevel regression models are multilevel regression models that contain more than one response variable. As such, they are comparable to classical multivariate analysis of variance (MANOVA) models, where we also have several outcome measures. The reason to use a multivariate model is usually because the researchers have decided to use multiple measurements of one underlying construct, to achieve a better construct validity. A classic example is in medical research when certain diseases manifest themselves in a *syndrome* that leads to a pattern of related effects (Sammel et al., 1999). By simultaneously using several outcome measures, researchers can obtain a better and more complete description of what is affected by changes in the predictor variables. Tabachnick and Fidell (2013) mention several advantages of using a multivariate approach instead of carrying out a series of univariate analyses. One advantage of multivariate analysis is that carrying out a series of univariate statistical tests inflates the type I error rate, which is controlled better in a multivariate analysis. A second advantage of multivariate analysis is that it often has more power. On each individual response measure, the differences may be small and non-significant, but for the total set of response measures, the joint effect may produce a significant effect (Tabachnick & Fidell, 2013). However, the disadvantage of multivariate models is that they are more complicated, and that their interpretation is more ambiguous.

In multilevel analysis, using multiple outcome measures leads to some very powerful analysis tools. First, like in analysis of variance, using several response variables may lead to more power. Since multilevel analysis does not assume that all response measures are available for all individuals, it may be used as an alternative for MANOVA when there are missing values on some of the response variables. Most software for MANOVA cannot cope with missing data on the response variables, while for multilevel analysis this poses no special problem. Since the multilevel model is much more flexible than MANOVA, there are some additional advantages to multivariate multilevel modeling. For instance, since multivariate multilevel analysis combines multiple response variables in one model, it is possible to test the equality of their regression coefficients or variance components by imposing equality constraints. In addition, it can be used to construct multilevel measurement models, by including a set of questions that form a scale as multivariate responses in a multilevel model.

10.1 THE MULTIVARIATE MODEL

The multilevel regression model is inherently a univariate model. Even so, it can be used to analyze multiple outcome variables by placing these in a separate ‘variables’ level. In the multivariate multilevel regression model, the different measures are the lowest-level units. In most applications, the different measures would be the first level, the individuals the second level, and if there are groups, these form the third level. Therefore, if we have p response variables, Y_{hij} is the response on measure h of individual i in group j .

Ignoring possible missing responses, at the lowest level (the variable level) we have p units which in fact are the p response variables. Each unit has a single response, which is the response of person i to question h . One way to represent the different outcome variables would be to define $p - 1$ dummy variables that indicate the variables 2, ..., P . In this scheme, variable 1 would be the base category, indicated by the value 0 for all dummy variables. However, this would give the first variable a special position. A much better way to indicate the multiple response variables is to leave out the intercept, and to define p dummy variables, one for each response variable. Thus, we have p dummy variables d_{phij} , defined for $p = 1, \dots, P$ by

$$d_{phij} = \begin{cases} 1 & p = h \\ 0 & p \neq h \end{cases} \quad (10.1)$$

To use these p dummy variables in a model, we must exclude the usual intercept from the model. Hence, on the lowest level we have

$$Y_{hij} = \pi_{1ij}d_{1ij} + \pi_{2ij}d_{2ij} + \dots + \pi_{pij}d_{pij} \quad (10.2)$$

We use an extra level, the *dummy-variable* level, to specify a multivariate model using software that is essentially made for univariate analyses. There is no lowest-level error term in Equation 10.2; the lowest level exists solely to define the multivariate response structure.¹ For the moment, we assume no explanatory variables, and we have the equivalent of the intercept-only model. Then, at the individual level (the second level in the multivariate model), we have

$$\pi_{pij} = \beta_{pj} + u_{pij} \quad (10.3)$$

At the group level (the third level in the multivariate model), we have

$$\beta_{pj} = \gamma_p + u_{pj} \quad (10.4)$$

By substitution we obtain

$$\begin{aligned} Y_{hij} = & \gamma_1 d_{1ij} + \gamma_2 d_{2ij} + \dots + \gamma_p d_{pij} + u_{1ij} d_{1ij} + u_{2ij} d_{2ij} + \dots \\ & + u_{pij} d_{pij} + u_{1j} d_{1ij} + u_{2j} d_{2ij} + \dots + u_{pj} d_{pij} \end{aligned} \quad (10.5)$$

In the univariate intercept-only model, the fixed part contains only the intercept, which is the overall mean, and the random part contains two variances, which are the variance at the individual and the group level. In the multivariate model that is equivalent to the univariate intercept-only model, the fixed part contains in the place of the intercept the P regression coefficients for the P dummy variables, which are the P overall means for the P outcome variables. The random part contains two covariance matrices, Ω_{ij} and Ω_j , which contain the variances and the covariances of the regression slopes for the dummies on the individual and the group level. Since Equation 10.5 is complicated, especially if we have many response variables, it is often expressed using sum notation:

$$Y_{hij} = \sum_{h=1}^P \gamma_h d_{hij} + \sum_{h=1}^P u_{hj} d_{hij} + \sum_{h=1}^P u_{hj} d_{hij} . \quad (10.6)$$

Just as in univariate modeling, explanatory variables at the individual or the group level can be added to the model. In general, we add an individual-level explanatory variable X_{ij} or a group-level variable Z_j to the model by multiplying it with all p dummy variables, and adding all p resulting interaction-variables to the equation. Since the dummy variables are equal to zero whenever $p \neq h$, these terms disappear from the model. Thus there are p distinct contributions to the multilevel regression equation, each specific to one of the p response variables.

We can specify random slopes for the individual level explanatory variables at the group level, and add cross-level interactions to explain random variation, completely analogous to adding explanatory variables and cross-level interactions to the univariate models discussed in Chapter 2. If we multiply each explanatory variable with all of the dummy variables, we allow that for each predictor each regression coefficients in the model may be different for each response variable. It would simplify the model considerably, if we could impose an equality constraint across all response variables, assuming that the effects are equal for all response variables. This of course makes sense only if all outcome variables are measured on the same scale and with equal reliability. There are two ways to accomplish this. For simplicity, let us assume that we have two response variables Y_1 and Y_2 , only one explanatory variable X , and no group structure. Equation 10.2 now becomes

$$Y_{hi} = \pi_{1i} d_{1i} + \pi_{2i} d_{2i} , \quad (10.7)$$

and Equation 10.5 simplifies to

$$Y_{hi} = \gamma_1 d_{1i} + \gamma_2 d_{2i} + u_{1i} d_{1i} + u_{2i} d_{2i} . \quad (10.8)$$

We add explanatory variable X_i to the model, by multiplying it with each dummy variable. This produces

$$Y_{hi} = \gamma_{01} d_{1i} + \gamma_{02} d_{2i} + \gamma_{11} d_{1i} X_i + \gamma_{12} d_{2i} X_i + u_{1i} d_{1i} + u_{2i} d_{2i} . \quad (10.9)$$

If we force the two regression coefficients for Y_1 and Y_2 to be equal by adding the constraint that $\gamma_{11} = \gamma_{12} = \gamma^*$, we get

$$Y_{hi} = \gamma_{01}d_{1i} + \gamma_{02}d_{2i} + \gamma^*d_{1i}X_i + \gamma^*d_{2i}X_i + u_{1i}d_{1i} + u_{2i}d_{2i}, \quad (10.10)$$

which can also be written as

$$Y_{hi} = \gamma_{01}d_{1i} + \gamma_{02}d_{2i} + \gamma^*[d_{1i}X_i + d_{2i}X_i] + u_{1i}d_{1i} + u_{2i}d_{2i}. \quad (10.11)$$

Since the two dummies that indicate the separate response variables are mutually exclusive, only one dummy variable will be equal to one for each specific response variable Y_{hi} , and the other is equal to zero. Therefore, equation 10.11 can also be written as

$$Y_{hi} = \gamma_{01}d_{1i} + \gamma_{02}d_{2i} + \gamma^*X_i + u_{1i}d_{1i} + u_{2i}d_{2i}. \quad (10.12)$$

This makes clear that imposing an equality constraint across all regression slopes for a specific explanatory variable is equal to adding this explanatory variable directly, without multiplying it with all the available dummies. This also implies that the model of Equation 10.12 is nested within the model of Equation 10.9. As a result, we can test whether simplifying model 10.9 to model 10.12 is justified, using the chi-square test on the deviances, with $p - 1$ degrees of freedom. The example given here involves changes to the fixed part, so we can use the deviance test only if we use full maximum likelihood (FML) estimation. If the explanatory variable X has random slopes at the group level, a similar argument would apply to the random part of the model. Adding a random slope for one single explanatory variable X to the model implies estimating one variance component. Adding a random slope to each of the explanatory variables constructed by multiplying X with each of the dummies implies adding a $p \times p$ (co)variance matrix to the model. This adds $p(p - 1) / 2$ parameter estimates to the model, and the degrees of freedom for the corresponding simultaneous chi-square difference test is $(p(p - 1) / 2) - 1$.

10.2 EXAMPLE OF MULTIVARIATE MULTILEVEL ANALYSIS: MULTIPLE RESPONSE VARIABLES

Chapter 6 discusses an example that analyzes response rates on face-to-face, telephone, and mail surveys, as reported in 47 studies over a series of years (Hox & de Leeuw, 1994). In this example, there are two indicators of survey response. The first is the completion rate, which is the number of completed interviews divided by the total number of persons approached. The second is the response rate, which is the number of completed interviews divided by the total number of persons approached *minus* the number of persons that are considered ineligible (address incorrect, deceased). Some studies report the completion rate, some the

response rate, and some both. The analysis reported in Chapter 6 analyzes response rates if available, and otherwise completion rates, with a dummy variable indicating when the completion rate is used. Since some studies report both the response rate and the completion rate, this approach is wasteful because it ignores part of the available information. Furthermore, it is an interesting question by itself, whether the response rate and completion rate behave similarly or differently over time. Using a multivariate model we can include all information, and carry out a multivariate meta-analysis to investigate the similarity between response rate and completion rate.

In Chapter 6, the model is a two-level model, with data collection conditions (face-to-face, telephone, and mail) as the lowest level, and the 47 studies the second level. For the multivariate model, we specify the response as the lowest level. The conditions (face-to-face, telephone, and mail) are the second level and the studies are the third level. Since the response variable is a proportion, we use a generalized linear model with a logit link and a binomial error distribution (for details on multilevel generalized linear models see Chapter 6). Let p_{hij} be the observed proportions of respondents on the response rate or completion rate in condition i of study j . At the response indicator level, we have two explanatory variables, *comp* and *resp*, which are dummies that indicate whether the response is a completion rate or a response rate. The multivariate empty model can now be written as

$$P_{hij} = \text{logistic}(\pi_{1ij} \text{comp}_{ij} + \pi_{2ij} \text{resp}_{ij}). \quad (10.13)$$

The empty model for these data is

$$P_{hij} = \text{logistic} \left(\gamma_{01} \text{comp}_{ij} + \gamma_{02} \text{resp}_{ij} + u_{1ij} \text{comp}_{ij} + u_{2ij} \text{resp}_{ij} + u_{1j} \text{comp}_{ij} + u_{2j} \text{resp}_{ij} \right). \quad (10.14)$$

The model in Equation 10.14 provides us with estimates (on the logit scale) of the average completion rate and response rate, and the covariance matrix between completion rate and response rate at the condition level and the study level.

The parameter estimates (using restricted maximum likelihood (RML) with penalized pseudo-likelihood (PQL) estimation and second-order Taylor linearization, cf. Chapter 6) are in Table 10.1. The first column shows the parameter estimates for the empty model. It produces two intercept estimates, indicated by ‘comprate’ and ‘resprate,’ one for the completion rate and one for the response rate.

Note that these estimates are not the same as the estimates we would get from two separate univariate analyses. If there is a tendency, for instance, to report only the response rate when the survey response is disappointing, because that looks better in the report, the omitted values for the completion rate are not missing completely at random. The univariate analysis of response rate has no way to correct for this bias; it assumes that any absent values are missing completely at random (MCAR). The multivariate model contains the covariance between the response rate and the completion rate. Hence, it can correct for the

Table 10.1 Results of survey response data

Model	M0: intercepts for comp. and resp. rate	M1: M0 + condition indicators
Fixed part		
Predictor	Coefficient (s. e.)	Coefficient (s. e.)
comprate	0.84 (0.13)	1.15 (0.16)
resprate	1.28 (0.15)	1.40 (0.16)
tel×comp		−0.34 (0.15)
tel×resp		−0.10 (0.11)
mail×comp		−0.69 (0.16)
mail×resp		−0.40 (0.13)
Random part		
$\sigma^2_{comp/cond}$	0.41 (0.09)	0.31 (0.07)
$\sigma^2_{resp/cond}$	0.20 (0.05)	0.18 (0.04)
$r_{cr/cond}$	0.96	0.97
$\sigma^2_{comp/cstudy}$	0.53 (0.17)	0.61 (0.17)
$\sigma^2_{resp/cstudy}$	0.89 (0.22)	0.83 (0.21)
$r_{cr/cstudy}$	0.99	0.95

bias in reporting the response rate; it assumes that any absent values are missing at random (MAR), which is a weaker assumption. Because of this implicit correction, the intercepts and other regression coefficients in the multivariate model can be different from those estimated separately in a series of univariate analyses. This is similar to the situation in multilevel longitudinal modeling (cf. Chapter 5), where panel dropout in the multilevel model is assumed to be missing at random. For an accessible discussion of the differences between MAR and MCAR see McKnight, McKnight, Sidani and Figueredo (2007). As in multilevel longitudinal modeling, the fact that the multivariate multilevel model assumes that any absent outcome variables are MAR rather than MCAR is an important advantage when we have incomplete data. The usual practice in MANOVA to analyze only complete cases using listwise deletion assumes MCAR, which is a much stronger assumption than MAR.

The second column in Table 10.1 shows the parameter estimates for the model where the dummy variables that indicate the data collection conditions are added separately for the completion rate and the response rate. The face-to-face condition is the reference category, and two dummy variables are added which indicate the telephone and mail condition. We do not assume that the effect of the conditions is the same for both completion and response rate. Therefore, the two condition dummies are entered as interactions with the dummies that indicate the completion and response rate. Thus, the model equation is

$$P_{hij} = \text{logistic} \left(\begin{array}{l} \gamma_{01} \text{comp}_{ij} + \gamma_{02} \text{resp}_{ij} \\ + \gamma_{03} \text{tel}_{ij} \text{comp}_{ij} + \gamma_{04} \text{tel}_{ij} \text{resp}_{ij} + \gamma_{05} \text{mail}_{ij} \text{comp}_{ij} + \gamma_{06} \text{mail}_{ij} \text{resp}_{ij} \\ + u_{1ij} \text{comp}_{ij} + u_{2ij} \text{resp}_{ij} + u_{1j} \text{comp}_{ij} + u_{2j} \text{resp}_{ij} \end{array} \right). \quad (10.15)$$

Both the two ‘intercepts’ for the completion rate and the response rate, and the regression slopes for the effect of the telephone and mail condition on the completion rate and the response rate seem to be quite different in Table 10.1. We can formally test the null-hypothesis that they are equal by testing the appropriate contrast. Testing the intercepts of *comp* and *resp* for equality, using the procedures described in Chapter 3, produces a chi-square of 6.82, which with one degree of freedom has a *p*-value of 0.01. Since the face-to-face condition is the reference category for the dummy variables, this gives a test of the equality of completion rate and response rate in the face-to-face condition. The same test produces for the telephone condition dummy variables a chi-square of 6.81, with one degree of freedom and a *p*-value of 0.01. For the mail condition, we get a chi-square of 8.94, with one degree of freedom and a *p*-value of 0.00. Clearly, the different data collection conditions affect the completion rate and the response rate in a different way.

The variance components are indicated in Table 10.1 by $\sigma^2_{\text{comp/cond}}$ for the intercept variance for the completion rate on the condition level, and $\sigma^2_{\text{comp/study}}$ for the intercept variance for the completion rate on the study level. Likewise, $\sigma^2_{\text{resp/cond}}$ indicates the intercept variance for the response rate on the condition level, and $\sigma^2_{\text{resp/study}}$ for the intercept variance for the response rate on the study level. Note that Tables 10.1 and 10.2 do not report the deviance. The estimation is based on the quasi-likelihood approach described in Chapter 6 (as implemented in MLwiN), and therefore the deviance is only approximate.

If we add the explanatory variables publication year and saliency of survey topic, contrast tests show that these have similar effects on both the completion rate and the response rate. As a result, we can either add them to the regression equation as interactions with the completion and response rate dummies, constraining the equivalent regression slopes to be equal (cf. Equations 10.9–10.11), or as a direct effect of the explanatory variables year and saliency (cf. Equation 10.12).

Table 10.2 presents the parameter estimates for both model specifications. Both specifications produce the same value for the parameter estimates and the corresponding standard errors for the explanatory variables ‘year’ and ‘saliency’. The model that includes the explanatory variables directly is given by

$$P_{hij} = \text{logistic} \left(\begin{array}{l} \gamma_{01} \text{comp}_{ij} + \gamma_{02} \text{resp}_{ij} \\ + \gamma_{03} \text{tel}_{ij} \text{comp}_{ij} + \gamma_{04} \text{tel}_{ij} \text{resp}_{ij} + \gamma_{05} \text{mail}_{ij} \text{comp}_{ij} + \gamma_{06} \text{mail}_{ij} \text{resp}_{ij} \\ + \gamma_{07} \text{year}_j + \gamma_{08} \text{saliency}_j \\ + u_{1ij} \text{comp}_{ij} + u_{2ij} \text{resp}_{ij} + u_{1j} \text{comp}_{ij} + u_{2j} \text{resp}_{ij} \end{array} \right). \quad (10.16)$$

Table 10.2 Results of survey response data, model comparison

Model	Year and saliency as interaction terms	Year and saliency directly
Fixed part		
Predictor	Coefficient (s. e.)	Coefficient (s. e.)
comprate	0.83 (0.43)	0.83 (0.43)
resprate	1.06 (0.43)	1.06 (0.43)
tel×comp	−0.32 (0.15)	−0.32 (0.15)
tel×resp	−0.41 (0.11)	−0.41 (0.11)
mail×comp	−0.71 (.16)	−0.71 (0.16)
mail×resp	−0.40 (0.13)	−0.40 (0.13)
year×comp ^a	−0.01 (0.01)	n/a
year×resp ^a	−0.01 (0.01)	n/a
sali×comp ^b	0.69 (0.17)	n/a
sali×resp ^b	0.69 (0.17)	n/a
year	n/a	−0.01 (0.01)
saliency	n/a	0.69 (0.17)
Random part		
$\sigma^2_{comp/cond}$	0.31 (0.07)	0.31 (0.07)
$\sigma^2_{resp/cond}$	0.18 (0.04)	0.18 (0.04)
$r_{cr/cond}$	0.97	0.97
$\sigma^2_{comp/cstudy}$	0.45 (0.14)	0.45 (0.14)
$\sigma^2_{resp/cstudy}$	0.52 (0.14)	0.52 (0.14)
$r_{cr/cstudy}$	0.91	0.91

a,b Slopes constrained to be equal

The model that includes these explanatory variables as interactions including two equality constraints, indicated by the superscripts *a* and *b*, is given by

$$P_{hij} = \text{logistic} \left(\begin{array}{l} \gamma_{01}comp_{ij} + \gamma_{02}resp_{ij} \\ + \gamma_{03}tel_{ij}comp_{ij} + \gamma_{04}tel_{ij}resp_{ij} + \gamma_{05}mail_{ij}comp_{ij} + \gamma_{06}mail_{ij}resp_{ij} \\ + \gamma_{07}^a year_j \times comp_{ij} + \gamma_{08}^a year_j \times resp_{ij} \\ + \gamma_{09}^b saliency_j \times comp_{ij} + \gamma_{10}^b saliency_j \times resp_{ij} \\ + u_{1ij}comp_{ij} + u_{2ij}resp_{ij} + u_{1j}comp_{ij} + u_{2j}resp_{ij} \end{array} \right). \quad (10.17)$$

Table 10.2 shows empirically what is derived in Equations 10.9–10.12, namely that the two representations are equivalent. Since adding year and saliency directly is simpler, this is the preferred method.

If we have a number of outcomes, all related to a single theoretical construct or syndrome, directly adding an explanatory variable to the model results in a higher power than adding them as a set of interactions with all outcome variables. The reason is that in the former case we use a one-degree of freedom test, and in the latter a p -degree of freedom overall test. Adding an explanatory variable directly assumes that all interactions result in the same regression weight, which can subsequently be constrained to be equal. This assumption of a common effect size is strong, and it is not realistic if outcome variables are measured on different scales. Sammel, Lin and Ryan (1999) discuss the possibility of smoothing the regression coefficients. They suggest scaling the outcome variables prior to the analysis in such a way that they are measured on the same scale. With continuous variables a transformation to standardized scores is appropriate. Raudenbush, Rowan and Kang (1991) employ a transformation to correct for differences in measurement reliability. To arrive at comparable effect sizes their approach means that the outcome variables are first divided by the square root of the corresponding reliability coefficient, and then standardized.

10.3 EXAMPLE OF MULTIVARIATE MULTILEVEL ANALYSIS: MEASURING GROUP CHARACTERISTICS

Sometimes the interest may be in measuring characteristics of the context, that is, of the higher-level units, which can be individuals, groups, or organizations. For instance, we may be interested in school climate, and use a questionnaire that is answered by a sample of pupils from each of the schools. In this example we are not necessarily interested in the pupils, they are just used as informants to judge the school climate. Similar situations arise in health research, where patients may be used to express their satisfaction with their general practitioner, and community research, where samples from different neighborhoods evaluate various aspects of the neighborhood in which they live. In these cases, we may use individual characteristics to control for possible measurement bias, but the main interest is in measuring some aspect of the higher-level unit (cf. Paterson, 1998; Raudenbush & Sampson, 1999; Sampson, Raudenbush & Earls, 1997). This type of measurement was called ‘ecometrics’ by Raudenbush and Sampson (1999).

Our example concerns data from an educational research study by Krüger (1994). In this study, male and female school managers were compared on a large number of characteristics. As part of the study, small samples of pupils from each school rated their school manager on six seven-point items that indicate a people-oriented approach toward leadership (the data are described in more detail in the appendix). There are ratings from 854 pupils within 96 schools, 48 with a male and 48 with a female school manager, on these six items. If we calculate the reliability coefficient, Cronbach’s α , for the six items, we get a reliability of 0.80, which is

commonly considered sufficient to sum the items to a scale (Nunnally & Bernstein, 1994). However, this reliability estimate is difficult to interpret, because it is based on a mixture of school-level and individual pupil-level variance. Since all judgments within the same school are ratings of the same school manager, within school variance does not give us information about the school manager. From the measurement point of view, within school variance is a form of error variance, and we want to concentrate only on the between schools variance.

One convenient way to model data such as these is to use a multivariate multilevel model, with separate levels for the items, the pupils, and the schools. Thus, we create six dummy variables to indicate the six items, and exclude the intercept from the model. Hence, at the lowest level we have

$$Y_{hij} = \pi_{1ij}d_{1ij} + \pi_{2ij}d_{2ij} + \dots + \pi_{6ij}d_{6ij} . \quad (10.18)$$

At the individual level we have

$$\pi_{pij} = \beta_{pj} + u_{pij} . \quad (10.19)$$

At the group level (the third level in the multivariate model), we have

$$\beta_{pj} = \gamma_p + u_{pj} . \quad (10.20)$$

By substitution, we obtain the single-equation version

$$\begin{aligned} Y_{hij} = & \gamma_1 d_{1ij} + \gamma_2 d_{2ij} + \dots + \gamma_6 d_{pij} \\ & + u_{1ij}d_{1ij} + u_{2ij}d_{2ij} + \dots + u_{6ij}d_{pij} \\ & + u_{1j}d_{1ij} + u_{2j}d_{2ij} + \dots + u_{6j}d_{pij} \end{aligned} \quad (10.21)$$

Using sum notation, we have:

$$Y_{hij} = \sum_{h=1}^6 \gamma_h d_{hij} + \sum_{h=1}^6 u_{hij} d_{hij} + \sum_{h=1}^6 u_{hj} d_{hij} . \quad (10.22)$$

The model described by Equations 10.21 and 10.22 provides us with estimates of the six item means, and of their variances and covariances at the pupil and school level. Since in this application we are mostly interested in the variances and covariances, RML estimation is preferred to FML estimation.

Table 10.3 presents the RML estimates of the covariances and the corresponding correlations at the pupil level, and Table 10.4 presents the same at the school level. The tables show that most of the variance of the six items is pupil-level variance, that is, variance between pupils within schools. Since within the same school all pupils are evaluating the same school manager, this variance must be regarded as systematic measurement variance. Apparently, the pupils differ systematically in the way they use the six items. The pattern of covariation in Table 10.3 shows how they differ. We can add pupil-level variables to the

Table 10.3 Covariances and correlations at the pupil level

	1	2	3	4	5	6
Item 1	1.19	0.57	0.44	0.18	0.25	<i>0.44</i>
Item 2	0.67	1.13	0.52	0.18	<i>0.26</i>	<i>0.38</i>
Item 3	0.49	0.57	1.07	<i>0.19</i>	<i>0.23</i>	<i>0.43</i>
Item 4	0.17	0.17	0.17	0.74	<i>0.60</i>	<i>0.30</i>
Item 5	0.22	0.23	0.20	0.42	0.66	<i>0.38</i>
Item 6	0.48	0.41	0.45	0.26	0.31	1.00

Note: the italic entries in the upper diagonal are the correlations

Table 10.4 Covariances and correlations at the school level

	1	2	3	4	5	6
Item 1	0.24	<i>0.91</i>	<i>0.87</i>	<i>0.57</i>	<i>0.93</i>	<i>0.96</i>
Item 2	0.30	0.45	<i>0.98</i>	<i>0.14</i>	<i>0.58</i>	<i>0.88</i>
Item 3	0.24	0.36	0.31	<i>0.07</i>	<i>0.53</i>	<i>0.87</i>
Item 4	0.12	0.04	0.02	0.19	<i>0.89</i>	<i>0.57</i>
Item 5	0.15	0.13	0.10	0.13	0.11	<i>0.90</i>
Item 6	0.16	0.20	0.17	0.09	0.10	0.12

Note: the italic entries in the upper diagonal are the correlation

model, to investigate whether we can model this covariation. However, what we model in that case is individual idiosyncrasies in the way the measurement instrument is used by the different pupils. From the perspective of measurement, we are mostly interested in Table 10.4, because this shows how the items perform on the school level. Although the variances at the school level are lower, the correlations are generally much higher. The mean correlation at the pupil level is 0.36, and at the school level 0.71. This is reassuring, because it means that at the school level the consistency of the measurement instrument is higher than at the individual level.

We can use the covariances or correlations in Table 10.4 to carry out an item-analysis on the student or the school level. We can use standard formulas from classical measurement theory to calculate the internal consistency reliability coefficient α . For instance, a convenient way to estimate the internal consistency given the results in Table 10.3 or 10.4 is to use the mean correlation (e.g., Nunnally & Bernstein, 1994). We can estimate the internal consistency of the scale from the mean correlation, using the Spearman–Brown formula for test length. With p items, the reliability of the p -item scale is given by

$$\alpha = p\bar{r}/(1+(p-1)\bar{r}) \tag{10.23}$$

where \bar{r} is the mean correlation of the items, and p is the scale length. The mean correlation at the school level is 0.71, and using the Spearman–Brown formula, we can estimate the school-level coefficient α internal consistency as 0.94. However, this is not a very accurate estimate, since it ignores the differences in the variance of the items, but it produces a rough approximation. For a more accurate estimate, we could use the covariances in Table 10.3 or Table 10.4 as input in a software program for reliability or factor analysis, for a more formal analysis of the relationships between the items. If we do this, the coefficient α is estimated as 0.92, and the item analysis further informs us that we should consider removing Item 4 from the scale, because of its low correlations with the other items.

There is one important consideration. The matrix of covariances or correlations at the school level is a maximum likelihood estimator of the population matrix. It can be analyzed directly using models and software that can handle direct input of such matrices. Using them for measurement at the school level is more questionable because that assumes that we can actually observe the school-level residual errors that give rise to the covariances and correlations in Table 10.4. In actual fact, we cannot observe these residuals directly, let alone calculate their sum or mean. What we can observe is the school-level means of the evaluations given by the pupils in a specific school. Unfortunately, these school-level observed means also reflect the pupil-level variation; part of the variation at the school level is due to differences between pupils within schools. This issue will be taken up in detail in the chapters on multilevel structural equation modeling (Chapters 14 and 15). In the context of multilevel measurement, it means that the observed school-level aggregated means contain error variation that is not visible in Table 10.4, so if their reliability is estimated using the covariances or correlations in Table 10.4 it will be overestimated.

Raudenbush, Rowan and Kang (1991) present an extensive discussion of the issues involved in multilevel measurement using observed group-level means. They provide equations to calculate both the pupil-level and school-level internal consistency directly, using the intercept variances at the three available levels estimated in an intercept only model (Raudenbush et al., 1991, pp. 309–312). This model can be written as

$$Y_{hij} = \gamma_{000} + u_{0hij} + u_{0ij} + u_{0j}. \quad (10.24)$$

The model in Equation 10.24 is the intercept-only model with three levels: the item, pupil, and school level. For our example, the variances are in Table 10.5, using an obvious notation for the subscripts of the variance components.

In Table 10.5, σ^2_{item} can be interpreted as an estimate of the variation due to item inconsistency, σ^2_{pupil} as an estimate of the variation of the scale score (mean item score) between different pupils within the same school, and σ^2_{school} as an estimate of the variation of the scale score between different schools. These variances can be used to produce the internal consistency reliability on the pupil and school level. If we have p items, the error variance in the scale score (computed as the mean of the items) is given by $\sigma^2_e = \sigma^2_{item} / p = 0.845 / 6 = 0.141$.

Table 10.5 Intercept and variances for school manager data

	Coefficient(s.e.)
Fixed part	
Intercept	2.57(.05)
Random part	
σ^2_{school}	0.179 (.03)
σ^2_{pupil}	0.341 (.03)
σ^2_{item}	0.845 (.02)

The item level exists only to produce an estimate of the variance due to item inconsistency. We are in fact using a scale score that is computed as the mean of the items. The intraclass correlation of the scale score for the schools is given by $\rho_1 = \sigma^2_{school} / (\sigma^2_{school} + \sigma^2_{pupil})$, which for our example is $0.179 / (0.179 + 0.341) = 0.344$. Therefore, for the scale score, about 34 percent of the variance is between schools.

The pupil-level internal consistency is estimated by $\alpha_{pupil} = \sigma^2_{pupil} / (\sigma^2_{pupil} + \sigma^2_{item} / p)$. For our example data this gives $\alpha_{pupil} = 0.341 / (0.341 + 0.845 / 6) = 0.71$. This reflects consistency in the variability of the ratings of the same school manager by pupils in the same schools. This internal consistency coefficient indicates that the pupil-level variability is not random error, but that it is systematic. It could be just systematic error, for instance response bias such as a halo effect in the judgments made by the pupils, or it could be based on different experiences of pupils with the same manager. This could be explored further by adding pupil characteristics to the model.

The school-level internal consistency is (Raudenbush et al., 1991, p. 312):

$$\alpha_{school} = \sigma^2_{school} / \left[\sigma^2_{school} + \sigma^2_{pupil} / n_j + \sigma^2_{item} / (p \cdot n_j) \right]. \tag{10.25}$$

In Equation 10.25, p is the number of items in the scale, and n_j is the number of pupils in school j . Since the number of pupils varies across schools, the school-level reliability also varies. In schools with a larger sample of pupils the management style is measured more accurately than in schools with a small sample of pupils. To obtain an estimate of the average reliability across all schools, Raudenbush, Rowan and Kang (1991, p. 312) suggest using the mean of the schools' internal consistencies as a measure of the internal consistency reliability. A simpler approach is to use Equation 10.25 with the mean number of pupils across all schools for n_j . In our example we have on average 8.9 pupils in each school, and if that number is plugged into Equation 10.25 the overall school-level internal consistency is estimated as:

$$\alpha_{school} = 0.179 / [0.179 + 0.341 / 8.9 + 0.845 / (8.9 \cdot 6)] = 0.77.$$

The value of 0.77 for the school-level internal consistency coefficient indicates that the school managers' leadership style is measured with sufficient consistency.² The number of pupils per class varies between 4 and 10. If we plug these values into the equation, we find a reliability of 0.60 with four pupils, and 0.91 with ten pupils. It appears that we need at least four pupils in each school to achieve sufficient measurement precision, as indicated by the school-level coefficient of internal consistency.

The school-level internal consistency depends on four factors: the number of items in the scale k , the mean correlation between the items on the school level \bar{r} , the number of pupils sampled in the schools n_j , and the intraclass correlation at the school level ρ_r . The school-level reliability as a function of these quantities is

$$\alpha_{school} = \frac{kn_j\rho_r\bar{r}}{kn_j\rho_r\bar{r} + [(k-1)\bar{r} + 1](1-\rho_r)}. \quad (10.26)$$

The mean item intercorrelation at the school level can conveniently be estimated using the variances in the intercept-only model by $\bar{r} = \sigma_{pupil}^2 / (\sigma_{pupil}^2 + \sigma_{item}^2)$.

Equation 10.26 shows that the internal consistency reliability can be improved by including more items in the scale, but also by taking a larger sample of pupils in each school. Raudenbush, Rowan and Kang (1991) demonstrate that increasing the number of pupils in the schools increases the school-level reliability faster than increasing the number of items in the scale. Even with a low inter-item correlation and a low intraclass correlation, increasing the number of pupils to infinity (admittedly hard to do) will in the end produce a reliability equal to one, whereas increasing the number of items to infinity will, in general, not.

If we have a measure consisting of only one item, the reliability at the pupil level cannot be determined. The reliability of the aggregated group mean at the school level is given by

$$\lambda_j = \frac{\sigma_{school}^2}{\sigma_{school}^2 + \sigma_{pupil}^2 / n} \quad (10.27)$$

where σ_{school}^2 is the between-schools variance, σ_{pupil}^2 is the within-schools (pupil-level) variance, and n is the common or average number of pupils per school (cf. Snijders & Bosker, 2012, pp. 25–26). Simulations by Schunck (2016) indicate that with small group sizes, such aggregated means scores can be quite unreliable. Croon and van Veldhoven (2007) show that for group-level measures based on lower-level indicators a latent variable model is to be preferred, an approach that is treated in Chapter 14.

In an analysis presented by Raudenbush, Rowan and Kang (1991), the measurement model is extended by combining items from several different scales in one analysis. The constant in the multilevel model is then replaced by a set of dummy variables that indicate to which scale each item belongs. This is similar to a confirmative factor analysis, with the restriction that the loadings of all items that belong to the same scale are equal, and that there is one common error variance. These are strong restrictions, which are often expressed as the assumption that the items are parallel (Lord & Novick, 1968). The usual

assumptions for the internal consistency index are considerably weaker. For a multivariate analysis of complex relationships on a number of distinct levels, multilevel structural equation modeling is both more powerful and less restrictive. These models are discussed in detail in Chapter 14.

If we want to predict the evaluation scores of the school manager using school-level variables, for instance the experience or gender of the school manager, or type of school, we can simply include these variables as explanatory variables in the multilevel model. Sometimes it is useful to have actual evaluation scores, for instance if we want to use these as explanatory variables in a different type of model. We can estimate the school managers' evaluation scores using the school level residuals from the intercept-only model. Since these are centered on the school mean, the school mean must be added again to these residuals, to produce so-called posterior means for the evaluation scores. Since the posterior means are based on the empirical Bayes residuals, they are not simply the observed mean evaluation scores in the different schools, but they are shrunk toward the overall mean. The amount each score is shrunk toward the overall mean depends on the reliability of that score, which depends among others on the number of pupils used in that particular school. The result is that we are using an estimate of the school-level true score of each school manager (cf. Lord & Novick, 1968; Nunnally & Bernstein, 1994). We can add pupil-level explanatory variables to the model, which would lead to evaluation scores that are conditional on the pupil-level variables. This can be used to correct the evaluation scores for inequalities in the composition of the pupil population across schools, which is important if different schools attract different types of pupils.

A nice feature of using multilevel modeling for measurement scales is that it accommodates incomplete data in a straightforward manner. If some of the item scores for some of the pupils are missing, this is compensated in the model. The model results and estimated posterior means are the correct ones, under the assumption that the data are missing at random (MAR). This is a weaker assumption than the missing completely at random (MCAR) assumption than is required with simpler methods, such as using only complete cases or replacing missing items by the mean of the observed items.

The measurement procedures just outlined are based on classical test theory, which means that they assume continuous multivariate normal outcomes. Most test items are categorical. If the items are dichotomous, we can use the logistic multilevel modeling procedures described in Chapter 6. Kamata (2001) shows that the two-level multilevel logistic model is equivalent to the Rasch model (Andrich, 1988), and discusses extensions to three-level models. If we have items with more than two categories, an ordinal multilevel can be used. Adams, Wilson and Wu (1997) and Rijmen, Tuerlinckx, de Boeck and Kuppens (2003) show how these models are related to Item-Response Theory (IRT) models in general. In the interest of accurate measurement, Maximum likelihood with numerical integration (cf. Chapter 6) or Bayesian estimation procedures (cf. Chapter 13) are preferable, especially with dichotomous items.

For general multivariate modeling of hierarchical data, multilevel structural equation modeling is more flexible than the multivariate multilevel regression model. These models are discussed in Chapters 14 and 15.

NOTES

- 1 The symbol π is used for the lowest-level regression coefficients, so we can continue to employ β for the individual level and γ for the group level regression coefficients.
- 2 The difference with the estimate of 0.92 obtained using classical psychometric methods earlier reflects the fact that here we take the variation at the item and pupil level into account when we estimate the school-level reliability. The method presented here is more accurate.

11

The Multilevel Approach to Meta-Analysis

SUMMARY

Meta-analysis is a systematic approach towards summarizing the findings of a collection of independently conducted studies on a specific research problem. In meta-analysis, statistical analyses are carried out on the published results of empirical studies on a specific research question. This chapter shows that multilevel regression models are attractive for analyzing meta-analytic data. They can be used for simple meta-regression, but their real advantage lies in the ability to analyze multivariate data with multiple outcomes per study.

11.1 META-ANALYSIS AND MULTILEVEL MODELING

Meta-analysis is a systematic approach towards the synthesis of a large number of results from empirical studies (cf. Glass, 1976; Lipsey & Wilson, 2001). The goal is to summarize the findings of a collection of independently conducted studies on a specific research problem. For instance, the research question might be: ‘What is the effect of social skills training on socially anxious children?’ In a meta-analysis, one would collect reports of experiments concerning this question, explicitly code the reported outcomes, and integrate the outcomes statistically into a combined ‘super outcome’. Often the focus is not so much on integrating or summarizing the outcomes, but on more detailed questions such as: ‘What is the effect of different durations for the training sessions?’ or ‘Are there differences between different training methods?’ These questions address the generalizability of the research findings. In these cases, the meta-analyst not only codes the study outcomes, but also codes study characteristics. These study characteristics are potential explanatory variables to explain differences in the study outcomes. Meta-analysis is not just the collection of statistical methods used to achieve integration. It is the application of systematic scientific strategies to the literature review. For a brief introduction to general meta-analysis we refer to Lipsey and Wilson (2001) and Card (2012). A thorough and complete treatment of methodological and statistical issues in meta-analysis, including a chapter on using multilevel regression methods can be found in Cooper, Hedges and Valentine (2009) and in Sutton, Abrams, Jones, Sheldon and Song (2000).

The core of meta-analysis is that statistical analyses are carried out on the published results of a collection of empirical studies on a specific research question. One approach is to combine the p -values of all the collected studies into one combined p -value. This is a simple

matter, but does not provide much information. A very general model for meta-analysis is the random-effects model (Hedges & Olkin, 1985, p. 198). In this model, the focus is not on establishing the statistical significance of a combined outcome, but on analyzing the variation of the effect sizes found in the different studies. The random-effects model for meta-analysis assumes that study outcomes vary across studies, not only because of random sampling effects, but also because there are real differences between the studies. For instance, study outcomes may vary because the different studies employ different sampling methods, use different experimental manipulations, or measure the outcome with different instruments. The random-effects model is used to decompose the variance of the study outcomes into two components: one component that is the result of sampling variation, and a second component that reflects real differences between the studies. Hedges and Olkin (1985) and Lipsey and Wilson (2001) describe procedures that can be used to decompose the total variance of the study outcomes into random sampling variance and systematic between-studies variance, and procedures to test the significance of the between-studies variance. If the between-studies variance is large and significant, the study outcomes are regarded as *heterogeneous*. This means that the studies do not all provide the same outcome, the outcomes have a distribution, and the available sample of studies is used to estimate the mean and variance of that distribution. The next goal is to identify study characteristics that explain the variance between the studies. Variables that affect the study outcomes are in fact moderator variables: variables that interact with the independent variable to produce variation in the study outcomes.

Meta-analysis can be viewed as a special case of multilevel analysis. We have a hierarchical data set, with subjects within studies at the first level, and studies at the second level. If the raw data of all the studies would be available, we could carry out a standard multilevel analysis, predicting the outcome variable using the available individual- and study-level explanatory variables. In our example on the effect of social skills training of children, we would have one outcome variable, for instance the result on a test measuring social skill, and one explanatory variable which is a dummy variable that indicates whether the subject is in the experimental or the control group. On the individual level, we have a linear regression model that relates the outcome to the experimental/control-group dummy variable. The general multilevel regression model assumes that each study has its own regression model. If we have access to all the original data, standard multilevel analysis can be used to estimate the mean and variance of the regression coefficients for the experimental/control dummy across the studies. If the variance of the regression slopes of the experimental/control-group variable is large and significant, we have heterogeneous results. In that case, we can use the available study characteristics as explanatory variables at the second (study) level to predict the differences of the regression coefficients.

These analyses can be carried out using standard multilevel regression methods and using standard multilevel software. However, in meta-analysis we usually do *not* have access to the original raw data. Instead, we have the published results in the form of means, standard

deviations or correlation coefficients, plus their standard errors, confidence intervals, or the p -values. Classical meta-analysis has developed a large variety of methods to integrate these statistics into one overall outcome, and to test whether these outcomes should be regarded as homogeneous or heterogeneous. Hedges and Olkin (1985) discuss the statistical models on which these methods are based. Hedges and Olkin describe a weighted regression model that can be used to model the effect of study characteristics on the outcomes, and Lipsey and Wilson (2001) show how conventional software for weighted regression analysis can be used to analyze meta-analytic data.

Even without access to the raw data, it is possible to carry out a multilevel meta-analysis on the summary statistics that are the available data for the meta-analysis. Raudenbush and Bryk (2002) view the random-effects model for meta-analysis as a special case of the multilevel regression model. The analysis is performed on sufficient statistics instead of raw data, and as a result, some specific restrictions must be imposed on the model. In multilevel meta-analysis, it is simple to include study characteristics as explanatory variables in the model. If we have hypotheses about study characteristics that influence the outcomes, we can code these and include them on *a priori* grounds in the analysis. Alternatively, after we have concluded that the study outcomes are heterogeneous, we can explore the available study variables in an attempt to explain the heterogeneity.

The major advantage of using multilevel analysis instead of classical meta-analysis methods is flexibility (Hox & de Leeuw, 2003). Using a multilevel framework, it is easy to add further levels to the model, for example to accommodate multiple outcome variables. Estimation can be done using maximum likelihood methods, and a range of estimation and testing methods are available (cf. Chapters 3 and 13). However, not all multilevel analysis software can be used for multilevel meta-analysis; the main requirement is that it is possible to impose constraints on the random part of the model.

11.2 THE VARIANCE-KNOWN MODEL

In a typical meta-analysis, the collection of studies found in the literature employs different instruments and use different statistical tests. To make the outcomes comparable, the study results must be transformed into a standardized measure of the effect size, such as a correlation coefficient or the standardized difference between two means. For instance, if we perform a meta-analysis on studies that compare an experimental group to a control group, an appropriate measure for the effect size is the standardized difference between two means g , which is given by $g = (\bar{Y}_E - \bar{Y}_C) / s$. The standard deviation s is either the standard deviation in the control group, or the pooled standard deviation for both the experimental and control group. Since the standardized difference g has a small upwards bias, it is often transformed to the unbiased effect size indicator $d = (1 - 3 / (4N - 9))g$, where N is the total sample size for the study. This correction is most appropriate when N is less than 20; with larger sample sizes the bias correction is negligible (Hedges & Olkin, 1985).

The general model for the study outcomes, ignoring possible study-level explanatory variables, is given by

$$d_j = \delta_j + u_j + e_j. \tag{11.1}$$

In Equation 11.1, d_j is the outcome of study j ($j = 1 \dots J$), δ_j is the corresponding population value, u_j is the deviation of the outcome of study j from the overall mean outcome, and e_j is the sampling error for this specific study. It is assumed that the e_j have a normal distribution with a known variance σ_j^2 . If the sample sizes of the individual studies are not too small, for instance between 20 (Hedges & Olkin, 1985, p. 175) to 30 (Raudenbush & Bryk, 2002, p. 207), it is reasonable to assume that the sampling distribution of the outcomes is normal, and that the known variance can be estimated for each study with sufficient accuracy. The assumption of underlying normality is not unique for multilevel meta-analysis; most classical meta-analysis methods also assume normality (cf. Hedges & Olkin, 1985). The variance of the sampling distribution of the outcome measures is assumed known from statistical theory.

Table 11.1 Some effect measures, their transformation and sampling variance

Measure	Estimator	Transformation	Sampling variance
Mean	\bar{x}	—	s^2/n
difference 2 means	$g = (\bar{y}_E - \bar{y}_C) / s$	$d = (1 - 3/(4N - 9))g$	$(n_E + n_C)/(n_E n_C) + d^2 / (2(n_E + n_C))$
Standard deviation	s	$s^* = \ln(s) + 1/(2df)$	$1/(2df)$
Correlation	r	$Z = 0.5 \ln((1+r)/(1-r))$	$1/(n-3)$
Proportion	p	$\text{Logit} = \ln(p/(1-p))$	$1/(np(1-p))$
difference 2 prop.	$d \approx Z_{p1} - Z_{p2}$	—	$\frac{2\pi p_1(1-p_1)e^{Z_{p1}^2}}{n_1} + \frac{2\pi p_2(1-p_2)e^{Z_{p2}^2}}{n_2}$
difference 2 prop.	Log odds ratio $\text{logit}(p_1) - \text{logit}(p_2)$	—	$\frac{1}{a} + \frac{1}{b} + \frac{1}{c} + \frac{1}{d}$ a, b, c, d are cell frequencies
Reliability coefficient α	Cronbach's α^1	$Z = 0.5 \ln \left(\frac{1 + \alpha }{1 - \alpha } \right)$	$1/(n-3)$

1 In the previous editions of this book Bonett's transformation was used for α , but simulations show that the Fisher Z is more accurate (Romano et al., 2010, 2011).

To obtain a good approximation to a normal sampling distribution, and to determine the known variance, a transformation of the original effect size statistic is often needed. For instance, since the sampling distribution of a standard deviation is only approximately normal, it should not be used with small samples. The transformation $s^* = \ln(s) + 1/(2df)$ of the standard deviation improves the normal approximation. The usual transformation for the correlation coefficient r is the familiar Fisher- Z transformation, and for the proportion it is the logit. Note that, if we need to perform a meta-analysis on logits, the procedures outlined in Chapter 6 are generally more accurate. Usually, after a confidence interval is constructed for the transformed variable, the endpoints are translated back to the scale of the original estimator. Table 11.1 lists some common effect size measures, the usual transformation if one is needed, and the sampling variance (of the transformed outcome if applicable) (Bonett, 2002; Lipsey & Wilson, 2001; Raudenbush & Bryk, 2002; Rosenthal, 1994).

Equation 11.1 shows that the effect sizes δ_j are assumed to vary across the studies. The variance of the δ_j is explained by the regression model

$$\delta_j = \gamma_0 + \gamma_1 Z_{1j} + \gamma_2 Z_{2j} + \dots + \gamma_p Z_{pj} + u_j, \quad (11.2)$$

where $Z_1 \dots Z_p$ are study characteristics, $\gamma_1, \dots, \gamma_p$ are the regression coefficients, and u_j is the residual error term, which is assumed to have a normal distribution with variance σ_u^2 . By substituting Equation 11.2 into Equation 11.1 we obtain the complete model

$$d_j = \gamma_0 + \gamma_1 Z_{1j} + \gamma_2 Z_{2j} + \dots + \gamma_p Z_{pj} + u_j + e_j. \quad (11.3)$$

If there are no explanatory variables, the model reduces to

$$d_j = \gamma_0 + u_j + e_j. \quad (11.4)$$

Model 11.4, which is the ‘intercept only’ or ‘empty’ model, is equivalent to the random-effects model for meta-analysis described by Hedges and Olkin (1985).

In Model 11.4, the intercept γ_0 is the estimate for the mean outcome across all studies. The variance of the outcomes across studies, σ_u^2 , indicates how much these outcomes vary across studies. Thus, testing if the study outcomes are homogeneous or heterogeneous is equivalent to testing the null-hypothesis that the variance of the residual errors u_j , indicated by σ_u^2 , is equal to zero. If the test of σ_u^2 is significant, the study outcomes are considered heterogeneous. The proportion of systematic between-study variance can be estimated by the intraclass correlation $\rho = \sigma_u^2 / (\sigma_u^2 + \sigma_e^2)$.

The general Model 11.3 includes study characteristics Z_{pj} to explain differences in the studies’ outcomes. In Model 11.3, σ_u^2 is the residual between-study variance after the explanatory variables are included in the model. A statistical test on σ_u^2 now tests whether the explanatory variables in the model explain all the variation in the studies’ outcomes, or

if there still is unexplained systematic variance left in the outcomes. The difference between the between-studies variance σ_u^2 in the empty model and in the model that includes the explanatory variables Z_{pj} , can be interpreted as the amount of variance explained by the explanatory variables, that is, by the study characteristics.

The multilevel meta-analysis model given by Equation 11.3 is equal to the general weighted regression model for random effects described by Hedges and Olkin (1985, Chapter 9). When the study-level variance is not significant, it can be removed from the model:

$$d_j = \gamma_0 + \gamma_1 Z_{1j} + \gamma_2 Z_{2j} + \dots + \gamma_p Z_{pj} + e_j. \quad (11.5)$$

Compared to Model 11.3, Model 11.5 lacks the study-level residual error term u_j . The result is called the fixed-effect model, which assumes that all studies are homogeneous and all estimate the same underlying population parameter δ . Thus, the fixed-effect model described by Hedges and Olkin (1985, Chapter 8) is a special case of the random effects weighted regression or the multilevel meta-analysis model. Omitting the study-level residual error term u_j implies that there is no variation in the effect sizes across all studies, or that the explanatory variables in the model explain all the variance among the studies. Thus, if the residual between-study variance is zero, a fixed-effect model is appropriate (Hedges & Vevea, 1998). However, this assumption is not very realistic. For instance, Schmidt and Hunter (2015) argue that the between-studies heterogeneity is partly produced by some unavoidable artifacts encountered in meta-analysis. Examples of such artifacts are the (usually untestable) assumption of a normal distribution for the sampling errors e_j , the correctness of statistical assumptions made in the original analyses, differences in reliability of instruments used in different studies, coder unreliability, and so on. It is unlikely that the available study-level variables cover all these artifacts. Generally, the amount of detail in the input for the meta-analysis, the research reports, papers and articles, is not enough to code all these study characteristics for all of the studies. Therefore, heterogeneous results are to be expected (cf. Engels et al., 2000). Since heterogeneous results are common, Schmidt and Hunter (2015) recommend as a rule of thumb that the study-level variance should be larger than 25 percent of all variance to merit closer inspection; study-level variance smaller than 25 percent is likely to be the result of methodological differences between the studies. However, simulations have shown that this '25 percent rule' is very inaccurate and therefore not recommended (Schulze, 2008).

If fixed-effect models are used in the presence of significant between-study variance, the resulting confidence intervals are biased and much too small (Villar et al., 2001; Brockwell & Gordon, 2001). If random-effects models are used, the standard errors are larger, and the estimate of the average effect may be different, depending on the relation between effect sizes and sample sizes in the primary studies (cf. Villar et al., 2001). Since there is as a rule unexplained variance in a meta-analysis, random-effects models are generally preferred

over fixed-effect models. Lipsey and Wilson (2001) describe a weighted least squares regression procedure for estimating the model parameters, which can be applied using standard statistical software for weighted regression. Just like multilevel meta-analysis, this is a powerful approach because one can include explanatory variables in the model. However, in the weighted-regression approach the investigators must supply an estimate of the between-study variance. This variance is estimated before the weighted regression analysis, and the estimated value is then plugged into the weighted-regression analysis (Lipsey & Wilson, 2001). Multilevel analysis programs estimate this variance component, typically using iterative maximum likelihood estimation, which in general is more precise and efficient. In practice, both approaches usually produce very similar parameter estimates. The multilevel approach has the additional advantage that it offers more flexibility, for example, by using a three-level model for multivariate outcomes.

11.3 EXAMPLE AND COMPARISON WITH CLASSICAL META-ANALYSIS

In this section we analyze an example data set using classical meta-analysis methods as implemented in the meta-analysis macros written by David Wilson (Lipsey & Wilson, 2001, appendix D). These macros are based on methods and procedures described by Hedges and Olkin (1985). The (simulated) data set consists of 20 studies that compare an experimental group and a control group.

Let us return to our example on the effect of social skills training on socially anxious children. We collect reports of experiments concerning this question. If we compare the means of an experimental and a control group, an appropriate outcome measure is the standardized difference between the experimental and the control group, originally proposed by Glass (1976) and defined by Hedges and Olkin as $g = (\bar{Y}_E - \bar{Y}_C) / s$, where s is the pooled standard deviation of the two groups. Because g is not an unbiased estimator of the population effect $\delta = (\mu_E - \mu_C) / \sigma$, Hedges and Olkin propose a corrected effect measure d : $d = (1 - 3 / (4(N - 9)))g$. The sampling variance of the effect estimator d is $(n_E + n_C) / (n_E n_C) + d^2 / (2(n_E + n_C))$ (Hedges & Olkin, 1985, p. 86).

Table 11.2 is a summary of the outcomes from a collection of 20 studies. The studies are presented in increasing order of their effect sizes (g , d). Table 11.2 presents both g and d for all 20 studies, with some study characteristics. The difference between g and d is very small in most cases, where study sample sizes are larger than about 20. Table 11.2 also presents the sampling variance of the effect sizes d ($\text{var}(d)$), the one-sided p -value of the t -test for the difference of the two means (p), the number of cases in the experimental (n_{exp}) and control group (n_{con}), and the reliability (r_{ii}) of the outcome measure used in the study. The example data set contains several study-level explanatory variables. A theoretically motivated explanatory variable is the duration in number of weeks of the experimental intervention. It is plausible to assume that longer interventions lead to a larger effect. In addition we have the reliability of the outcome measure (r_{ii}), and the size of the experimental and control group.

Table 11.2 Example meta-analytic data from 20 studies

Study	Weeks	g	d	$\text{var}(d)$	p	n_{exp}	n_{con}	r_{ii}
1	3	-.268	-.264	.086	.810	23	24	.90
2	1	-.235	-.230	.106	.756	18	20	.75
3	2	.168	.166	.055	.243	33	41	.75
4	4	.176	.173	.084	.279	26	22	.90
5	3	.228	.225	.071	.204	29	28	.75
6	6	.295	.291	.078	.155	30	23	.75
7	7	.312	.309	.051	.093	37	43	.90
8	9	.442	.435	.093	.085	35	16	.90
9	3	.448	.476	.149	.116	22	10	.75
10	6	.628	.617	.095	.030	18	28	.75
11	6	.660	.651	.110	.032	44	12	.75
12	7	.725	.718	.054	.003	41	38	.90
13	9	.751	.740	.081	.009	22	33	.75
14	5	.756	.745	.084	.009	25	26	.90
15	6	.768	.758	.087	.010	42	17	.90
16	5	.938	.922	.103	.005	17	39	.90
17	5	.955	.938	.113	.006	14	31	.75
18	7	.976	.962	.083	.002	28	26	.90
19	9	1.541	1.522	.100	.0001	50	16	.90
20	9	1.877	1.844	.141	.00005	31	14	.75

11.3.1 Classical Meta-Analysis

Classical meta-analysis includes a variety of approaches that complement each other. For instance, several different formulas are available for combining p -values. A classic procedure is the so-called Stouffer method (Rosenthal, 1991). In the Stouffer method, each individual (one-sided) p is converted to the corresponding standard normal Z -score. The Z -scores are then combined using $Z = (\sum Z_j) / \sqrt{k}$, where Z_j is the Z -value of study j , and k is the number of studies. For our example data, the Stouffer method gives a combined Z of 7.73, which is highly significant ($p < 0.0001$).

The combined p -value gives us evidence that an effect exists, but no information on the size of the experimental effect. The next step in classical meta-analysis is to combine the effect sizes of the studies into one overall effect size, and to establish the significance or a confidence interval for the combined effect. Considering the possibility that the effects may differ across the studies, the random-effects model is preferred to combine the studies.

In classical meta-analysis, the fixed-effects model is used first to combine the effect sizes. It is clear that larger studies include less sampling error, and therefore deserve a larger weight in combining the effect sizes. Hedges and Olkin (1985) prove that the optimal weight is not the sample size, but the precision, which is equal to the inverse of the sampling variance. The sample size and the inverse variance weight are obviously highly related. Hence, the fixed effect model weights each study outcome with the inverse variance of the effect size: $w_j = 1 / \text{var}(d_j)$. The combined effect size is simply the weighted mean of the effect sizes. The standard error of the combined effect size is calculated as the square root of the sum of the inverse variance weights:

$$SE_{\bar{d}} = \sqrt{\frac{1}{\sum w_j}}. \quad (11.6)$$

The test statistic to test for homogeneity of study outcomes is:

$$Q = \sum w_j (d_j - \bar{d})^2, \quad (11.7)$$

which has a chi-square distribution with $J - 1$ degrees of freedom. If the chi-square is significant, we reject the null-hypothesis of homogeneity and conclude that the studies are heterogeneous; there is significant study-level variation. In classical meta-analysis, the study-level variance is estimated by a method of moments estimator given by

$$\sigma_u^2 = \frac{Q - (J - 1)}{\sum w_j - \left(\frac{\sum w_j^2}{\sum w_j} \right)}. \quad (11.8)$$

The random effects model follows the same procedures, but recalculates the weights by plugging in the estimate of the study-level variance:

$$w_j^* = \frac{1}{\text{var}(d_j) + \sigma_u^2}. \quad (11.9)$$

The random effects model adds the between study-level variance to the known variances when calculating the inverse variance weight. Subsequently, the same methods are used to estimate the combined effect size and its standard error.

A meta-analysis of the effect sizes in Table 11.2, using the random-effects model and the methods described earlier (using the macro MEANES in SPSS), estimates the overall effect as $\delta = 0.580$, with a standard error of 0.106. Using this information, we can carry out a null-hypothesis test by computing $Z = d / SE(d) = 0.58 / 0.106 = 5.47$ ($p < 0.0001$). The 95 percent confidence interval for the overall effect size is $0.37 < \delta < 0.79$. The usual significance test of the between-study variance used in meta-analysis is a chi-square test on the residuals, which for our example data leads to $\chi^2 = 49.59$, ($df = 19$, $p < 0.001$). This test is equivalent to the chi-square residuals test described by Raudenbush & Bryk (2002) and implemented

in HLM. As the result is clearly significant, we have heterogeneous outcomes. This means that the overall effect 0.58 is not the estimate of a fixed population value, but an estimate of the mean of the distribution of effects in the population. The Z -value of 5.47 computed using the random-effects model is not the same as the Z -value of 7.73 computed using the Stouffer method. This difference is most likely due to a difference in power between these methods (Becker, 1994). Since the random-effects meta-analysis produces a standard error which can be used to establish a confidence interval, we will use the results from the meta-analysis.

The parameter variance σ_u^2 is estimated as 0.14, and the proportion of systematic variance is estimated as 0.65 (estimated as σ_u^2 divided by the weighted observed variance). This is much larger than the 0.25 that Schmidt and Hunter (2015) consider a lower limit for examining differences between studies. The conclusion is that the between-study variance is not only significant, but also large enough to merit further analysis using the study characteristics at our disposal. The usual follow-up in classical meta-analysis is to use weighted regression to analyze differences between study outcomes. When the random-effects model is used, the same variance estimate described earlier is plugged into the calculation of the weight, and then weighted regression methods are used to estimate regression weights for the study-level variables. Instead of using the plug-in estimate, iterative maximum likelihood methods are also available, but they are less commonly used (cf. Lipsey & Wilson, 2001, p. 119). Using the method of moments estimator, the regression coefficient of the variable *weeks* is estimated as 0.14, with a standard error of 0.034 and an associated p -value of 0.0000. So the hypothesis that the intervention effect is larger with longer durations of the intervention is sustained. The result of the homogeneity test, conditional on the predictor *weeks*, is $Q = 18.34$ ($df = 18$, $p = 0.43$). There is no evidence for study-level heterogeneity once the differences in duration are accounted for. The residual variance σ_u^2 is estimated as 0.04. The explained variance can be estimated as $(0.14 - 0.04) / 0.14 = 0.71$. Given that the residual variance is not significant, one could decide to consider a fixed model where the variable *weeks* is included. However, the chi-square test for the between-study variance has a low power unless the number of studies is large (at least 50), so it is recommended to keep the between-studies variance in the model (cf. Huedo-Medina et al., 2006).

11.3.2 Multilevel Meta-Analysis

A multilevel meta-analysis of the 20 studies using the empty ‘intercept-only’ model produces virtually the same results as the classical meta-analysis. Since in meta-analysis we are strongly interested in the size of the between-study variance component, restricted maximum likelihood (RML) estimation is the best approach.¹ Using RML, the intercept, which in the absence of other explanatory variables is the overall outcome, is estimated as $\gamma_0 = 0.57$, with a standard error of 0.11 ($Z = 5.12$, $p < 0.001$). The parameter variance σ_u^2 is estimated as 0.15 (s.e. = 0.111, $Z = 1.99$, $p = 0.02$). As the Wald test is inaccurate for

testing variances (cf. Chapter 3), the variance is also tested with the deviance difference test. This produces a chi-square of 10.61 ($df = 1$, halved $p < 0.001$). The proportion of systematic variance is 0.71, which is much larger than 0.25, the lower limit for examining differences between studies (Schmidt and Hunter, 2015). The differences between these results and the results computed using the classical approach to meta-analysis are small, indicating that the classical approach is quite accurate when the goal of the meta-analysis is to synthesize the results of a set of studies.

When we include the duration of the experimental intervention as an explanatory variable in the regression model, we have:

$$d_j = \gamma_0 + \gamma_1 duration_{ij} + u_j + e_j \tag{11.10}$$

The results of the multilevel meta-analysis are summarized in Table 11.3, which presents the results for both the empty (null) model and the model that includes duration, and the results obtained by the classical (random-effects) meta-analysis.

The results are very close. It should be noted that the chi-square from the method of moments analysis is not straightforward: to obtain correct estimates and standard errors for the regression parameters in the second column, we need to use a random-effects model with the plug-in variance estimate; to obtain the correct chi-square for the residual variance we must use the fixed-effects model. The multilevel analysis, using the built-in meta-analysis option in HLM, directly produces the chi-square residuals test. (Different choices and variations in software implementation are discussed in section 11.6.)

After including duration as explanatory variable in the model, the residual between-study variance is much smaller, and no longer significant. The regression coefficient for the duration is 0.14 ($p < 0.001$), which means that for each additional week the expected gain in study outcome is 0.14. The intercept in this model is -0.23 , with a standard error of 0.21 ($p = 0.27$). The intercept is not significant, which is logical, because it refers to the expected

Table 11.3 Results for random effects method-of-moments and multilevel estimation

Analysis	Method of moments	Method of moments	Multilevel REML	Multilevel REML
Delta/intercept	.58 (.11)	-.22 (.21)	.58 (.11)	-.23 (.21)
Duration		.14 (.03)		.14 (.04)
σ_u^2	.14	.04	.15 (.08)	.04 (.04)
χ^2 deviance test and p -value	n.a.	n.a.	$\chi^2=10.6$ $p<.001$	$\chi^2=1.04$ $p=.16$
χ^2 residuals test and p -value	$\chi^2=49.6$ $p < 0.001$	$\chi^2=26.4$ $p=.09$	$\chi^2=49.7$ $p < 0.001$	$\chi^2=26.5$ $p = 0.09$

outcome of a hypothetical experiment with duration of zero weeks. If we center the duration variable by subtracting its overall mean, the intercept does not change from one model to the next, and reflects the expected outcome of the average study. The residual variance in the last model is 0.04, which is not significant. If we compare this with the parameter variance of 0.14 in the empty model, we conclude that 73 percent of the between-studies variance can be explained by including ‘*duration*’ as the explanatory variable in the model.

In the multilevel analyses reported in Table 11.3, RML estimation is used, and the residual between-studies variance is tested for significance twice; once using the deviance difference test, and once using the chi-square test proposed by Raudenbush and Bryk (2002). (The deviance test is not available in the method of moments.) As explained in more detail in Chapter 3, there are two reasons to choose for RML estimation and *not* using the Wald test on the variance. First, in standard applications of multilevel analysis, the variances are often viewed as nuisance parameters. It is important to include them in the model, but their specific value is not very important, because they are not interpreted. In meta-analysis, the question whether all the studies report essentially the same outcome is an important research question. The answer to this question depends on the size and on the decision about the significance of the between-studies variance. Therefore, it is very important to have a good estimate of the between-studies variance and its significance. For this reason, RML estimation is used instead of full maximum likelihood (FML). Generally, FML and RML estimation lead to very similar variance estimates, but if they do not, using RML provides better estimates (Browne, 1998). Second, the asymptotic Wald test on the variance computes the test statistic Z by dividing the variance estimate by its standard error. This assumes a normal sampling distribution for the variance. This assumption is not justified, because variances are known to have a chi-square sampling distribution. Compared to other tests, the Wald test of the variance has a much lower power (Berkhof & Snijders, 2001), and in general the deviance difference test is preferred (Berkhof & Snijders, 2001; LaHuis & Ferguson, 2009). The difference between the deviance difference test and the residuals chi-square test is small, unless the group sample sizes are small. A practical reason for reporting the chi-square residuals test for the variance in a meta-analysis is that the residuals chi-square test proposed by Raudenbush and Bryk (2002) follows the same logic as the chi-square test on the residuals in classic meta-analysis, which facilitates comparison.

Since the study outcome depends in part on the duration of the experiment, reporting an overall outcome for the 20 studies does not convey all the relevant information. We could report the expected outcome for different duration, or calculate which duration is minimally needed to obtain a significant outcome. This can be accomplished by centering the explanatory variable on different values. For instance, if we center the duration around two weeks, the intercept can be interpreted as the expected outcome at two weeks. Some multilevel analysis programs can produce predicted values with their expected error variance, which is also useful to describe the expected outcome for experiments with a different duration.

11.4 CORRECTING FOR ARTIFACTS

Schmidt and Hunter (2015) encourage the correction of study outcomes for a variety of artifacts. It is common to correct the outcome for the attenuation that results from unreliability of the measure used. The correction simply divides the outcome measure by the square root of the reliability, for instance $d^* = d / \sqrt{r_{ii}}$, after which the analysis is carried out as usual. This is the same correction as the classical correction for attenuation of the correlation coefficient in psychometric theory (cf. Nunnally & Bernstein, 1994). Schmidt and Hunter (2015) describe many more corrections. All these corrections share major methodological and statistical problems. One problem is that the majority of corrections always result in larger effect sizes. For instance, if the studies use instruments with a low reliability, the corrected effect size is much larger than the original effect size. If the reported reliability is incorrect, so will be the correction. Because the large effects have in fact not been observed, routinely carrying out such corrections is controversial. A second problem with all these corrections is that they influence the standard error of the outcome measure. Lipsey and Wilson (2001) present proper standard errors for some corrections. However, if the values used to correct outcomes are themselves subject to sampling error, the sampling variance of the outcome measure becomes still larger, and impossible to assess accurately. Especially if many corrections are performed, their cumulative effect on the bias and accuracy of the outcome-measures is totally unclear.

A different approach to correcting artifacts is to include them as covariates in the multilevel regression analysis. For reliability of the outcome measure, this is not optimal, because the proper correction is a nonlinear multiplicative model (cf. Nunnally & Bernstein, 1994), and regression analysis is linear and additive. However, if the reliabilities are not extremely low (Nunnally and Bernstein suggest as a rule of thumb that the reliability of a ‘good’ measure should be larger than 0.70), a linear additive model is a reasonable approximation, and we can always include quadratic or cubic trends in the analysis if that is needed. Figure 11.1 shows the effect of the correction for attenuation for $d = 0.5$ (medium effect size) and a reliability ranging between zero and one. It is clear that for reliabilities larger than 0.5 the relationship is almost linear.

The advantage of adding reliability as a predictor variable is that the effect of unreliability on the study outcomes is estimated based on the available data and not by a priori corrections. Another advantage is that we can test statistically if the correction has indeed a significant effect. Lastly, an interesting characteristic of multilevel modeling in meta-analysis is that it is possible to add an explanatory variable only to the random part, excluding it from the fixed part. Hence, if we suspect that a certain covariate, for instance poor experimental design, has no systematic influence, but increases the variability of the outcomes, we have the option to include it only in the random part of the model, where it affects the between-studies variance, but not the average outcome.

A variation on correcting for artifacts is controlling for the effect of study size. An important problem in meta-analysis is the so-called *file drawer problem*. The data for a

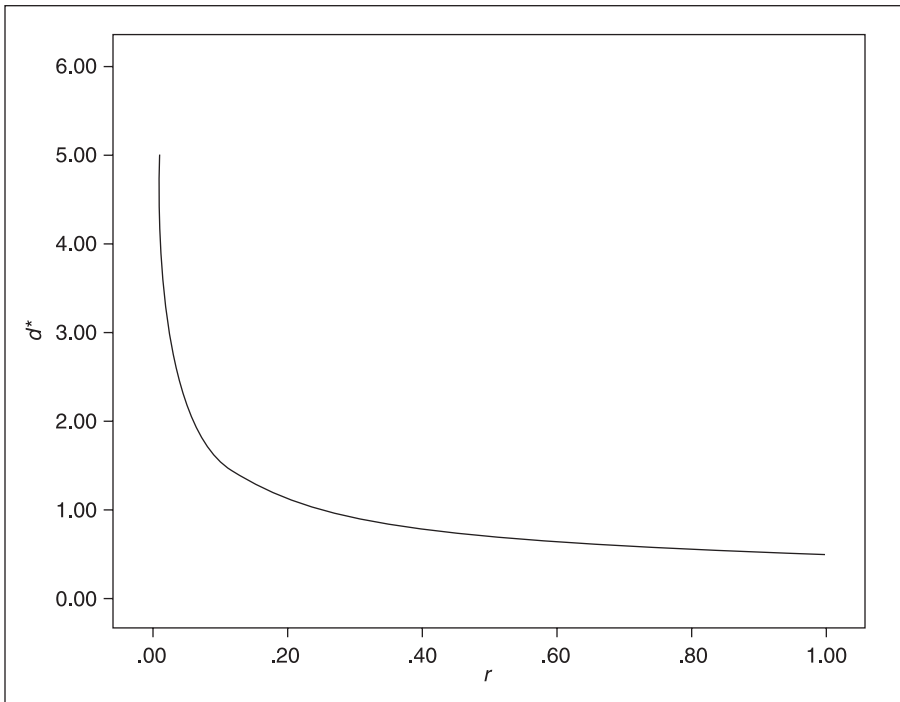


Figure 11.1 Corrected values for $d = 0.5$ for a range of reliabilities.

meta-analysis are the results from previously published studies. Studies that find significant results may have a greater probability of being published. As a result, a sample of published studies can be biased in the direction of reporting large effects. In classical meta-analysis, one way to investigate this issue is to carry out a fail-safe analysis (Rosenthal, 1991). This answers the question how many unpublished non-significant papers must lie in various researchers' file drawers to render the combined results of the available studies non-significant. If the fail-safe number is high, we assume it is unlikely that the file drawer problem affects our analysis. An alternative approach to the file drawer problem is drawing a *funnel plot*. The funnel plot is a plot of the effect size versus the total sample size (Card, 2012). Macaskill, Walter and Irwig (2001) recommend using the inverse of the sampling variance instead of the studies' sample size, because this is a more direct indicator of a study's expected variability; Sterne, Becker & Egger (2005) suggest using the standard error. These are all indicators of the studies' precision, and are all highly correlated. If the sample of available studies is 'well-behaved' the plot should be symmetric and have the shape of a funnel. The outcomes from smaller studies are more variable, but estimate the same underlying population parameter. If large effects are found predominantly in smaller studies, this indicates the possibility of publication bias, and the possibility of many other

non-significant small studies remaining unpublished in file drawers. In addition to a funnel plot, the effect of study sample size can be investigated directly by including the total sample size of the studies as an explanatory variable in a multilevel meta-analysis. This variable should *not* be related to the outcomes. When instead of sample size the standard error of the effect is included in the model as a predictor, the resulting test is equivalent to the Egger test, a well-known test for funnel asymmetry (Sterne & Egger, 2005).

The example data in Table 11.2 have an entry for the reliability of the outcome measure (r_{ii}). These (fictitious) data on the effect of social skills training assume that two different instruments were used to measure the outcome of interest; some studies used one instrument, some studies used another instrument. These instruments, in this example tests for social anxiety in children, differ in their reliability as reported in the test manual. If we use classical psychometric methods to correct for attenuation by unreliability, followed by classical meta-analysis using the random-effects model, the combined effect size is estimated as 0.64 instead of the value of 0.58 found earlier. The parameter variance is estimated as 0.23 instead of the earlier value of 0.17.

If we include the reliability and the sample size as explanatory variables in the regression model, we obtain the results presented in Table 11.4. All predictor variables are centered on their grand mean, to retain the interpretation of the intercept as the ‘average outcome’. The first model in Table 11.4 is the empty ‘intercept-only’ model presented earlier. The second model, which follows Equation 11.2, includes the total sample size as a predictor. The third model includes the reliability of the outcome measure. The fourth model includes the duration of the experiment, and the fifth includes all available predictors. Both the univariate and the multivariate analyses show that only the duration has a significant effect on the study outcomes. Differences in measurement reliability and study size are no major threat to our substantive conclusion about the effect of duration. Since there is no relation between the study size and the reported outcome, the existence of a file drawer problem is unlikely.

Table 11.4 Multilevel meta-analyses on example data

Model	intercept-only	+ N_{tot}	+ reliability	+duration	+all
Intercept	0.58 (.11)	0.58 (.11)	0.58 (.11)	0.57 (.08)	0.58 (.08)
N_{tot}		0.001 (.01)			-.00 (.01)
Reliability			0.51 (1.40)		-.55 (1.20)
Duration				0.14 (.04)	0.15 (.04)
σ_u^2	0.14	0.16	0.16	0.04	0.05
p -value χ^2 deviance	$p < .001$	$p < .001$	$p < .001$	$p = .15$	$p = .27$
p -value χ^2 residuals	$p < .001$	$p < .001$	$p < .001$	$p = .09$	$p = .06$

The last model that includes all predictor variables simultaneously is instructive. The (non-significant) regression coefficient for reliability is negative. This is counterintuitive. This is also in the opposite direction of the regression coefficient in the model with reliability as the only predictor. It is the result of a so-called ‘repressor’ effect caused by the correlations (from 0.25 to 0.33) among the predictor variables. Since in meta-analysis the number of available studies is often small, such effects are likely to occur if we include too many explanatory study-level variables. In the univariate model in Equation 11.3, the regression coefficient of reliability is 0.51. This implies that, if the reliability goes from 0.75 to 0.90, the expected outcome increases by $(0.15 \times 0.51 =)$ 0.08. This is reasonably close to the correction of 0.06 that results from applying the classical correction for attenuation. However, the large standard error for reliability in Model 11.3 suggests that this correction is not needed. Thus, the corrected results using classical methods may well be misleading.

In meta-analysis it is typical to have many study characteristics—and typically many of these are correlated. This leads to substantial multicollinearity, and makes it difficult to determine what effects are important. The approach taken above, to evaluate each effect separately and next look at multiple effects, is a reasonable strategy. The problem of predictor variable selection is a general problem in multiple regression when there are many potential predictors, but it is especially important in meta-analysis because the number of available studies is often small.

11.5 MULTIVARIATE META-ANALYSIS

The example in Section 11.4 assumes that for each study we have only one effect size, which leads to analysis models with two levels. However, there are several situations that can lead to three-level models. Three-level structures are appropriate if there are multiple studies within the same publication (or multiple studies by the same group of researchers), or if there are multiple effect sizes used in the same study. Such situations lead to a meta-analysis with multiple effect measures, sometimes denoted as a multiple endpoint meta-analysis (Gleser & Olkin, 1994). Three-level structures are also appropriate if the studies investigate the difference between several different treatment groups and one control group. This leads to a collection of effect size measures, which all share the same control group, sometimes denoted as a multiple treatment meta-analysis (Gleser & Olkin, 1994). In both cases, there are dependencies between the effect sizes within studies.

In classical meta-analysis, such dependencies are often ignored by carrying out a series of univariate meta-analyses, or solved by calculating an average effect size across all available outcome measures. For several reasons, this approach is not optimal, and more complex procedures have been proposed to deal with dependent effect sizes (Gleser & Olkin, 1994).

In a multilevel model, we can deal with multiple dependent effect sizes by specifying a multivariate outcome model. Thus, a level is added for the multiple outcome variables, analogous to the multivariate multilevel models discussed in Chapter 10. When some

studies do not report on all available outcomes, we have a missing data problem, which is dealt with in the same way as in a standard multivariate multilevel model.

The univariate model for meta-analysis is written as $d_j = \gamma_0 + u_j + e_j$ (cf. Equation 11.4). The corresponding equation for a bivariate random effects meta-analysis is

$$d_{ij} = \gamma_{0j} + u_{ij} + e_{ij} . \quad (11.11)$$

In Equation 11.11, the j is an index that refers to the outcome, and in the bivariate case $j = 1, 2$. The sampling variances of e_{11} and e_{12} are assumed known, and in addition the covariance between the sampling errors e_{11} and e_{12} is assumed known. The variances and covariance of the u_{ij} that represent differences between studies are estimated. Thus, replacing the variance terms in the univariate meta-analysis, we have the known covariance matrix Ω_e at the second level, and the estimated covariance matrix Ω_u at the third level. The lowest level is used only to specify the multivariate structure, following the procedures explained in Chapter 10. Thus, in the bivariate case we have

$$\Omega_e = \begin{pmatrix} \sigma_{e11}^2 & \sigma_{e1e2} \\ \sigma_{e1e2} & \sigma_{e22}^2 \end{pmatrix} \quad (11.12)$$

and

$$\Omega_u = \begin{pmatrix} \sigma_{u11}^2 & \sigma_{u1u2} \\ \sigma_{u1u2} & \sigma_{u22}^2 \end{pmatrix}. \quad (11.13)$$

The covariance between e_1 and e_2 can also be written as $\sigma_{e1e2} = \sigma_{e1} \sigma_{e2} \rho_w$, where ρ_w is the known within-study correlation. Generally, ρ_w is estimated by the correlation between the outcome variables in the control group or the pooled correlation across the control and experimental group (Gleser & Olkin, 1994). From the estimated matrix Ω_u we can calculate the between-studies correlation ρ_B , using $\rho_B = \sigma_{u1u2} / \sigma_{u1} \sigma_{u2}$.

Table 11.5 presents the formula for the sampling covariance of some effect measures (cf. Raudenbush & Bryk, 2002). The covariance between two correlations is a complicated expression discussed in detail by Steiger (1980) and presented in an accessible manner by Becker (2007).

Currently HLM is the only software that directly inputs the vector of effect sizes and the sampling (co)variances, although other software can be used with special command setups. These and other software issues are discussed in Section 11.6.

A serious limitation for multivariate meta-analysis is that the required information on the correlations between the outcome variables is often not available in the publications. Some approximations may be available. For instance, if standardized tests are used, the test manual generally provides information on the correlations between subtests. If a subset of the studies reports the relevant correlations, they can be meta-analyzed in a preliminary step, to obtain a global estimate of the correlation between the outcomes. Riley, Thompson

Table 11.5 Some effect measures, their transformation and sampling covariance

Measure	Estimator	Transformation	Sampling covariance
Mean	\bar{X}	—	s^2/n
difference 2 means	$g = (\bar{y}_E - \bar{y}_C) / s$	$d = (1-3/(4N-9))g$	$\rho_w(n_E+n_C)/(n_E n_C) + \rho_w^2 d_1 d_2 / (2(n_E+n_C))$
Standard deviation	S	$s^* = \text{LN}(s)+1/(2df)$	$\rho_w^2/(2df)$
Correlation	r	—	$\sigma(r_{st}, r_{uv}) = [0.5 r_{st} r_{uv} (r_{su}^2 + r_{sv}^2 + r_{tu}^2 + r_{tv}^2) + r_{su} r_{tv} + r_{sv} r_{tu} - (r_{st} r_{su} r_{sv} + r_{ts} r_{tu} r_{tv} + r_{us} r_{uv} r_{ut} + r_{vs} r_{vnu} r_{vr})]/n,$
Proportion	P	$\text{logit} = \text{LN}(p/1-p)$	$1/((np(1-p_1)(np(1-p_2))$

and Abrams (2008) suggest to set the within-study covariance equal to the covariance between the effect measures. Alternatively, researchers can conduct a ‘sensitivity analysis’ in which a range of plausible values for the correlation between outcome measures can be used to determine the likely effect of this issue on substantive interpretations. Cohen (1988) suggested values of 0.10 for a small correlation, 0.30 for a medium correlation, and 0.50 for a large correlation. Taking these suggestions as a starting point, a sensitivity analysis using the values 0.00, 0.10, 0.30 and 0.50 appears reasonable.

To illustrate the process we analyze a bivariate meta-analytic data set discussed by Nam, Mengersen and Garthwaite (2003). The data are from a set of 59 studies that investigate the relationship between children’s environmental exposure to smoking (ETS) and the child health outcomes of asthma and lower respiratory disease (LRD). Table 11.6 lists for a selection of ten studies the logged odds-ratio (LOR) for asthma and LRD, and their standard errors. Study-level variables are average age of subjects, publication year, smoking (0 parents, 1 other in household), and covariate adjustment used (0 = not, 1 = yes).

There are two effect sizes, the logged odds ratio for asthma and lower respiratory disease (LRD). Only 8 of the 59 studies report both. There is no information on the correlation between LOR asthma and LRD within the studies; at the study level the correlation is 0.80, calculated on the 8 studies that report both. However, this is an ecological correlation, which confounds within-study and between-study effects. The analysis choices are to model the within-study variances only, setting the covariance to zero, or to assume a common value for the within-study variance (for example, $r = 0.30$, a medium size correlation). As a first approximation, we set the covariance to zero. To analyze these data, the data file in Table 11.6 must be restructured in a ‘long’ or ‘stacked’ file format (cf. Chapter 10), where the outcomes for asthma and LRD become conditions i nested within studies j . Since many studies report only one outcome, these studies have only one condition. The intercept-only model for these bivariate data is

Table 11.6 Selected data from studies reporting odds ratios for asthma and LRD

ID	Size	Age	Year	Smoke	Logged- odds ratio asthma	Standard error logged- odds ratio asthma	Logged- odds ratio LRD	Standard error logged- odds ratio LLRD
3	1285	1.1	1987	0			0.39	0.27
4	470	9.0	1994	0	0.04	0.20		
6	1077	6.7	1995	0			0.35	0.15
8	550	1.7	1995	0	0.61	0.18		
10	850	9.4	1996	0			0.25	0.23
17	2216	8.6	1997	1			−0.27	0.15
24	9670	5.0	1989	0	0.05	0.09	−0.04	0.12
25	318	8.2	1995	0			0.34	0.36
26	343	9.5	1995	0	0.85	0.28		
28	11534	9.5	1996	1	0.12	0.06	−0.02	0.11

$$LOR_{ij} = \beta_{0j}Astma + \beta_{1j}LDR + e(A)_{ij} + e(L)_{ij} . \tag{11.14}$$

In Equation 11.14, the variables *Astma* and *LDR* are dummy variables referring to the asthma and LDR outcomes. The error terms $e(A)_{ij}$ and $e(L)_{ij}$ are also specific for each outcome, and are assumed to be uncorrelated.

Table 11.7 Bivariate meta-analysis for exposure to smoking, covariance constrained to zero

Model	Intercept-only	Equality	+ age (centered)
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept asthma	0.32 (.04)	0.29 (.04)	0.29 (.03)
Intercept LRD	0.27 (.05)	0.29 (.04)	0.29 (.03)
Age			−0.03 (.006)
Random part			
Variance (asthma)	0.06 (.02)	0.08 (.03)	0.06 (.02)
Variance (LRD)	0.07 (.02)	0.05 (.02)	0.03 (.01)
Covariance (AL)	0.06 (.02)	0.06 (.02)	0.05 (.01)
Deviance	44.2	44.7	32.4

Table 11.7 presents the results of a series of models for the exposure to smoking data. The intercept-only model shows a clear effect; children who are exposed to environmental smoking face increased odds of having asthma or LRD. The variances are significant by the Wald test. Both the univariate deviance difference test (removing the study-level variances individually) and the multivariate deviance difference test (removing the study-level variances simultaneously) confirm this. The effect on LRD appears somewhat stronger than the effect on asthma. In a multivariate analysis this difference can be tested by a Wald test, or by constraining these regression coefficients to be equal. The Wald test for this equality constraint produces a chi-square of 1.232, with $df=1$ and $p=0.27$ clearly not significant. The column marked 'equality' in Table 11.7 reports the estimates when an equality constraint is imposed on the regression coefficients for asthma and LRD. The deviance difference test can not be used here to test the difference, since the estimates use REML (restricted maximum likelihood). The last column adds the variable *age*, which is the only significant study-level predictor. Older children show a smaller effect of exposure to smoking. Age is entered as a single predictor, not as interactions with the asthma or LRD dummy. This assumes that the effect of age on asthma and LRD is the same. Exploratory analysis show indeed very similar regression coefficients when asthma and LRD are modeled separately in a bivariate meta-analysis, and the Wald equality test on the regression coefficients is not significant ($p=.45$).

The results reported in Table 11.7 are estimates where the common correlation between the outcomes is constrained to be zero. This causes some bias; Riley, Thompson and Abrams (2008) report a simulation that shows that this leads to an upward bias in the study-level variances, which in turn leads to some bias in the fixed effects and increased standard errors for the fixed effects. They recommend either to impute a reasonable value for r , or to estimate only one covariance parameter that confounds the within and between study-level covariance. They report simulations that show that the latter strategy is quite successful. In our case, we carry out a sensitivity analysis, where several plausible values are specified for the covariance between the error terms $e(A)_{ij}$ and $e(L)_{ij}$. Since $e(A)_{ij}$ and $e(L)_{ij}$ are standardized to have a variance equal to one, the covariance is equal to the correlation. Table 11.8 shows the results when the common correlation is constrained to 0.1, 0.3 and 0.5 (Cohen's suggestions (1988) for a small, medium and large correlation) and when a single common covariance is estimated for the between-study and the within-study part. Two conclusions are evident. First, the estimated effect of passive smoking on asthma and LRD is similar to the results reported in Table 11.7, and second, all results are remarkably similar. It should be noted that in this meta-analytic data the variation between studies is small. Riley, Thompson and Abrams (2008) report simulations that show that with larger between-study variation the differences are larger. Still, they also report that the estimates for the fixed effects are not affected much by the different specifications for the within-study correlation.

Multivariate meta-analysis is especially useful if most studies do not report on all possible outcomes. A series of univariate meta-analyses on such data assumes that the

Table 11.8 Results of bivariate meta-analysis for exposure to smoking, for three values of covariance between outcomes

Covariance =	0.10	0.30	0.50	Common
Fixed part	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)	Coefficient (s.e.)
Intercept asthma	0.29 (.03)	0.29 (.03)	0.29 (.03)	0.29 (.03)
Intercept LRD	0.29 (.03)	0.29 (.03)	0.29 (.03)	0.29 (.03)
Age	-.03 (.006)	-.03 (.006)	-.03 (.006)	-.03 (.006)
Random part				
Variance (asthma)	0.03 (.01)	0.03 (.01)	0.03 (.01)	0.03 (.01)
Variance (LRD)	0.06 (.02)	0.06 (.02)	0.07 (.02)	0.06 (.02)
Covariance (AL)	0.05 (.01)	0.05 (.01)	0.05 (.01)	0.05 (.01)
Deviance	32.6	32.3	31.6	32.7

missing outcome variables are missing completely at random (MCAR). A multivariate meta-analysis assumes that the missing outcomes are missing at random, a less strict assumption. In the ETS meta-analysis, reporting both asthma and LRD is associated with having a smaller effect of ETS, which suggests that the missingness is not MCAR. In addition, a multivariate meta-analysis allows testing equality of effect sizes and regression coefficients, as exemplified in the bivariate exposure to smoking example.

For details on multivariate multilevel meta-analysis see Kalaian and Raudenbush (1996), Normand (1999), van Houwelingen, Arends and Stijnen (2002) and Kalaian and Kasim (2008).

Another interesting extension of multilevel meta-analysis arises when we have access to the raw data for at least some of the studies. This situation leads to a multilevel model that combines both sufficient statistics, as in standard meta-analysis, and raw data to estimate a single effect size parameter. Higgins, Whitehead, Turner, Omar and Thompson (2001) describe the general framework for this hybrid meta-analysis, and discuss classical and Bayesian analysis methods. Examples of such hybrid meta-analyses are the studies by Goldstein, Yang, Omar, Turner and Thompson (2000) and Turner, Omar, Yang, Goldstein and Thompson (2000).

Given the generally small samples of studies, and the strong interest in the between-studies variance, Bayesian estimation is attractive for meta-analysis.

11.6 SOFTWARE

The multilevel software HLM (Raudenbush et al., 2011) has a built-in provision for meta-analysis, which is restricted to two levels. If we need three levels, we can use the standard HLM software, using an adapted program setup. Other multilevel software can be used,

provided it is possible to put restrictions on the random part. MLwiN (Rasbash et al., 2015) and Proc Mixed in SAS (Littell et al., 1996) have this capacity, and can therefore be used for meta-analysis, again with an adapted setup.

There are some minor differences between the programs. HLM uses by default an estimator based on restricted maximum likelihood (RML), while MLwiN by default uses full maximum likelihood (FML, called IGLS (iterative generalised least squares) in MLwiN). Since RML is theoretically better, especially in situations where we have small samples and are interested in the variances, for meta-analysis we should prefer RML (called RIGLS (restricted iterative generalised least squares) in MLwiN). If in a specific case the difference between RML and FML is small, we can choose FML because it allows testing regression coefficients using the deviance difference test. The results reported in this chapter were all estimated using RML.

An important difference between HLM and other multilevel analysis software is the test used to assess the significance of the variances. HLM by default uses the variance test based on a chi-square test of the residuals (Raudenbush & Bryk, 2002, cf. Chapter 3 of this book). MLwiN estimates a standard error for each variance, which can be used for a Z-test of the variance. In meta-analysis applications, this Z-test is problematic. First, it is based on the assumption of normality, and variances have a chi-square distribution. Second, it is a large-sample test, and with small sample sizes and small variances the Z-test is very inaccurate. In meta-analysis the sample size is the number of studies that are located, and it is quite common to have at most 20 studies. An additional advantage of the chi-square test on the residuals is that for the empty model this test is equivalent to the chi-square variance test in classical meta-analysis (Hedges & Olkin, 1985). The variance tests reported in this chapter use both the deviance difference test and the chi-square test on the residuals. MLwiN does not offer this test, but it can be produced using the MLwiN macro language.

It should be noted that the standard errors that are used to test the significance of the regression coefficients and to establish confidence intervals are also asymptotic. With the small samples common in meta-analysis, they can lead to confidence intervals that are too small, and p -values that are spuriously low (Brockwell & Gordon, 2001). It appears prudent not to use the standard normal distribution, but the Student's t -distribution with degrees of freedom equal to $k - p - 1$, where k is the number of studies and p the number of study-level explanatory variables in the model. In HLM this is the standard test for the regression coefficients. In simulations by Berkey, Hoaglin, Antczak-Bouckoms, Mosteller and Colditz (1998) this provided correct p -values. Brockwell and Gordon (2001) recommend profile likelihood methods and bootstrapping. These are covered in Chapter 13 in this book. Nam, Mengersen and Garthwaite (2003) discuss several Bayesian meta-analysis models, using the exposure to environmental smoking data as their example.

For estimating complex models, Bayesian procedures are promising and are coming into use (cf. Sutton et al., 2000). These use computer-intensive methods such as Markov chain Monte Carlo (MCMC) to estimate the parameters and their sampling distributions. These

methods are attractive for meta-analysis (DuMouchel, 1994; Smith et al., 1995) because they are less sensitive to the problems that arise when we model small variances in small samples. Bayesian models are covered in Chapter 13 in this book. Bayesian modeling starts with the specification of a prior distribution that reflects a priori beliefs about the distribution of the parameters. In principle, this provides an elegant method to investigate the effect of publication bias. An example of such an analysis is Biggerstaff, Tweedy and Mengersen (1994). Although the software MLwiN includes Bayesian methods, at present these cannot analyze meta-analytic models, and more complicated software is needed, such as the general Bayesian modeling program BUGS (Lunn et al., 2012). Cheung (2008) has shown how to use the structural equation software Mplus for meta-analysis. Since Mplus includes Bayesian estimation, it can also be used for Bayesian meta-analysis.

NOTE

- 1 If RML is used, it is not possible to test the effect of moderator variables using the deviance test. In practice, when the difference between FML and RML estimation is small, it may be advantageous to use FML rather than RML. If the differences are appreciable, RML is recommended.

12

Sample Sizes and Power Analysis in Multilevel Regression

SUMMARY

Questions about sample size tend to focus on two topics: what sample size is sufficient to apply a specific statistical estimation method, and what sample size is needed to obtain a specific power? In multilevel analysis, these problems are made more difficult because there are sample size issues at more than one level, and because the model includes a fixed and a random part, and typically the fixed part can be estimated with more precision than the random part. This chapter reviews both the sample size and the power issues.

12.1 SAMPLE SIZE AND ACCURACY OF ESTIMATES

The maximum likelihood estimation methods used commonly in multilevel analysis are asymptotic, which translates to the assumption that the sample size is large. This raises questions about the accuracy of the various estimation methods with relatively small sample sizes. Most research on this problem uses simulation methods, and investigates the accuracy of the fixed and random parameters with small sample sizes at either the individual or the group level. Comparatively less research has investigated the accuracy of the standard errors used to test specific model parameters.

12.1.1 Simulation Methods

A simulation study is a common approach to study how well estimation methods perform under small sample size and to study the relation between sample size and power. It is also referred to as a Monte Carlo study and relies on computer-intensive methods. Given a statistical model, population values of all model parameters and sample sizes at each level of the multilevel data structure, a large number of data sets is generated. Modern fast computers allow the generation of many data sets in a short time and the number of data sets is typically set to 1000, 5000 or even 10,000.

For each generated data set the model parameters and their standard errors are estimated and these estimates are summarized over all generated data sets on the basis of various criteria. The parameter bias of a model parameter is the discrepancy between the average estimate and the population value that was used to generate the data. The standard error bias is the discrepancy between the average standard error and the standard deviation of all

estimates of that parameter. Both biases are often expressed in percentages, and biases less than 5 to 10 percent are generally considered acceptable. Another criterion for evaluation is the coverage of 95 percent confidence intervals, which is the percentage of generated datasets for which the population value of a model parameter lies within the estimated confidence interval. Obviously, this percentage should not deviate too much from the desired 95 percent. The empirical power of a model parameter is the proportion datasets for which the null hypothesis of zero effect is rejected. Furthermore, it is good practice to record for how many data sets the estimation process did not converge within the maximum number of iterations and for how many datasets inadmissible estimates, such as negative variance components, were found.

The computer program Mplus (Muthén & Muthén, 1998–2015) has a built-in feature to perform simulation studies. MLwiN (Rasbash et al., 2015) allows the user to generate random data and can also be used to perform simulation studies. The freeware software R (R Core Team, 2014) is another package to use for simulation study purposes. Guidelines on how to perform a simulation study are given by Arnold, Hogan, Colford and Hubbard (2011); Boomsma (2013); Burton, Altman, Royston and Holder (2006); Landau and Stahl (2013); Muthén and Muthén (2002); Paxton, Curran, Bollen, Kirby and Chen (2001); and Skrondal (2002).

The main difficulty of a simulation study is that the statistical model along with the population values of all model parameters should be specified to generate data. So not only the population value of the model parameter of main interest, such as a treatment effect in a randomized controlled trial, needs to be known but also the population values of all other parameters, including correlations and variance components. This causes a vicious circle since an empirical study is generally conducted to gain insight in the values of the model parameters, while these values need to be known in advance in order to design the study efficiently. It is often advised to replace the unknown population values by an educated guess based on findings from the literature. This seems an easy task at first glance, but it is often difficult to find prior studies that use exactly the same model, the same variables and the same instruments to measure these variables. Especially for complex models, such as multilevel models, the population values of many parameters need to be specified. It is therefore necessary to schedule a sufficient amount of time for a literature search to find plausible values of all model parameters. One should keep in mind that a sample size calculation should not be considered a final issue of grant proposals that can be conducted very easily within limited time.

12.1.2 Accuracy of Fixed Parameters and their Standard Errors

The estimates for the regression coefficients are generally unbiased, for ordinary least squares (OLS), generalized least squares (GLS), and maximum likelihood (ML) estimation (van der Leeden & Busing, 1994; van der Leeden et al., 1997; Maas & Hox, 2004a, 2004b; Moerbeek

et al., 2003a). Baldwin and Fellingham (2013) conclude that Bayesian estimation performs equally well when compared to ML estimation with respect to bias, efficiency, and coverage of interval estimates. They note that any distinction between methods for fixed effects are only prominent when sample sizes are very small; and as sample sizes increase, these differences will fade (see also, Hox et al., 2014, and Jongerling et al., 2015).

OLS estimates are less efficient because they often have a larger sampling variance. Kreft (1996) reports that OLS estimates are about 90 percent efficient. As illustrated in Chapter 2, the OLS-based standard errors are severely biased downward. The asymptotic Wald tests, used in most multilevel software to test fixed effects, assume large samples. A large simulation by Maas and Hox (2004a) finds that the standard errors for the fixed parameters are slightly biased downward if the number of groups is less than 50. With 30 groups, they report an operative type I error rate of 6.4 percent while the nominal significance level is 5 percent. Similarly, simulations by van der Leeden & Busing (1994) and van der Leeden, Busing and Meijer (1997) suggest that when assumptions of normality and large samples are not met, the standard errors have a small downward bias. GLS estimates of fixed parameters and their standard errors are less accurate than ML estimates. Analytical findings show that in some cases the standard error of the OLS may be biased upward, such as in multicenter clinical trials without center by treatment interactions (Moerbeek et al., 2003b).

Recent simulation studies focused on minimal sample sizes at both levels. Bell, Morgan, Schoeneberger, Kromrey and Ferron (2014) also used a two-level linear model but included more covariates at both levels and multiple cross-level interactions. The covariates were measured on a dichotomous or continuous scale. They focused on number of groups 10, 20 or 30 and groups sizes randomly sampled from the ranges 5–10, 10–20 or 20–40. They used restricted maximum likelihood with Kenward–Roger adjusted degrees of freedom and concluded that biases of fixed effects were minimal, and type I error rates and coverages of confidence intervals for fixed effects were slightly conservative.

The power of the Wald test for the significance of the individual-level regression coefficients depends on the total sample size. The power of tests of higher-level effects and cross-level interactions depends more strongly on the number of groups than on the total sample size. Both simulations (Mok, 1995; van der Leeden & Busing, 1994) and analytic work (Cohen, 1998; Moerbeek et al., 2000; Raudenbush & Liu, 2000; Snijders & Bosker, 1993) suggest a trade-off between sample sizes at different levels. For accuracy and high power a large number of groups appears more important than a large number of individuals per group.

12.1.3 Accuracy of Random Parameters and their Standard Errors

Estimates of the residual error at the lowest level are generally very accurate. The group-level variance components are sometimes underestimated. Simulations by Busing (1993) and van der Leeden and Busing (1994) show that GLS variance estimates are less accurate than ML estimates. The same simulations also show that for accurate group-level variance estimates

many groups (more than 100) are needed (cf. Afshartous, 1995). However, using later versions of the MLn software, Browne and Draper (2000) show that with as few as six to twelve groups, restricted ML (RML) estimation can provide reasonable variance estimates. With 48 groups, full ML (FML) estimation also produces good variance estimates. Maas and Hox (2004a) report that with as low as 30 groups, RML estimation produces accurate variance estimates. When the number of groups is around 10, the variance estimates are much too small.

Since multilevel structural equation modeling (multilevel SEM, introduced in Chapter 14) is essentially based on within- and between-groups covariances, the sample size issues are similar to issues with second-level variance estimates. In fact, Meuleman and Billiet (2009), who focused on multilevel SEM models in cross-national research, concluded that 50 to 100 countries are needed for accurate estimation. Their simulation study was reanalyzed by Hox, van de Schoot and Matthijse (2012) using Bayesian methods. They concluded that a sample of about 20 countries is sufficient for accurate Bayesian estimation. With smaller number of groups, even with Bayesian estimation problems occur (see also Hox et al., 2014). Small cluster size can lead to overestimates of reliability at the between level of analysis (Geldhof et al., 2014), but the smaller the sample size the more carefully a prior should be chosen especially for variance components (Baldwin & Fellingham, 2013).

The asymptotic Wald test for the variance components implies the unrealistic assumption that they are normally distributed. For this reason, other approaches have been advocated, among which estimating the standard error for sigma (the square root of the variance, Longford, 1993), and using the likelihood ratio test. Bryk and Raudenbush (1992) advocate a chi-square test based on the OLS residuals. The literature contains no complete comparisons between all these methods. Simulations by van der Leeden, Busing and Meijer (1997) show that, especially with small numbers of small groups, the standard errors used for the Wald test are often estimated too small, with RML again more accurate than FML. Symmetric confidence intervals around the estimated value also do not perform well. Browne and Draper (2000), and Maas and Hox (2004a) report similar results. Typically, with 24–30 groups, the operating alpha level was almost 9 percent, and with 48–50 groups about 8 percent. In the simulations by Maas and Hox (2004a), with 100 groups the operating alpha level was 6 percent, which is close to the nominal 5 percent. Chapter 13 of this book treats some alternatives to the asymptotic Wald tests, which may be preferable when small variance components are tested, or when the number of groups is less than 50.

12.1.4 Accuracy and Sample Size

It is clear that with increasing sample sizes at all levels, estimates and their standard errors become more accurate. Kreft (1996) suggests a rule of thumb, which she calls the ‘30/30 rule.’ To be on the safe side, researchers should strive for a sample of at least 30 groups with at least 30 individuals per group. From various simulations, this seems sound advice if the interest is mostly in the fixed parameters. However, it seems that this rule will likely

not yield high power levels for fixed effects at both levels (Bell et al. 2014). For certain applications, one may modify this rule of thumb. Specifically, if there is strong interest in cross-level interactions, the number of groups should be larger, which leads to a 50/20 rule: about 50 groups with about 20 individuals per group. If there is strong interest in the random part, the variance and covariance components and their standard errors, the number of groups should be considerably larger, which leads to a 100/10 rule: about 100 groups with at least about 10 individuals per group. Theall et al. (2011) studied the effects of small group sizes (i.e. less than five). They found that when the number of groups was as large as 459, the fixed and random effects were not affected by group size. When the number of groups decreased, inflated standard errors of fixed and random effects were found. Group-level variance estimates were more inflated than fixed effects. Raudenbush (2008) also treats the case of many small groups. Many small groups always arise when the object of study is twins, married couples, families, or short time series (Raudenbush, 2008, p. 215). The general advice is to keep the model simple, with few random components at the second level. The exception are short time series, where often relatively much and reliable variation is found at the subject level (Raudenbush, 2008, p. 218).

When the number of groups is smaller than 20, fixed parameter estimates and their standard errors become inaccurate. When the interest is in variance components, as in structural equation modeling (SEM), the minimum number of groups is 50 (Meuleman & Billiet, 2009). Hox, van de Schoot and Mattijsse (2012) show that with Bayesian estimation, SEM with as few as 20 groups is feasible. We refer to McNeish and Stapleton (2016) for a general review of the problems associated with having a small number of groups.

These rules of thumb take into account that there are costs attached to data collection, so if the number of groups is increased, the number of individuals per group decreases. In some cases, this may not be a realistic reflection of costs. For instance, in school research an extra cost will be incurred when an extra class is included. Testing only part of the class instead of all pupils will usually not make much difference in the data collection cost. Given a limited budget, an optimal design should reflect the various costs of data collection. Snijders and Bosker (1993), Cohen (1998), Raudenbush and Liu (2000) and Moerbeek, van Breukelen and Berger (2000) all discuss the problem of choosing sample sizes at two levels while considering costs. Moerbeek, van Breukelen and Berger (2001) discuss the problem of optimal design for multilevel logistic models. Essentially, optimal design is a question of balancing statistical power against data collection costs. Data collection costs depend on the details of the data collection method. The problem of estimating power in multilevel designs is treated later in this chapter.

12.1.5 Accuracy and Sample Size with Proportions and Dichotomous Data

Multilevel analysis of proportions generally uses generalized linear models with a logit link (cf. Chapter 6), which gives us the model:

$$\pi_{ij} = \text{logistic}(\gamma_{00} + \gamma_{10}X_{ij} + u_{0j}). \quad (12.1)$$

The observed proportions P_{ij} are assumed to have a binomial distribution with known variance

$$\text{var}(P_{ij}) = (\pi_{ij} (1 - \pi_{ij})) / n_{ij}. \quad (12.2)$$

The π_{ij} are estimated by prediction from the current model. If the variance term is not constrained to one, but estimated, we can model over- and underdispersion. If this extra binomial variation is significantly different from one, this is usually interpreted as an indication that the model is misspecified, for instance by leaving out relevant levels, interactions among predictors, or in time series data, by not allowing autocorrelation in the error structure.

Most programs rely on a Taylor expansion to linearize the model. The program MLwiN (Rasbash et al., 2015) uses by default a first-order Taylor expansion and marginal (quasi-) likelihood (MQL1: P_{ij} predicted by fixed part only). MLwiN can also use a second-order expansion and predictive or penalized (quasi-) likelihood (PQL2: P_{ij} predicted by both fixed and random part), while HLM (Raudenbush et al., 2011) by default uses first-order expansion and predictive or penalized (quasi-) likelihood (PQL1).

Simulations by Rodriguez and Goldman (1995, 2001) show that marginal quasi-likelihood estimation with first-order Taylor expansion (MQL1) underestimates both the regression coefficients and the variance components, especially if the group sizes are small. Goldstein and Rasbash (1996) compare MQL1 and PQL2 by simulating data according to the worst performing dataset of Rodriguez and Goldman. This is a three-level data set, with 161 communities that contain in total 1558 women who reported 2449 births. Therefore, each community has on average 9.7 women, who on average report on 1.6 births. In Goldstein and Rasbash's simulation, the means of the MQL1 estimates for the fixed effects, from 200 simulation runs, were underestimated by about 25 percent. The means of the MQL1 estimates for the random effects were underestimated by as much as 88 percent. Moreover, 54 percent of the second-level variances were estimated as zero, while the population value is one. For the same 200 simulated datasets, the means of the PQL2 estimates for the fixed effects underestimated the population value by at most 3 percent, and for the random effects by at most 20 percent. None of the PQL2 variance estimates was estimated as zero.

Browne and Draper (2000) also report a simulation study based on the structure of the Rodriguez and Goldman data. In their simulation, the MQL1 method had an abysmal performance. The PQL2 method fares somewhat better: the regression coefficients are close, but the actual coverage of the 95 percent confidence interval is close to 95 percent only for the lowest-level predictor; for the predictors on the woman- and the community-level the actual coverage is about 90 percent. The variances are still not estimated very accurately: the PQL2 method underestimates the woman-level variance by 11 percent, and the community-level

variance by 43 percent, and the actual coverage of the 95 percent confidence interval for the variance estimates is 78 percent for the woman level and 27 percent for the community level.

If anything, the analysis of proportions and binomial data requires larger samples than the analysis of normally distributed data. The Rodriguez and Goldman data set is extreme, because the data are dichotomous, the variance components are large, and the sample size at the lowest level is very small. Consequently, the estimated proportions at the lowest level are very inaccurate. In less extreme cases, it appears that penalized quasi-likelihood with second order Taylor expansion is often sufficiently accurate for the regression coefficients and in many cases good enough for the random parameters. A review of the available literature shows that PQL-based estimates and tests for the regression coefficients are accurate with samples of modest sizes (Moerbeek et al., 2003a), but estimates and tests of the variances are not. However, with some data sets the PQL2 algorithm breaks down, and the MLwiN manual recommends commencing with the simpler MQL1 approach to obtain good starting values for the more complicated PQL2 approach. Using maximum likelihood estimation with numerical integration of the likelihood provides generally better estimates, but does not compensate that binary data contain less information than normal data, and therefore also needs larger sample sizes for accurate estimation. Moineddin, Matheson and Glazier (2007) report a simulation study on multilevel logistic regression using numerical integration (SAS NLMIXED procedure). They find that multilevel logistic models require larger sample sizes than models for normal data, and that the sample size requirements increase when the modeled proportions are close to zero or one. They recommend having at least 50 groups with a group size of 50. Paccagnella (2011) also used numerical integration from the SAS NLMIXED procedure in his simulation study. Good accuracy of the standard errors of fixed effects was achieved with 50 groups. Many more groups are needed for a good accuracy of standard errors for random effects. Bauer and Sterba (2011) compared PQL and numerical integration for ordinal responses. They concluded that, in contrast to binary data, PQL often performs as well as numerical integration. The performance of PQL is typically superior when the number of clusters is 50 or fewer.

At least it is advocated to compare results obtained with PQL to those obtained from numerical integration in cases where PQL is known to produce biased estimates (Benedetti, Platt & Atherton, 2014). In the context of designs with many small groups, Raudenbush (2008, p. 234) notes that nonlinear models, for example multilevel logistic regression models, pose serious estimation problems when the group sizes are small. He recommends numerical integration, and that random effects should be kept to a minimum unless group sizes approach 20 (Raudenbush, 2008, p. 234).

For problematic data structures, such as proportions very close to 0 or 1 and small numbers sample sizes, bootstrapping approaches and Bayesian estimation using Gibbs sampling offer improvements. These are described in Chapter 13.

12.2 POWER ANALYSIS

In what follows, we focus on the frequentist framework of null hypothesis testing. Statistical testing controls the risk of erroneously rejecting the null hypothesis (H_0) or committing a Type I error by setting a significance level α . The significance level is the maximum probability tolerated for falsely rejecting the null hypothesis. By convention, it is usually set equal to $\alpha = 0.05$, and less often to the more rigorous $\alpha = 0.01$. Sometimes, as in explorative analyses, the more lenient $\alpha = 0.10$ is chosen.

When the null hypothesis is false, it should be rejected in favor of the alternative hypothesis H_A , which states that a certain effect exists. Failure to reject the null hypothesis in this case implies another error, denoted by β or Type II error. The probability of committing this error is as a rule discussed in terms of the *power* of the statistical test, the probability of rejecting the null hypothesis when it is in fact not true. Power increases when α is set to a higher level, and with larger samples or larger effect sizes. In the so-called Newman–Pearson approach to hypothesis testing (Barnett, 1999), a specific value for the alternative hypothesis H_A is stipulated, and both α and β are chosen to balance the relative costs of committing a Type I or a Type II error. In the absence of clear conceptions of these costs, Cohen (1988, 1992) recommends using a power of 0.80 (corresponding to $\beta = 0.20$) as a conventional value for a high power, because this is an adequate power level, which still keeps the sample size requirements within acceptable limits. A power level of 0.50 is considered moderate.

The power of a statistical test is a function of the significance level, the sample size, and the population effect size. For decisions about the research design and sample size to be employed, it is useful to estimate the sample size that is needed to achieve a specific power for a given α and hypothesized effect size. This is called an *a priori* power analysis. The most difficult part is the specification of the population effect size. For a particular test, the effect size indicates the degree to which the null hypothesis is false in the population. Since this population value is in general unknown, the effect size can be understood as the smallest relevant departure from H_0 that we want to be able to detect with a given probability.

For a broad variety of statistical tests, Cohen (1988) presents indices of effect size, and procedures to determine the sample sizes needed to reach a specified power. Since researchers often have only a vague idea of what constitutes a plausible effect size, Cohen also proposes conventions that define ‘small’, ‘medium’, and ‘large’ effect sizes. For instance, for testing two independent means, the effect size δ is the difference in means divided by the standard deviation: $\delta = (\mu_1 - \mu_2) / \sigma$. This is often referred to as a standardized effect size since it does not depend on the arbitrary scale of the variable. Cohen (1988, 1992) proposes 0.2, 0.5, and 0.8 as conventions for ‘small’, ‘medium’, and ‘large’ effect sizes. Cohen remarks that a small effect is of a size that needs statistical analysis to detect it, while a medium effect is an effect size that one would become aware of given daily experience. A large effect is an effect, which is immediately obvious.

The general procedure to estimate the power of a statistical test is illustrated in Figure 12.1. Let us assume that we have a test that results in a standardized Z -test statistic. Under the null hypothesis, H_0 , the critical value for a one-sided test at $\alpha = 0.05$ is $Z_{crit} = 1.65$. Under the alternative hypothesis, H_A , we have a Z distribution, which also has a variance equal to one, but its mean is shifted by $\delta = (\text{effect size}) / (\text{standard error})$. This distribution is known as the noncentral Z -distribution, with noncentrality parameter δ , which in this case is simply the mean of the Z -distribution under H_A . The power of the test is the probability of exceeding the critical value $Z_{crit} = 1.65$ in the noncentral Z -distribution.

A convenient formula for power analysis is (Snijders & Bosker, 2012, p. 178):

$$\frac{\text{effect size}}{\text{standard error}} \approx Z_{1-\alpha} + Z_{1-\beta}. \quad (12.3)$$

This equation holds for a one-sided alternative hypothesis; for a two-sided alternative hypothesis α needs to be replaced by $\alpha / 2$. Equation 12.3 contains four quantities: the effect size, the sample size (as part of the standard error), the type I error rate α and the power level $1 - \beta$. If three of them are known, we can compute the fourth one. For example, we wish to compare two independent means and assume the (standardized) effect size is small: $(\mu_1 - \mu_2) / \sigma = 0.2$. The corresponding standard error is $2 / \sqrt{n}$. The desired power level is $1 - \beta = 0.8$ and the test has a one-sided alternative hypothesis with significance level $\alpha = 0.05$. We have $Z_{1-\alpha} = Z_{crit} = 1.65$ and $Z_{1-\beta} = 0.84$. This implies the standard error should be 0.08, from which we calculate a total sample size $n = 620$ is needed (i.e. 310 per treatment group).

In this example the sample size to achieve a desired power level was calculated. This should be done during the planning phase of a study to get insight into the number of subjects that need to be recruited. Such a power analysis is called an *a priori* power analysis. In many trials the maximum number of subjects is fixed beforehand, for instance because of financial constraints, and the power of the test can be calculated. Low sample sizes often result in low power levels and a decision must be made to search for additional funding such that a sufficient level of power can be achieved, to conduct the study and accept low chances

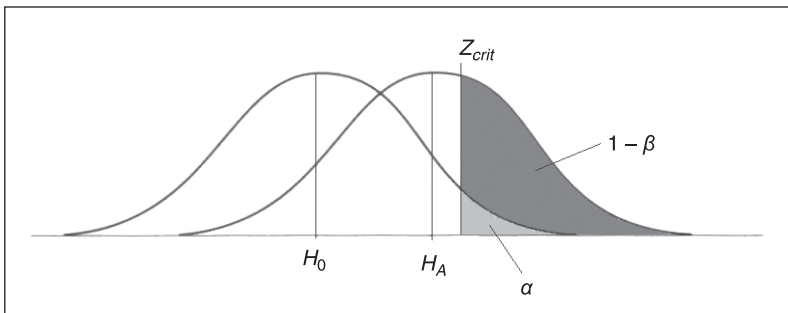


Figure 12.1 Significance and power in the Z -test.

of finding effects, or not to conduct the study at all. Whenever one wants to calculate the required sample for a given power level or the power for a given sample size, it is necessary to obtain an educated guess based on expert knowledge or findings from the literature to get a plausible estimate of the population value of the effect size.

It is also possible to conduct a power analysis after a study has been concluded. Such a power analysis is called a post-hoc, retrospective or a posteriori power analysis and it is often performed when the effect is non-significant. The power is calculated using the estimate of the effect and its standard error. When the post-hoc power is low then it is often concluded that the observed effect may indicate a real effect but the study was of insufficient size to actually detect it. The use of a post-hoc power analysis is controversial, as is further discussed in Hoenig and Heisey (2001) and Thomas (1997).

For simple situations, such as the comparison of two independent means, simple equations for the relationship between sample size and power are available in common textbooks (Cohen, 1988) and software (e.g. *G*Power*, Faul et al., 2007). For studies with multilevel data, simple equations have been derived, in particular for experimental designs with non-varying group sizes and continuous or dichotomous outcomes. These are further discussed in the next section. For more complicated designs, and in particular for observational studies, it is often not possible to derive such equations and one has to rely on simulation studies, as is further demonstrated in Section 12.4.

12.3 METHODS FOR RANDOMIZED CONTROLLED TRIALS

In an a priori power analysis, we want to estimate the power of our test for a specific effect size. Typically, we want to assess which sample size we need to achieve, say, a power of 0.80. In multilevel regression analysis, two factors complicate things.

First, we have sample sizes at different levels. The same or similar power values may be obtainable with different numbers of groups and group sizes. To decide which of these are going to be used, we must consider the cost of collecting data from more group members, or of collecting one more group. For example, assume that we want to assess the effect of an anti-smoking program which is offered in school classes. In many cases, school research uses written questionnaires for data collection. In this case, once a class is selected for the study, it makes sense to collect data from all pupils in that class, since the extra cost of selecting one more pupil in a class is very low. Therefore, if the average class size is 20, we may decide to collect data from 10 experimental and 10 control classes, which gives us 400 pupils. On the other hand, if the data collection is done by computer, and the teacher has to send the pupils one by one to the computer to respond to the questionnaire, the cost (if only in time) of collecting one more pupil in a selected class is considerable. It may be better to select only at random 10 pupils in each class, and compensate by collecting data from in total 40 classes. In fact, since the intervention is done on the class level, which means that the variable that codes for the intervention has no within-class variance, collecting data

from more classes would certainly increase the power of our test. Since there are always cost considerations, the question of the best sample size always involves decisions about the optimal design.

Second, a decision must be made at which level of the multilevel data structure randomization must be performed. Technically randomization can be carried out at any of the available levels. In the example above, there is an issue of whether the randomization should take place at the pupil level or the class level. Randomization within classes is more efficient but it can also lead to ‘treatment group contamination’, where information leaks from the experimental to the control group. This can result in an underestimate of the treatment, especially when the amount of contamination is large (Moerbeek, 2005). On the other hand, if randomization is at the class level it is impossible to estimate a random component for the treatment variable. In other words, it is not possible to estimate a class by treatment interaction.

A trial in which randomization is done at the group level is generally referred to as group or cluster randomized trial and is often chosen if control group contamination is likely to be present, such as in trials that evaluate the effects of interventions that rely on interpersonal communication and peer pressure. In such trials blinding is no option to avoid contamination of the control group. In a multi-site trial, randomization is done at the subject level within sites (i.e. groups). These is a viable option in pharmacological trials, where the experimental treatment is a new drug, and due to double blinding neither the patients nor their health professionals know who is randomized to which treatment. The multi-site trial is an important design in biomedical research, where the number of patients in any specific location may be too small to be useful. By combining the data from experiments carried out at a number of different sites, the power of the statistical analysis of the treatment can be increased (Woodruff, 1997).

12.3.1 Group Randomized Trials

The primary focus of this section is on group randomized trials. Randomization is done at the group level and all subjects within the same group receive the same treatment condition. For a trial with k groups with common group size n_{clus} the variance of the estimator of treatment effect can be show to be equal to

$$\frac{4\sigma^2}{kn_{clus}} \left[1 + (n_{clus} - 1)\rho \right], \quad (12.4)$$

see Raudenbush (1997) and Moerbeek, van Breukelen and Berger (2000). Here, $\sigma^2 = \sigma_e^2 + \sigma_{u0}^2$ is the total variance, which is the sum of the between-group variance σ_{u0}^2 and within-group variance σ_e^2 . The first term is simply the variance of a randomized controlled trial where there is no nesting of subjects within groups; such a trial is generally referred to as a simple randomized trial. The second term is the so-called design effect,

which is larger than one unless $n_{clus} = 1$ (i.e. each group consists of one subject) and/or $\rho = 0$ (i.e. there is no correlation between outcomes of subjects within the same group). Both conditions are hardly ever met in group randomized trials.

The design effect is also used in surveys and quantifies the effect of two-stage sampling versus one-stage sampling (Kish, 1965, 1987). The design effect is used to calculate the effective sample size n_{eff} :

$$n_{eff} = \frac{n}{[1 + (n_{clus} - 1)\rho]}, \quad (12.5)$$

where $n = kn_{clus}$ is the total sample size. Suppose the group size is $n_{clus} = 20$ and the intraclass correlation coefficient is $\rho = 0.05$, then the design effect is 1.95. Suppose the actual total sample size is $n = 620$, then the effective total sample size is just 318!

The design effect can be used to calculate the sample size for a group randomized trial on the basis of a sample size calculation of a simple randomized trial. First, an effect size must be specified and the required sample size for a simple randomized trial must be calculated. In the example of the previous section a small effect size was chosen and 620 subjects are needed to achieve a power level of 0.80 for a simple randomized trial. Second, the design effect must be calculated on the basis of the group size and a prior estimate of the intraclass correlation coefficient. Again we suppose $n_{clus} = 20$ and $\rho = 0.05$, meaning the design effect is 1.95. Third, the sample size of a simple randomized trial is multiplied by the design effect to calculate the sample size of a group randomized trial. In this case, 1209 subjects are needed, which means 60 groups of size 20 in total, or 30 groups per treatment arm. The total sample size is almost twice as large as in a simple randomized trial! It should therefore be justified why a group randomized trial is chosen over a simple randomized trial. For instance, the costs of data collection per subject may be (much) lower in a group randomized trial because subjects are (geographically) nested within groups, which decreases travel and administrative costs.

The simplest analysis for a group randomized trial is ignoring the nested data structure altogether and using a traditional regression model for a simple randomized trial. It has been shown by means of mathematical expressions that this results in an inflated type I error rate and hence increased power levels (Moerbeek et al., 2003b). This is also illustrated in Table 12.1 which shows power levels for a simple randomized trial and a group randomized trial in a test with a one-sided alternative hypothesis at $\alpha = 0.05$, a small effect size $\sigma = 0.2$ and $\rho = 0.05$. As in the previous section the effect size is defined as $\delta = (\mu_1 - \mu_2) / \sigma$. In other words, the model is scaled such that the total variance is equal to 1. Again, the effect size is a standardized effect size as it does not depend on the arbitrary scales of the variables. Here we can adhere to Cohen's (1988) rule of thumb that states that small, medium and large effects are of size 0.2, 0.5 and 0.8, respectively.

The group size in Table 12.1 is fixed at $n_{clus} = 20$ and the number of groups varies from 30 to 90. This implies the total sample size varies from 600 to 1800, but the effective

Table 12.1 Power of a simple randomized trial, group randomized trial and group randomized trial with a covariate

k	$n = k * n_{clus}$	n_{eff}	Simple randomized trial	Group randomized trial	Group randomized trial with covariate
30	600	308	0.79	0.54	0.59
40	800	410	0.88	0.65	0.70
50	1000	513	0.94	0.73	0.78
60	1200	615	0.97	0.80	0.84
70	1400	718	0.98	0.85	0.89
80	1600	821	0.99	0.89	0.92
90	1800	923	1.00	0.92	0.94

Note: $n_{clus} = 20$

sample size in a group randomized trial is much lower and varies from 308 to 923. So, an analysis that ignores correlation of outcomes within the same group results in over-optimistic conclusions with respect to the effect of treatment.

In the previous section it was mentioned that power depends on Type I error rate, effect size and sample size. For group randomized trials, and for any study with a multilevel data structure in general, there are more factors that influence power. First, there is not just one sample size but sample sizes at the group (k) and subject level (n_{clus}). Of course, power increases with increasing group size and/or number of groups, but the effect of the number of groups is stronger than the effect of group size. This is because the number of groups only appears in the denominator of Equation 12.4, while the group size appears in both the numerator and denominator. In the example, a power of 0.80 can be achieved with 60 groups of size 20. At second thought a higher power level of 0.90 is requested. When the group size is kept constant at 20 then 84 groups are needed, which is an increase of the number of groups by 40 percent. When the number of groups is kept constant at 60 then a group size of 48 is needed, which is an increase of the group size by 140 percent. A comparison of these two percentages shows that increasing the number of groups is more efficient than increasing the group size.

For many randomized controlled trials, such as the group randomized trial, simple mathematical relations between sample size and power are available. It is often the case the group size n_{clus} is fixed beforehand. For instance, class size is often limited, and also the number of participants in peer-pressure groups is often limited to promote dialog among participants. In that case the required number of groups k is calculated from

$$k = 4 \frac{1 + (n_{clus} - 1)\rho}{n_{clus}} \left(\frac{z_{1-\alpha} + z_{1-\beta}}{\delta} \right)^2. \quad (12.6)$$

In other trials the number of groups is fixed beforehand, for instance when the number of groups that is willing to participate in a trial is limited. In that case the required group size follows from

$$n_{clus} = 4 \frac{1 - \rho}{\left(\frac{\delta}{z_{1-\alpha} + z_{1-\beta}} \right)^2 k - 4\rho} . \quad (12.7)$$

The desired power level will not always be achieved in a trial with a limited number of groups, even when the group size can be increased without bounds. This is explained by the fact that the group size n_{clus} does not only appear in the denominator of the variance in Equation 12.4 but also in the numerator. The feasibility check by Hemming, Girling, Sitch, Marsh and Lilford (2011) shows that only when $k > 2n_{clus}\rho$ the number of available groups is sufficient.

Note that Equations 12.6 and 12.7 use the normal distribution as reference distribution, which works well when the number of groups is large, say, larger than 30. For smaller number of groups the t -distribution with $k - 2$ degrees of freedom should be used, which often results in slightly larger sample sizes.

When neither the group size nor the number of groups is fixed beforehand, a budgetary constraint can be used to calculate the optimal sample sizes. Suppose the costs at the group level are c_g and the costs at the subject level are c_s . The costs C of sampling, implementing the intervention and measuring are then calculated as

$$C = c_s k n_{clus} + c_g k. \quad (12.8)$$

One can now derive a design that minimizes the budget to achieve a desired power level or, vice versa, maximizes the power given a fixed budget. In both cases the optimal group size is

$$n_{clus} = \sqrt{\frac{c_g \sigma_e^2}{c_s \sigma_{u0}^2}} = \sqrt{\frac{c_g (1 - \rho)}{c_s \rho}}, \quad (12.9)$$

and the optimal number of groups is

$$k = \frac{C}{\sqrt{\frac{\sigma_e^2}{\sigma_{u0}^2} + c_g}} = \frac{C}{\sqrt{\frac{(1 - \rho)}{\rho} + c_g}}. \quad (12.10)$$

From Equation 12.9 it follows that the group size increases when it becomes relatively more expensive to include a group in the trial. This equation also shows that a larger group size is needed when the within-group variability increases. The cost function 12.8 implies

fewer groups can be included when group size increases, and vice versa. Equation 12.10 shows the number of groups increases when the budget C increases, but the group size is independent of the budget, as follows from Equation 12.9.

Equations 12.8–12.10 are based on the assumption that there are as many groups in the intervention as in the control. This implies the average cost at the group level can be used when the group-level costs vary across treatment conditions. Furthermore, it is assumed that all groups are of equal size. When group sizes vary it often suffices to sample 11 percent more groups (van Breukelen et al., 2007).

These sample size formulae are for group randomized trials with continuous outcomes. Sample size formulae for dichotomous outcomes are very similar and further discussed in Moerbeek, van Breukelen and Berger (2001). Jahn-Eimermacher, Ingel and Scheider (2013) and Moerbeek (2012) focus on group randomized trials with survival outcomes.

Group randomized trials are less efficient than simple randomized trials. Various methods have been proposed to increase power in group randomized trials. One such method is the inclusion of predictive covariates. As is obvious, a higher increase in power can be achieved when the covariate has a stronger association with the outcome. Associations tend to be much stronger at the group level than at the individual level (Bloom, 2005; Raudenbush et al., 2007). Examples of group-level covariates are school type or class size; covariates can also be aggregate variables such as a school's mean socio-economic status or percentage of boys within a class. If the between-group correlation between the covariate and outcome is denoted ρ_B , then the between-group variance σ_{u0}^2 declines to $(1 - \rho_B^2)\sigma_{u0}^2$ after inclusion of the covariate. For instance, a group-level covariate that has a correlation of $\rho_B = 0.5$ with the outcome results in a decline of 25 percent of the group-level variance. The last column of Table 12.1 shows that a covariate of this strength has an increasing effect on power of at most 5 percent.

The main drawback of the group randomized trial is that it is based on between-group rather than on within-group comparisons. Extensions that make within-group comparisons possible within the setting of a group randomized trial are the cross-over design (Rietbergen and Moerbeek, 2011) and the stepped-wedge design (Hussey and Hughes, 2007). The latter is a special kind of cross-over design where crossing over is only done from the control to the intervention condition and is suitable when the effect of intervention cannot be undone, such as in interventions that aim to teach participants skills. It should be taken into account that both designs include more measurements in the form of repeated measures than the standard group randomized trial, and therefore come at higher costs.

The power of a group randomized trial decreases with increasing intraclass correlation coefficient. An educated guess of the value of this parameter must be provided beforehand to calculate the sample size needed for a desired power level. The intraclass correlation coefficient tends to be inversely related to the size of the group. It is much lower in general practices with hundreds or even thousands of patients than in households with just a few members. In general practices, correlation is often the result of treatment by the same professional, while in households correlation is often due to mutual influence

and genetic similarities between family members. In the past two decades some 50 papers that provide estimates of the intraclass correlation coefficient in various fields have been published with the aim of aiding researchers to plan their experiments efficiently. A list of such papers is given by Moerbeek and Teerenstra (2016). Recent advances in solving the problem of unknown intraclass correlation coefficients in the design stage of a trial focus on adaptive designs, such as internal pilot designs (Lake et al., 2002; van Schie and Moerbeek, 2014). The idea is that an educated guess of the intraclass correlation coefficient is used to calculate the sample size. Then part of the data is collected in a pilot study, and the intraclass correlation coefficient is re-estimated and used to provide a new calculation of the sample size. The final analysis is based on all data, including the data from the pilot.

12.3.2 Multi-Site Trials

Group randomized trials are often chosen to avoid the risk of treatment group contamination. When such contamination is likely to be absent or small, a multi-site trial should be considered since it has higher power for the same sample sizes at the group and subject levels and it allows to test whether the effect of treatment varies across sites. In the calculations that follow it is assumed that the sites have equal size n_{clus} and that there is 50–50 randomization to the intervention and control condition within each site.

Again it is useful to translate the model under consideration into a standardized model so that the logic of power analysis does not depend on the arbitrary scales of the variables. Raudenbush and Liu (2000) propose standardizing the lowest-level variance to $\sigma_e^2 = 1$. Note that this is a different standardization than for group randomized trials, where the total variance $\sigma_e^2 + \sigma_{u0}^2$ is standardized to 1. It makes sense to standardize $\sigma_e^2 = 1$ since a multi-site trial is based on within-group comparisons rather than between-group comparisons. For the mean effect of treatment we can adhere to Cohen's rule of thumb: small, medium and large effects are of size 0.2, 0.5 and 0.8. The mean effect of treatment can be estimated by calculating the difference in mean scores of both treatments per group, and then averaging across groups. The variance of this estimator is

$$\frac{4[\sigma_e^2 + n_{clus}\sigma_{u1}^2]}{kn_{clus}}, \quad (12.11)$$

where σ_e^2 is the within-group variance and σ_{u1}^2 is the variance of the treatment effect. It is obvious the test on the mean treatment effect has a lower power when the treatment effect varies largely across groups. Furthermore, the effects of sample sizes are similar as in group randomized trials: increasing the number of groups is more efficient than increasing the group size, and for small number of groups the desired power level cannot always be achieved, not even with large group sizes.

The mean effect of treatment can be tested by a t -test. Under the null hypothesis the test statistic follows a central t -distribution with $k - 1$ degrees of freedom. The degrees of freedom

are 1 higher than in a group randomized trial since within-group rather than between-group comparisons are made. For large number of groups the standard normal approximation can be used and power levels can be easily calculated on the basis of Equation 12.3. The power depends on the slope variance and it is useful to have rules of thumb about the variance components. Raudenbush and Liu (2000) suggest values of 0.05, 0.10, and 0.15 as small, medium, and large variances for the slope of an intervention dummy coded $-0.5, +0.5$. Such suggestions are, of course, tentative and study-specific, but these values seem reasonable. For instance, Cohen (1988, 1992) views an intervention effect of 0.5 as a medium effect size. If the corresponding regression coefficient has a slope variance of 0.05, this translates to a standard deviation of 0.22. Assuming normality, 95 percent of the slopes would be between 0.06 and 0.94.¹ The combination of a medium treatment effect and a small variance across treatment sites leads to the result that virtually all population intervention effects are positive. A small intervention effect of 0.20 combined with a medium slope variance of 0.10 leads to an interval for the intervention effects across sites between -0.42 and $+0.82$. In this situation, 26 percent of the intervention outcomes are expected to be zero or negative. This clearly underscores the importance of evaluating the treatment effect across sites. It also supports the rules of thumb chosen for small, medium, and large slope variances. The variance of the treatments across sites becomes important only if it has an effect size that is considerably larger than the effect size of the treatment.

Table 12.2 lists power levels for a small mean treatment effect (i.e. $\delta = 0.2$) in a one-sided test with $\alpha = 0.05$ and a common group size of $n_{clus} = 20$. The variance of the treatment effect is assumed to be of small ($\sigma_{u1}^2 = 0.05$) or medium ($\sigma_{u1}^2 = 0.10$) size. For a small variance of the treatment effect a power level of 0.80 is achieved with 60 groups while over 90 groups are needed in case the variance of the treatment effect is of medium size.

Table 12.2 Power of the test on mean intervention effect and power of the test on intervention variability

K	$n = k * n_{clus}$	Mean effect treatment ($\sigma_{u1}^2 = 0.05$)	Mean effect treatment ($\sigma_{u1}^2 = 0.10$)	Variance effect treatment ($\sigma_{u1}^2 = 0.05$)	Variance effect treatment ($\sigma_{u1}^2 = 0.10$)
30	600	0.53	0.41	0.22	0.47
40	800	0.64	0.50	0.27	0.57
50	1000	0.72	0.57	0.31	0.64
60	1200	0.80	0.64	0.34	0.71
70	1400	0.84	0.70	0.38	0.76
80	1600	0.88	0.75	0.41	0.81
90	1800	0.91	0.79	0.44	0.85

In multi-site trials it is of interest to test if the treatment effect varies across groups. If it turns out the variability is significant and large, it makes sense to identify group-level covariates to explain part of this variability. For instance, it could turn out that the effect of some medical treatment is larger in private hospitals than in public hospitals because there is a higher budget to train the personnel who deliver the treatment. The last two columns in Table 12.2 show the power for the test on the variance of the treatment effect when this variance is of small or medium size. Of course a larger power is achieved with a larger variance but for both sizes the power is smaller than of the test on the mean effect of treatment. Furthermore, power increases with the number of groups (see Table 12.2) but also with the group size (results not shown). Raudenbush and Liu (2000) show that the group size has a larger effect on power than the number of groups. So the effects of group size and number of groups are the inverse of those for the mean effect of treatment.

12.4 METHODS FOR OBSERVATIONAL STUDIES

In the previous section simple mathematical relations between sample sizes and power were given and interpreted. Unfortunately, such simple equations do not always exist, and in such situations one must rely on other methods for power analysis, such as a simulation study. This is often the case in observational studies, where complex models with many independent variables, random effects and cross-level interactions are used. Simulation studies are also common when the outcome variables are not measured on a continuous or dichotomous scale, or when multilevel structural equation models are considered.

The Thai educational data from Chapter 6 are used as an example of how to perform a post-hoc power analysis for an observational study. The outcome variable measures whether a child had to repeat a class; predictor variables are gender, whether the child had preschool education and school mean SES. A model with main effects only is assumed and both child-level predictors have a fixed effect. The estimates of the intercept, threshold and school-level residual variance as obtained with numerical integration are given in the last column of Table 6.3 and are used as the basis for the power analysis. In addition to that, the exogenous (predictor) variables must be generated. School mean SES is generated from a normal distribution with sample mean 0.0097 and variance 0.141; gender and preschool education from a binomial distribution with probability 0.5. These distributions conform to the distributions found in the sample data. The number of schools is 356 and a mean school size of 21 is used. The school sizes ranged from 2 to 41 but taking all school sizes into account is too cumbersome in a simulation study like this.

Software for simulation studies are further discussed in the next section. For this example Mplus (Muthén & Muthén, 1998–2015) was used and the power turned out to be 1.0 for gender and preschool education and a mere 0.261 for school mean SES.

Suppose a replication of this study is planned (e.g. in another year or another country) and the main interest lies in the effect of having had preschool education. The power for the test of

this effect should be 0.8 and the question is how many schools are needed, given an average sample size at the school level of 21. This is an *a priori* power analysis and the underlying statistical model and population values of model parameters must be specified. In this case estimates from the Thai education data are used as estimates of the population values.

Muthén and Muthén (2002) advise that parameter and standard error biases are below 10 percent, and that the standard error bias of the parameter for which the power is calculated is below 5 percent. Furthermore, the coverage of the 95 percent confidence interval should be between 0.91 and 0.98. For a sample of 35 schools the power for the test on the effect of preschool education is slightly too low at 77 percent. This low number of schools also causes the coverage of the confidence interval for school mean SES to be a bit too low at 90 percent and the standard error bias for this parameter to be a bit too high at 11.9 percent. When 40 schools are used the power for the test on preschool education is 0.805, but the standard error bias for school mean SES is still slightly too high at 0.105. At least, the number of schools can be much lower than the 356 in the original study when primary interest lies in testing the effect of preschool education.

This example shows that the underlying statistical model and population values of the model parameters must be known to perform an *a priori* simulation study. In this case estimates from a previous study could be used, but this is seldom the case in practice. A sufficient amount of time should be reserved for a thorough research of the literature to find plausible values for the parameters of the model at hand to be used as input of the simulation study.

12.5 METHODS FOR META-ANALYSIS

Chapter 11 contains the results of a meta-analysis using multilevel analysis techniques. Table 11.4, which is repeated here, presents the results of separately adding three explanatory study characteristics to the model. One of these is each study's total sample size N_{tot} . This variable is important, because if it shows a relationship with the effect size of the studies, this indicates that there may have been selective publication. The relationship is in fact not significant, with a regression coefficient estimated as 0.001 and a standard error of 0.01. However, there is the problem of power. There are only 20 studies, so it is possible that this nonsignificance is the result of low power, rather than the absence of a real effect in the population.

To investigate this possibility, we must specify what effect size we wish to be able to detect. For a correlation coefficient, a medium effect is defined as 0.30, or 9 percent explained variance. For a regression model, we may consider a predictor to have a medium effect if it explains 10 percent of the variance, which is a nice round figure. In the intercept-only model in Table 11.4, the between studies variance is estimated as $\sigma_u^2 = 0.14$. Ten percent of that variance equals 0.014. That variance must be explained using a term of the form γN_{tot} . In our data set in Table 11.4, we can calculate the variance of the total sample size N_{tot} , which turns out to have a variance of 155.305. To reduce that to 0.014, the regression coefficient gamma must be equal to $\gamma = \sqrt{0.014} / \sqrt{155.305} = 0.01$. Therefore, we want to test an effect

Table 11.4 (repeated) Multilevel meta-analyses on example data

Model	intercept-only	+ N_{tot}	+ reliability	+duration	+all
Intercept	0.58 (.11)	0.58 (.11)	0.58 (.11)	0.57 (.08)	0.58 (.08)
N_{tot}		0.001 (.01)			-.00 (.01)
Reliability			0.51 (1.40)		-.55 (1.20)
Duration				0.14 (.04)	0.15 (.04)
σ_u^2	0.14	0.16	0.16	0.04	0.05
p -value χ^2 deviance	$p < .001$	$p < .001$	$p < .001$	$p = .15$	$p = .27$
p -value χ^2 residuals	$p < .001$	$p < .001$	$p < .001$	$p = .09$	$p = .06$

size of $\gamma = 0.01$, with an associated standard error of 0.01 (the value of the standard error for N_{tot} in Table 8.4), and the significance level set at $\alpha = 0.05$. We again use Equation 12.3: (effect size) / (standard error) $\approx (Z_{1-\alpha} + Z_{1-\beta})$, which in this case becomes $(0.01) / (0.01) = (1.64 + Z_{1-\beta})$. So, $Z_{-\beta} = 1 - 1.64 = -0.64$. This leads to a post-hoc power estimate of 0.74, which appears adequate. The failure to find a significant effect for the study sample size is not likely to be the result of insufficient power of the statistical test.

Post-hoc power analysis is not only useful in evaluating one's own analysis, as just shown, but also in the planning stages of a new study. By investigating the power of earlier studies, we find which effect sizes and intraclass correlations we may expect, which should help us to design our own study.

In applications such as meta-analysis, it is important to be able to detect between-study heterogeneity, or between-study variance. In the multilevel approach to meta-analysis (cf. Chapter 11 in this book), this translates to the significance of the second-level intercept variance. Longford (1993, p. 58) shows that the sampling variance of the intercept variance σ_u^2 is equal to

$$\text{var}(\sigma_u^2) = \frac{2\sigma_e^4}{kn_{clus}} \left(\frac{1}{n_{clus} - 1} + 2\omega + n_{clus}\omega^2 \right) \quad (12.12)$$

where k is the number of groups or groups, n_{clus} is the group size, and ω is the ratio of the between- and within-studies variance: $\omega = \sigma_u^2 / \sigma_e^2$. Equation 12.12 can be used to estimate the power of detecting any specific between study variance.

If we analyze standardized effect sizes, the first-level variance is implicitly fixed to 1.0. Following Raudenbush and Liu (2000), we may use values of 0.05, 0.10, and 0.15 as small, medium, and large between-study variances for the standardized effect. We wish to be able to detect a medium variance of 0.10 with a power of 0.80.

Suppose we plan a meta-analysis on a specific topic. We have carried out a computerized literature search, and found 19 references on our topic. Three are available in the local

library. We collect these three studies, and code their effect sizes and total sample sizes. The results are in Table 12.3.

The question is this: given the results coded in the first three studies (actually, the first three studies in the meta-analysis example of Bryk & Raudenbush, 1992), is it worthwhile to go on, meaning retrieving and coding the remaining 16 studies? We can use an a priori power analysis to formulate an answer to this question. Specifically, assume that we wish to test whether the studies are heterogeneous, i.e., whether the between-studies variance σ_u^2 is significant. We require a power of 0.80 to detect the study-level variance at the conventional $\alpha = 0.05$ significance level when the proportion between-study variance is at least 0.25 of the total variance, a value that Schmidt and Hunter (2015) consider an important lower limit. Because we meta-analyze standardized effect sizes, the within-study variance is fixed at $\sigma_e^2 = 1.0$. For the proportion between-study variance to be 0.25, the between-study variance must be $\sigma_u^2 = 0.33$ ($0.25 = 0.33 / 1.33$), and therefore $\omega = 0.33$. With $k = 19$ studies, an average study sample size $n_{clus} = 195$ (the average in Table 12.1), and $\omega = 0.33$, we obtain $\text{var}(\sigma_u^2) = 0.012$. Thus, the standard error of the second-level variance estimate σ_u^2 is 0.11. Using Equation 12.3, we find that the power of the test of $\sigma_u^2 = 0.33$ while the standard error is 0.11 is estimated as (assuming a one-sided test: $p(Z > (1.64 - 0.33 / 0.11) = p(Z > 0 - 1.31) =) 0.91$, which appears more than adequate. If the sample sizes of the three available studies are typical for all studies, it appears worthwhile to continue the meta-analysis.

Similar calculations using the *design effect* (cf. Section 12.2.2) allow us to assess the power of the overall test for the effect size δ . Suppose we are interested in detecting a combined small effect, meaning an effect size as low as $\delta = 0.20$. This is small, but one of the advantages of meta-analysis is the possibility to detect small effects. If the sample sizes of the three available studies are typical for all studies, all studies together involve ($19 \times 195 =$) 3705 subjects. However, we do not have one giant experiment with 3705 independent observations, we have 19 smaller experiments. We again assume that the between-studies variance is 0.25 of the total variance. In other words, we assume clustered data with 19 groups of 195 subjects, and an intraclass correlation of 0.25. Using Equation 12.4 to estimate the effective sample size from the intraclass correlation and the average group size, we obtain $n_{eff} = 3705 / (1 + 19 \times 0.25) = 75$. Using the standard formula for the sampling error of the effect size (cf. Table 11.1), using 75 subjects with equal sample sizes for the experimental

Table 12.3 Three studies for an intended meta-analysis

Study	<i>d</i>	<i>N</i> _{tot}
1	0.03	256
2	0.12	185
3	−0.14	144

and control groups, we obtain an expected standard error for d of 0.23. Thus, the power estimate is (assuming a two-sided test: $p(Z > 1.96 - 0.10 / 0.077) = p(Z > 1.53) =) 0.06$. We conclude that the power of our meta-analysis for detecting a small experimental effect is very poor. If we are interested in medium size effects, the power estimate is (assuming a two-sided test: $p(Z > 1.96 - 0.30 / 0.23) = p(Z > 0.66) = 0.25$, which is again not adequate.

12.6 SOFTWARE FOR POWER ANALYSIS

Various computer programs have appeared with the aim of helping researchers to calculate the power at a given sample size, or to calculate the sample sizes to achieve a desired power level.

We first focus on software that relies on mathematical equations. The first program that appeared is PINT, which stands for **P**ower analysis in **T**wo-level designs (Bosker, Snijders & Guldemon, 2003). The underlying equations are derived in Snijders and Bosker (1993). PINT is restricted to linear multilevel models with two levels of nesting, but it is rather general in the sense that many predictor variables at the first and second level can be considered and first-level predictors can have a fixed or random effect. The consequence is that quite a lot of information must be supplied: the number of predictor variables, the means, variances and covariances of the predictor variables, and the variances and covariances of the residuals. There are two options to calculate the required sample sizes: the first uses a budgetary constraint while the second uses all combinations of the sample sizes at the first and second level between some minimum and maximum values. The input must be given in a parameter file and the output consists of two files that contain the standard errors of the estimated regression coefficients and variance-covariance matrices of the estimates for a wide range of combinations of sample sizes. From these the most efficient design can be selected.

The main focus of the Optimal Design program (Spybrook et al., 2011) is on experimental designs, in particular cluster randomized trials, multi-site trials and trials with repeated measures. Two and three levels of nesting are taken into account and for most designs the outcome is assumed continuous, although for a few designs dichotomous outcomes are also included. Less prior knowledge is needed than in the PINT program; in many cases a prior estimate of the standardized effect size and intraclass correlation suffices. The program gives a graphical presentation of the power level as a function of many design factors, such as sample size, effect size or intraclass correlation coefficient. The program also allows evaluating the effect of a covariate on power.

Another program for power analysis in experimental designs is SPA-ML (Moerbeek & Teerenstra, 2016), which is short for **S**tatistical **P**ower Analysis in **M**ulti**L**evel designs. This program includes a wide range of experimental designs including cross-over trials, stepped wedge designs and pseudo-cluster randomized trials. It calculates the sample size at a given level when the sample size at the other level is fixed, or it uses a budgetary constraint. The output is given in text format in the form of a power statement which can be copied and pasted to project proposals, and power is also drawn in a graph as a function of sample size.

The advantage of using mathematical equations for the relation between power and sample size is that calculations are often fast. When no mathematical equations are available one can perform a simulation study as an alternative. The Mplus software has a built-in command for simulation studies (Muthén & Muthén, 1998–2015) and for each model parameter various statistics are written to an output file after the simulation has been concluded, among which the power level. Mplus does not restrict to continuous outcomes and can handle many types of outcomes variables, among which ordinal, nominal and count outcomes. Furthermore, group sizes can vary across groups. In longitudinal trials Mplus can also handle various types of missing data patterns. A nice feature is that Mplus can store the parameter estimates of a real data analysis in a file, which can then be used as population parameter values for data generation. As such it can use parameter estimates from an empirical study as *a priori* estimates of a future study.

Researchers with some background in programming can also program their own simulation study in R (R Development Core Team, 2011) or MLwiN (Rasbash et al., 2015). The software package MLPowSim (Browne, Golarizadeh Lahi & Parker, 2009) has been written to facilitate simulation studies in MLwiN or R. It creates R scripts or MLwiN macros which can be executed in those packages. It can handle sample size calculations for models with more than two levels of nesting, for models with crossed random effects, for unbalanced data and for outcomes that do not necessarily have a normal distribution. As an alternative one can use the ML-DEs software (Cools et al., 2008) which generates macros to perform simulations in MLwiN and R scripts to handle the output of the simulations in R.

NOTE

- 1 Note that this is not the 95 percent confidence interval. The 95 percent confidence interval relates to the precision of the estimate of the average effect across sites. In a random coefficient model, we assume variation around this average. The associated interval is the 95 percent predictive interval.

13

Assumptions and Robust Estimation Methods

SUMMARY

This chapter discusses the assumptions underlying the multilevel regression model, and outlines ways to test these assumptions. When distributional assumptions are not met, there are several approaches to deal with this. To establish an accurate confidence interval for a variance component, we need a technique that results in a confidence interval that is not symmetric. The profile likelihood method is one such method based on maximum likelihood estimation. More general methods to deal with non-normal data are using robust standard errors, bootstrapping and Bayesian estimation.

13.1 INTRODUCTION

The assumptions of the multilevel regression model are an extension of the assumptions of the linear multiple regression model (cf. Tabachnick & Fidell, 2013). The main assumptions are a sufficient sample size (see Chapter 12), linear relationships, absence of multicollinearity, and (multivariate) normality for dependent variables, which is the focus of the current chapter. Multilevel software does not excel in features to detect failure to meet these assumptions, but standard multiple regression software generally does. So, testing these assumptions can be performed in standard multiple regression software, using procedures outlined in, e.g., Tabachnick and Fidell (2013) or Meuleman, Loosveldt and Emonds (2015). Although the significance levels of single-level models applied to multilevel data cannot be trusted, graphical procedures such as scatterplots to inspect linearity, and multicollinearity diagnostics designed for single-level data are also useful for multilevel data. Hox and van de Schoot (2013) show that simple single-level diagnostic procedures are useful to identify problematic subjects or groups in multilevel data.

In addition, multilevel models generally assume that the residuals at different levels are independent from each other, and that they have a multivariate normal distribution. Most multilevel software can produce residuals at separate levels, and these can be analyzed to detect outliers and influential cases.

Although Bayesian estimation is increasingly used, the most-often used method to estimate the parameters of the multilevel regression model is still maximum likelihood estimation. This produces parameter estimates and asymptotic standard errors, which can be used to test the significance of specific parameters, or to set a confidence interval around

a specific parameter. In Chapter 3 some alternatives to this standard approach to estimation and testing have been introduced, and this chapter discusses several of these alternative estimation methods in relation to non-normality. First we introduce an example data set and show the issue of non-normality when using the Wald test.

13.2 EXAMPLE DATA AND SOME ISSUES WITH NON-NORMALITY

To provide more insight into the details and show the effects of different estimation methods, two example data sets will be used throughout this chapter. The first is a small data set, containing 16 independent measurements of the estrone level in a single blood sample from five women (the data are described in Appendix E). This data set is presented and discussed by Fears, Benichou and Gail (1996) to illustrate the fallibility of the Wald statistic (based on the parameter estimate divided by the estimated standard error) for testing variance components in certain situations. In this example data, the Wald test fails to detect a variance component for two reasons: first, because the sample size is small (Fears et al., 1996), and second, because the likelihood for the subject-level variance is decidedly non-normal (Pawitan, 2000). In addition to this data set, which is known to be problematic, the pupil popularity data introduced in Chapter 2 is used. This is a large data set (2000 pupils in 100 classes), which has been generated following the assumptions of the multilevel model using maximum likelihood. Given the generous sample size, this well-behaved data set should produce accurate estimates and standard errors for all estimation methods.

The estrone data file is restructured to create a ‘long’ or ‘stacked’ data file that contains the 16 measurements nested within the five subjects (cf. Chapter 5). Following Fears, Benichou and Gail (1996) the (ten-base) logarithm of the estrone level is used as dependent variable. Assuming independence of the 16 measurements on the same blood samples, one-way random effects analysis of variance can be used to assess whether the five women have significantly different average estrone levels. Since the data set is balanced, standard analysis of variance methods (Tabachnick & Fidell, 2013) produce exact results. An analysis of variance on the estrone data yields the results in Table 13.1.

The *F*-ratio is highly significant, providing strong evidence that estrone levels vary between individuals. The variance components estimated by the analysis of variance method lead to an intraclass correlation of $\rho = 0.84$, which indicates that most of the

Table 13.1 Analysis of variance on estrone data, random effects model

Source	df	SS	MS	var. comp.	F-ratio	<i>p</i>
Subjects	4	1.133	0.283	0.0175	87.0	<.0001
Error	75	0.244	0.003	0.0022		
Total	79	1.377				

variation in this data is between-subject variation. Multilevel analysis using restricted maximum likelihood estimation should lead to similar estimates. Using REML (restricted maximum likelihood) estimation, the variance components are estimated as $\sigma_{u0}^2 = 0.0175$ on the subject level and $\sigma_e^2 = 0.00325$ on the measures (error) level. These estimates are close to the values obtained using analysis of variance, and the multilevel method produces an intraclass correlation of $\rho = 0.84$. However, using the Wald test by dividing the variance estimate of 0.0175 by its estimated standard error of 0.0125 produces a standard normal variate $Z = 1.40$, corresponding to a one-sided p -value of 0.081, which is not significant by conventional criteria. Clearly, the Wald test is not performing well with these data; the p -value is increased substantially, which points to a lack of power for the Wald test. The difference in the estimated variance components is trivial, so the problem is not the (restricted) maximum likelihood estimation method, but the Wald test itself. The reason that the Wald test is performing badly in this example is simple. The Wald test depends on the assumption that the parameter tested has a normal sampling distribution, with a sampling variance that can be estimated from the information matrix. In the estrogen data, we are testing a variance component, which does not have a normal distribution, especially not under the conditions of a very small sample size and close to its boundary value of zero.

Some simple alternatives work well for these data. For instance, Longford (1993) and Snijders and Bosker (2012) suggest basing the Wald test not on the variance, but on the standard deviation $s_{u0} = \sqrt{s_{u0}^2}$, with standard error equal to $s.e.(s_{u0}) = s.e.(s_{u0}^2) / (2s_{u0})$. The standard deviation is a square root transformation of the variance, and its distribution should be closer to normality. For our data, s_{u0} is 0.132, with estimated standard error calculated as $0.0125 / (2 \times 0.132) = 0.047$. A Wald test on the standard deviation produces a test value $Z = 2.81$, with $p = 0.003$. So this test indeed performs better. However, in the general case, solving the problem by applying some transformation to the estimated variance is problematic. Fears, Benichou and Gail (1996) show that, since the Wald test depends on the parameterization of the model, by making a shrewd choice of a power transformation for s_{u0}^2 , one can obtain any p -value between 0 and 1. This is awkward, and better methods than transforming the variance estimate are preferable.¹

If we use the chi-square test discussed in Chapter 3, and implemented in HLM, we find $\chi_4^2 = 348.04$, with $p < 0.001$. Similarly, if we use the deviance difference test discussed in Chapter 3, we find a deviance difference of 114.7 (RML). This is distributed as a chi-square variate with one degree of freedom, and can be converted to a standard normal Z -variate by taking its square root. This produces a $Z = 10.7$, which is highly significant. In effect, both the residuals chi-square method and the chi-square test on the difference of the deviances work well on these data. However, these methods cannot be used if we wish to establish a confidence interval for the subject-level variance. The Wald statistic can be used to set a confidence interval, but only if it has a normal distribution. For regression coefficients it is sufficient that the residuals have a normal distribution; for variance components other methods should be used.

13.3 CHECKING ASSUMPTIONS: INSPECTING RESIDUALS

Inspection of residuals is a standard tool in multiple regression analysis to examine whether assumptions of normality and linearity are met (cf. Stevens, 2009; Tabachnick & Fidell, 2013). Multilevel regression analysis also assumes normality and linearity. Since the multilevel regression model is more complicated than the ordinary regression model, checking such assumptions is even more important. For example, Bauer and Cai (2009) show that neglecting a non-linear relationship may result in spuriously high estimates of slope variances and cross-level interaction effects. Inspection of the residuals is one way to investigate linearity and homoscedasticity. There is one important difference from ordinary regression analysis; we have more than one residual, in fact, we have residuals for each random effect in the model. Consequently, many different residuals plots can be made, some of which we introduce in the next section.

13.3.1 Examples of Residuals Plots

The equation below represents the one-equation version of the direct effects model for our example data (see Chapter 2 for details). This is the multilevel model without the cross-level interaction. Since the interaction explains part of the extraversion slope variance, a model that does not include this interaction produces a graph that displays the actual slope variation more fully:

$$\begin{aligned} popularity_{ij} = & \gamma_{00} + \gamma_{10} gender_{ij} + \gamma_{20} extraversion_{ij} + \gamma_{01} experience_j \\ & + u_{2j} extraversion_{ij} + u_{0j} + e_{ij} \end{aligned}$$

In this model, we have three residual error terms: e_{ij} , u_{0j} , and u_{2j} . The e_{ij} are the residual prediction errors at the lowest level, similar to the prediction errors in ordinary single-level multiple regression. A simple boxplot of these residuals will enable us to identify extreme outliers. An assumption that is usually made in multilevel regression analysis is that the variance of the residual errors is the same in all groups. This can be assessed by computing a one-way analysis of variance of the groups on the absolute values of the residuals, which is the equivalent of Levene's test for equality of variances in analysis of variance (Tabachnick & Fidell, 2013). Raudenbush and Bryk (2002) describe a chi-square test that can be used for the same purpose, which is available in their program HLM.

The u_{0j} are the residual prediction errors at the group level, which can be used in ways analogous to the investigation of the lowest-level residuals e_{ij} . The u_{2j} are the residuals of the regression slopes across the groups. By plotting the regression slopes for the various groups, we get a visual impression of how much the regression slopes actually differ, and we may also be able to identify groups which have a regression slope that is wildly different from the others.

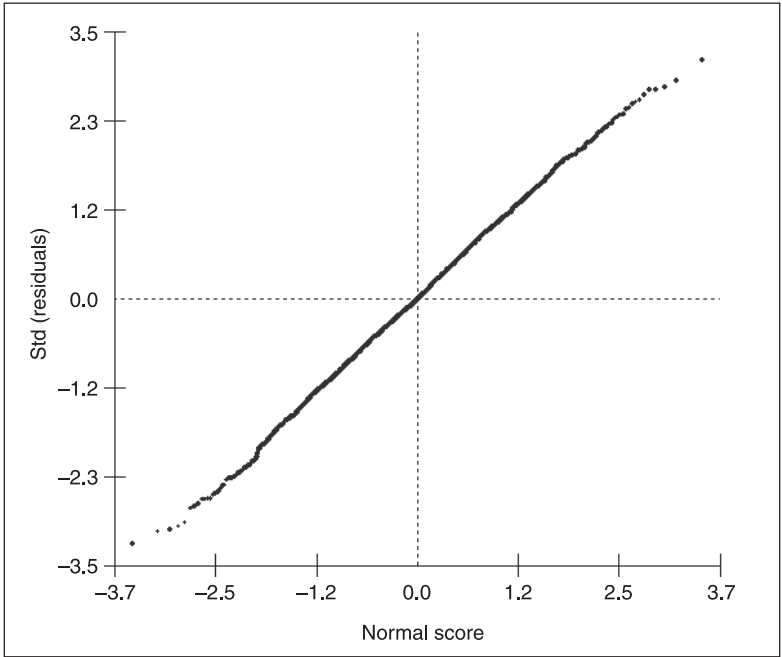


Figure 13.1 Plot of first-level standardized residuals against normal scores.

To test the normality assumption, we can plot standardized residuals against their normal scores. If the residuals have a normal distribution, the plot should show a straight diagonal line. Figure 13.1 is a scatterplot of the standardized first-level residuals, calculated for the final model including cross-level interaction, against their normal scores. The graph indicates close conformity to normality, and no extreme outliers. Similar plots can be made for the second-level residuals.

We obtain a different plot if we plot the residuals against the predicted values of the outcome variable popularity using the fixed part of the multilevel regression model for the prediction. Such a scatter plot of the residuals against the predicted values provides information about possible failure of normality, nonlinearity, and heteroscedasticity. If these assumptions are met, the plotted points should be evenly divided above and below their mean value of zero, with no strong structure (cf. Tabachnick & Fidell, 2013, p. 163). Figure 13.2 shows this scatter plot for the first-level residuals. For our example data, the scatter plot in Figure 13.2 does not indicate strong violations of the assumptions.

Similar scatter plots can be made for the second-level residuals for the intercept and the slope of the explanatory variable pupil extraversion. As an illustration, Figure 13.3 shows the scatterplots of the second-level residuals around the average intercept and around the average slope of pupil extraversion against the predicted values of the outcome variable popularity. Both scatterplots indicate that the assumptions are reasonably met.

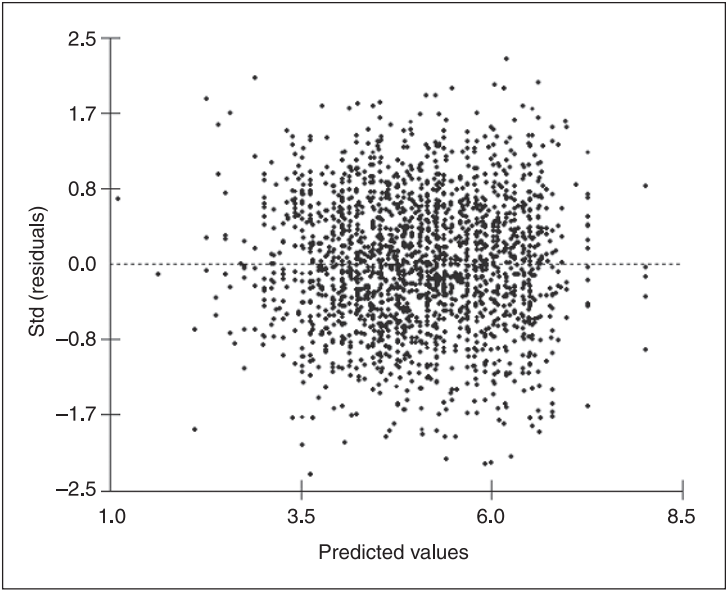


Figure 13.2 First-level standardized residuals plotted against predicted popularity.

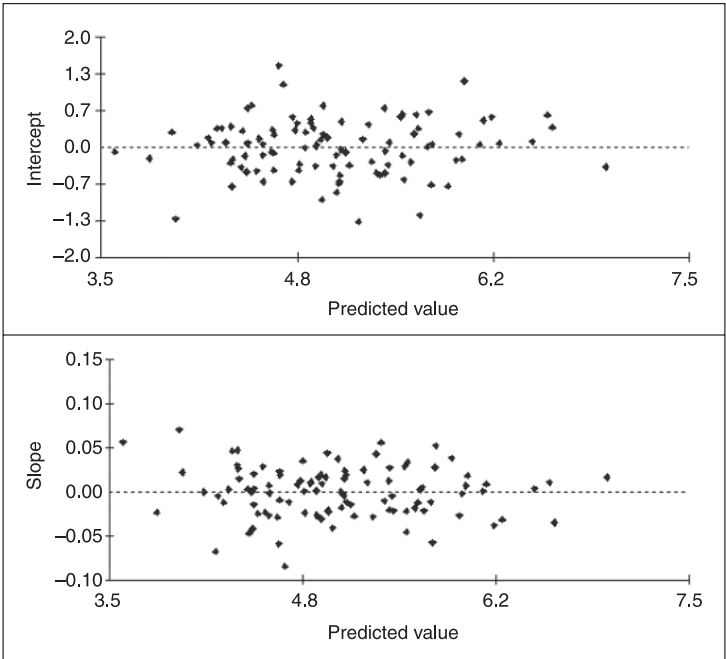


Figure 13.3 Second-level residuals plotted against predicted popularity.

An interesting plot that can be made using the second-level residuals is a plot of the residuals against their rank order, with an added error bar. In Figure 13.4, an error bar frames each point estimate and the classes are sorted in rank order of the residuals. The error bars represent the confidence interval around each estimate, constructed by multiplying its standard error by 1.39 instead of the more usual 1.96. Using 1.39 as multiplication factor results in confidence intervals with the property that if the error bars of two classes do not overlap, they have significantly different residuals at the 5 percent level (Goldstein, 2011). For a discussion of the construction and use of these error bars see Goldstein and Healy (1995) and Goldstein and Spiegelhalter (1996). In our example, this plot, sometimes called the *caterpillar* plot, shows some outliers at each end. This is an indication of exceptional residuals for the intercept. A logical next step would be to identify the classes at the extremes of the rank order, and to seek for a post-hoc interpretation of what makes these classes different.

Examining residuals in multivariate models presents us with a problem. For instance, the residuals should show a nice normal distribution, which implies absence of extreme outliers. However, this applies to the residuals after including all important explanatory variables and relevant parameters in the model. If we analyze a sequence of models, we have a series of different residuals for each model, and scrutinizing them all at each step is not practical. On the other hand, our decision to include a specific variable or parameter in our model might well be influenced by a violation of some assumption. Although there is no perfect solution to this dilemma, a reasonable approach is to examine the two residual terms in the intercept-only model, to find out if there are gross violations of the assumptions

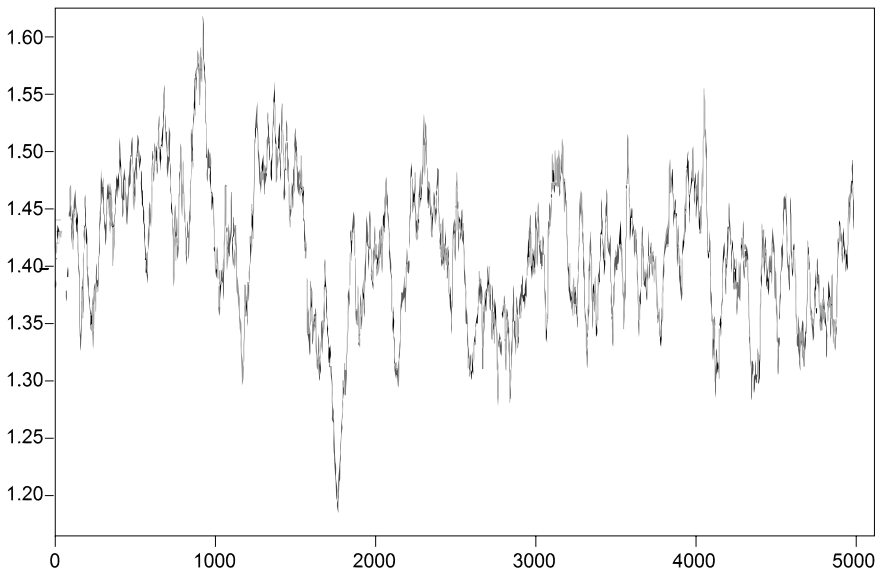


Figure 13.4 Error bar plot of level-2 residuals.

of the model. If there are, we should accommodate them, for instance by applying a normalizing transformation, by deleting certain individuals or groups from our data set, or by including a dummy variable that indicates a specific outlying individual or group. When we have determined our final model, we should make a more thorough examination of the various residuals. If we detect gross violations of assumptions, these should again be accommodated, and the model should be estimated again. Of course, after accommodating an extreme outlier, we might find that a previously significant effect has disappeared, and that we need to change our model again. Procedures for model exploration and detection of violations in ordinary multiple regression are discussed, for instance, in Tabachnick and Fidell (2013) or Field (2013). In multilevel regression, the same procedures apply, but the analyses are more complicated because we have to examine more than one set of residuals, and must distinguish between multiple levels.

As mentioned in the beginning of this section, graphs can be useful in detecting outliers and nonlinear relations. However, an observation may have an undue effect on the outcome of a regression analysis without being an obvious outlier. Figure 13.5, a scatter plot of the so-called Anscombe data (Anscombe, 1973), illustrates this point. There is one data point in Figure 13.5, which by itself almost totally determines the regression line. Without this one observation, the regression line would be very different. Yet, when the residuals are inspected, it does not show up as an obvious outlier.

In ordinary regression analysis, various measures have been proposed to indicate the influence of individual observations on the outcome (cf. Tabachnick & Fidell, 2013). In

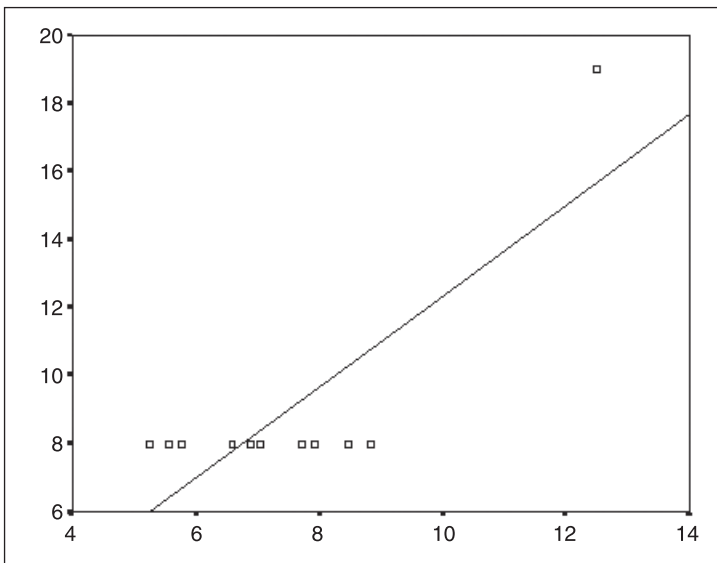


Figure 13.5 Regression line determined by one single observation.

general, such *influence* or *leverage* measures are based on a comparison of the estimates when a specific observation is included in the data or not. Langford and Lewis (1998) discuss extensions of these influence measures for the multilevel regression model. Since most of these measures are based on comparison of estimates with and without a specific observation, it is difficult to calculate them by hand. However, if the software offers the option to calculate influence measures, it is advisable to do so. If a unit (individual or group) has a large value for the influence measure, that specific unit has a large influence on the values of the regression coefficients. It is useful to inspect cases with extreme influence values for possible violations of assumptions, or even data errors.

13.3.2 Examining Slope Variation: OLS and Shrinkage Estimators

The residuals can be added to the average values of the intercept and slope, to produce predictions of the intercepts and slopes in different groups. These can also be plotted.

For example, Figure 13.6 plots the 100 regression slopes for the explanatory variable pupil extraversion in the 100 classes. It is clear that, for most classes, the effect is strongly

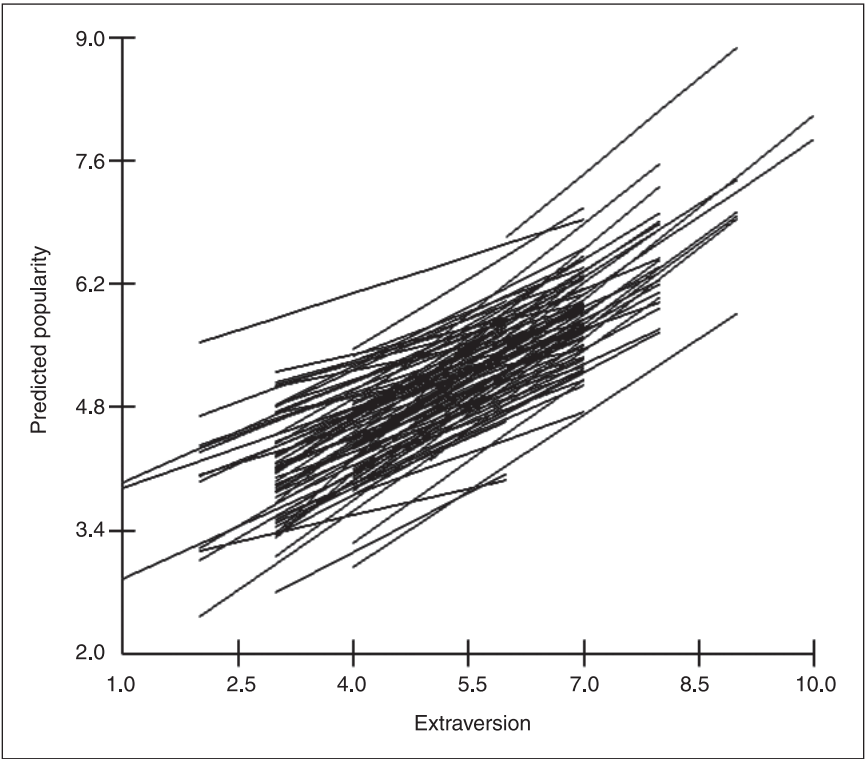


Figure 13.6 Plot of the 100 class regression slopes for pupil extraversion.

positive: extravert pupils tend to be more popular in all classes. It is also clear that in some classes the relationship is more pronounced than in other classes. Most of the regression slopes are not very different from the others, although there are a few slopes that are clearly different from the others. It could be useful to examine the data for these classes in more detail, to find out if there is a reason for the unusual slopes.

The predicted intercepts and slopes for the 100 classes are not identical to the values we would obtain if we carry out 100 separate ordinary regression analyses in each of the 100 classes, using standard ordinary least squares (OLS) techniques. If we would compare the results from 100 separate OLS regression analyses to the values obtained from a multilevel regression analysis, we would find that the results from the separate analyses are more variable. This is because the multilevel estimates of the regression coefficients of the 100 classes are weighted. They are so-called empirical Bayes (EB) or *shrinkage* estimates; a weighted average of the specific OLS estimate in each class and the overall regression coefficient, estimated for all similar classes (cf. Raudenbush & Bryk, 2002, Chapter 3).

As a result, the regression coefficients are *shrunk* back towards the mean coefficient for the whole data set. The shrinkage weight depends on the reliability of the estimated coefficient. Coefficients that are estimated with small accuracy shrink more than very accurately estimated coefficients. Accuracy of estimation depends on two factors: the group size, and the distance between the group-based estimate and the overall estimate. Estimates in small groups are less reliable, and shrink more than estimates from large groups. Other things being equal, estimates that are very far from the overall estimate are assumed less reliable, and they shrink more than estimates that are close to the overall average. The statistical method used is called *empirical Bayes* (EB) estimation. Due to this shrinkage effect, empirical Bayes estimators are biased. However, they are usually more precise, a property that is often more useful than being unbiased (cf. Kendall, 1959).

The equation to form the empirical Bayes estimate of the intercepts is given by

$$\hat{\beta}_{0j}^{\text{EB}} = \lambda_j \hat{\beta}_{0j}^{\text{OLS}} + (1 - \lambda_j) \gamma_{00}, \quad (13.1)$$

where λ_j is the reliability of the OLS estimate $\hat{\beta}_{0j}^{\text{OLS}}$ as an estimate of β_{0j} , which is given by the equation $\lambda_j = \sigma_{u_0}^2 / (\sigma_{u_0}^2 + \sigma_e^2 / n_j)$ (Raudenbush & Bryk, 2002), and γ_{00} is the overall intercept. The reliability λ_j is close to 1.0 when the group sizes are large and/or the variability of the intercepts across groups is large. In these cases, the overall estimate γ_{00} is not a good indicator of each group's intercept. If the group sizes are small and there is little variation across groups, the reliability λ_j is close to 0.0, and more weight is put on the overall estimate γ_{00} . Equation 2.14 makes clear that, since the OLS estimates are unbiased, the empirical Bayes estimates $\hat{\beta}_{0j}^{\text{EB}}$ must be biased towards the overall estimate γ_{00} . They are *shrunk* towards the average value γ_{00} . For that reason, the empirical Bayes estimators are also referred to as shrinkage estimators. Figure 13.7 presents boxplots for the OLS and the EB estimates of the intercept and the extraversion regression slopes in the model without

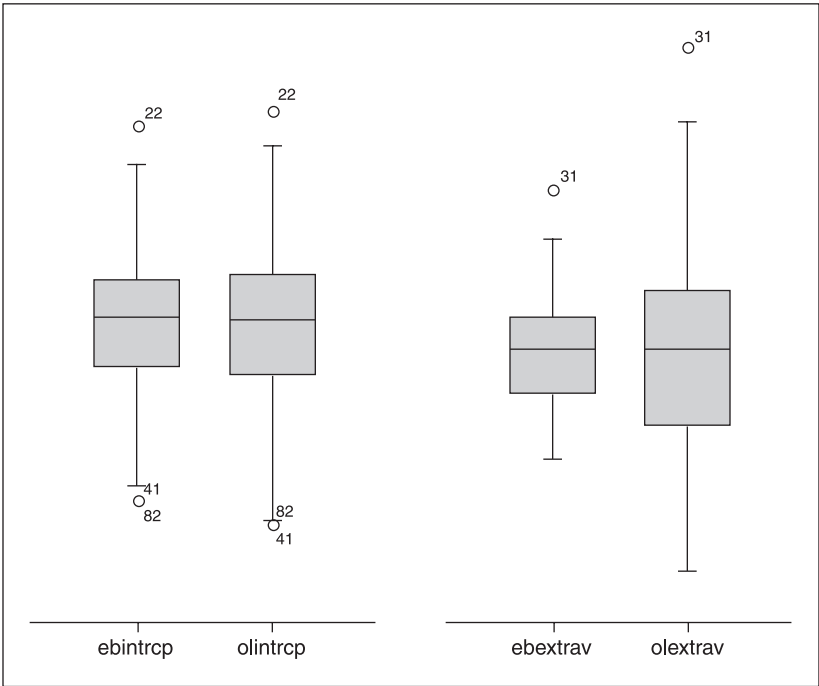


Figure 13.7 OLS and EB estimates for intercept and slope.

the cross-level interaction (model M_{1A} in Table 2.3). It is clear that the OLS estimates have a higher variability.

Although the empirical Bayes or shrinkage estimators are biased, they are also in general closer to the (unknown) values of β_{oj} . If the regression model includes a group-level model, the shrinkage estimators are conditional on the group-level model. The advantages of shrinkage estimators remain, provided that the group-level model is well specified (Bryk & Raudenbush, 1992, p. 80). This is especially important if the estimated coefficients are used to describe specific groups. For instance, we can use estimates for the intercepts of the schools to rank them on their average outcome. If this is used as an indicator of the quality of schools, the shrinkage estimators introduce a bias, because high-scoring schools will be presented too negatively, and low-scoring schools will be presented too positively. This is offset by the advantage of having a smaller standard error (Carlin & Louis, 1996; Lindley & Smith, 1972). Bryk and Raudenbush discuss this problem in an example involving the effectiveness of organizations (Bryk & Raudenbush, 1992, Chapter 5); see also the cautionary points made by Raudenbush and Willms (1991) and Snijders and Bosker (2012, pp. 58–63). All stress that the higher precision of the empirical Bayes residuals is bought at the expense of a certain bias. The bias is largest when we inspect groups that are both

small and far removed from the overall mean. In such cases, inspecting residuals should be supplemented with other procedures, such as comparing error bars for all schools (Goldstein & Healy, 1995). Error bars are illustrated in this chapter in Figure 13.4.

13.4 THE PROFILE LIKELIHOOD METHOD

After inspection of the residuals it might be concluded that these residuals are not normally distributed. For the estrone data, the (RML, MLwiN) estimate for the intercept is 1.418 (s.e. = 0.06). The estimate for the subject-level variance σ_{u0}^2 is 0.0175. The deviance for the model is calculated as -209.86 .² If we restrict this variance component to zero, the deviance becomes -97.95 . It has gone up by a considerable amount, and the difference of 111.91 can be tested against the chi-square distribution with one degree of freedom. Using the deviance test, the variance component is clearly significant. Since the Wald procedure is suspect for these data, a 95 percent confidence interval for the subject-level variance based on the asymptotic standard error is also questionable. An alternative is a confidence interval that is based directly on the deviance test, similar to the procedures followed in the null-hypothesis test based on the deviance. Such a procedure exists, namely the *profile likelihood* method, and the resulting confidence interval is called a *profile likelihood* interval.

To construct a profile likelihood interval for the estrone data, we need a multilevel analysis program that allows putting constraints on the fixed and random parameters in the model. First, we constrain all parameters to their estimated values. As a check, this should produce the same deviance as freely estimating them (within bounds of rounding error). Next, we constrain the value for the parameter that we wish to test to a different value. As a result, the deviance goes up. To reach significance, the increase in deviance must exceed the critical value in the chi-square distribution with one degree of freedom. For a 95 percent confidence interval, this critical value is 3.8415. So, to establish a 95 percent confidence interval around the subject-level variance estimate $s_{u0}^2 = 0.0175$, we must find an upper limit $U(s_{u0}^2)$ for which the deviance is $-209.86 + 3.84 = -206.02$, and a lower limit $L(s_{u0}^2)$ for which the deviance is also -206.02 . These limits can be found by trial and error, or more efficiently by using a simple search method such as setting an interval that is on both sides of the limit we are looking for, and successively halving the interval until the limit is estimated with sufficient precision.

Using the profile likelihood method on the estrone data, we find a 95 percent confidence interval for σ_{u0}^2 : $0.005 < \sigma_{u0}^2 < 0.069$. The profile likelihood confidence interval does not include zero, so the null hypothesis of no subject-level variance is rejected. The profile likelihood interval is not symmetric around the estimated value of $\sigma_{u0}^2 = 0.018$. Of course, it is known that variance components follow a chi-square distribution, which is not symmetric, so a valid confidence interval for a variance component should also be non-symmetric.

13.5 ROBUST STANDARD ERRORS

When the residuals do not have a normal distribution, the parameter estimates produced by the maximum likelihood method are still consistent and asymptotically unbiased, meaning that they tend to get closer to the true population values as the sample size becomes larger (Eliason, 1993). However, the asymptotic standard errors are incorrect, and they cannot be trusted to produce accurate significance tests or confidence intervals (Goldstein, 2011, pp. 93–94). This problem does *not* always vanish when the samples get larger.

Sometimes it is possible to obtain more nearly normal variables by transforming the outcome variable. If this is undesirable or even impossible, another method to obtain better tests and intervals is to correct the asymptotic standard errors. One available correction method to produce robust standard errors is the so-called Huber–White or sandwich estimator (Huber, 1967; White, 1982). In maximum likelihood estimation, the usual estimator of the sampling variances and covariances is based on the information matrix, or more general on the inverse of the so-called Hessian matrix (cf. Eliason, 1993). The standard errors used in the Wald test are simply the square root of the sampling variances that are found on the diagonal of this inverse. Thus, using matrix notation, the asymptotic variance-covariance matrix of the estimated regression coefficients can be written as:

$$\mathbf{V}_A(\hat{\beta}) = \mathbf{H}^{-1} \quad (13.2)$$

where \mathbf{V}_A is the asymptotic covariance matrix of the regression coefficients, and \mathbf{H} is the Hessian matrix. The Huber–White estimator is given as

$$\mathbf{V}_R(\hat{\beta}) = \mathbf{H}^{-1} \mathbf{C} \mathbf{H}^{-1} \quad (13.3)$$

where \mathbf{V}_R is the robust covariance matrix of the regression coefficients, and \mathbf{C} is a correction matrix. In Equation 13.3, the correction matrix is ‘sandwiched’ between the two \mathbf{H}^{-1} terms, hence the name ‘sandwich estimator’ for the Huber–White standard errors. The correction term is based on the observed raw residuals. If the residuals follow a normal distribution, \mathbf{V}_A and \mathbf{V}_R are both consistent estimators of the covariances of the regression coefficients, but the model-based asymptotic covariance matrix \mathbf{V}_A is more efficient since it leads to the smallest standard errors. However, when the residuals do not follow a normal distribution, the model-based asymptotic covariance matrix is not correct, while the observed residuals-based sandwich estimator \mathbf{V}_R is still a consistent estimator of the covariances of the regression coefficients. This makes inference based on the robust standard errors less dependent on the assumption of normality at the cost of sacrificing some statistical power. The precise form of the correction term is different in different models; for a technical discussion see Greene (1997). In multilevel analysis the correction is based on the cross-product matrix of the residuals, taking the multilevel structure of the data into account. Several multilevel

packages can produce robust standard errors for the fixed part, MLwiN and Mplus also produce robust sandwich estimators for the standard errors of the variance components.

When heteroscedasticity is involved due to non-normality, outliers, or misspecification of the model, the asymptotic standard errors are generally too small. Typically, the robust standard errors do not completely correct this, but they do result in more accurate significance tests and confidence intervals (Beck & Katz, 1997). So, when strong non-normality is suspected, it is prudent to use the sandwich standard errors. Since the robust standard errors are partly based on the observed residuals, they do need a reasonable second-level sample size to be accurate; single-level simulation results by Long and Ervin (2000) suggest a sample size of at least 100. In multilevel analysis, this would translate to a minimal second-level sample size of 100 for the robust standard errors to work well. Multilevel simulations with strongly non-normal two-level data (Hox & Maas, 2001) confirm these recommendations. Cheong, Fotiu and Raudenbush (2001) find that robust standard errors even provide reasonable protection against omitting an entire level from the analysis. On the other hand, when distributional assumptions are met, robust standard errors tend to be larger than asymptotic standard errors (Kauermann & Carroll, 2001), so their routine use in situations where the assumptions are justified results in standard errors that are too large and hence to loss of power.

Since the sandwich estimator needs a reasonable sample size to work well, the estrone data with $N = 5$ are not a good example. We will use the pupil popularity data introduced

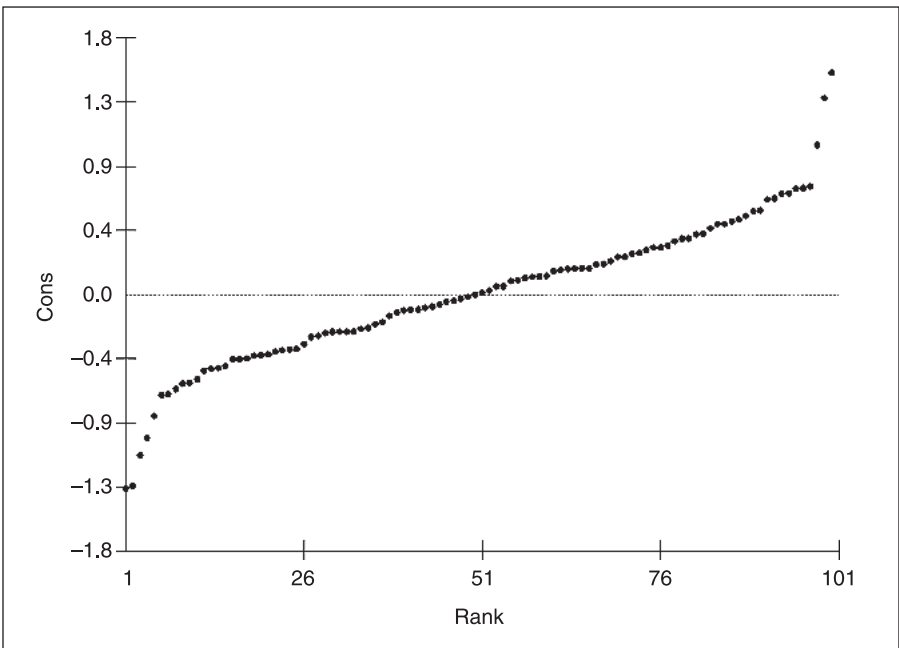


Figure 13.8 Popularity data: plot of second-level residuals against their rank.

in Chapter 2 to illustrate the use of sandwich standard errors. The model that we use is a random component model, with grand mean-centered predictors and FML estimation. By omitting the significant variance term for the slope of pupil extraversion we introduce a misspecification in the model, which causes heteroscedasticity in the second-level residuals. Figure 13.1 shows a plot of the second-level residuals u_0 against their ranks in this model. There is indeed some evidence of non-normality at the extremes.

Table 13.2 presents the parameter estimates, standard errors, and 95 percent confidence intervals using both the asymptotic and the sandwich standard errors. The parameter estimates are of course the same, and most of the standard errors and confidence intervals are the same or very close. Only the robust standard error of the slope for pupil extraversion is larger. The 95 percent confidence interval, which has been calculated carrying more decimals, shows a small difference for the CI for pupil extraversion and for the class-level variance. Presumably, this reflects the misspecification caused by ignoring the random component for the extraversion slope.

Table 13.2 Comparison of asymptotic and robust results, popularity data

	ML estimates, asymptotic s.e. (a.s.e.)		ML estimates robust s.e. (r.s.e.)	
	Coefficient (s.e.)	95% CI	Coefficient (s.e.)	95% CI
Fixed				
Intercept	5.07 (.06)	4.96–5.18	5.07 (.06)	4.96–5.18
Pupil gender	1.25 (.04)	1.18–1.33	1.25 (.04)	1.18–1.32
Pupil extraversion	0.45 (.02)	0.42–0.49	0.45 (.03)	0.41–0.50
Teacher experience	0.09 (.01)	0.07–0.11	0.09 (.01)	0.07–0.11
Random				
σ_e^2	0.59 (.02)	0.55–0.63	0.59 (.02)	0.55–0.63
σ_{u0}^2	0.29 (.05)	0.20–0.38	0.29 (.05)	0.19–0.39

The generalized estimating equations (GEE; Liang and Zeger, 1986) estimation method described in Chapter 3 strongly relies on robust standard errors for significance testing and confidence intervals. GEE estimation is a quasi-likelihood approach that starts by estimating the variance components directly from the raw residuals, followed by GLS estimation for the regression coefficients. This results in estimates for the regression coefficients that are consistent, but less efficient than maximum likelihood estimates (cf. Goldstein, 2011, p. 25; for a discussion of the GEE, for other approaches see Pendergast et al., 1996). If the second-level sample size is reasonable ($N > 100$, cf. Long & Ervin, 2000; Hox & Maas, 2001), the GEE estimates for the standard errors are not very sensitive to misspecification of the variance component structure. Raudenbush and Bryk (2002, p. 278) suggest that comparing the

asymptotic standard errors calculated by the maximum likelihood method to the robust standard errors is a way to appraise the possible effect of model misspecification and non-normality. Used in this way, robust standard errors become an indicator for possible misspecification of the model or its assumptions. If the robust standard errors are much different from the asymptotic standard errors, this should be interpreted as a warning sign that some distributional assumption is violated, and as an advice to look into the problem.

13.6 MULTILEVEL BOOTSTRAPPING

Another way to deal with non-normality is to use bootstrapping, introduced in brief in Chapter 3, which repeatedly draws random samples with replacement from the observed data. In each of these random samples, the model parameters are estimated, generally using either FML or RML maximum likelihood estimation. This process is repeated b times. For each model parameter, this results in a set of b parameter estimates. The variance of these b estimates is used as an indicator of the sampling variance associated with the parameter estimate obtained from the full sample. Since the bootstrap samples are obtained by resampling from the total sample, bootstrapping falls under the general term of resampling methods (cf. Good, 1999). Bootstrapping can be used to improve both the point estimates and the standard errors. Typically, at least 1000 bootstrap replications are needed for sufficient accuracy, and at least 5000 for accurate confidence intervals. This makes the method computationally demanding, but less so than the Bayesian methods treated in the next section.

If the residuals actually have a normal distribution, the bootstrap method and conventional maximum likelihood estimation are equivalent. If the data do not have a normal distribution, the maximum likelihood method is strictly speaking not valid. The bootstrap method reproduces this irregularity in the bootstrap samples. In theory, this should produce valid standard errors and confidence intervals for non-normal data.

The application of the bootstrap method to obtain standard errors for parameter estimates and establishing confidence intervals is straightforward. If we could sample, say, 1000 real samples from our population, we could calculate the sampling variance directly. Since this is not possible, we use the computer to *resample* 1000 samples from our sample data. This simulates the actual sampling, which is in practice not possible, and provides a simulated estimate of the sampling variance. In addition to providing parameter estimates and sampling variances, there are some less obvious refinements to the bootstrap method. For instance, it is possible to use the bootstrap method to correct the asymptotic parameter estimates. The mean of the bootstrapped parameters is not necessarily equal to the estimate in the original sample. On the contrary, it can be rather different. If that is the case, the assumption is that the statistic under consideration is biased. Whatever mechanism is operating to produce bias in the bootstrap samples is assumed to be operating in the original sample as well. To correct for this bias, we use the difference between the original estimate and the mean bootstrap estimate as an estimate of the amount of bias in the original estimate (cf. Hox & van de Schoot, 2013).

The bias corrected bootstrap (usually shortened to bc-bootstrap) assumes that the difference between the mean of the bootstrap replications and the parameter estimate in the actual sample indicates the estimation bias. The bias in a parameter estimate $\hat{\theta}$ is defined as the difference between the expected value of the parameter estimate and the population value:

$$\text{Bias}(\hat{\theta}) = \theta - E(\hat{\theta}). \quad (13.4)$$

Many statistics, for example the sample mean, are generally an unbiased estimate of the corresponding population value. Other statistics, for example the sample correlation, are known to be biased estimators of the corresponding population value. For such statistics, the amount of bias can be estimated using

$$\text{Bias}_B(\hat{\theta}) = \hat{\theta} - \bar{\theta}_B, \quad (13.5)$$

which estimates the bias as the difference between the asymptotic parameter estimate and the mean of the bootstrapped estimates. A similar bias correction is applied to the percentiles of the confidence interval, which leads to the bias-corrected percentile confidence interval (Stine, 1989; Efron & Tibshirani, 1993; Mooney & Duval, 1993). The bias-corrected bootstrap can be repeated, with each subsequent bootstrap including the bias correction estimated previously. This leads to the *iterated bootstrap*, which in combination with a large number of bootstrap samples for accuracy can be computationally demanding.

13.6.1 Bootstrapping Multilevel Regression Models

In bootstrapping single-level regression models, we have two basic choices (Stine, 1989; Mooney & Duval, 1993): bootstrapping cases or bootstrapping residuals. First, we can resample complete cases. This appears straightforward, but it runs against the assumption that in regression analysis the explanatory variables are fixed values. This means that in any replication of the study, we expect that the predictor variables have *exactly* the same values and only the residual error and hence the outcome variable will be different. To simulate this situation, we can resample not entire cases, but only the residuals. To bootstrap residuals, we first perform an ordinary multiple regression analysis and estimate the regression coefficients and the residuals. Next, in each bootstrap replication, the fixed values and regression coefficients are used to produce predicted outcomes, and to the predicted outcomes, a bootstrapped set of residuals is randomly added. These bootstrapped responses are then used to estimate the regression coefficients and other parameters of the model.

The choice between bootstrapping cases or residuals depends on the actual design and sampling process. Resampling residuals follows the statistical regression model completely. The statistical model assumes that the predictor variables are fixed by design, and that, if we replicate the study, the explanatory variables have exactly the same values. This can be

appropriate if the study is an experiment, with the values of the explanatory variables fixed by the experimental design. However, in much social and behavioral science, the values of the explanatory variables are actually as much sampled as the responses. In a replication, we do not expect that the explanatory variables have exactly the same values. In this case, resampling cases would be justifiable.

In multilevel regression, bootstrapping cases is more complicated than in ordinary regression models, because it implies bootstrapping units at all available levels. This not only changes the values of the explanatory and outcome variables, but also the multilevel structure: the sample sizes and the way the variance is partitioned over the different levels. For example, imagine sampling cases from the popularity example data, which has 2000 pupils in 100 classes. The class sizes are not all equal, so if we take a bootstrap sample of classes we are likely to have a sample of pupils larger or smaller than 2000. We can adjust by changing the class samples, but then the class sizes are not correct. The resulting redistribution of the variance affects all the other estimates. Currently, none of the specialist software packages supports multilevel casewise bootstrapping. The program MLwiN supports bootstrapping residuals, in two different varieties. The first variety is the nonparametric bootstrap. In the nonparametric bootstrap, the multilevel regression estimation is carried out once on the total data set. The regression coefficients from this estimation are used to produce predicted values, and the residuals from this analysis are resampled in the bootstrap iterations.³ This approach is called the nonparametric bootstrap because it preserves the possibly non-normal distribution of the residuals. An example of using the non-parametric bootstrap to construct confidence intervals for non-normal data is given by Carpenter, Goldstein and Rasbash (2003). The second approach, the parametric bootstrap, is to simulate the residuals using a multivariate normal distribution. In this approach, the residuals by definition always have a nice normal distribution. Given that the bootstrap is used when distributional assumptions are not met, the nonparametric (residuals) bootstrap is generally preferred.

MLwiN contains the bootstrap-based bias correction described earlier, for both the non-parametric and the parametric bootstrap method. The bias correction can be repeated several times, by bootstrapping repeatedly using the corrected parameter estimates. This is the iterated bootstrap described above.

Bootstrapping takes the observed data as the sole information about the population, and therefore it is best used with a reasonable second-level sample size. When we estimate variance components, a minimum of 50 second-level units is recommended for bootstrapping. If the interest is mainly in the fixed effects, which usually have a well-behaving symmetric distribution, we might get away with as few as 10 to 12 units (cf. Good, 1999, p. 109).

13.6.2 An Example of the Multilevel Bootstrap

We will use the pupil popularity data introduced in Chapter 2 to illustrate bootstrapping. The model is a random component model. By omitting the significant variance for the

slope of pupil extraversion, we misspecify the model, and as a result introduce some heteroscedasticity in the second-level residuals. The same model is used in Section 13.3 for the robust standard errors, and in Section 13.5 on Bayesian estimation.

Using MLwiN, there are several choices in the bootstrapping menu, such as setting the number of iterations for the bootstrap, or the number of iterated bootstraps. One choice is vital: allowing the program to estimate negative variance components. Many programs, including MLwiN, by default set negative variance estimates to zero, because negative variances are impossible. However, although setting an offending variance estimate to zero produces a better estimate, it also produces bias. To use bootstrapped estimates to estimate a parameter or establish a confidence interval, we need unbiased estimates in the bootstrap samples.

Table 13.3 presents the results of a parametric bootstrap using three iterated bootstrap runs of $b = 1000$ iterations each. The 95 percent confidence interval for the bootstrap can be obtained in two different ways: by applying the usual procedure taking the bias-corrected estimate ± 1.96 times the bootstrapped standard error, or by taking the 2.5th and 97.5th percentile of the bootstrap distribution of the last of the three bootstraps. Especially when bootstrapping parameter estimates that do not have a normal sampling distribution, such as variances, using the percentile method is superior. For the purpose of comparison, Table 13.3 shows both bootstrap intervals: the normal and the percentile method.

The bootstrap results in Table 13.3 are almost identical to the asymptotic estimates. Since we have on purpose omitted a significant variance component for pupil gender, we know that the second-level residuals do not have a normal distribution, and Figure 13.2 confirms this. Therefore, simulating residuals from a normal distribution, as is done in the parametric bootstrap, is not optimal. The non-parametric bootstrap uses the non-normal residuals in the bootstrap samples, and for that reason produces estimates that reflect the underlying distribution better. Table 13.4 shows the results of three iterated non-parametric bootstrap runs of 1000 iterations each.

Table 13.3 Comparison of asymptotic and bootstrap results, popularity data

	ML estimates		Parametric bootstrap		
	Coefficient (s.e.)	95% CI	Coefficient (s.d.)	95% CI (normal)	95% CI (percent)
Fixed					
Intercept	5.07 (.06)	4.96–5.18	5.07 (.06)	4.96–5.19	4.96–5.19
Pupil gender	1.25 (.04)	1.18–1.33	1.26 (.04)	1.18–1.33	1.18–1.33
Pupil extraversion	0.45 (.02)	0.42–0.49	0.46 (.02)	0.42–0.49	0.42–0.49
Teacher experience	0.09 (.01)	0.07–0.11	0.09 (.01)	0.07–0.11	0.07–0.11
Random					
σ_e^2	0.59 (.02)	0.55–0.63	0.59 (.02)	0.55–0.63	0.56–0.63
σ_{u0}^2	0.29 (.05)	0.20–0.38	0.30 (.05)	0.20–0.39	0.20–0.38

Table 13.4 Comparison of asymptotic and iterated bootstrap results, popularity data

	ML estimates		Non-parametric bootstrap		
	Coefficient (s.e.)	95% CI	Coefficient (s.d.)	95% CI (normal)	95% CI (percent)
Fixed					
Intercept	5.07 (.06)	4.96–5.18	5.08 (.06)	4.97–5.19	4.96–5.19
Pupil gender	1.25 (.04)	1.18–1.33	1.26 (.04)	1.18–1.33	1.18–1.33
Pupil extraversion	0.45 (.02)	0.42–0.49	0.46 (.02)	0.42–0.49	0.42–0.49
Teacher experience	0.09 (.01)	0.07–0.11	0.09 (.01)	0.07–0.11	0.07–0.11
Random					
σ_e^2	0.59 (.02)	0.55–0.63	0.59 (.02)	0.55–0.63	0.56–0.63
σ_{u0}^2	0.29 (.05)	0.20–0.38	0.30 (.05)	0.21–0.40	0.21–0.40

The bootstrapped results are again very close to the asymptotic estimates, demonstrating that these data are closely following the assumptions for the asymptotic estimates. The bias-corrected estimates are close to the asymptotic estimates, indicating that there is no important bias in the asymptotic estimates. If there is a distinct difference between the asymptotic and the bias-corrected parameter estimates, the estimates of the successive iterated bootstraps should be monitored, to check that the series of iterated bootstraps has converged with sufficient accuracy. By way of example, Figure 13.9 shows the trend for the asymptotic and the bias-corrected estimate for the class-level variance component σ_{u0}^2 in a series of three iterated bootstraps.

There is a very small bias-correction visible in the first bootstrap iteration, and the second and third bootstraps do not change the estimate much. Therefore, we conclude that the iterated bootstrap has converged. The difference between the asymptotic estimate of 0.296 and the final

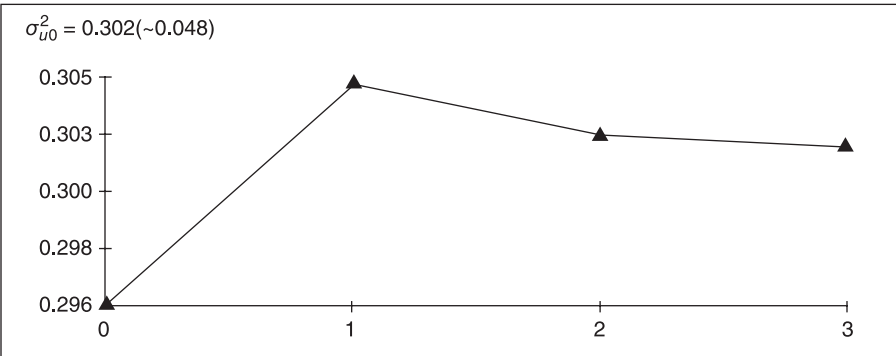


Figure 13.9 Bias-corrected estimate for σ_{u0}^2 after three iterated bootstraps.

bias-corrected estimate of 0.304 is of course trivial. It is as an indication of a real, but very small, and therefore in practice negligible, negative bias in the second-level variance estimate.

13.7 BAYESIAN ESTIMATION METHODS

Statistics is about uncertainty. We estimate unknown population parameters by statistics, calculated in a sample. In classical statistical inference, we express our uncertainty about how well an observed statistic estimates the unknown population parameter by examining its sampling distribution over an infinite number of possible samples. Since we generally have only one sample, the sampling distribution is based on a mathematical sampling model. An alternative basis is bootstrapping, discussed in the previous section, which simulates the sampling process. The sampling variance, or rather its square root, the standard error, is used for significance testing and establishing confidence intervals.

In Bayesian statistics (see also Chapter 3), we express the uncertainty about the population value of a model parameter by assigning to it a probability distribution of possible values. This probability distribution is called the *prior* distribution, because it is specified independently from the data. The Bayesian approach is fundamentally different from classical statistics. In classical statistics, the population parameter has one specific value, only we happen to not know it. In Bayesian statistics, we consider a probability distribution of possible values for the unknown population parameter. For a very gentle introduction to Bayesian modeling, we refer the novice reader to, among many others, Kaplan (2014), or van de Schoot et al. (2014). More detailed information about Bayesian multilevel modeling can be found in Hamaker and Klugkist (2011) or Gelman and Hill (2007).

After we have collected our data, this *prior distribution* is combined with the likelihood of the data to produce a *posterior* distribution, which describes our uncertainty about the population values after observing our data. Typically, when assuming a normally distributed prior, the variance of the posterior distribution is smaller than the variance of the prior distribution, which means that observing the data has reduced our uncertainty about the possible population values.

In Bayesian statistics, each unknown parameter in the model must have an associated probability distribution. For the prior distribution, we have a fundamental choice in the level of informativeness of the prior distribution varying between using an informative prior or an uninformative prior. An informative prior expresses a strong belief about the unknown population parameter. An informative prior will, especially when the sample or cluster size is small, strongly influence the posterior distribution, and hence our conclusions (e.g., Depaoli and Clifton, 2015, or van de Schoot et al., 2015). For this reason, some prefer an uninformative or diffuse prior, which has very little influence on the conclusions, and only serves to produce the posterior. An example of an uninformative prior is the uniform distribution, which simply states that the unknown parameter value is between a minimum and maximum value, with all values in between equally likely. Another example of an uninformative prior is a normal

distribution with a very large variance. Sometimes such a prior is called an ignorance prior, to indicate that we know nothing about the unknown parameter. However, this is not accurate, since total ignorance does not exist, at least not in Bayesian statistics, and even a noninformative prior can become highly informative after applying for example a link function as in logistic regression (Seaman, Seaman and Stamey, 2012). All priors add some information to the data, but diffuse priors add very little information, and therefore do not have much influence on the posterior. One way to express the information added to the data is to view the prior as a certain number of hypothetical cases, which are added to the data set.

If the posterior distribution has a mathematically simple form, such as a normal distribution, we can use the known characteristics of this distribution to calculate a point estimate and a confidence interval for the population parameter. In the case of a normal distribution, we could choose the mean as the point estimate, and base a confidence interval on the standard deviation of the posterior distribution. However, when Bayesian methods are applied to complex multivariate models, the posterior is generally a multivariate distribution with a complicated shape, which makes it difficult to use mathematical means to establish confidence intervals. When the posterior distribution is difficult to describe mathematically, it is approximated using Markov chain Monte Carlo simulation procedures. Markov chain Monte Carlo (MCMC) procedures are simulation techniques that generate random samples from a complex posterior distribution. By producing a large number of random draws from the posterior distribution, we can closely approximate its true shape. The simulated posterior distribution is then used to compute a point estimate and a confidence interval. Typically, the marginal (univariate) distribution of each parameter is used. The mode of the marginal posterior distribution is an attractive point estimate of the unknown parameter, because it is the most likely value, and therefore the Bayesian equivalent of the maximum likelihood estimator. Since the mode is more difficult to determine than the mean, the mean of the posterior distribution is also often used. In skewed posterior distributions, the median is an attractive choice. The confidence interval generally uses the $100 - \frac{1}{2}\alpha$ percentile limits around the point estimate. In the Bayesian terminology, this is referred to as the $100 - \alpha$ *central credibility interval*.

Bayesian methods have some advantages over classical methods. To begin, in contrast to the asymptotic maximum likelihood method, they are valid in small samples. Given the correct probability distribution, the estimates are always proper, which solves the problem of negative variance estimates. Since the random draws are taken from the correct distribution, there is no assumption of normality when variances are estimated. And finally, in contrast to ML estimation, one can prove that the method always converges provided that enough MCMC iterations are used.⁴

13.7.1 Simulating the Posterior Distribution

Different simulation methods are used to generate draws from the posterior distribution. Most methods use Markov chain Monte Carlo (MCMC) sampling. Given a set of initial

values from a specific multivariate distribution, MCMC procedures generate a new random draw from the same distribution. Suppose that $Z^{(1)}$ is a draw from a target distribution $f(Z)$. Using MCMC methods, we generate a series of new draws: $Z^{(1)} \rightarrow Z^{(2)} \rightarrow \dots \rightarrow Z^{(t)}$. MCMC methods are attractive because, even if $Z^{(1)}$ is not from the target distribution $f(Z)$, if t is sufficiently large, in the end $Z^{(t)}$ is a draw from the target distribution $f(Z)$. Having good initial values for $Z^{(1)}$ helps, because it speeds up the convergence on the target distribution, so maximum likelihood or OLS estimates are often used as initial values for $Z^{(1)}$.

The number of iterations t needed before the target distribution is reached is referred to as the ‘burn-in’ period of the MCMC algorithm. It is important that the burn-in is complete. To check if enough iterations of the algorithm have passed to converge on the target distribution, several diagnostics are used. A useful diagnostic is a graph of the successive values produced by the algorithm. A different procedure is to start the MCMC procedure several times with widely different initial values. If essentially identical distributions are obtained after t iterations, we decide that t has been large enough to converge on the target distribution (Gelman & Rubin, 1992). This can be formalized as follows. The MCMC procedure is started in 2 or 4 separate *chains*. To assess convergence to the correct distribution, the within-chain and between-chain variance in parameter estimates is monitored. When the *potential scaling reduction* (PSR, Gelman & Rubin, 1992) that reflects the amount of between-chain variance is small, for example smaller than 0.05 or 0.01 (we prefer $\text{PSR} < 0.01$), we conclude the MCMC algorithm has converged on the target distribution. In other words: the burn-in was long enough.

Typically, the number of MCMC iterations is much higher than the number of bootstrap samples. Using 10,000 or more MCMC iterations is common. The basic rule in Bayesian MCMC (and related methods) estimation is: there is no such thing as too many iterations. In case of doubt, increase the number of iterations (drastically). Depaoli and van de Schoot (2017) provide a checklist which can be followed to determine whether a model has reached convergence based on visual inspection of the trace plots, a various number of diagnostic tools and computing relative bias between two model with a different number of iterations (e.g. to determine how much parameters have changed in a model with 10,000 iterations when compared to a model with 50,000 iterations).

13.7.2 Bayesian Estimation Using MLwiN: The Estrone Data

At the time of writing, the only multilevel software that includes Bayesian methods for multilevel analyses are MLwiN, Mplus and some packages in R (see Gelman and Hill, 2007, for an introduction to Bayesian regression modeling in R). Here we will analyze the estrone data in MLwiN. Since the data set is very small (16 multiple measures on five women), asymptotic maximum likelihood does not work well for these data, and Bayesian methods may do better.

By default, MLwiN uses non-informative priors (for regression coefficients, a uniform distribution is used; for variances a very flat inverse gamma distribution). To start, we use

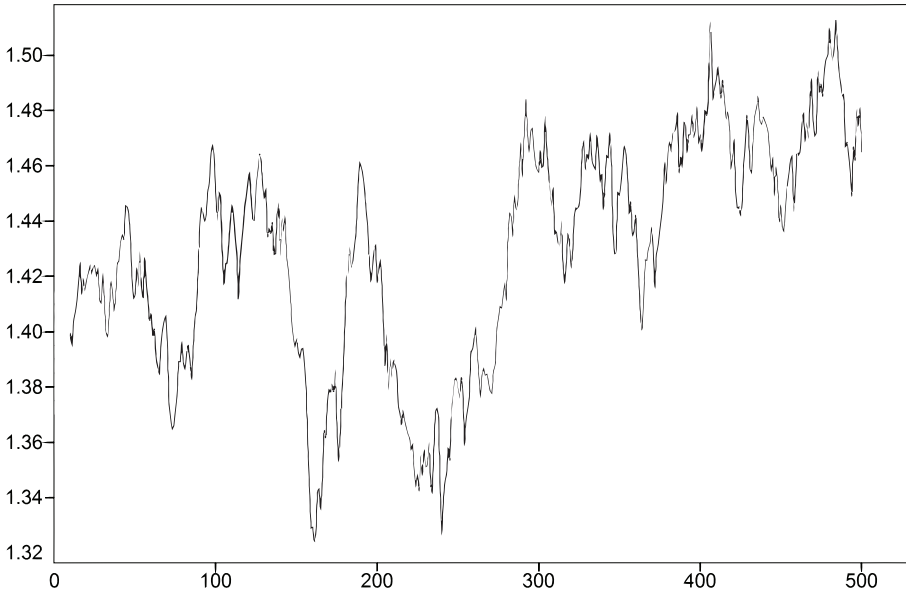


Figure 13.10 Plot of 500 burn-in estimates of the intercept b_0 , estrone data.

the default burn-in period of 500 iterations, and 5000 subsequent iterations for the MCMC chain. MLwiN produces a variety of plots and statistics to judge whether these quantities are sufficient. Figure 13.10 shows a plot of the first 500 burn-in estimates for the intercept β_0 . It is clear from this figure that the series of estimates shows a slight trend, and that this trend has not yet flattened out after 500 initial iterations. This suggests that we need more than 500 initial iterations for the burn-in.

Based on the plots in Figure 13.10, we decide to increase the burn-in period to 5000 iterations. Figure 13.11 shows the first 5000 estimates for the intercept. The plot of these 5000 estimates suggests that the series of estimates still did not reach convergence and we call for 500,000 MCMC iterations after the burn-in, and use a *thinning factor* of 100. That is, to reduce memory demands the program stores each 100th set of MCMC estimates, and discards the other estimates.⁵ This will give us 5000 MCMC estimates, each 100 MCMC iterations apart.

Figure 13.12 shows the last 500 estimates of the intercept which looks more stable than Figure 13.10, especially when inspecting the entire chain as can be seen in Figure 13.14. Note that these are the thinned estimates taken at each 100th iteration.

The plot of the total thinned chain of 5000 estimates (see Figure 13.13) looks quite stable, and the distribution of the generated values is nearly normal. MLwiN produces several diagnostics to evaluate the accuracy of the MCMC estimates. The Raftery–Lewis (Raftery & Lewis, 1992) diagnostic is an estimate of the number of MCMC iterations needed to be 95 percent confident that the 2.5th and 97.5th percentile are estimated with an error smaller than 0.005. Typically, the Raftery–Lewis diagnostics (one for each boundary) suggest a

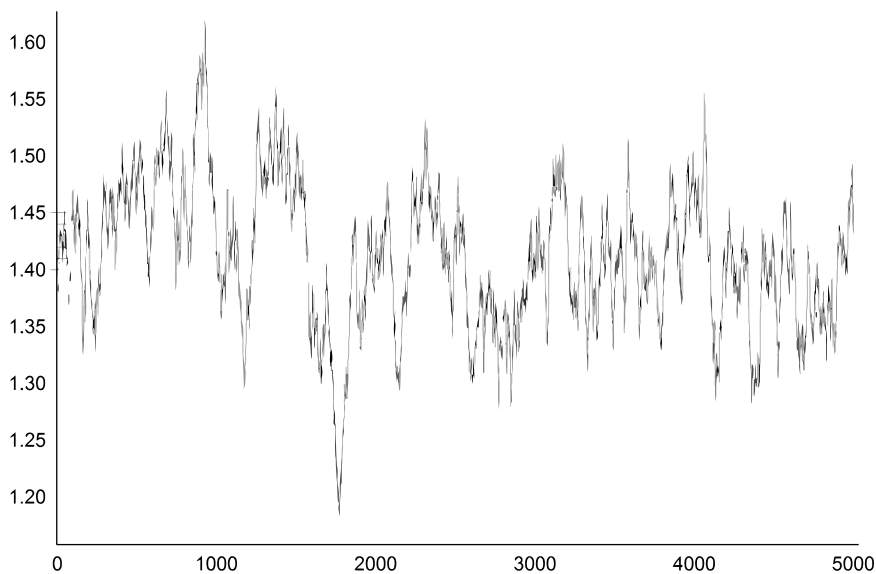


Figure 13.11 Plot of first 5000 estimates of the intercept b_0 , estrone data.

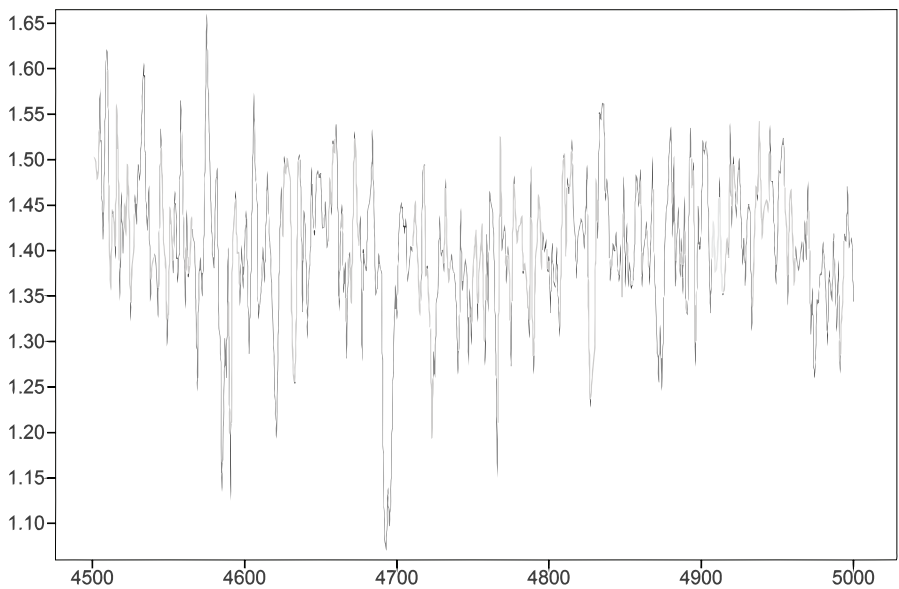


Figure 13.12 Plot of last 500 estimates of the intercept b_0 , estrone data.

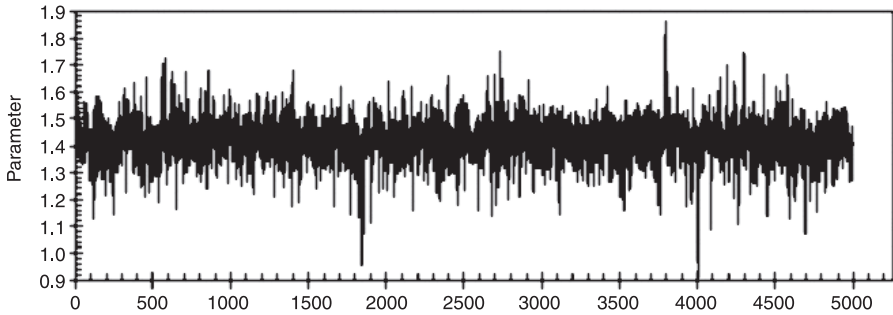


Figure 13.13 Diagnostic plots for 5000 thinned estimates of the intercept b_0 , estrone data.

very large number of iterations to achieve this level of accuracy. For our example data, they indicate that we need to carry out about 1,000,000 MCMC iterations. The Brooks–Draper diagnostic indicates the length of chain required to produce an estimate of the mean accurate to n significant figures. In the estrone example, the Brooks–Draper indicates that we need 39 iterations to estimate the mean within two significant decimals (this is of course after the thinning factor). MLwiN also reports an effective sample size ESS of 1325 for our estimates, which means that the autocorrelation between the draws (which are already thinned by a factor of 100) reduces our chain of 5000 iterations to an equivalent of 1325 independent draws.

Given the normal distribution of the intercept estimates, we can use the mode of 1.42 as a point estimate. The standard deviation of the MCMC estimates is 0.083, which we can use as a standard error in the usual way. This produces a Bayesian 95 percent credibility interval of 1.26–1.58. The Bayesian central 95 percent credibility interval determined from the 2.5th and 97.5th percentile of the 5000 observed estimates is 1.24–1.58, which is very close. The maximum likelihood point estimate is 1.42, with a standard error of 0.06, and a 95 percent confidence interval of 1.30–1.54. Since maximum likelihood is applied here in a very small sample, the MCMC confidence intervals are likely to be much more realistic.

In this example, we are mostly interested in the between-subject variance estimate σ_{u0}^2 . Figure 13.14 presents the plot of the last 500 estimates for σ_{u0}^2 .

The plot of the variance appears stable; most estimates are close to zero, with a few spikes that indicate an occasional large estimate. Given the small sample of subjects, this is normal; see for a non-normal case and possible solutions van de Schoot et al. (2015).

Figure 13.15 presents the kernel density plot which is based on the histogram of all the parameter estimates of Figure 13.15. This kernel plot is an approximation of the posterior distribution and can be used to obtain a summary statistic like the mean, mode or median, or the 95 percent credibility interval. The kernel plot for the variance highlights an important feature of the Bayesian estimation method used in MCMC: it always produces proper estimates. That is, by default all software packages specify a prior distribution for (residual) variance

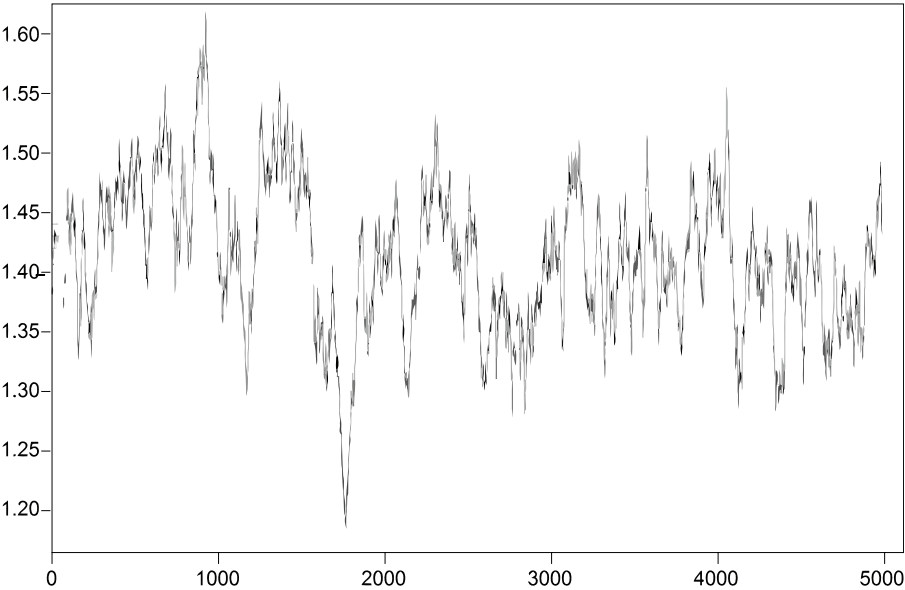


Figure 13.14 Plot of last 500 estimates of the variance σ^2_{u0} , estrone data.

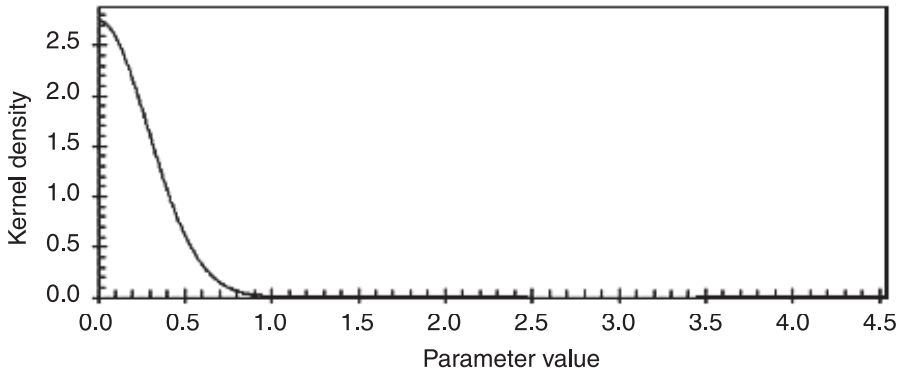


Figure 13.15 Kernel density of the variance σ^2_{u0} , estrone data.

parameters that can only obtain positive values, for example an inverse gamma distribution. As a consequence, the Bayesian result will never produce a negative variance estimate. If a negative estimate is obtained when using ML estimation, it might be attractive to use Bayes instead. We want to warn naïve users that often obtaining a negative variance estimate is an indication that the model is not specified correctly.

Since MCMC methods, with proper priors, will never produce negative variance estimates, they have a positive bias. As a result, *no* central credibility interval for a variance component will *ever* include the value zero. For instance, in the estrone example, the central 95 percent

interval for the variance estimates is 0.01–0.14. If the variance term σ_{u0}^2 indeed belongs in the model, the 0.01–0.14 interval is a reasonable 95 percent confidence interval, although the Raftery–Lewis statistic again indicates that we should use many more MCMC iterations for accuracy. However, since the value for the variance term is very small, we may well conclude that the between-subject variance term should be omitted from the model. The fact that the value zero is outside the central 95 percent interval is no evidence that the variance term is ‘significant’, because when variances are estimated, the value zero will *always* lie outside the central 95 percent interval. To carry out a Bayesian significance test, to determine if σ_{u0}^2 belongs in the model at all, we need different methods, which are not implemented in MLwiN. The program Mplus actually produces Bayes Factors for testing variance parameters; see Section 3.4.2 for more discussion on variance testing in the Bayesian framework.

13.7.3 An Example of Bayesian Estimation Using MLwiN: The Popularity Data

To illustrate Bayesian MCMC methods they are also applied to the popularity data set, which consists of 2000 pupils in 100 classes. As in the section on bootstrapping, the model is a variance component model, on purpose omitting the significant variance term for pupil extraversion and the cross-level interaction of pupil extraversion and teacher experience. To facilitate estimation, all predictor variables are grand mean-centered. Using 500 iterations for the burn-in and a chain of 5000 for the estimates, MLwiN produces the plots shown in Figures 13.16 and 13.17.

Figure 13.16 shows the plots of the last 500 estimates. All plots look well-behaved, meaning that no marked overall trend is visible, and the generating process appears stable. All other plots look fine: chaotic, without obvious patterns or trends.

In addition to the plots, the convergence of the MCMC chain can also be studied by starting it with different initial values, and inspecting if and after how many MCMC iterations the different chains converge on the same distribution. For instance, we may replace the customary maximum likelihood starting values by different values such as: intercept is 0 (FIML (full information maximum likelihood): 5.07); slope pupil gender is 0.5 (FIML: 1.25), slope pupil extraversion is 2 (FIML: 0.45), slope teacher experience is 0.1 (FIML: 0.09), variance class level is 0.2 (FIML: 0.29), and pupil level is 0.8 (FIML: 0.59). These initial values are reasonable, but deviate noticeably from the maximum likelihood estimates. If we monitor the burn-in process that starts with these initial estimates, we find the plots given in Figure 13.17.

Figure 13.17 nicely illustrates what happens if we start the MCMC algorithm with poor starting values in the presence of an informative data set. It prolongs the burn-in period. In this case, it is clear that after about 200–400 iterations, the successive MCMC estimates have stabilized. Only the intercept term β_0 might need a longer burn-in. This result reassures us that the MCMC chain is converging on the correct distribution. If the data contain little information on the model parameters (which is another way of stating that the model is too

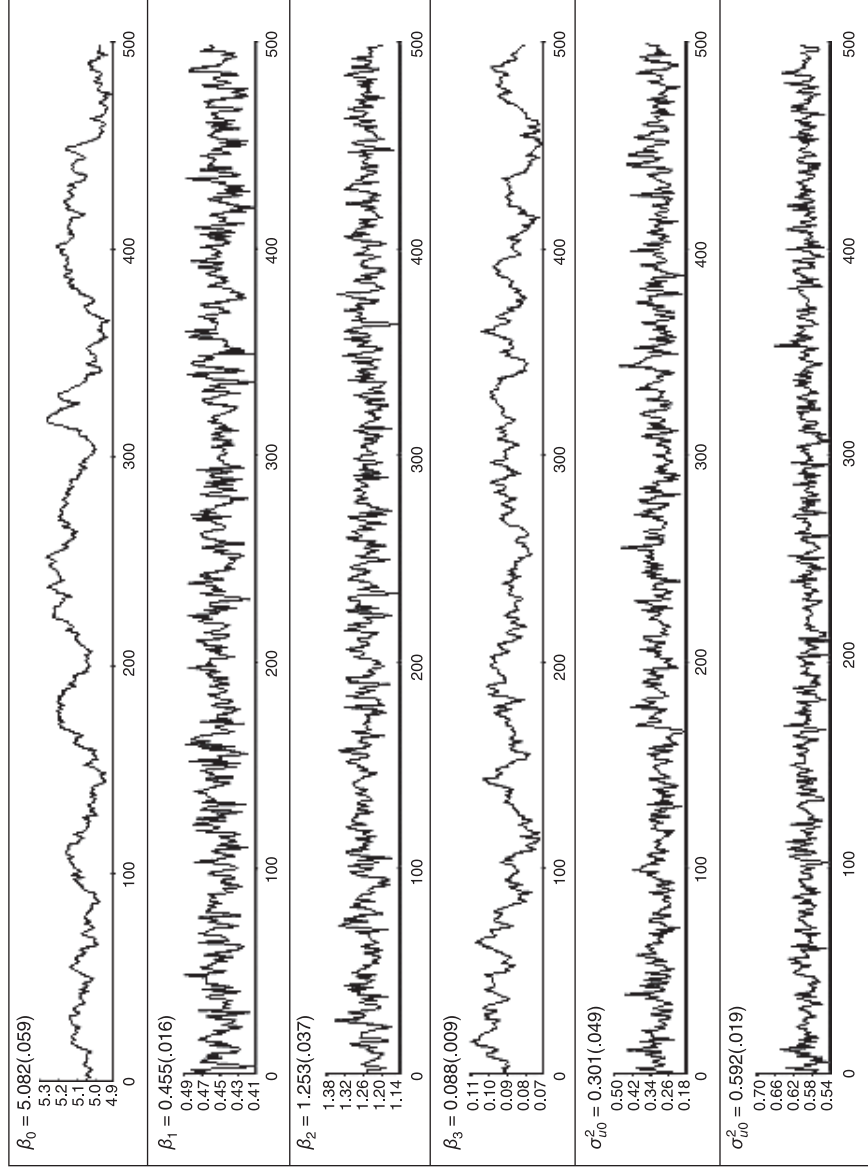


Figure 13.16 Plot of last 500 estimates of all parameters, popularity data.

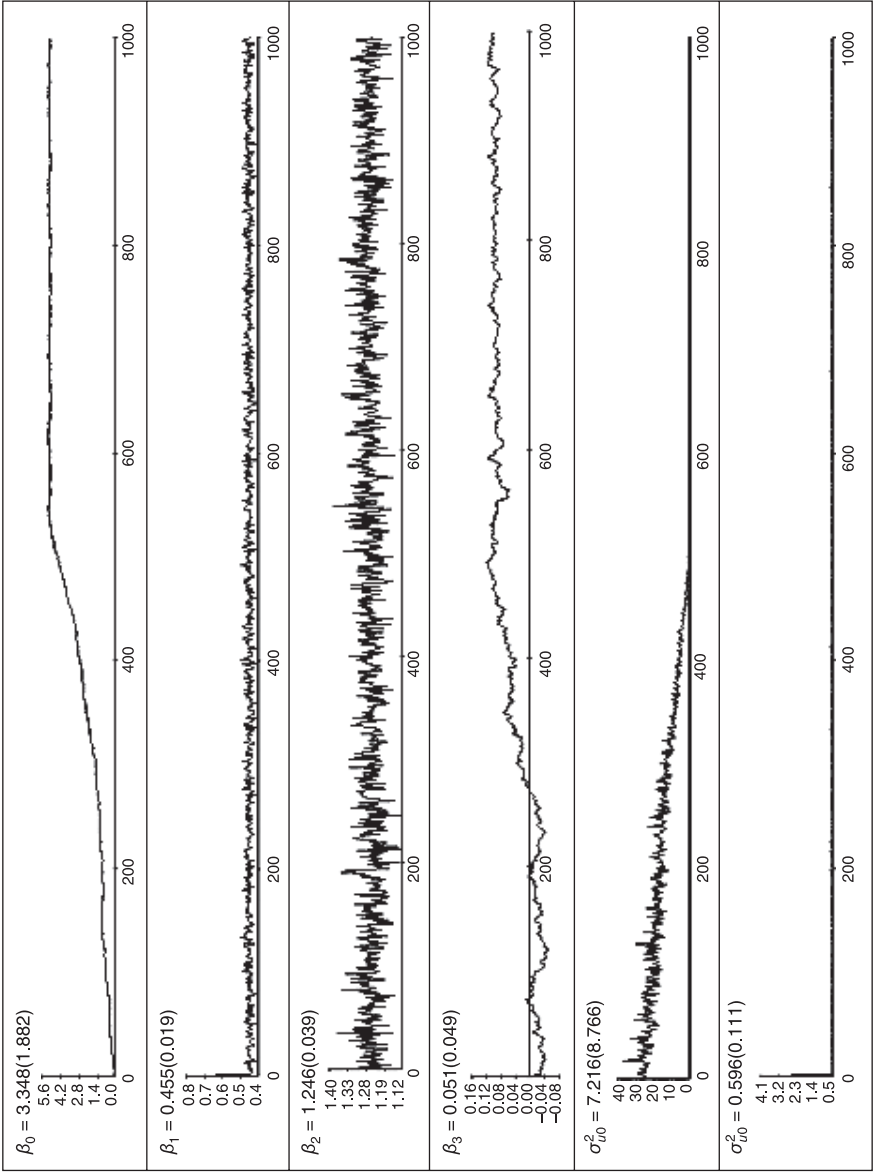


Figure 13.17 Plot of first 1000 estimates, deviant initial values.

complex for the available data), the MCMC chains started with different starting values would converge very slowly. The appropriate action would be to simplify the model.

For the final MCMC analysis, the analysis is repeated, with the burn-in set at 1000, and a MCMC chain of 50,000 iterations, with a thinning factor of 10. In this analysis, all diagnostics look fine. Table 13.5 presents the results, together with the asymptotic estimates. The maximum likelihood estimates are based on FML, and the 95 percent confidence interval is based on the standard normal approximation. For the Bayesian results, the posterior mode is used as the point-estimate, because with normal data this is equivalent to the maximum likelihood estimate. The Bayesian central 95 percent credibility interval is based on the 2.5th and 97.5th percentile points of the posterior distribution.

The Bayesian estimates in Table 13.5 are very close to the maximum likelihood estimates. Only the 95 percent central confidence interval for the class-level variance is somewhat different. Just as in the bootstrap example, the observed interval is not symmetric around the modal estimate, which reflects the non-normal distribution of the variance parameter.

13.7.4 Some Remarks on Bayesian Estimation Methods

An advantage of the Bayesian approach is that when the posterior distribution is simulated, the uncertainty of the parameter estimates is taken into account. So, the uncertainty in the parameter estimates for the fixed part is taken into account in the estimates for the random part. Moreover, simulating a large sample from the posterior distribution is useful because it provides not only point estimates (i.e., posterior mode or mean) of the unknown parameters, but also credibility intervals that do not rely on the assumption of normality for the posterior distribution. As a result, credibility intervals are also accurate for small samples (Tanner & Wong, 1987).

Table 13.5 Comparison of asymptotic and Bayesian results, popularity data

	ML estimates		MCMC estimates	
	Coefficient (s.e.)	95% CI	Coefficient (s.d.)	95% CI
Fixed				
Intercept	5.07 (.06)	4.96–5.18	5.07 (.06)	4.96–5.19
Pupil gender	1.25 (.04)	1.18–1.33	1.25 (.04)	1.18–1.33
Pupil extraversion	0.45 (.02)	0.42–0.49	0.45 (.02)	0.42–0.49
Teacher experience	0.09 (.01)	0.07–0.11	0.09 (.01)	0.07–0.11
Random				
σ_e^2	0.59 (.02)	0.55–0.63	0.59 (.02)	0.56–0.63
$\sigma_{\mu 0}^2$	0.29 (.05)	0.20–0.38	0.30 (.05)	0.22–0.41

In the large popularity example, the Bayesian estimation method performs well. But even in this well-behaved data set, the analyst must inspect the output carefully for indications of non-convergence or other problems. In the final analysis, with the burn-in set at 1000, and a MCMC chain of 50,000 iterations, with a thinning factor of 10, the Raftery–Lewis statistic still indicates that more iterations are needed. However, the Raftery–Lewis statistic is rather conservative. The Raftery–Lewis statistic is a lower-bound estimate (Raftery & Lewis, 1992) that often indicates huge numbers of MCMC iterations. It estimates the number of MCMC iterations needed to be 95 percent confident that the 2.5th and 97.5th percentile are estimated with an error smaller than 0.005. In essence, it requires that we are 95 percent confident that the end-points of the 95 percent confidence interval are correct to two decimal places. If several chains of far smaller numbers of iterations converge on the same confidence interval estimates, we may conclude that the smaller number is sufficient. In fact, if we analyze the pupil popularity data using the standard 500 iterations for the burn-in with 5000 consecutive iterations (no thinning) for monitoring, we find almost the same results. As suggested in Depaoli and van de Schoot (2017) we also recommend to re-run the model with (1) an increased number of iterations and (2) different starting values to find out if the MCMC has converged to the desired stable pattern. Not only visual inspection of the trace plots should be used, but it should always be combined with inspection of convergence diagnostics. However, it should be noted that there is no general consensus which of these diagnostics is best.

Bayesian estimation methods involve all the usual assumptions. They are *not* non-parametric, such as the non-parametric bootstrap. They use different methods to find point estimates and assess sampling variance, and they can be used in situations where asymptotic maximum likelihood methods are problematical. In addition, since the parameter distributions are chosen to be appropriate for the corresponding parameter (e.g. uniform or normal for regression coefficients, inverse chi-square or inverse gamma for variances), the simulated parameter distributions are always proper, which makes Bayesian estimation robust against non-normality of observed data (Hox & van de Schoot, 2013).

As indicated earlier, all priors add some information to the data. As a result, Bayesian estimates are biased. When the sample size is reasonable, the amount of bias is small. This bias is acceptable, because Bayesian methods promise more precision and better estimates of the sampling variance. Simulation research (Browne, 1998; Browne & Draper, 2000) confirms this, especially when we are dealing with non-linear models.

In this section, all priors used are non-informative. This is useful, because with normal data and large datasets, the resulting estimates are equivalent to maximum likelihood estimates. In addition, most analysts would be cautious in adding prior information to the data, because this could be interpreted as manipulating the outcome. However, sometimes we do have valid prior information. For instance, when we use a normed intelligence test as outcome variable, we know that its mean is in the neighborhood of 100, with a standard deviation of about 15. If we use a 10-point scale, we know that the mean must be somewhere between zero and ten, and the

variance cannot be larger than 25. So, using a prior for the variance that implies that the variance can be any number between zero and infinity appears to be wasting real information. Novick and Jackson already in 1974 suggest in their excellent introduction to Bayesian methods that in a scientific debate it can be constructive to define two different priors that correspond to two different hypotheses about a phenomenon. After data are collected and analyzed, the two posterior distributions should be more similar than the two prior distributions, indicating that observing the data allows the conclusions to converge.

It is clear that Bayesian MCMC methods, like bootstrapping, are computationally intensive methods. However, given modern computer equipment, they are well within present computer capabilities. The techniques presented in this section all use MLwiN (vers. 2.10). However, the issues that are addressed, such as deciding on the length of the burn-in and monitoring the MCMC chains, are general, and apply also to Bayesian estimation using Mplus or WinBUGS (Lunn et al., 2000). These decisions must be made by the analyst, and should be based on careful inspection of relevant plots and diagnostics. The number of iterations is usually much larger than in bootstrapping. However, since MCMC methods are based on generating estimates, and bootstrap methods on generating or shuffling around raw data, MCMC methods are often faster.

13.8 SOFTWARE

Multilevel software differs widely in the options available for checking assumptions. However, since checking assumptions often relies on inspection of residual plots, the options available in general (single-level) software are also useful for checking assumptions in multilevel data. If the software allows constraining regression coefficients and variances to specific values, the profile likelihood method can be carried out manually, but the process is tedious. Robust standard errors are more routinely available.

Multilevel bootstrapping and Bayesian estimation totally depend on the software. MLwiN is the only software that has a full implementation of different multilevel bootstrapping methods. Both MLwiN and Mplus support Bayesian estimation, and some Bayesian estimation software such as WinBUGS can estimate multilevel models. To use the methods described in this chapter, the analyst is totally dependent on what the software has to offer.

NOTES

- 1 It should be noted that HLM, MLwiN, and SPSS all produce slightly different results for the second-level variance and its standard error. When recalculated to a standard deviation and its associated standard error, these differences become exaggerated, another reason why this procedure is not recommended.
- 2 Using RML in MLwiN; using RML in HLM produces a slightly different estimate. The difference is that MLwiN cannot calculate the RML deviance, so RML estimation is combined with values from the FML deviance. MLwiN is used exclusively throughout this chapter because it can impose constraints on variances, which is necessary here. Most multilevel software does not contain the profile likelihood method, so we must carry out this procedure by hand. Note that Bayesian estimation also leads to an asymmetric interval.

- 3 Since the observed residuals are themselves a sample, their variance is not exactly equal to the variance estimated by the maximum likelihood procedure. Therefore, before the residuals are resampled, MLwiN transforms them to make them conform exactly to the estimated variances and covariances at all levels, cf. Rasbash et al., 2015. Since a model is still needed to estimate the residuals, Carpenter and Bithell (2000) reserve the name 'nonparametric bootstrap' for the cases bootstrap, and call the residuals bootstrap 'semi-parametric'.
- 4 But note that this number of iterations could be impossibly large.
- 5 Thinning is needed because MLwiN stores all data in memory; in general it is preferred to retain all iterations.

14

Multilevel Factor Models

SUMMARY

The models described in the previous chapters are all multilevel variants of the conventional multiple regression model. This is not as restrictive as it may seem, since the multiple regression model is very flexible and can be used in many different applications. Still, there are models that cannot be analyzed with multiple regression, notably factor analysis and path analysis models.

A general approach that includes both factor and path analysis is *structural equation modeling*, or SEM. The interest in structural equation modeling is generally on theoretical constructs, which are represented by the latent factors. The factor model, which is often called the measurement model, specifies how the latent factors are measured by the observed variables. The relationships between the theoretical constructs are represented by regression or path coefficients between the factors. This chapter describes the multilevel confirmatory factor analysis, and the two major estimation methods currently in use: weighted least squares (WLS) and maximum likelihood (ML). In addition, it reviews methods to obtain standardized coefficients, and goodness of fit in multilevel SEM models.

14.1 INTRODUCTION

Structural equation modeling is a general and convenient framework for statistical analysis that includes as special cases several traditional multivariate procedures, such as factor analysis, multiple regression analysis, discriminant analysis, and canonical correlation. It has its roots in path analysis, which was invented by the geneticist Sewall Wright (Wright, 1921). Structural equation models are often visualized by a graphical *path diagram*. A path diagram consists of boxes and circles, which are connected by arrows. In Wright's notation, observed (or measured) variables are represented by a rectangle or square box, and latent (or unmeasured) factors by a circle or ellipse. Single-headed arrows or 'paths' are used to define hypothesized causal relationships in the model, with the variable at the tail of the arrow being the cause of the variable at the head. Double-headed arrows indicate covariances or correlations, without a causal interpretation. Statistically, the single-headed arrows or paths represent regression coefficients, and double-headed arrows covariances. The statistical model is usually represented in a set of matrix equations. Since the focus in this chapter is

on structural equation models for multilevel data, and not on structural equation modeling itself, the models will generally be introduced using path diagrams.

Often a distinction is made between the measurement model and the structural model. The measurement model, which is a confirmatory factor model, specifies how the latent factors are related to the observed variables. The structural model contains the relationships between the latent factors. In this chapter, we discuss multilevel factor analysis, and introduce the techniques available to estimate multilevel factor models. Multilevel path models, which are structural models that may or may not include latent factors, are discussed in Chapter 15. For a general introduction in SEM, we refer to the introductory article by Hox and Bechger (1998) and the introductory book by Kline (2015). A statistical treatment is presented by Bollen (1989).

Structural equation models are often specified as models for the means and covariance matrix of multivariate normal data. The model is then:

$$\mathbf{y}_i = \boldsymbol{\mu} + \mathbf{\Lambda}\boldsymbol{\eta}_i + \boldsymbol{\varepsilon}, \quad (14.1)$$

which states that the observed variables \mathbf{y}_i are predicted by a regression equation involving an intercept $\boldsymbol{\mu}$, and the regression coefficients or factor loadings in matrix $\mathbf{\Lambda}$ multiplying the unobserved factor scores $\boldsymbol{\eta}_i$ plus a residual measurement error $\boldsymbol{\varepsilon}$. This can then be expressed as a model for the covariance matrix $\boldsymbol{\Sigma}$ by:

$$\boldsymbol{\Sigma} = \mathbf{\Lambda}\boldsymbol{\Phi}\mathbf{\Lambda}^T + \boldsymbol{\Theta}, \quad (14.2)$$

where the covariance matrix $\boldsymbol{\Sigma}$ is expressed as a function of the factor loading matrix $\mathbf{\Lambda}$, the matrix of covariances between factors $\boldsymbol{\Phi}$, and the (co)variances of the residual measurement errors in $\boldsymbol{\Theta}$.

This chapter discusses two different approaches to multilevel SEM. The first approach, described by Rabe-Hesketh, Skrondal and Zheng (2007) as the ‘within and between formulation’ focuses on determining separate estimates for the within (subject-level) covariance matrix and the between (group-level) covariance matrix. These are then modeled separately or simultaneously by a subject-level (within) factor model and a group-level (between) factor model, analogous to the single-level equation given in Equation 14.2. This works well, but has limitations, which will be discussed in the next section (14.2) that describes this approach in more detail. The second approach models the observed multilevel data directly with a model that includes variables at each available level and accommodates group-level variation of intercepts and slopes. It is the most accurate and versatile approach, but in some circumstances computationally demanding. It is also at the moment not widely available in standard multilevel or SEM software. This approach is described in Section 14.3.

14.2 THE WITHIN AND BETWEEN APPROACH

The within and between approach is based on an analysis of the subject-level and the group-level covariance matrix. This is in turn based on a decomposition of the variables to the available levels, which is discussed in the next section.

14.2.1 Decomposing Multilevel Variables

Multilevel structural models assume that we have a population of individuals that are divided into groups. The individual data are collected in a p -variate vector \mathbf{Y}_{ij} (subscript i for individuals, j for groups). The individual data \mathbf{Y}_{ij} are decomposed into a between-groups component $\mathbf{Y}_B = \bar{\mathbf{Y}}_j$ and a within-groups component $\mathbf{Y}_W = \mathbf{Y}_{ij} - \bar{\mathbf{Y}}_j$. In other words, for each individual we replace the observed total score $\mathbf{Y}_T = \mathbf{Y}_{ij}$ by its components: the group component \mathbf{Y}_B (the disaggregated group mean) and the individual component \mathbf{Y}_W (the individual deviation from the group mean). These two components have the attractive property that they are orthogonal and additive (cf. Searle, Casella & McCulloch, 1992):

$$\mathbf{Y}_T = \mathbf{Y}_B + \mathbf{Y}_W. \quad (14.3)$$

This decomposition can be used to compute a between-groups covariance matrix Σ_B (the population covariance matrix of the disaggregated group means \mathbf{Y}_B) and a within-groups covariance matrix Σ_W (the population covariance matrix of the individual deviations from the group means \mathbf{Y}_W). These covariance matrices are also orthogonal and additive:

$$\Sigma_T = \Sigma_B + \Sigma_W. \quad (14.4)$$

Following the same logic, we can also decompose the sample data. Suppose we have data from N individuals, divided into G groups (subscript i for individuals, $i = 1 \dots N$; subscript g for groups, $g = 1 \dots G$). If we decompose the sample data, the sample covariance matrices are also orthogonal and additive:

$$\mathbf{S}_T = \mathbf{S}_B + \mathbf{S}_W. \quad (14.5)$$

Multilevel structural equation modeling assumes that the population covariance matrices Σ_B and Σ_W are described by distinct models for the between-groups and within-groups structure. To estimate the model parameters, the factor loadings, path coefficients, and residual variances, we need maximum likelihood estimates of the population between-groups covariance matrix Σ_B and the population within-groups covariance matrix Σ_W . Several different methods have been offered for estimating multilevel factor models based on the within and between approach. Historically, the first method that was useful and could be estimated using

existing SEM software was a method based on analyzing S_B and S_W separately, proposed by Muthén (1989, 1994) who called it the MUML (for Muthén's ML). However, this method assumes equal group sizes, and simulation studies (Hox and Maas, 2001; Hox et al., 2010) find that its accuracy is limited. Yuan and Hayashi (2005) show analytically that the MUML method only leads to correct inferences when the between-level sample size goes to infinity and the coefficient of variation of the group sizes goes to zero. Most modern structural equation software still includes the MUML approach for two-level data, but the WLS and ML approaches described below are much more accurate.

14.2.2 Analysis of the Within and Between Matrix Using Weighted Least Squares

Asparouhov and Muthén (2007) describe an approach to multilevel SEM that uses separate estimation of the population covariance matrices, followed by estimating separate models for the within and between part of the multilevel factor model. In this approach, univariate maximum likelihood methods are used to estimate the vector of means μ at the between-group level, and the diagonal elements (the variances) of S_W and S_B . In the case of ordinal categorical variables, thresholds are estimated as well. Next, the off-diagonal elements of S_W and S_B are estimated using bivariate maximum likelihood methods. Note that in this approach S_B is not the covariance matrix of the observed group means, but an ML estimate of the population covariance matrix Σ_B . Finally, the asymptotic variance-covariance matrix for these estimates is obtained, and the multilevel SEM is estimated for both levels using weighted least squares (WLS). Currently, this approach is only available in Mplus (Muthén & Muthén, 1998–2015).

WLS is an estimation method that uses the asymptotic sampling variance-covariance matrix of S_W and S_B as a weight matrix in the estimation and to obtain correct chi-squares and standard errors. If the number of variables or the number of parameters is large, the asymptotic covariance matrix becomes very large. Unless the sample size is huge, the weight matrix is estimated poorly, resulting in inaccurate parameter estimates. Especially for the between part of the model, the number of elements in the full weight matrix can easily become larger than the number of groups. With realistic sample sizes, it is preferable to use only the diagonal of this weight matrix (often called DWLS for diagonal WLS; cf. Muthén et al., 1997). In Mplus, the default for multilevel modeling of non-normal variables is WLSM, which is diagonal WLS with a robust chi-square (WLSM using a mean-corrected (first-order) and WLSMV using a mean-and-variance-corrected (second-order) correction). ML estimation is also available for non-normal multilevel data, but it is computationally demanding, and WLSM is a much faster estimation method. WLSM can also be used with continuous variables, but in that case has no advantage over ML estimation.

14.3 FULL MAXIMUM LIKELIHOOD ESTIMATION

In two-level data, the factor structure given by Equation 14.1 becomes

$$\begin{aligned} \mathbf{y}_{ij} &= \boldsymbol{\mu}_j + \boldsymbol{\Lambda}_W \boldsymbol{\eta}_{ij} + \boldsymbol{\varepsilon}_W \\ \boldsymbol{\mu}_j &= \boldsymbol{\mu} + \boldsymbol{\Lambda}_B \boldsymbol{\eta}_{ij} + \boldsymbol{\varepsilon}_B, \end{aligned} \quad (14.6)$$

where μ_j are the random intercepts that vary across groups. The first equation models the within-groups variation, and the second equation models the between-groups variation. Since the individual-level variables are centered on the group means, at the individual level all means are by definition zero, and the μ_j are at the group level. By substitution and rearranging terms we obtain

$$\mathbf{y}_{ij} = \boldsymbol{\mu}_j + \boldsymbol{\Lambda}_W \boldsymbol{\eta}_{ij} + \boldsymbol{\Lambda}_B \boldsymbol{\eta}_{ij} + \boldsymbol{\varepsilon}_B + \boldsymbol{\varepsilon}_W. \quad (14.7)$$

Except for the notation, the structure of Equation 14.7 follows that of a random intercept regression model, with fixed regression coefficients (the factor loadings) in the factor matrices $\boldsymbol{\Lambda}$ and first-level and second-level error terms. If we allow group-level variation in the factor loadings we can generalize this to a random coefficient model. In the context of multilevel factor analysis, varying loadings are problematic because they imply that the measurement model is not equivalent across the different groups. In the context of multilevel path analysis, random coefficients for relationships between variables provide information on differences between groups that have a substantive interpretation.

To provide maximum likelihood estimates for the parameters in the general case of unbalanced groups we need to model the observed raw data. Unbalanced groups can be viewed as a form of incomplete data. For incomplete data, the maximum likelihood approach defines the model and the likelihood in terms of the raw data, which is why it is sometimes called the raw likelihood method. Raw ML minimizes the function (Arbuckle, 1996):

$$F = \sum_{i=1}^N \log |\boldsymbol{\Sigma}_i| + \sum_{i=1}^N \log (\mathbf{x}_i - \boldsymbol{\mu}_i)' \boldsymbol{\Sigma}_i^{-1} (\mathbf{x}_i - \boldsymbol{\mu}_i), \quad (14.8)$$

where the subscript i refers to the observed cases, \mathbf{x}_i to the variables observed for case i , and μ_i and Σ_i contain the population means and covariances of the variables observed for case i .

Mehta and Neale (2005) show that models for multilevel data, with individuals nested within groups, can be expressed as a structural equation model. The fit function given by Equation 14.8 applies, with clusters as units of observation, and individuals within clusters as variables. Unbalanced data, here unequal numbers of individuals within clusters, are included the same way as incomplete data in standard SEM. While the two-stage WLS approach can include only random intercepts in the between-groups model, the ML representation can incorporate random slopes as well (Mehta & Neale, 2005). In theory, any modern SEM software that allows for incomplete data can be used to estimate multilevel SEM. In practice, specialized software is used that makes use of the specific multilevel structure in the data to simplify calculations. Full maximum likelihood multilevel SEM is currently available for three-level models in Mplus and for many-level models in GLLAMM. A recent development is to use robust standard errors and chi-squares for

significance testing. With multilevel data, robust chi-squares and standard errors offer some protection against unmodeled heterogeneity, which may result from misspecifying the group-level model, or by omitting a level. Finally, Skrondal and Rabe-Hesketh (2004) show how to combine this with a generalized linear model for the observed variables, which allows for non-normal variables. This is currently available only in Mplus and GLLAMM.

The next section analyzes an example data set, using WLS and ML estimation. Simulations (Hox et al., 2010) have shown that the difference between WLS and ML is generally negligible. Our example confirms that WLS and ML estimation produces very similar results. When ML estimation is possible, it is the method of choice, but when the demands for ML estimation overtax the computer capacity, WLS is a viable alternative.

The maximum likelihood approach is the only approach that allows random slopes in the model. In a confirmatory factor analysis, this means that factor loadings are allowed to vary across groups. In our example, none of the six individual-level factor loadings has significant slope variation across families. In confirmatory factor analysis this is desirable, because finding varying factor loadings implies that the scales involved are not measuring the same thing in the same way across families.

14.4 AN EXAMPLE OF MULTILEVEL FACTOR ANALYSIS

The example data are the scores on six intelligence measures of 400 children from 60 families, patterned after van Peet (1992). The six intelligence measures are: word list, cards, matrices, figures, animals, and occupations. The data have a multilevel structure, with children nested within families. Since intelligence is strongly influenced by shared genetic and environmental influences in the families, we may expect rather strong between-family effects. In this data set, the intraclass correlations of the intelligence measures range from 0.38 to 0.51.

14.4.1 Full Maximum Likelihood Estimation

Given that full maximum likelihood estimation is the norm, we begin the analysis of the example data using this estimation method. Muthén (1994) recommends starting the analysis with an analysis of the total scores. This may have been good advice when the complicated pseudo-balanced model setups were used, but given user-friendly multilevel SEM software, this step is superfluous. Since the effective first-level sample size ($N - G$) is almost always much larger than the second-level sample size (G), it is good practice to start with the within part, either by specifying a saturated model for the between part, or by analyzing only the pooled within matrix.

In the example data, the number of observations on the individual level is $400 - 60 = 340$, while on the family level it is 60. Thus, it makes sense to start on the individual level by constructing a model for S_{pw} only, ignoring S_B .

An exploratory factor analysis on the correlations derived from S_{pw} suggests two factors, with the first three measures loading on the first factor, and the last three measures on the last. A confirmatory factor analysis on S_{pw} confirms this model ($\chi^2 = 6.0, df = 8, p = 0.56$). A model with just one general factor for S_{pw} is rejected ($\chi^2 = 207.6, df = 9, p < 0.001$).

The next step is to specify a family model. For explorative purposes, we could carry out a separate analysis on the estimated between-groups covariance matrix S_B . This matrix, which is a maximum likelihood estimator of Σ_B (not the scaled between matrix discussed in Section 14.1.2), is obtained by specifying a saturated model for both the within and the between level (Mplus generates these matrices automatically). In the example data, given the good fit of the within model, we carry on with an analysis of the multilevel data, with the two-factor model retained for the within part.

We start the analysis of the between structure by estimating some ‘benchmark’ models for the group level, to test whether there is any between-family structure at all. The simplest model is a null model that completely leaves out the specification of a family-level model. If the null model holds, there is no family-level structure at all; all variances and covariances in S_B are the result of individual sampling variation. If this null model holds, we may as well continue our analyses using simple single-level analysis methods.

The next model tested is the independence model, which specifies only variances on the family level, but no covariances. If the independence model holds, there is family-level variance, but no substantively interesting structural model. We can simply analyze the pooled within matrix, at some cost in losing the within-groups information from G observations that is contained in the between-groups covariance matrix. If the independence model is rejected, there is some kind of structure on the family level. To examine the best possible fit given the individual-level model, we can estimate the saturated model; which fits a full covariance matrix to the family-level observations. This places no restrictions on the family model. Table 14.1 shows the results of estimating these benchmark models on the family level.

The null model and the independence model are both rejected. Subsequently, we specify for the family level the same one-factor and two-factor models we have used at the individual level. The one-factor model fits well ($\chi^2 = 11.9, df = 17, p = 0.80$). The two-factor model is no improvement (difference chi-square 0.15, $p = 0.70$).

Table 14.1 Family level benchmark models

	Chi-square	df	p
Family model			
Null	323.6	29	.00
Independence	177.2	23	.00
Saturated	6.7	8	.57

Another natural two-level model is a model with the same factor structure at the within and between level, and equality constraints on corresponding factor loadings across the two levels. Jak, Oort & Dolan (2013) show that in a multigroup model equal factor loadings across groups implies equal factor loadings across levels in a two-level model. Equal factor loadings across levels are needed to ensure that the common factors at the between level can be interpreted as the aggregate of the within-level factor. This allows the computation of the intraclass correlation of the factor (Mehta & Neale, 2005) using the factor variances ϕ at each level:

$$ICC_{\text{factor}} = \phi_{\text{BETWEEN}} / (\phi_{\text{BETWEEN}} + \phi_{\text{WITHIN}}). \tag{14.9}$$

If factor loadings are not equal across levels, the common factors have different interpretations across levels. In a model with equal factor loadings across levels, residual variance at the between level represents measurement bias (Jak et al., 2013; Rabe-Hesketh et al., 2007). In our example, the two-level model with equal factor loadings across levels fits the data well ($\chi^2 = 18.75$, $df = 20$, $p = 0.54$). The parameter estimates of this model, fitted with robust maximum likelihood estimation in Mplus, are given in Table 14.2. Plugging in the factor variances at each level in Equation 14.9 shows that 47.1 percent of the variance in ‘Numeric’ is at the family level $(.892 / (.892 + 1) = .471)$ and that 52.5 percent of the variance in ‘Perception’ is at the family level $(1.092 / (1.092 + 1) = .525)$.

Table 14.2 Parameter estimates for equivalent model on both levels

	Individual			Family		
	Numeric	Perception	Residual variation	Numeric	Perception	Residual variation
Wordlist	3.20 (.28)		6.14 (.78)	3.20 (.28)		1.23 (.50)
Cards	3.17 (.21)		5.33 (.65)	3.17 (.21)		1.35 (.60)
Matrix	2.97 (.21)		6.58 (.77)	2.97 (.21)		1.89 (.60)
Figures		2.95 (.20)	7.11 (.76)		2.95 (.20)	2.12 (.65)
Animals		3.12 (.17)	5.08 (.60)		3.12 (.17)	0.56 (.57) ns.
Occupation		2.94 (.15)	5.02 (.72)		2.94 (.15)	1.90 (.63)
Factor variance	1.000	1.000		0.892 (.25)	1.092 (.28)	
Factor covariance	.388 (.05)			.972 (.24)		
Factor correlation	.388			.985		

The principle of using the simplest model that fits well leads to acceptance of the one-factor model on the family level, at the expense of a more complicated interpretation since here the factor structure is not the same for the child and family level. The chi-square model test is not significant, and the fit indices are fine: CFI is 1.00 and the RMSEA is 0.00 (see 14.6). Figure 14.1 presents the within and between model in a single path diagram. Note that the between-level variables that represent the family-level intercept variance of the observed variables, are latent variables, depicted by circles or ellipses.

Using the maximum likelihood method (ML) in Mplus leads to the estimates reported in Table 14.3.

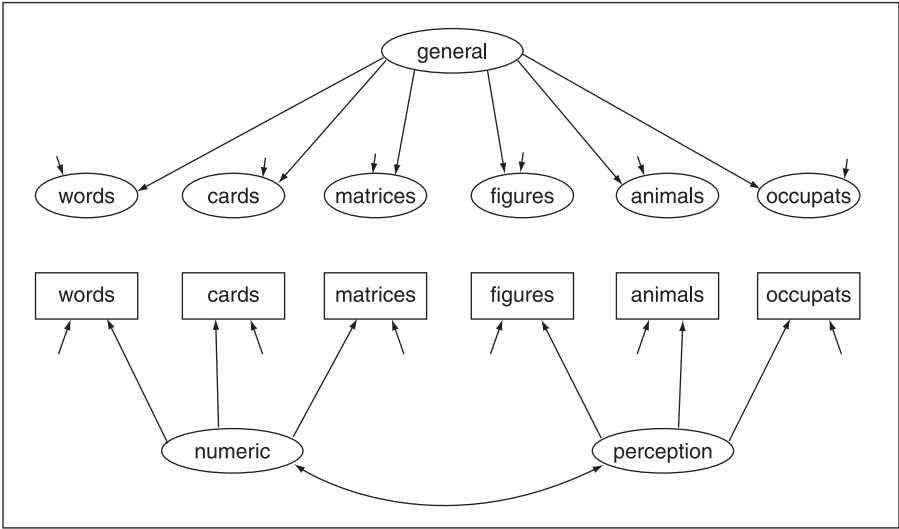


Figure 14.1 Diagram for family IQ data 1

Table 14.3 Individual and family level estimates, ML estimation

	Individual level			Family level	
	Numeric	Perception	Residual variation	General	Residual variation
Wordlist	3.18 (.20)		6.19 (.74)	3.06 (.39)	1.25 (.57)
Cards	3.14 (.19)		5.40 (.69)	3.05 (.39)	1.32 (.59)
Matrix	3.05 (.20)		6.42 (.71)	2.63 (.38)	1.94 (.67)
Figures		3.10 (.20)	6.85 (.76)	2.81 (.40)	2.16 (.71)
Animals		3.19 (.19)	4.88 (.70)	3.20 (.38)	0.66 (.49)
Occupation		2.78 (.18)	5.33 (.60)	3.44 (.42)	1.58 (.62)

Standard errors in parentheses. Correlation between individual factors: 0.38.

14.4.2 Weighted Least Squares Estimation

Using the separate estimation/WLS method with robust chi-square (WLSMV) in Mplus leads to the estimates reported in Table 14.4.¹ The chi-square model test accepts the model ($\chi^2 = 5.91$, $df = 7$, $p = 0.55$), the fit indices are good: CFI is 1.00 and the RMSEA is 0.00. The parameter estimates in Table 14.4 are similar to the full maximum likelihood estimates, but not identical. The robust standard errors lead to the same conclusions as the asymptotic standard errors used with full maximum likelihood estimation.

Table 14.4 Individual and family level estimates, WLS estimation

	Individual level			Family level	
	Numeric	Perception	Residual variation	General	Residual variation
Wordlist	3.25 (.15)		5.67 (.84)	3.01 (.48)	1.51 (.62)
Cards	3.14 (.18)		5.44 (.68)	3.03 (.38)	1.25 (.71)
Matrix	2.96 (.22)		6.91 (.92)	2.62 (.45)	2.02 (.69)
Figures		2.96 (.22)	7.67 (.92)	2.80 (.46)	2.03 (.72)
Animals		3.35 (.21)	3.79 (.99)	3.15 (.41)	0.96 (.61)
Occupation		2.75 (.24)	5.49 (.94)	3.43 (.44)	1.67 (.63)

Standard errors in parentheses. Correlation between individual factors: 0.38.

14.5 STANDARDIZING ESTIMATES IN MULTILEVEL STRUCTURAL EQUATION MODELING

The estimates reported are all unstandardized estimates. For interpretation, it is often useful to inspect the standardized estimates as well, because these can be used to compare the loadings and residual variances for variables that are measured in a different metric. A convenient standardization is to standardize both the latent factors and the observed variables on each level separately. Table 14.5 presents the standardized estimates for the ML estimates. It shows that the factor structure at the family level is stronger than at the individual level. This is typical; one reason is that measurement errors accumulate at the individual level.

The separate standardization presented in Table 14.5 is called the within-groups completely standardized solution. Standardization takes place separately in the within part and in the between part.

Table 14.5 Individual and family level estimates, standardized estimates

	Individual level			Family level	
	Numeric	Perception	Residual variation	General	Residual variation
Wordlist	0.79 (.03)		0.38 (.05)	0.94 (.03)	0.12 (.06)
Cards	0.80 (.03)		0.35 (.05)	0.94 (.03)	0.12 (.06)
Matrix	0.77 (.03)		0.41 (.05)	0.88 (.05)	0.22 (.08)
Figures		0.76 (.03)	0.42 (.05)	0.89 (.04)	0.22 (.08)
Animals		0.82 (.03)	0.32 (.05)	0.97 (.02)	0.06 (.05)
Occupation		0.77 (.03)	0.40 (.05)	0.94 (.03)	0.12 (.05)

Standard errors in parentheses. Correlation between individual factors: 0.38.

14.6 GOODNESS OF FIT IN MULTILEVEL STRUCTURAL EQUATION MODELING

SEM programs produce, in addition to the chi-square test, a number of goodness-of-fit indices that indicate how well the model fits the data. Statistical tests for model fit have the problem that their power varies with the sample size. If we have a very large sample, the statistical test will almost certainly be significant. Thus, with large samples, we will always reject our model, even if the model actually describes the data quite well. Conversely, with a very small sample, the model will always be accepted, even if it fits rather badly.

Given the sensitivity of the chi-square statistic to the sample size, researchers have proposed a variety of alternative fit indices to assess model fit. All goodness-of-fit measures are some function of the chi-square and the degrees of freedom. Most of these fit indices do not only consider the fit of the model, but also its simplicity. A saturated model, that specifies all possible paths between all variables, always fits the data perfectly, but it is just as complex as the observed data. In general, there is a trade-off between the fit of a model and the simplicity of a model. Several goodness-of-fit indices assess simultaneously both the fit and the simplicity of a model. The goal is to produce a goodness-of-fit index that does not depend on the sample size or the distribution of the data. In fact, simulations have shown that most goodness-of-fit indices still depend on sample size and distribution, but the dependency is much smaller than that of the routine chi-square test.

Most SEM software computes a bewildering array of goodness-of-fit indices. All of them are functions of the chi-square statistic, but some include a second function that penalizes complex models. For instance, Akaike’s Information Criterion (AIC) is twice the chi-square statistic minus the degrees of freedom for the model. For a detailed review and evaluation of a large number of fit indices, including those mentioned here, we refer to Gerbing and Anderson (1992).

Jöreskog and Sörbom (1989) have introduced two goodness-of-fit indices called GFI (goodness of fit index) and AGFI (adjusted GFI). The GFI indicates goodness-of-fit, and the AGFI attempts to adjust the GFI for the complexity of the model. Bentler (1990) has introduced a similar index called the comparative fit index (CFI). Two other well-known fit measures are the Tucker–Lewis index (TLI) (Tucker & Lewis, 1973), also known as the non-normed fit index (NNFI), and the normed fit index (NFI) (Bentler & Bonett, 1980). Both the NNFI and the NFI adjust for complexity of the model. Simulation research shows that all these indices still depend on sample size and estimation method (e.g., ML or GLS), with the CFI and the TLI/NNFI showing the best overall performance (Chou & Bentler, 1995; Kaplan, 1995). If the model fits perfectly, these fit indices should have the value 1. Usually, a value of at least 0.90 is required to accept a model, while a value of at least 0.95 is required to judge the model fit as ‘good.’ However, these are just rules of thumb.

A different approach to model fit is to accept that models are only approximations, and that perfect fit may be too much to ask for. Instead, the problem is to assess how well a given model approximates the true model. This view led to the development of an index called RMSEA, for root mean square error of approximation (Browne & Cudeck, 1992). If the approximation is good, the RMSEA should be small. Typically, a RMSEA of less than 0.10 is required to accept a model (Kline, 2015), with RMSEA less than 0.05 judged ‘good’. Statistical tests or confidence intervals can be computed to test if the RMSEA is significantly larger than this lower bound.

Given the many possible goodness-of-fit indices, the customary advice is to assess fit by inspecting several fit indices that derive from different principles. Therefore, for the confirmatory factor model for the family data, we have reported the chi-square test, and the fit indices CFI and RMSEA.

A general problem with these goodness-of-fit indices in multilevel SEM is that they apply to the entire model. Therefore, the goodness-of-fit indices reflect both the degree of fit in the within model and in the between model. Since the sample size for the within part is generally the largest, this part of the model dominates the value of the fit indices, and fit indices do not reflect lack of fit in the between part (Ryu, 2014). It makes sense to assess the fit for both parts of the model separately.

Since the within-groups sample size is usually much larger than the between-groups sample size, we do not lose much information if we model the within-groups matrix separately, and interpret the fit indices produced in this analysis separately.

A simple way to obtain goodness-of-fit indices for the within or the between model separately is to specify a saturated model for one level, and inspect the fit indices for the other level. The saturated model estimates all covariances between all variables. It has no degrees of freedom, and always fits the data perfectly. As a result, the degree of fit indicated by the goodness-of-fit indices, represents the (lack of) fit of the level that is not saturated. This is not the best way to assess the fit of the between model, because the perfect fit of the saturated part also influences the value of the fit index. Fit indices that are mostly sensitive

to the degree of fit will show a spuriously good fit, while fit indices that also reflect the parsimony of the model may show a spurious lack of fit.

A better way to indicate the fit of the within and between model separately is to calculate these by hand. Most fit indices are a simple function of the chi-square, sample size N , and degrees of freedom df . Some consider only the current model, the target model M_t , others also consider a baseline model, usually the independence model M_i . By estimating the independence and the target model for the within matrix, with a saturated model for the between matrix, we can assess how large the contribution to the overall chi-square is for the various within models. In the same way, by estimating the independence and the target model for the between matrix, with a saturated model for the within matrix, we can assess how large the contribution to the overall chi-square is for the various between models. Using this information, we can calculate the most common goodness-of-fit indices. Most SEM software produces the needed information, and the references and formulas are in the user manuals and in the general literature (e.g., Gerbing & Anderson, 1992).

Table 14.6 gives the separate chi-squares, degrees of freedom, and sample sizes for the independence model and the final model for the family intelligence example.

Table 14.6 Chi-squares and degrees of freedom separate for individual and family level models

	Individual level, between model saturated		Family level, within model saturated	
	Independence	2 factors	Independence	1 factor
Chi-square	805.51	6.72	168.88	4.74
Degrees of freedom	30	8	15	9
n	340	340	60	60

The comparative fit index CFI (Bentler, 1990) is given by

$$CFI = 1 - \frac{\chi_t^2 - df_t}{\chi_i^2 - df_i} . \tag{14.10}$$

In Equation 14.10, χ_t^2 is the chi-square of the target model, χ_i^2 is the chi-square for the independence model, and df_t and df_i are the degrees of freedom for the target and the independence model. If the difference of the chi-square and the degrees of freedom is negative, it is replaced by zero. So, for example, the CFI for the family level model is given by

$$CFI = 1 - (4.74 - 9) / (168.88 - 15) = 1 - 0 / 153.88 = 1.00 .$$

The Tucker–Lewis index (TLI) which is also known as the non-normed fit index (NNFI) is given by

$$TLI = \frac{\frac{\chi^2_l}{df_l} - \frac{\chi^2_t}{df_t}}{\frac{\chi^2_l}{df_l} - 1}. \quad (14.11)$$

Finally, the root mean square error of approximation (RMSEA) is given by

$$RMSEA = \sqrt{\left(\frac{\chi^2_l - df_l}{Ndf_l} \right)} \quad (14.12)$$

where N is the total sample size. If RMSEA is negative, it is replaced by zero. Using Equations 14.10 to 14.12 and the values in Table 14.6, we can calculate the CFI, TLI and RMSEA separately for the within and between models. The results are in Table 14.7.

The goodness-of-fit indices in Table 14.7 all indicate excellent fit, for both the within and between models.

Table 14.7 Fit indices for individual and family level models separately

	Individual level, 2 factors	Family level, 1 factor
CFI	1.00	1.00
TLI	1.01	1.05
RMSEA	0.00	0.00

14.7 SOFTWARE

Most modern SEM software includes routines for two-level SEM. Having only two levels may seem an important limitation, but one must appreciate that SEM is an inherently multivariate technique, and multilevel regression is univariate. Consequently, for multivariate analysis or including a measurement model, multilevel regression needs an extra ‘variable’ level, and for longitudinal analysis it needs an ‘occasion’ level. Multilevel SEM does not need this.

Nevertheless, having only two levels can put strong limits on the analysis. At the time, Mplus (Muthén & Muthén, 1998–2015) can deal with three levels, and GLLAMM (Rabe-Hesketh & Skrondal, 2008) can analyze multiple-level SEM.

The two-stage WLS approach is simpler than the general random coefficient model. It is comparable to the multilevel regression model with higher-level variation only for the intercepts. There is no provision for randomly varying slopes (variation for factor loadings

and path coefficients). An interesting approach is allowing different within-groups covariance matrices in different subsamples, by combining two-level and multigroup models.

When maximum likelihood estimation is used, multilevel SEM can include varying slopes. At the time, only Mplus and GLLAMM support this. Muthén and Muthén (2015) have extended the standard path diagram by using a black dot on an arrow in the level-1 model to indicate a random intercept or slope. This slope appears in the level-2 model as a latent variable. This is consistent with the use of latent variables for the level-2 intercepts. This highlights an important link between multilevel regression and multilevel SEM: random coefficients are latent variables, and many multilevel regression models can also be specified in the SEM context (Curran, 2003; Mehta & Neale, 2005).

Figure 14.2 shows an example of a path diagram from the Mplus manual (Muthén & Muthén, 1998–2015). The within model depicts a simple regression of the outcome variable y on the predictor variable x . The black dot on y indicates a random intercept for y , which is referred to as y in the between part of the model. The black dot on the arrow from x to y indicates a random slope, which is referred to as s in the between part of the model. In the between part of the model, there are two predictors which are measured only at the between level: the group-level variable w and the group mean on the variable x which is referred to as xm .

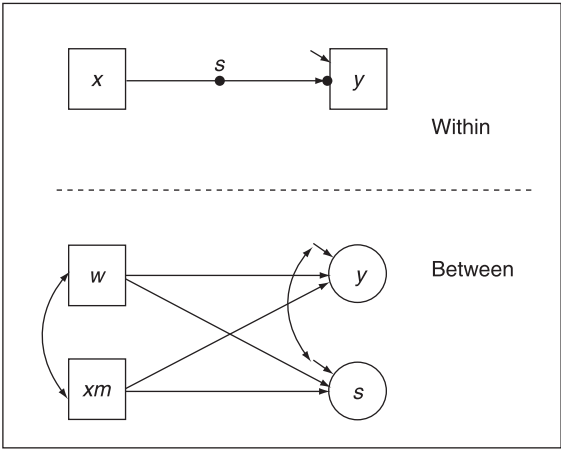


Figure 14.2 Example of path model with random slope and intercept.

NOTE

1 The asymptotic chi-square is available by specifying full WLS estimation. As explained earlier, this leads to a very large weight matrix. With a group level sample size of only 60 this is a recipe for disaster, hence the choice for a robust WLS estimation.

15

Multilevel Path Models

SUMMARY

Path models are structural equation models that consist of complex paths between latent and/or observed variables, possibly including both direct and indirect effects, and reciprocal effects between variables. As mentioned in Chapter 14, often a distinction is made between the structural and the measurement part of a model. The measurement model specifies how the latent factors are measured by the observed variables, and the structural model specifies the structure of the relationships between the theoretical constructs, which may be latent factors or observed variables in the model. A multilevel path model uses the same approaches outlined in Chapter 14 for multilevel factor analysis. Chapter 14 discusses several different estimation methods; in this chapter maximum likelihood is used throughout, but as outlined in Chapter 4, Bayesian estimation is recommended when the number of clusters is relatively small.

With multilevel path models, we often have the complication that there are pure group-level variables (*global* variables in the terminology of Chapter 1). An example would be the global variable *group size*. This variable simply does not exist on the individual level. We can of course disaggregate group size to the individual level. However, this disaggregated variable is constant within each group, and as a result the variance and covariances with the individual deviation scores are all zero. Actually, what we have in this case is a different set of variables at the individual and the group level. Some SEM software (e.g., Mplus) can deal directly with groups or levels that do not have the same variables. Estimation is not a problem with such software. Some SEM software (e.g., LISREL) requires that both groups or levels have the same variables. This problem can be solved by viewing the group-level variable as a variable that is systematically missing in the individual-level data.

15.1 EXAMPLE OF A MULTILEVEL PATH ANALYSIS

The issues in multilevel path analysis will be illustrated with a data set from a study by Schijf and Dronkers (1991). They analyzed data from 1377 pupils (out of a total of 1559 pupils, using listwise deletion of incomplete cases) in 58 schools. We have the following pupil-level variables: father's occupational status, *focc*; father's education, *feduc*; mother's education, *meduc*; pupil sex, *sex*; the result of the GALO school achievement test, *GALO*; and the teacher's advice about secondary education, *advice*. On the school level we have one global variable: the school's denomination, *denom*. Denomination is coded 1 = Protestant,

2 = nondenominational, 3 = Catholic (categories based on optimal scaling). The research question is whether the school’s denomination affects the GALO score and the teacher’s advice, after the other variables have been accounted for.

We can use a sequence of multilevel regression models to answer this question. The advantage of a path model is that we can specify one model that describes all hypothesized relations between independent, intervening, and dependent variables. However, we have multilevel data, with one variable on the school level, so we must use a multilevel model to analyze these data.

Figure 15.1 shows part of the school data. The GALO data illustrate several problems that occur in practice. First, the school variable *denom* does not vary within schools. This means that it has an intraclass correlation of 1.00, and must be included only in the between model. In this specific example, there is another problematic variable, which is *pupil sex*. This variable turns out to have an intraclass correlation of only 0.005, which is very small, which means that there is almost no variation between schools in the gender composition. All schools have about the same proportion of girls and boys, and gender is not relevant at the school level. However, since *pupil sex* turned out to have no significant covariances with any of the other variables at the pupil level, in the end it is completely removed from the analyses.

As a result of this empirical finding, the variable *pupil sex* can only be used at the pupil level, and must be omitted from the school level. The other variables have intraclass

	school	sex	galo	advice	feduc	meduc	focc	denom
1	1	2	78	1	1	1	2	2
2	1	1	104	4	4	3	4	2
3	1	2	93	2	1	1	2	2
4	1	1	114	4	2	1	5	2
5	1	1	95	2	2	2	5	2
6	1	1	98	2	1	1	2	2
7	1	1	114	4	1	3	1	2
8	1	1	79	2	1	1	999	2
9	1	2	84	2	1	1	2	2
10	1	2	101	2	1	1	2	2
11	1	2	99	2	3	4	2	2
12	1	2	102	2	5	5	4	2
13	1	2	86	2	1	1	4	2
14	2	1	110	2	4	3	2	3
15	2	2	111	4	5	3	6	3
16	2	1	100	2	4	5	3	3
17	2	1	79	0	4	2	2	3
18	2	2	111	4	2	1	3	3

Figure 15.1 Part of data file for school example where ‘999’ indicates missing values.

correlations that range from 0.14 for *advice* to 0.29 for *father occupation*. The analyses in this chapter have been carried out using Mplus (version 7.4), which has the option of declaring variables as existing only at the *within* or the *between* level.

A second problem is the occurrence of missing data, coded in the data file as '999'. Schijf and Dronkers (1991) analyze only the complete data ($N = 1377$) using a series of multilevel regression models, and Hox (2002) analyzes also the complete data using MUML path analysis. Listwise deletion of incomplete cases assumes that the incomplete data are missing completely at random (MCAR). In the GALO data, the largest proportion of incomplete data is in the variable *father occupation*, which is missing in almost 8 percent of the cases. A missing score on the variable *father occupation* may be the result of the father being unemployed, which is likely to be correlated with education, and also likely to affect the teacher's advice about secondary education. In fact, missingness on the *focc* variable is related to both *feduc* and *advice*, with a missing code for father occupation related to a lower father education and a lower advice. Evidently, an analysis method that assumes missing completely at random is likely to result in biased estimates. Full information maximum likelihood analysis (FIML) of incomplete data assumes missing at random (MAR), a much weaker assumption. The distinction between MCAR and MAR is discussed in more detail in Chapter 5 in the context of longitudinal data. Thus, all analyses in the current chapter are carried out using FIML, and using robust estimation (MLR). In this analysis all 1559 pupils are included, who are in 58 schools.

15.1.1 Preliminaries: Separate Analysis for Each Level

The pooled within-groups covariance matrix S_{pw} is an unbiased estimate of Σ_w , and we can use it for a preliminary analysis of only the pupil level. The problematic variable *pupil sex* is removed completely from the model, since it has no significant relations with any of the other variables. Since there are incomplete data, the sample size for S_{pw} is undefined. As an approximation, we specify a sample size based on the complete cases: $N = (\text{number of pupils} - \text{number of schools}) = 1377 - 58 = 1319$. Since robust estimation requires raw data, the preliminary analyses on S_{pw} use ML.

Figure 15.2 below depicts the pupil-level model, which contains one latent variable 'SES' measured by the observed variables *focc*, *fedu* and *medu*.

The analysis of the pupil-level model on S_{pw} only gives a chi-square of 15.3, with $df = 4$ and $p < 0.01$. The goodness-of-fit indices are reasonable: CFI = 1.00, TLI = 0.99, RMSEA = 0.05. Modification indices suggest adding a covariance between the residuals of father occupation and father education. Typically in most situations we advise against adding residual covariances to a measurement model, but in some situations it is defensible, for example in our model where both father occupation and father education are obtained from the same source. If this residual covariance is added, we obtain a chi-square of 3.5, with $df = 3$ and $p = 0.32$. The goodness-of-fit indices are excellent: CFI = 1.00, TLI = 1.00, RMSEA = 0.01. This model is accepted.

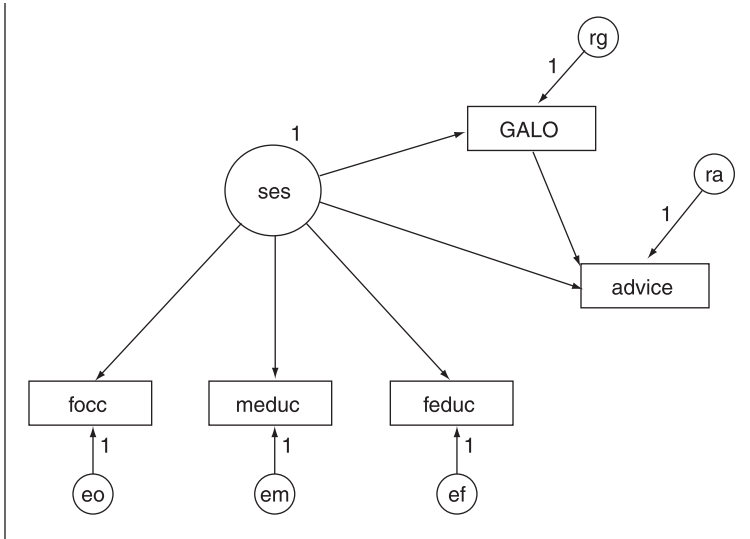


Figure 15.2 Initial pupil-level path diagram.

The next step is specifying a school-level model. When maximum likelihood estimation is used, we can estimate a saturated model for both the within and the between level, which will provide the maximum likelihood estimate for Σ_B .¹ We start the analysis of the estimated between-groups matrix $\hat{\Sigma}_B$ by specifying the initial pupil-level model as depicted in Figure 15.2, specifying the sample size as 58. The school-level variable denomination is used as a predictor variable for both GALO and advice. This model is rejected: chi-square is 63.3, with $df=6$ and $p<0.01$. The goodness-of-fit indices also indicate bad fit: CFI = 0.92, TLI = 0.79, RMSEA = 0.41. In addition, the estimate of the residual variance of father education is negative, and the effect of denomination on advice is not significant ($p=0.64$). Further pruning of the model leads to the model depicted in Figure 15.3. This model still does not fit well: chi-square is 65.6, with $df=8$ and $p<0.01$. The goodness-of-fit indices also indicate bad fit: CFI = 0.92, TLI = 0.84, RMSEA = 0.35. There are no large modification indices, so there are no obvious ways to improve this school-level model.

Observation of the school-level correlation matrix shows that at the school level father education and mother education have a high correlation, while the correlations with father occupation are much lower. Also, the covariances of father occupation and father education with other variables appear different. This indicates that assuming a latent variable SES at the school level may be wrong. An entirely different way to model the effect of these variables on GALO and advice is to use a regression model. The initial path diagram for such a model is in Figure 15.4.

The model depicted in Figure 15.4 is a saturated model, and therefore cannot fail to fit. It turns out that the effects of denomination and father occupation on advice are not significant, so the final model becomes the model as shown in Figure 15.5.

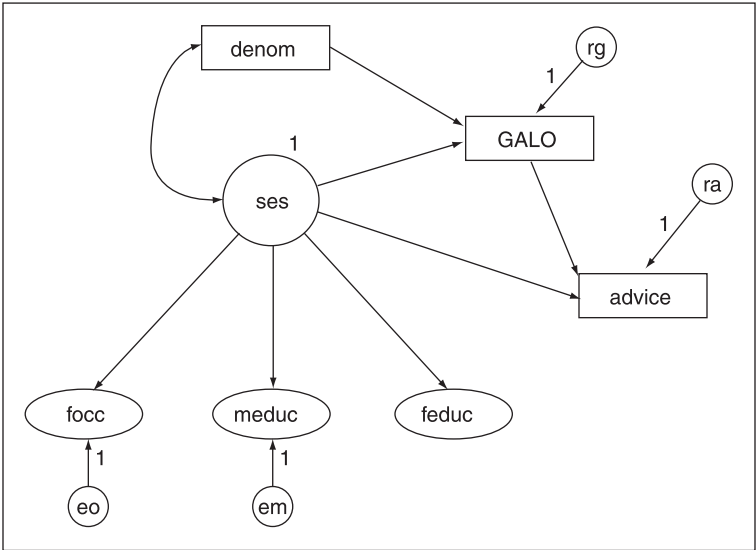


Figure 15.3 Final school-level path diagram, SES as latent variable.

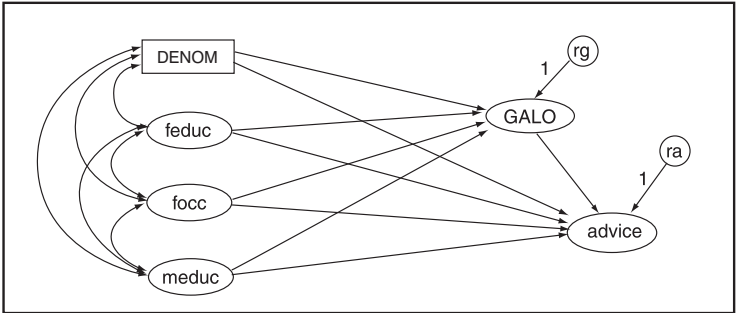


Figure 15.4 Initial school-level path diagram, regression model.

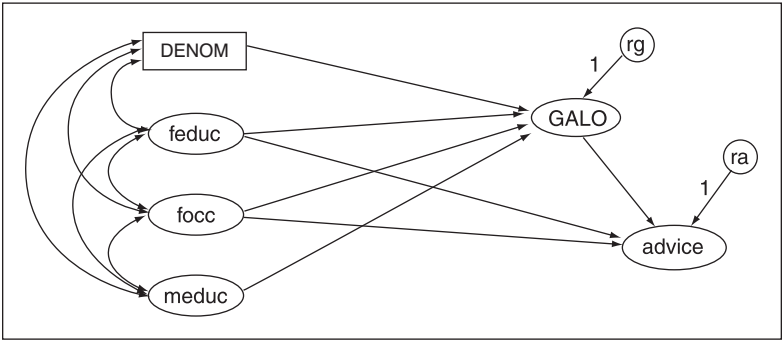


Figure 15.5 Final school-level path diagram, regression model.

The final school-level regression model fits well: chi-square is 2.1, with $df = 2$ and $p = 0.34$. The goodness-of-fit indices also indicate good fit: CFI/TLI = 1.00, RMSEA = 0.04. The SES model in Figure 15.3 and the regression model in Figure 15.5 are not nested, but they can be compared using the information criteria AIC and BIC which only requires the same variance-covariance matrix and same sample size. For the SES model AIC = 148.03 and BIC = 172.76, and for the regression model AIC = 78.56 and BIC = 97.11. Both the AIC and the BIC indicate a preference for the regression model.

15.1.2 Putting It Together: Two-Level Analysis

The preliminary analyses give a good indication of what to expect when the models are combined in a two-level model, with simultaneous estimation on both levels. There will be differences. First, because the two-level analysis is simultaneous, misspecifications on one level will also affect the other level. This has a positive side as well. The estimated between-groups covariance matrix used earlier is estimated using a saturated model for the within-groups part. If we have a well-fitting parsimonious within model, the between model is more stable. Second, the preliminary analyses are based on maximum likelihood estimates of the corresponding population covariances, but in the presence of incomplete data the sample size is an approximation.

When the individual-level model is combined with a school-level model in a simultaneous analysis, it turns out that the model with latent variable SES at the school level fits better than the regression model. Table 15.1 presents the chi-squares and fit indices for several different school-level models, all fitted with the within schools model established earlier, and the fit indices CFI, TLI and RMSEA calculated by hand specifically for the school level.

Table 15.1 Fit indices for several school-level models

Model	χ^2	df	p	CFI	TLI	RMSEA	AIC*	BIC*
Independent	577.7	18	.00	—	—	—	5560	5684
SES	11.0	11	.45	1.00	1.00	.00	5124	5279
Regression	22.9	8	.00	.97	.94	.03	5140	5311

* AIC and BIC – 25,000 for legibility

Thus, the final two-level model is for the pupil level as depicted in Figure 15.6, and the school-level model is as depicted earlier in Figure 15.3. The combined model fits well, chi-square = 14.9, $df = 11$, $p = 0.45$, CFI/TLI = 1.00, RMSEA = 0.00.

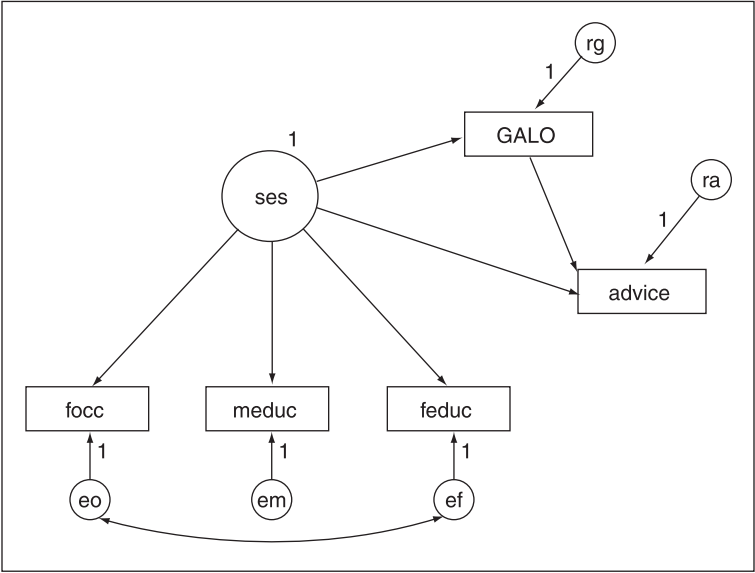


Figure 15.6 Final pupil-level model.

Since we have a latent variable SES at both the individual and the school level, the question is relevant if we can constrain the loadings of father occupation, mother education and father education to be identical across the two levels. If these constraints hold, and all residual measurement variances at the school level are zero, we have measurement invariance across the pupil and school level (Jak, Oort & Dolan, 2013). A model with equality constraints for these loadings across the two levels fits quite well, chi-square = 20.6, $df = 13$, $p = 0.07$, CFI/TLI = 1.00, RMSEA = 0.02. Constraining all residual measurement errors to zero increases the chi-square to 22.1, $df = 16$, $p < 0.01$. Allowing one non-zero variance for *foccup* results in partial measurement invariance and a well-fitting model: chi-square = 22.8, $df = 15$, $p = 0.09$, CFI/TLI = 1.00, RMSEA = 0.02. In this model, the variance of SES is fixed at 1.00 on the individual level, and freely estimated as 0.62 on the school level. The intraclass correlation for the latent variable SES is 0.38, which is considerably higher than the ICC's for the observed variables father occupation, mother education, and father education. This is typical, since measurement error in the observed variables ends up at the lowest level (Muthén, 1991b).

Table 15.2 presents the path coefficients and corresponding standard errors. There are strong school-level effects on the GALO score and on the advice. The school-level variable *denomination* turns out to have an effect only on the school-level GALO test score.

In the multilevel regression analyses presented by Schijf and Dronkers (1991), denomination has a significant effect on both the teachers' advice and on the GALO tests score. The path model presented here shows that the main influence of denomination is mediated by the GALO test score; the different advices given by teachers in schools of different denominations are

Table 15.2 Path coefficients for final GALO model

Effect on	GALO pupil	Advice pupil	GALO school	Advice school
Effect from:				
SES	0.43 (.04)	0.12 (.02)	0.52 (.09)	0.31 (.06)
GALO	–	0.85 (.03)	–	0.54 (.11)
Denomination	–	–	0.24 (.08)	not significant

apparently the result of differences in GALO test scores between such schools. This indirect effect is precisely the kind of result that a sequence of separate regression analyses cannot show. The indirect effect of denomination through GALO on the advice is estimated as 0.13 (the multiplication of the path coefficient from denomination to GALO and the path coefficient from GALO to ADVICE), with a standard error of 0.052 ($p < 0.01$).

Figure 15.4 also shows that SES has a school-level effect on the variables GALO and advice. Since the within-groups scores are group mean deviations, at the pupil level the effect of SES on advice reflects only individual variation. The substantive interpretation of the school level results must be interpreted as a combination of two effects. One potential explanation is different composition with respect to SES, explained by assuming that the schools attract or select pupils on the basis of their SES. The second explanation is the contextual effect of being a pupil in a school with a high average SES level, which assumes that the concentration of high or low SES pupils in a school has its own effect on the school career variables. It is interesting to note that, on the school level, the effect of the school average on the GALO test on the average advice is negative. This can be interpreted as a typical context effect, in which the GALO score is apparently interpreted differently by teachers if the overall score of a school on the test is high.

On individual level the effect of SES on the advice is also mediated by the GALO score, and on the school level the effect of SES is partially mediated by GALO.

15.2 STATISTICAL AND SOFTWARE ISSUES

It should be noted that multilevel factor and path models differ from multilevel regression models, because often they do not have random regression slopes. The variation and covariation on the group level is intercept variation. If there are no random slopes, there are also no cross-level interaction effects. In multilevel factor models, the group-level variation can properly be interpreted as group-level variance of the group means of the latent factors. In path analysis, the interpretation of group-level path coefficients is in terms of composition and contextual effects, which are added to the individual effects. Random slopes and cross-level interaction terms in multilevel structural equation models are possible, but may lead to estimation problems.

A full maximum likelihood solution to the problem of multilevel factor and path analysis requires maximization of a complicated likelihood function. LISREL (version 8.5 and later; du Toit & du Toit, 2001) includes a full maximum likelihood estimation procedure for multilevel confirmatory factor and path models, including an option to analyze incomplete data. The LISREL 8.5 user's manual (du Toit & du Toit, 2001) cautions that this procedure still has some problems; it frequently encounters convergence problems, and needs good starting values. Mplus (Muthén & Muthén, 1998–2015) offers weighted least squares and full maximum likelihood estimation for two- and three-level models. Mplus allows fitting multilevel structural equation models with random coefficients, regressions among latent variables varying at two different levels, and mixtures of continuous and ordered or dichotomous data. Rabe-Hesketh and Skrondal (2008) present the software GLLAMM (for Generalized Linear Latent And Mixed Models) that runs in the statistical package STATA. The program and manual are available for free (Rabe-Hesketh et al., 2004), but the commercial package STATA is needed to run it. Like Mplus, GLLAMM can fit very general multilevel structural equation models, with no formal limit to the number of levels.

More complex multilevel path models with latent variables, for instance including random slopes and cross-level effects, can be estimated using Bayesian methods. Mplus allows Bayesian estimation for multilevel models with random slopes, see for an example Johnson, van de Schoot, Delmar and Crano (2015). Multilevel structural equation models can also be estimated using Bayesian methods in general Bayesian software like OPENBUGS (Lunn et al., 2009), but this requires an intimate knowledge of both structural equation modeling and Bayesian estimation methods. We refer to MacKinnon (2012) for an introduction to multilevel mediation analysis.

Multilevel structural equation modeling is a rapidly developing field, both in statistical science and in software development. Given its general availability in modern SEM software, maximum likelihood or Bayesian estimation are the preferred methods. For non-normal data, weighted least squares is attractive because it is computationally faster, but this is available only in Mplus, and does not include random slopes.

The analysis issues in multilevel path models are comparable to the issues in multilevel factor analysis. Thus, the recommendations given in Chapter 14 about inspecting goodness-of-fit indices separately for the distinct levels that exist in the data, and about the standardization, also apply to multilevel path models.

All approaches to multilevel factor and path analysis model only one single within-groups covariance matrix. In doing so, they assume that the within-groups covariances are homogeneous, i.e., that all groups have the same within-groups covariance matrix. This is not necessarily the case. The effect of violating this assumption is currently unknown. Simulation studies on the assumption of homogeneous covariance matrices in MANOVA show that MANOVA is robust against moderate differences in the covariances, provided the group sizes are not too different (Stevens, 2009). Strongly different group sizes pose a problem in MANOVA. When larger variability exists in the smaller group sizes, the

between-group variation is overestimated; when larger variability exists in the larger group sizes, the between-group variation is underestimated.

If we assume that the covariance matrices differ in different groups, one possible solution is to divide the groups in two or more separate subsets, with each subset having its own within-groups model. For instance, we may assume that within-group covariances differ for male and female respondents. Or, in the situation where we have larger variances in small groups and vice versa, we may divide the data into a set of small and a set of large groups. Then we use two-group modeling and specify a different within-groups model for each set of groups, and a common between-groups model. Mplus and GLLAMM allow multilevel mixture modeling, where the subsets or latent classes are unobserved. This approach provides a different way to allow different covariance matrices at the individual or the group level.

NOTE

- 1 With Mplus, estimates for Σ_w and Σ_b are produced as part of the sample statistics output.

16

Latent Curve Models

SUMMARY

An interesting model for fixed-occasion panel data is the latent curve model (LCM). This model has been applied mainly to developmental or growth data, hence the often-used name latent growth model (LGM). In the latent curve model, the time or measurement occasion variable is defined in the measurement model of the latent factors. For instance, in a linear growth model, consecutive measurements are modeled by a latent variable for the intercept of the growth curve, and a second latent variable for the slope of the curve. The latent curve model is a single-level SEM, but it is very similar to the multilevel approach to longitudinal data described in Chapter 5. This chapter describes the latent curve model, and points out the similarities to and differences from the longitudinal multilevel model.

16.1 INTRODUCTION

Figure 16.1 shows the path diagram of a simple latent curve model for panel data with five occasions, and one time-independent explanatory variable Z . In Figure 16.1, Y_0 , Y_1 , Y_2 , Y_3 and Y_4 are the observations of the response variable at the five consecutive time points. In the latent curve model, the expected score at time point zero is modeled by a latent *intercept* factor. The intercept is constant over time, which is modeled by constraining the loadings of all time points on the intercept factor equal to one. The latent slope factor is the slope of a linear curve, modeled by constraining the loadings of the five time points on this factor to be equal to 0, 1, 2, 3, and 4 respectively. Following the usual custom in the graphical model presentation in SEM, the one path that is constrained to zero is not drawn. Obviously, a quadratic trend would be specified by a third latent variable, with successive loadings constrained to be equal to 0, 1, 4, 9, and 16. What is not immediately obvious from the path diagram in Figure 16.1 is that the latent curve model *must* include the intercepts of the observed variables and the means of the factors in the model. Therefore, the regression equations that predict the observed variables from the latent factors, depicted by the single-headed arrows towards the observed variables in Figure 16.1, also contain terms for the intercept.

In the latent curve model, the intercepts of the response variable at the five time points are all constrained to zero, and as a result, the mean of the intercept factor is an estimate of the common intercept. In Figure 16.1, this is visible in the zeros placed close to the observed variables and error terms; these indicate means and intercepts that are constrained to zero.

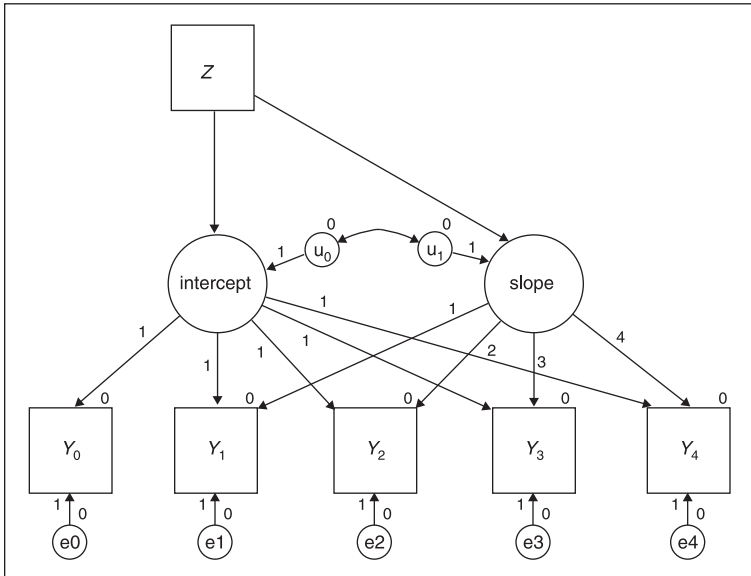


Figure 16.1 Latent curve model for five occasions.

The successive loadings for the slope factor define the slope as the linear trend over time (the first path from the slope factor to variable Y_0 , which is equal to zero, is omitted from the diagram). The mean of the slope factor is an estimate of the common slope (c.f. Meredith & Tisak, 1990; Muthén, 1991a; Duncan et al., 2006). Individual deviations from the common intercept are modeled by the variance of the intercept factor, and individual deviations in the slope of the curve are modeled by the variance of the slope factor. Both the intercept and slope factor can be modeled by a path model including explanatory variables, in our example the one explanatory variable Z .

The latent curve model is a random coefficient model for change over time, completely equivalent to the multilevel regression model for longitudinal data that is described in Chapter 5. To clarify the relationship between the two models, we write the equations for both specifications. In the multilevel linear growth model, the model described by Figure 16.1 can be expressed as a multilevel regression model with, at the lowest level, the occasion level:

$$Y_{ti} = \pi_{0i} + \pi_{1i} T_{ti} + e_{ti}, \quad (16.1)$$

where T_{ti} is an indicator variable for the occasions, which is set to 0, 1, 2, 3, 4 to indicate the five occasions, with subscript t indicating occasions and subscript i the individuals. At the second level, the individual level, we have

$$\pi_{0i} = \beta_{00} + \beta_{01} Z_i + u_{0i} \quad (16.2)$$

$$\pi_{1i} = \beta_{10} + \beta_{11}Z_i + u_{1i} \quad (16.3)$$

By substitution, we get the single equation model:

$$Y_{it} = \beta_{00} + \beta_{10}T_{it} + \beta_{01}Z_i + \beta_{11}Z_iT_{it} + u_{1i}T_{it} + u_{0i} + e_{it} \quad (16.4)$$

In a typical SEM notation, we can express the path model in Figure 16.1 as:

$$Y_{it} = \lambda_{0i} \text{intercept}_i + \lambda_{1i} \text{slope}_i + e_{it} \quad (16.5)$$

where λ_{0i} are the factor loadings for the intercept factor, and λ_{1i} are the factor loadings for the slope factor.

Note the similarity between the Equations 16.5 and 16.1. In both cases, we model an outcome variable that varies across times t and individuals i . In Equation 16.1, we have the intercept term π_{0i} , which varies across individuals. In Equation 16.5, we have a latent intercept factor, which varies across individuals, and is multiplied by the factor loadings λ_{0i} to predict the Y_{it} . Since the factor loadings λ_{0i} are all set equal to one, they can be left out of Equation 16.5, and we see that the intercept factor in equation 16.5 is indeed equivalent to the regression coefficient π_{0i} in equation 16.1. Next, in equation 16.1, we have the slope term π_{1i} , which varies across individuals, and is multiplied by the 0, ..., 4 values for the occasion indicator T_{it} . In Equation 16.5, we have a latent slope factor, which varies across individuals, and gets multiplied by the factor loadings λ_{1i} to predict the Y_{it} . Since the factor loadings λ_{1i} are set to 0, ..., 4, we see that the slope factor in Equation 16.5 is indeed equivalent to the regression coefficient π_{1i} in Equation 16.1. Therefore, the fixed factor loadings for the slope factor play the role of the time variable T_{it} in the multilevel regression model and the slope factor plays the role of the slope coefficient π_{1i} in the multilevel regression model. The random regression coefficients in the multilevel regression model are equivalent to the latent variables in the latent curve model.

In a manner completely analogous to the second-level Equations 16.2 and 16.3 in the multilevel regression model, we can predict the intercept and the slope factor using the time-independent variable Z . For these equations, using for consistency the same symbols for the regression coefficients, we have

$$\text{intercept}_i = \beta_{00} + \beta_{01}Z_i + u_{0i} \quad (16.6)$$

$$\text{slope}_i = \beta_{10} + \beta_{11}Z_i + u_{1i} \quad (16.7)$$

which lead to a combined equation

$$Y_{it} = \beta_{00} + \beta_{10}\lambda_{1i} + \beta_{01}Z_i + \beta_{11}Z_i\lambda_{1i} + u_{1i}\lambda_{1i} + u_{0i} + e_{it} \quad (16.8)$$

Keeping in mind that the factor loadings $0, \dots, 4$ in λ_{it} play the role of the occasion indicator variable in T_p , we see that the multilevel regression model and the latent curve model are indeed equivalent. The only difference so far is that multilevel regression analysis generally assumes one common variance for the lowest-level errors e_{it} , while structural equation analysis typically estimates different residual error variances for each time point. However, this is easily solved by imposing a constraint on the latent curve model that the variances for e_0, \dots, e_4 are all equal. If we impose this constraint, we have exactly the same model. Similarly, we can replace the single lowest-level error term in a multilevel regression by five error terms connected with five dummy variables, one for each time point (see for details the multivariate multilevel model presented in Chapter 10). Full maximum likelihood estimation, using either approach, should give essentially the same results. For a more detailed evaluation of the similarities and differences of the multilevel and the latent curve approach to repeated measures see Chou, Bentler and Pentz (1998).

16.2 EXAMPLE OF LATENT CURVE MODELING

The longitudinal grade point average (GPA) data from Chapter 5 are used again, with a standard latent curve model as in Figure 16.1 applied to the data. The example data are a longitudinal data set, with longitudinal data from 200 college students. The students' GPA has been recorded for six successive semesters. At the same time, it was recorded whether the student held a job in that semester, and for how many hours. This is recorded in a variable *job* (with categories 0 = no job, 1 = 1 hour, 2 = 2 hours, 3 = 3 hours, 4 = 4 or more hours), which for the purpose of this example is treated as an interval-level variable. In this example, we also use the student variables high school GPA and sex (0 = male, 1 = female).

In a statistical package such as SPSS or SAS, such data are typically stored with the students defining the cases, and the repeated measurements as a series of variables, such as GPA1, GPA2, ..., GPA6, and JOB1, JOB2, ..., JOB6. As explained in Chapter 5, multilevel regression software requires a different data structure. However, latent curve analysis views the successive time point as multivariate outcome variables, and thus we can use the data file as it is. We start with a model that includes only the linear trend over time. Figure 16.2 shows the path diagram for this model.

The model in Figure 16.2 is equivalent to a multilevel regression model with a linear predictor coded $0, \dots, 5$ for the successive occasions, and a random intercept and slope on the student level. To make the models completely equivalent, the error variances of the residual errors e_1, \dots, e_6 for the successive occasions are all constrained to be equal to e . In the graphical model in Figure 16.2 this is symbolized by the label e next to each residual error variable. The means of the intercept and slope factor are freely estimated; all other means and intercepts in the model are constrained to zero, which is symbolized by placing a zero next to the constrained variable. The mean of the intercept is freely estimated as 2.60, and the mean

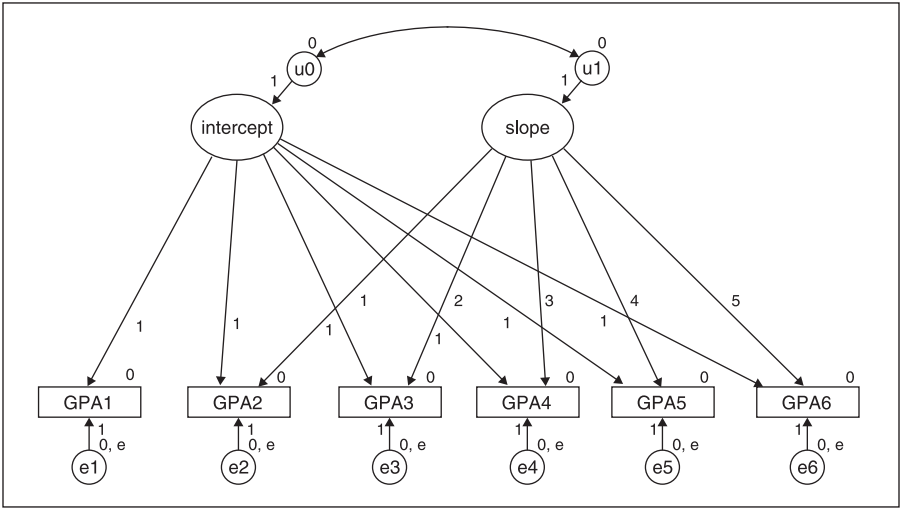


Figure 16.2 Path diagram for linear model GPA example data.

of the slope is estimated as 0.11. This is identical to the estimates of the intercept and slope in the (fixed effects) multilevel regression model in Table 5.3 in Chapter 5.

For simplicity, we omit the time varying *job* variable for the moment, and start with specifying a latent curve model using only the six *GPA* scores, and the time-independent (student level) variables *high school GPA* and *student sex*. The path diagram, which includes the unstandardized parameter estimates obtained by standard SEM estimation, is shown in Figure 16.3.

In the path diagram we see that in this model, which includes an interaction between the slope of the linear development over time and the student's sex, the average slope over time is 0.06. The slope variance in the figure is given in two decimals as 0.00, in the text output it is given as 0.004, with standard error 0.001. This is identical to the estimates in the equivalent multilevel regression model presented in Table 5.4 in Chapter 5.

The SEM analysis of the latent curve model gives us some information that is not available in the multilevel regression analyses. The fit indices produced by the SEM software tell us that the models depicted in Figures 16.2 and 16.3 do not describe the data well. The model in Figure 16.2 has a chi-square of 190.8 ($df = 21, p < 0.001$) and an RMSEA fit index of 0.20, and the model in Figure 16.3 has a chi-square of 195.3 ($df = 30, p < 0.001$) and an RMSEA fit index of 0.17. The SEM analysis also provides us with diagnostic information about the locus of the fit problem. The program output contains so-called *modification indices* that signify constraints that decrease the fit of the model. All large modification indices indicate that the constraint of equal error variances for the residual errors e_1, \dots, e_6 does not fit well, and that the implicit constraint of no correlations between the residual errors e_1, \dots, e_6 does not fit well either. Presumably, the multilevel regression models presented in Chapter 5 also have these problems. Since in Chapter 5 we did not carry out a residuals analysis or

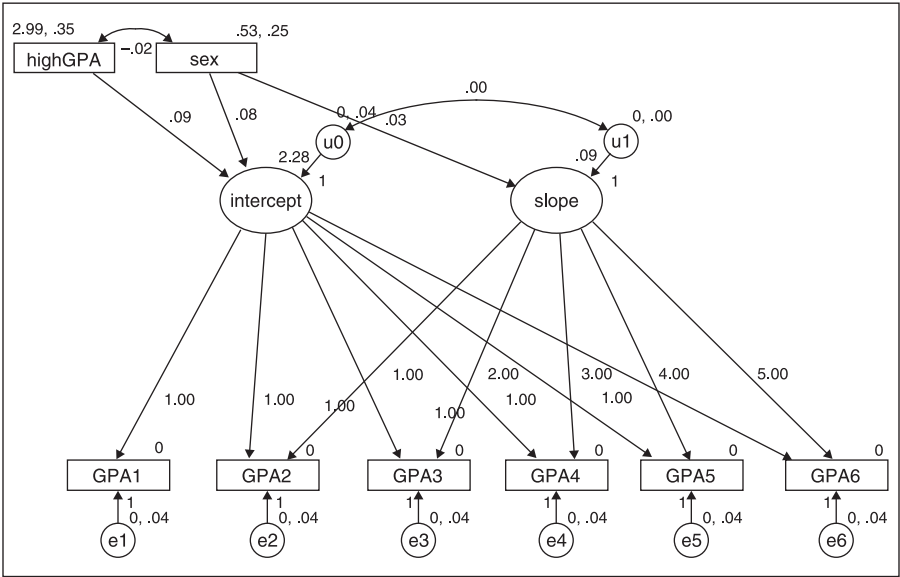


Figure 16.3 Path diagram and parameter estimates for a linear curve model with two predictors.

some other procedure to check for model misspecifications, we do not have any information about model fit. In SEM, we do have such information; it is automatically provided by the software. If we remove the equality constraint on the residual errors, the model fit becomes much better, as indicated by a chi-square of 47.8 ($df = 25, p = 0.01$) and an RMSEA fit index of 0.07. Allowing correlated errors between the two first measurement occasions improves the fit to a chi-square of 42.7 ($df = 24, p = 0.01$) and an RMSEA of 0.06. Since the other estimates do not change much because of these modifications, the last model is accepted.

To bring the time-varying variable *job status* into the model, we have several choices. Equivalent to the multilevel regression models for these data, which are treated in Chapter 5, we can add the variables job_1, \dots, job_6 as explanatory variables to the model. These predict the outcomes GPA_1, \dots, GPA_6 , and since the multilevel regression model estimates only one single regression for the effect of *job status* on *GPA*, we must add equality constraints for these regression coefficients to have an equivalent model.

The path diagram for this model is given in Figure 16.4. Note the zeros that indicate means and intercepts are constrained to zero. The variances of these variables are not constrained, which is visible in the diagram because there are no constraints visible next to the zeros. The common regression coefficient for *job status* on the *GPA* is estimated as -0.12 (s.e. 0.01), which is close to the multilevel regression estimates in Table 5.4. However, the model including all the job status variables does not fit well, with a chi-square of 202.1 ($df = 71, p < 0.001$) and an RMSEA of 0.10. There are no large modification indices, which indicates

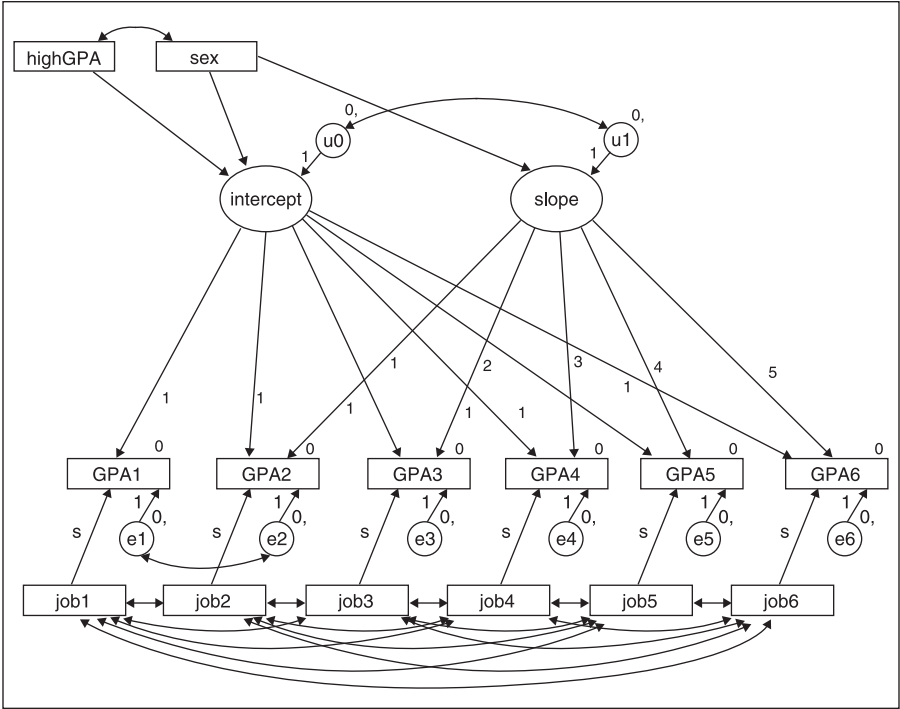


Figure 16.4 Path diagram for GPA example, including effects for job status.

that there exists no single model modification, which substantially improves the model. We probably need many small modifications to make the model fit better.

An advantage of latent curve analysis over multilevel regression analysis of repeated measures is that it can be used to analyze structures that are more complex. For instance, we may attempt to model the changes in hours spend on a job using a second latent curve model. The path diagram for the latent curve model for *job status* at the six time points is presented in Figure 16.5.

Figure 16.5 has some features that merit discussion. To ensure that the variances of the job slope factor is positive, the variance is modeled by an error term r with the variance set at 1, and the path to job slope is estimated. In this specific case, the more usual procedure of setting the path at 1 and estimating the error variances resulted in negative variance estimates. The model specification in Figure 16.6 leads to a latent curve model that fits quite well, with a chi-square of 17.8 ($df = 17, p = 0.40$) and an RMSEA of 0.02. All estimates in this model are acceptable. A powerful feature of structural equation modeling, compared to standard multilevel regression models, is that both models can be combined into one large model for change of both job status and GPA over time. Figure 16.6 shows one such model.

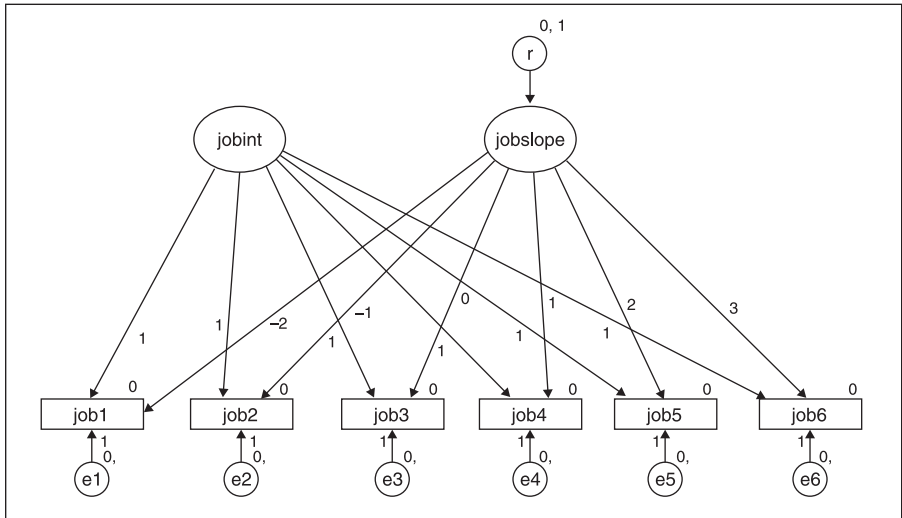


Figure 16.5 Latent curve model for job status.

The model depicted by the path diagram in Figure 16.6 has a moderate fit. The chi-square is 166.0 ($df=85, p<.001$) and the RMSEA is 0.07. The AIC for the model in Figure 16.5, which is equivalent to a multilevel regression model, is 298.3. In comparison, the AIC for the model in Figure 16.7, which is *not* equivalent to a multilevel regression model, is 243.1. Although the complex latent curve model does not show an extremely good fit, it fits better than the related multilevel regression model.

Figure 16.6 also illustrates that with complicated models with constraints on intercepts and variances, a path diagram quickly becomes cluttered and difficult to read. At some point, presenting the model by describing a sequence of equations becomes simpler. Table 16.1 presents the estimates for the regression weights for the predictor variables *sex* and *high school GPA*, and the intercepts and slopes.

Figure 16.7 presents the same information, but now as standardized path coefficients with only the structural part of the path diagram shown.

Figure 16.7 shows results similar to the results obtained with the multilevel regression analyses in Chapter 5. Females have a higher GPA to begin with, and their GPA increases over the years at a faster rate than the male students do. The relations between the intercepts and slopes in Figure 16.7 show the mutual effects of changes over time in both job status and GPA. Initial job status has virtually no effect. Changes in job status, as reflected in the slope for job status, have a negative effect on the GPA. If the job status changes in the direction of spending more time on the job, the overall increase in GPA ends, and in fact can become negative. There is also an effect of initial GPA on job status: students with a high initial GPA increase their job workload less than other students do.

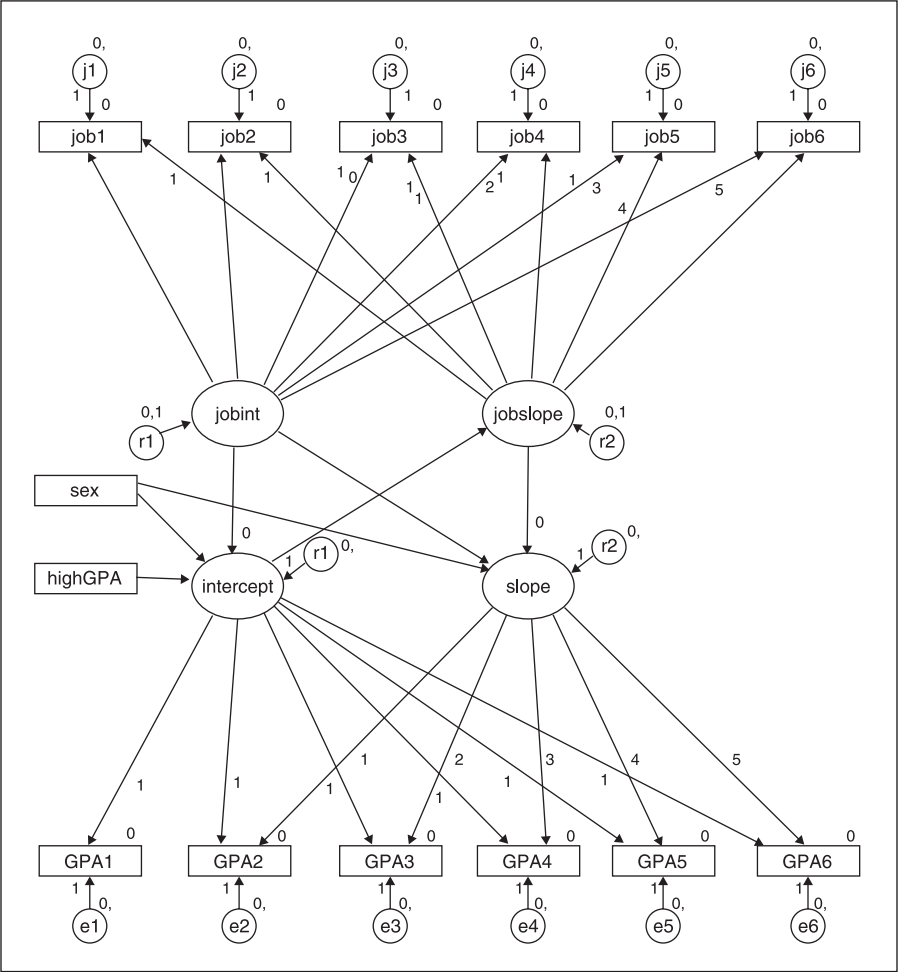


Figure 16.6 Path diagram for change in job status and GPA over time.

Table 16.1 Path coefficients for structural model in Figure 16.7

Predictor	Job slope (s.e.)	GPA interc. (s.e.)	GPA slope (s.e.)
Sex		0.07 (.03)	0.02 (.01)
High school GPA		0.07 (.02)	
Job intercept		1.06 (.04)	0.03 (.01)
Job slope			−0.46 (.11)
GPA intercept	−0.29 (.06)		

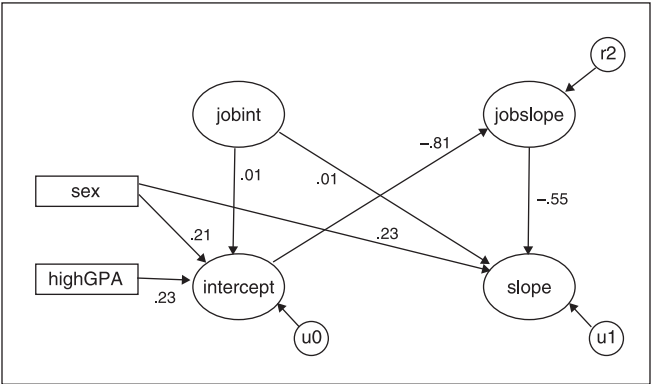


Figure 16.7 Standardized path coefficients for structural model in Figure 16.6

16.3 A COMPARISON OF MULTILEVEL REGRESSION ANALYSIS AND LATENT CURVE MODELING

When equivalent multilevel regression analysis and latent curve modeling are applied to the same data set, the results are identical (Chou, Bentler & Pentz, 1998). Plewis (2001) compares three different approaches to longitudinal data, including multilevel regression and latent curve models. Using empirical examples, he concludes that multilevel and latent curve models are very useful in testing interesting hypotheses about longitudinal data, for which they share many strengths and limitations.

A clear advantage of multilevel regression analysis is that adding more levels is straightforward. Modeling development over time of pupils nested within classes, nested in schools, is a simple procedure when multilevel regression is used, provided the analysis software can deal with more than three levels. When latent curve models and SEM software are used, adding a group level is simple (cf. Muthén, 1997). Adding more than three levels is virtually impossible. Multilevel regression also allows varying relationships at different levels, and modeling this variation by cross-level interactions with explanatory variables at the higher levels. In the SEM context, only the software Mplus (Muthén & Muthén, 1998–2015) and GLLAMM (Rabe-Hesketh et al., 2004) can deal with random slopes.

As remarked earlier in Chapter 5, multilevel regression copes automatically with missing data due to panel dropout. Since there is no requirement that each person has the same number of measurements, or that the measures are taken at the same occasions, multilevel regression works very well on incomplete data. The latent curve model is a fixed-occasions model. If different respondents are measured at different occasions, the latent curve model can deal with this only by specifying paths for all possible measurement occasions that occur in the data set, and regarding individuals observed at different measurement occasions as instances of incomplete data. When there are many and varying time points, the setup

becomes complicated, and the estimation procedure may have convergence problems. Later developments in latent variable modeling do allow varying occasions (Bollen & Curran, 2006), but including varying *time scores* is not an option in most SEM software.

Latent curve models estimated with SEM software, on the other hand, have the advantage that it is straightforward to embed them in more complex path models. For instance, in latent growth methodology it is simple to specify a path model where the slope factor is itself a predictor of some later outcome. This represents the hypothesis that the rate of growth is a predictor of some outcome variable. An example of such a path model was given in the previous section, where the rate of change in the latent slope for job status is a predictor for the rate of change indicated by the GPA slope factor. This model combines two latent curve models in one larger model, to investigate whether the rate of change in one process depends on the rate of change in a second process. This kind of hypothesis is difficult to model in standard multilevel software. Hoeksma and Knol (2001) present an example of a growth model where the slope factor is a predictor of an outcome variable. Their discussion makes clear that these models can in fact be specified in the multilevel regression framework, but also that this is difficult and leads to complicated software setups. Using the latent curve approach, this model is a straightforward extension of the basic latent curve model.

In the SEM latent growth curve approach, it is also simple to allow for different errors or correlated errors over time, which is possible in multilevel regression analysis, but more difficult to set up in the current software. A second interesting extension of the latent curve model is adding a measurement model for the variable that is measured over time or for the explanatory variables. To add a measurement model to the variable that is measured over time, it is indicated by a set of observed variables, and the variable that is modeled using the latent curve defined by the intercept and slope factors is then itself a latent variable. A final advantage of the latent curve model is that standard SEM software provides information on goodness-of-fit, and suggests model changes that improve the fit.

Finally, it should be noted that in latent curve models, the variances of the intercept and slope factors are important. The general usage in both multilevel regression and SEM is to test variances using the Wald test. As discussed in Chapter 3, using the Wald test for variances is not optimal, and the deviance difference test is much better. The same holds for latent curve models in SEM. As explained by Berkhof and Snijders (2001), the resulting *p*-value must be divided by two (cf. Chapter 3). Stoel, Galindo, Dolan and van den Wittenboer (2006) discuss this in detail in the context of latent curve modeling using SEM.

16.4 SOFTWARE

Since the latent curve model is a standard structural equation model, all SEM software can be used to estimate it. Modern SEM software can also include incomplete data, so occasional absence and panel dropout can be handled. Only Mplus has provisions to include varying measurement occasions in the model.

Appendix A

Checklist for Multilevel Reporting

Several authors, for instance Dedrick et al. (2009) have reviewed published articles that report on multilevel analyses. Their analyses of reporting practices indicate that many articles do not publish sufficient information about the data and the analyses performed to let the reader assess the adequacy of the analysis and interpretation. In this appendix, we provide a checklist for reporting on multilevel analyses, outlining the analysis details that we think multilevel analysts should at least provide. We appreciate that journal space is at premium, so in some cases we suggest how to report certain results in one or two sentences. We provide a checklist in three sections: first a checklist that we feel is general, meaning that any kind of multilevel analysis should report these details, and next two sections on multilevel regression and multilevel SEM, respectively.

MULTILEVEL ANALYSIS REPORTING, GENERAL

Issues that arise in multilevel modelling can be roughly divided into modelling issues and data issues. Modeling issues include model and variable selection, linear vs. nonlinear models, estimation method and hypothesis testing. Data issues include sample sizes, checking distributional assumptions, estimating the ICCs, incomplete data, and centering.

Modeling Issues

- *Model selection.* Typically, several models are examined. If explorative analyses are used, the model exploration strategy should be described. Most multilevel modeling involves a sequence of models, for instance in multilevel regression first fixed effects, followed by random effects, or in multilevel SEM first the first-level model, followed by the second-level model. The sequence followed should be described. An important issue is the number of models examined. Dedrick et al. (2009) report that of the 94 studies where the number of models could be roughly categorized (five studies provided no information), 55 percent reported 1–10 models, 28 percent reported 11–20 models, and the remainder reported more than 21 models, up to a total of 430! It is clear that when a model is selected as the ‘best’ out of 430 models tried out, there is serious doubt whether it will replicate at all. The number of models estimated, especially in a data-driven explorative approach, is important information.

- *Variable selection.* Model exploration often involves variable selection. Many approaches exist here, the most often used is a forward selection procedure, where variables are selected and kept if they have a significant effect. In multilevel regression often predictors are added in stages, starting with the lowest level and subsequently adding higher levels. The order of inclusion may also be determined by theory, or by the role of the predictors, e.g. substantive variables first, covariates to be controlled for next. The actual procedure is often a mix of a-priori considerations and the results of significance tests (Dedrick et al., 2009). If variable selection has taken place, the strategy chosen and the resulting selection should be reported.
- *Non-linear models.* Outcome variables that are intrinsically non-normal, such as binomial, categorical ordinal, or count data, generally require special estimation methods. In this case, not all estimation methods are equally accurate. Estimation procedures using numerical integration of the likelihood are generally more accurate than estimation procedures based on the quasi-likelihood (MQL, PQL). Stating the estimation method and software used is therefore important. Examples are: ‘the outcome variable is a count, and we used Laplace estimation in HLM 7.1 for the estimation’. Or: ‘the factor indicators are ordinal with three categories, and therefore we used WLSM estimation in Mplus 7.4’.
- *Estimation method.* Often there is a choice of estimation methods, a choice that is almost always determined by software defaults. Sometimes analysts choose to change the defaults, for instance by changing default ML to robust ML to deal with non-normal continuous data. Since software defaults may change with different versions of the same program, the estimation method employed should always be reported. Convergence problems that require increasing the number of iterations, or impossible estimates such as negative variances should be reported, together with the measures taken to deal with these.
- In *Bayesian estimation*, one must specify the priors used. Estimation uses MCMC methods, and convergence is to the correct distribution, not to a specific value. Convergence must be monitored and checked. Bayesian analysis should report the precise estimation method, the priors used, how convergence was assessed, and the results of this. Example: ‘we used Bayesian estimation in MLwiN 2.34, with uniform priors for the regression coefficients and inverse Gamma priors for the variances. The MCMC estimation used a Gibbs sampler with 5000 iterations burn-in and 5000 iterations for parameter estimation. Inspection of the trajectories of the highest-level parameter estimates showed that this is sufficient.’ (Note: a more detailed checklist for Bayesian estimation is given in Depaoli and van de Schoot (2017)).
- *Hypothesis testing.* For *fixed parameters*, Wald tests are usually employed. In general these are referred to the standard normal distribution, assuming large sample sizes. In multilevel regression models they are sometimes referred to as Student’s *t*-distribution, with *df* estimated by some procedure. If this is the case, the *df* and the procedure should

be reported. Example: ‘Regression coefficients were tested using a Wald test, with df estimated using the Kenward–Roger method as implemented in SAS Proc Mixed 9.0.’

- *Hypothesis testing.* For *random parameters* (variances), Wald tests are usually employed. These are not the most accurate, especially with small variances and small numbers of groups. The chi-square difference test is generally better, but must be carried out manually. In both cases the p -value can be halved (one-sided test). The method to test the variances should be reported. For example: ‘the significance test for the second-level variances was based on the change in the deviance, with p -values halved since the null-hypothesis is on the border of the parameter space.’

Data Issues

- *Sample sizes.* In multilevel modeling, there are several levels of sampling, and the number of units at each level should be reported. If the group sizes are small or very variable, this can be interesting information as well.
- *Distributional assumptions.* Multilevel modeling generally assumes (multivariate) normal distributions for the dependent variables; this should be checked. If the data are obviously non-normal, this should be reported, together with the measures taken to deal with this.
- *Incomplete data.* If there are missing values, the report should state how many data points are missing. If listwise deletion would result in deleting more than 5 percent of the cases, a principled solution should be used, such as multilevel multiple imputation, full information maximum likelihood estimation, or Bayesian estimation.

MULTILEVEL REGRESSION

- *Covariance structure.* When there are multiple random effects at the higher level, there is a choice of covariance structures. If the multilevel data are persons within groups, a full covariance matrix is generally used. If there are estimation problems related to small sample sizes, using a variance component model that constrains all covariances to zero is defensible. When the structure is repeated measures within subjects, other covariance structures can be considered, for instance autoregression or simplex structures. In any case the report should state which covariance structure was modeled. The multilevel regression table should report at least all variances. If autoregression is modeled, the autoregression parameter should be reported as well.
- *Measurement error in predictors.* Just as single-level multiple regression, the assumption is that predictors are measured without error. The tenability of this assumption should be discussed.

MULTILEVEL SEM

- *Goodness-of-fit.* In structural equation modeling, goodness-of-fit indices such as CFI or RMSEA are often reported. In multilevel SEM, interpretation is best served by reporting these indices separately for each level. Unfortunately, with current software this means hand calculation.

Appendix B

Aggregating and Disaggregating

A common procedure in multilevel analysis is to aggregate individual-level variables to higher levels. In most cases, aggregation is used to attach to higher-level units (e.g., groups, classes, teachers) the mean value of a lower-level explanatory variable. However, other aggregation functions may also be useful. For instance, one may have the hypothesis that classes that are heterogeneous with respect to some variable differ from more homogeneous classes. In this case, the aggregated explanatory variable would be the group's standard deviation or the range of the individual variable. Another aggregated value that can be useful is the group size.

In SPSS, aggregation is handled by the procedure *aggregate*. This procedure produces a new data set that contains the grouping variable and the (new) aggregated variables. In SPSS/Windows *aggregate* is available in the DATA menu. A simple syntax to aggregate the variable IQ in a file with grouping variable groupnr is as follows:

```
GET FILE 'indfile.sav'. AGGREGATE OUTFILE = 'aggfile.sav' /  
BREAK = groupnr / meaniq = MEAN(iq) / stdeviq = SD(iq).
```

Disaggregation means adding group-level variables to the individual data file. This creates a file where the group-level variables are repeated for all individuals in the same group. In SPSS, this can be accomplished by the procedure JOIN MATCH, using the so-called TABLE lookup. Before JOIN MATCH is used, the individual and the group file must both be sorted on the group identification variable. In SPSS/Windows JOIN MATCH is available in the DATA menu. For instance, if we want to read the aggregated mean IQ and IQ standard deviation to the individual file, we have the following setup:

```
JOIN MATCH FILE = 'indfile.sav' / TABLE = 'aggfile.sav' / BY  
groupnr / MAP.
```

The example below is a complete setup that uses aggregation and disaggregation to get group means and individual deviation scores for IQ:

```
GET FILE 'indfile.sav'.  
SORT groupnr.  
SAVE FILE 'indfile.sav'.
```

```

AGGREGATE   OUTFILE   =   'aggfile.sav'   /   PRESORTED   /
BREAK = groupnr / meaniq = MEAN(iq) / stdeviq = SD(iq).
JOIN MATCH FILE = 'indfile.sav' / TABLE = 'aggfile.sav' / BY
groupnr / MAP.
COMPUTE deviq = iq-meaniq.
SAVE FILE 'indfile2.sav'.

```

This setup uses the AGGREGATE subcommand PRESORTED to indicate that the file is already sorted on the BREAK variable groupnr. The subcommand MAP on the JOIN MATCH procedure creates a map of the new system file, indicating from which of the two old system files the variables are taken. In this kind of 'cutting and pasting' it is extremely important to check the output of both AGGREGATE and JOIN MATCH very carefully to make sure that the cases are indeed matched correctly.

It should be noted that the program HLM contains a built-in procedure for centering explanatory variables. The programs MLwiN and Mplus have procedures to add group means to the individual data file, and commands to create centered and group-centered variables.

A particular form of disaggregation is when we have a file with repeated measures, with repeated measures represented by separate variables. Many programs need data where each measurement occasion is seen as a separate row of data, with time-invariant variables repeated in the new data file. The GPA data in Chapter 5 are a good example. To create the 'long' data file the following SPSS syntax is used:

```

GET FILE 'd:\data\gpa.sav'.
WRITE OUTFILE 'd:\data\gpalong.dat' RECORDS = 6/
student '0' gpa1 job1 sex highgpa /
student '1' gpa2 job2 sex highgpa /
student '2' gpa3 job3 sex highgpa /
student '3' gpa4 job4 sex highgpa /
student '4' gpa5 job5 sex highgpa /
student '5' gpa6 job6 sex highgpa.
EXECUTE.
DATA LIST FILE 'd:\ data\gpalong.dat' FREE /
student occasion gpa job sex highgpa.
SAVE OUTFILE 'd:\ data\gpalong.sav'.
DESCRIPTIVES ALL.

```

This syntax first writes out the data in ASCII format, and then reads these back into SPSS using the DATA LIST command with a different structure. The final command DESCRIPTIVES is used to check if all variables have plausible values.

A complication arises if the original data file has missing values. These are often coded in SPSS as system missing values, which are written out as *spaces*. When the command DATA LIST 'filename' FREE / is used in SPSS, these are read over and after the first such occurrence all other variables have incorrect values. To prevent this, we need to insert a command that recodes all system missing values into a real code, and after creating the flat data file, records that contain such missing value codes must be removed. To create the 'long' data file needed from the incomplete data set gpamiss we used the following SPSS syntax:

```
GET FILE 'd:\data\gpamiss.sav' .
RECODE gpa1 to job6 (SYSMIS = 9) .
WRITE OUTFILE 'd:\joop\Lea\data\mislong.dat' RECORDS = 6/
student '0' gpa1 job1 sex highgpa /
student '1' gpa2 job2 sex highgpa /
student '2' gpa3 job3 sex highgpa /
student '3' gpa4 job4 sex highgpa /
student '4' gpa5 job5 sex highgpa /
student '5' gpa6 job6 sex highgpa .
EXECUTE .
DATA LIST FILE 'd:\ data\mislong.dat' FREE /
student occasion gpa job sex highgpa .
COUNT out = gpa job (9) .
SELECT IF (out = 0) .
SAVE OUTFILE 'd:\ data\mislong.sav' .
```

Most software packages have automatic procedures to restructure the data from wide to long format, but the examples above show that it is always possible to do it by using more general setups.

Appendix C

Recoding Categorical Data

Including categorical data in a linear regression system has been discussed in detail by Cohen (1968), and later in Pedhazur (1997). There was great interest in these methods in the 1960s because there was a lack of software for analysis of variance designs, and this instigated much interest in coding categorical predictor variables for analysis using multiple regression methods. Interestingly, interest in these coding methods has returned, since multilevel regression and (multilevel) structural equation modeling are also regression models, and categorical variables need to be given special codes to include them in these models.

DUMMY CODING

The simplest way to code a categorical variable is dummy coding, which assigns a ‘1’ to indicate the presence in a specific category, and a ‘0’ to indicate absence. Assume that we have a treatment variable with three categories, with 1 indicating no treatment, 2 indicating treatment A, and 3 indicating treatment B. For a categorical variable with three categories we need two dummy variables. One category is the reference category, which is coded ‘0’ for both dummy variables. Since category 1 is the control group, it makes sense to designate this category as the reference category, and we get the coding in Table C1.

Since *dummy1* refers to treatment A and *dummy2* to treatment B, we can rename the dummies as *TreatA* and *TreatB*, which directly reflects their meaning. In a regression with only the two dummies, the intercept is the predicted outcome for the control group, and the regression coefficients for the dummies indicate how much treatment A or B adds to or subtracts from the control group mean. If we remove the intercept from the model, we can include dummy variables for all available categories.

Table C1 Dummy coding for two treatments and one control group

Treatment	Dummy1	Dummy2
1 = Control	0	0
2 = Treatment A	1	0
3 = Treatment B	0	1

Table C2 Effect coding for two treatments and one control group

Treatment	Effect1	Effect2
1 = Control	-1	-1
2 = Treatment A	1	0
3 = Treatment B	0	1

EFFECT CODING

A different way to code a categorical variable is effect coding. With effect coding, the effect codes take on values ‘-1’, ‘0’, and ‘1’, with the reference category coded ‘-1’ for all effect variables. This produces the coding in Table C2.

With effect coding, the intercept represents the grand mean, and the regression coefficients of the effect variables reflect how much the indicated treatment adds to or subtracts from the grand mean. In analysis of variance the deviation of a cell from the grand mean is called the treatment effect, hence the name ‘effect coding’ for this system. When there is an unambiguous control group, effect coding is less useful than simple dummy coding. However, if there are three treatments in our example, and no real control group, effect coding is a useful way to analyze which treatment has the largest effect. In this case, leaving out the intercept and including all possible effect codes is very effective.

CONTRAST CODING

Contrast coding is mainly used to code for a specific hypothesis. It is a powerful and flexible coding method for constructing and testing relationships between a categorical variable and a continuous variable. For example, assume that treatments A and B in our example are a vitamin supplement, with treatment B being a more powerful dose than treatment A. Reasonable hypotheses about this experiment are: (1) Does supplementing vitamins help at all? and (2) Does an increased dose have a larger effect? This can be coded in the contrast codes shown in Table C3.

Table C3 Contrast coding for two treatments and one control group

Treatment	Contrast1	Contrast2
1 = Control	-1	0
2 = Treatment A	.5	-.5
3 = Treatment B	.5	.5

In this scheme, the first contrast compares the control group to both treatment groups, and the second contrast compares treatment A against treatment B. In general, contrast codes represent hypotheses by a set of contrast weights. Positive and negative weights are used to indicate which groups or categories are compared or contrasted. A usual requirement for contrast weights is that they sum to zero across all groups or categories. Sometimes contrast codes are constructed that are orthogonal, that is, mutually independent. This is the case if the sum of the products of the contrast weights equals zero. Independence of contrast codes is nice, but it is more important that the codes reflect the hypotheses of interest accurately.

NOTES

In addition to the coding methods discussed above, there are other coding methods, such as difference coding and (reverse) Helmert coding. These are useful in special situations, and are discussed in the ANOVA literature because they are used for planned or post-hoc testing. One coding system that is often used for trend analysis is orthogonal polynomials. These are discussed in Appendix D.

When a categorical variable is represented by a set of codes, one would generally treat these coded variables as a block, with an overall significance test rather than separate tests for each. This is especially the case with dummy or effect coding; with contrast codes that each represent a distinct hypothesis, testing the contrasts separately is common.

Interactions with coded categorical variables follow the same rules as interactions for continuous variables (see Aiken & West, 1991, for a discussion).

When using statistical software that allows categorical variables (often called ‘factors’) in regression models, it is important to know what the default coding method is for categorical variables in regression models, and which category is treated as the reference category. In many cases, the default option may not be optimal for the analysis problem at hand, and manually coding the preferred coding method is better.

Appendix D

Constructing Orthogonal Polynomials

When a categorical variable represents increasing levels of a dosage, or successive measurement occasions, the trend is often studied using polynomial regression. Thus, if the measurement occasion is represented by the variable t , the polynomial regression model will have the form $Y = b_0 + b_1t + b_2t^2 + \dots, + b_it^i$. The graph of Y against t will be curved. Nevertheless, the polynomial equation is not strictly a nonlinear equation; mathematically it is linear. This makes polynomial regression a very flexible way to model complex curves, or to approximate a smooth curve (it is used for this purpose in discrete time survival analysis; see Chapter 8 for an example). The disadvantage of polynomial regression is that few processes under observation actually follow polynomial curves. This means that polynomial results can rarely be interpreted in theoretical terms.

A disadvantage of polynomials as simple powers of the time variable is that these predictors tend to be highly correlated. Therefore, *orthogonal polynomials* are used, which are transformed values that reflect the various degrees of the simple polynomial, but are uncorrelated.

When the levels of the categorical variable are evenly spaced, and there are equal numbers of subjects in the categories, constructing orthogonal polynomials is straightforward. For unequal spacing or unequal n s, adaptations exist (see Cohen & Cohen, 1983). However, if the unbalance is not extreme, standard orthogonal polynomials will still work well, even though they are not really orthogonal anymore.

How to construct orthogonal polynomials using matrix procedures built into the major software packages like SPSS and SAS is explained in detail by Hedeker and Gibbons (2006). Their procedure requires knowledge of matrix algebra, but has the advantage that it can deal with uneven spacing of the time variable. For our example, we construct orthogonal polynomials for the longitudinal GPA data analyzed in the chapter on longitudinal models (Chapter 5). In this example, we have GPA data for students in six consecutive semesters. Table D1 below codes the measurement occasion as 0–5 and lists all possible polynomials.

Table D2 shows the correlations between these four time measures.

The correlations between the simple polynomials are very high, and certain to produce collinearity problems when these polynomials are all used together. Since we have evenly spaced measurement occasions, we can use standard tables for orthogonal polynomials, for example as given by Pedhazur (1997). The four orthogonal polynomials are shown in Table D3.

The correlations between these orthogonal polynomials are indeed all zero. Hedeker and Gibbons (2006) suggest dividing each of these polynomial variables by the square root of the sum of the squared values, which transforms all polynomials to the same scale,

Table D1 Four simple polynomials

t_1	t_2	t_3	t_4
0	0	0	0
1	1	1	1
2	4	8	16
3	9	27	81
4	16	64	256
5	25	125	625

Table D2 Correlations between four simple polynomials

	t_1	t_2	t_3	t_4
t_1	1.00	0.96	0.91	0.86
t_2	0.96	1.00	0.99	0.96
t_3	0.91	0.99	1.00	0.99
t_4	0.86	0.96	0.99	1.00
t_5	0.82	0.94	0.98	1.00

Table D3 Orthogonal polynomials for six occasions

t_1	t_2	t_3	t_4
-5	5	-5	1
-3	-1	7	-3
-1	-4	4	2
1	-4	-4	2
3	-1	-7	-3
5	5	5	1

so they can be directly compared. The same effect can be accomplished by standardizing all orthogonal polynomials, which standardizes them to a mean of zero and a standard deviation of one.

Finally, if there are many polynomials, and the interest is only in controlling their combined effect, it is possible to combine them all into one predictor variable by using the predicted values in a polynomial regression model as the single predictor. This is known as the sheaf coefficient (Whitt, 1986).

Appendix E

Data and Stories

This appendix describes the data used for the examples in *Multilevel Analysis: Techniques and Applications* (third edition). Some of the examples are real data; other data sets have been simulated especially for their use in this book. The simulated data sets have been constructed following some hypothetical but plausible real-world scenario. This appendix describes the various data sets, giving either a reference to the study where they come from, or the ‘story’ that has been used as a template to generate the data.

Data are currently available on the Internet in SPSS system-file and portable file format, and in addition in the format in which they were analyzed for the book (e.g. HLM or MLwiN files). Most analyses in this book can be carried out by the majority of the available multilevel software. Obviously, there is a limit to the number of computer packages one can master. Most of the multilevel regression analyses in this book have been carried out in both HLM and MLwiN, and the multilevel SEM analyses have been carried out using LISREL and Mplus. System files and setups using these packages, where present, will also be made available on the Internet (<https://multilevel-analysis.sites.uu.nl/>). I invite users of other multilevel software to use these data for their own learning or teaching. I appreciate receiving data sets and setups that have been transferred to other software systems, so I can make them also available to other users.

The format of the variables is chosen in such a way that writing the variables out in ASCII format results in a file where all variables are separated by at least one space. This file can be read into other programs using the *free format* option. The data sets are described in the order that they are introduced in the book.

CHAPTER 2: THE BASIC TWO-LEVEL REGRESSION MODEL

Popularity Data

The popularity data in *popular2.** are simulated data for 2000 pupils in 100 schools. The purpose is to offer a very simple example for multilevel regression analysis. The main outcome variable is the *pupil popularity*, a popularity rating on a scale of 1–10 derived by a sociometric procedure. Typically, a sociometric procedure asks all pupils in a class to rate all the other pupils, and then assigns the average received popularity rating to each pupil. Because of the sociometric procedure, group effects as apparent from higher-level variance components are rather strong. There is a second outcome variable: pupil popularity as rated by their teacher, on a scale from 1 to 10. The explanatory variables are pupil gender

(boy = 0, girl = 1), pupil extraversion (10-point scale), and teacher experience in years. The pupil popularity data are used as the main example in Chapter 2. They could also be used with both outcome variables as an example for the multilevel multivariate analysis in Chapter 10 (Chapter 10 uses the survey meta-analysis data for that purpose; a multivariate multilevel analysis of the popularity data is left as an exercise for the reader). These data are also used as the vehicle to compare the different estimation and testing procedures described in Chapter 3 and Chapter 13. The popularity data have been generated to be a ‘nice’ well-behaved data set: the sample sizes at both levels are sufficient, the residuals have a normal distribution, and the multilevel effects are strong.

A second version of this data is produced named *popular2incomplete*. This is used in Chapter 4 in the discussion of incomplete data. Here the variables extraversion and popularity were copied into new variables, each with 25 percent of the cases missing. For popularity, if the extraversion score was below the median, for the 40 percent lowest extraversion scores the variable popularity is set to missing. If the extraversion score was above the median, for the 10 percent lowest extraversion scores the variable popularity is set to missing. Similarly, if the popularity score was below the median, for the 10 percent lowest popularity scores the variable extraversion is set to missing, and if the popularity score was above the median, for the 40 percent lowest popularity scores the variable extraversion is set to missing. Listwise deletion on this data file results in the loss of 870 cases, leaving 1130 cases for the analysis. The missingness mechanism is extreme, but it is missing at random.

Nurses

The files *nurses.** contains three-level simulated data from a hypothetical study on stress in hospitals. The data are from nurses working in wards nested within hospitals. It is a cluster-randomized experiment. In each of 25 hospitals, four wards are selected and randomly assigned to an experimental and a control condition. In the experimental condition, a training program is offered to all nurses to cope with job-related stress. After the program is completed, a sample of about 10 nurses from each ward is given a test that measures job-related stress. Additional variables are: nurse age (years), nurse experience (years), nurse gender (0 = male, 1 = female), type of ward (0 = general care, 1 = special care), and hospital size (0 = small, 1 = medium, 2 = large). The data have been generated to illustrate three-level analysis with a random slope for the effect of *ExpCon*.

CHAPTER 5: ANALYZING LONGITUDINAL DATA

GPA Data

The GPA data are a longitudinal data set, where 200 college students have been followed for six consecutive semesters. The data are simulated. In this data set there are GPA measures

taken on six consecutive occasions, with a job status variable (how many hours worked) for the same six occasions. There are two student-level explanatory variables: the gender (0 = male, 1 = female) and the high school GPA. These data are used in the longitudinal analyses in Chapter 5, and again in the latent curve analysis in Chapter 14. There is also a dichotomous student-level outcome variable, which indicates whether a student has been admitted to the university of their choice. Since not every student applies to a university, this variable has many missing values. The outcome variable 'admitted' is not used in any of the examples in this book.

These data come in several varieties. The basic data file is *gpa*. In this file, the six measurement occasions are represented by separate variables. Some software packages (e.g., PRELIS) use this format. Other multilevel software packages (HLM, MLwiN, MixReg, SAS) require that the separate measurement occasions are different data records. The GPA data arranged in this 'long' data format are in the data file *gpalong*. A second data set based on the GPA data involves a process of panel attrition being simulated. Students were simulated to drop out, partly based on having a low GPA in the previous semester. This dropout process leads to data that are missing at random (MAR). A naive analysis of the incomplete data gives biased results. A sophisticated analysis using multilevel longitudinal modeling or SEM with the modern raw data likelihood (available in AMOS, Mplus and MX, and in recent versions of LISREL) should give unbiased results. Comparing analyses on the complete and the incomplete data sets gives an impression of the amount of bias. The incomplete data are in files *gpamiss* and *gpamisslong*.

The Curran Longitudinal Data

The data in the SPSS file(s) *curran*.sav* are a data set constructed by Patrick Curran for a symposium 'Comparing Three Modern Approaches to Longitudinal Data Analysis: An Examination of a Single Developmental Sample' conducted at the 1997 Biennial Meeting of the Society for Research in Child Development. In this symposium, several different approaches to longitudinal modeling (latent growth curves, multilevel analysis, and mixture modeling) were compared and contrasted by letting experts analyze a single shared data set. This data set, hereafter called the *curran data*, was compiled by Patrick Curran from a large longitudinal data set. Supporting documentation and the original data files are available on the Internet.

The data are a sample of 405 children who were within the first two years of entry to elementary school. The data consist of four repeated measures of both the child's antisocial behavior and the child's reading recognition skills. In addition, on the first measurement occasion, measures were collected of emotional support and cognitive stimulation provided by the mother. The data were collected using face-to-face interviews of both the child and the mother at two-year intervals between 1986 and 1992.

CHAPTER 6: THE MULTILEVEL GENERALIZED LINEAR MODEL FOR DICHOTOMOUS DATA AND PROPORTIONS

Thailand Education Data

The Thailand education data in file *thaieduc* are one of the example data sets that are included with the software HLM (also in the student version of HLM). They are discussed at length in the HLM user's manual. They stem from a large survey of primary education in Thailand (Raudenbush & Bhumerat, 1992). The outcome variable is dichotomous, an indicator whether a pupil has ever repeated a class (0 = no, 1 = yes). The explanatory variables are pupil gender (0 = girl, 1 = boy), pupil pre-primary education (0 = no, 1 = yes), and the school's mean SES. The example in Chapter 6 of this book uses only pupil gender as explanatory variable. There are 8582 cases in the file *thaieduc*, but school mean SES is missing in some cases; there are 7516 pupils with complete data.

Note that these missing data have to be dealt with before the data are transported to a multilevel program. In the analysis in Chapter 6 they are simply removed using listwise deletion. However, the percentage of pupils with incomplete data is 12.4 percent, which is too large to be simply ignored in a real analysis.

Survey Response Meta-Analysis Data

The survey response data used to analyze proportions in Chapter 6 are from a meta-analysis by Hox and de Leeuw (1994). The basic data file is *metaresp*. This file contains an identification variable for each study located in the meta-analysis. A mode identification indicates the data collection mode (face-to-face, telephone, mail). The main response variable is the proportion of sampled respondents who participate. Different studies report different types of response proportions: we have the completion rate (the proportion of participants from the total initial sample) and the response rate (the proportion of participants from the sample without ineligible respondents (moved, deceased, address nonexistent)). Obviously, the response rate is usually higher than the completion rate. The explanatory variables are the year of publication and the (estimated) saliency of the survey's main topic. The file also contains the denominators for the completion rate and the response rate, if known. Since most studies report only one of the response figures, the variables 'comp' and 'resp' and the denominators have many missing values.

Some software (e.g., MLwiN) expects the *proportion* of 'successes' and the denominator on which it is based; other software (e.g., HLM) expects the *number* of 'successes' and the corresponding denominator. The file contains the proportion only; the number of successes must be computed from the proportion if the software needs that. The file *multresp* contains the same information, but now in a three-level format useful if the data are analyzed using the multivariate outcome, which is demonstrated in Chapter 11.

CHAPTER 7: THE MULTILEVEL GENERALIZED LINEAR MODEL FOR CATEGORICAL AND COUNT DATA

Street Safety Data

A sample of 100 streets are selected, and on each street a random sample of 10 persons are asked how often they feel unsafe while walking that street. The question about feeling unsafe is asked using three answer categories: 1 = never, 2 = sometimes, 3 = often. Predictor variables are age and gender; street characteristics are an economic index (standardized *Z*-score) and a rating of the crowdedness of the street (7-point scale). File: *Safety*. Used in Chapter 7 on ordinal data.

Epilepsy Data

The epilepsy data come from a study by Leppik et al. (1987). They have been analyzed by many authors, including Skrondal and Rabe-Hesketh (2004). The data come from a randomized controlled study on the effect of an anti-epileptic drug versus a placebo. It is a longitudinal design. For each patient the number of seizures was measured for a two-week baseline. Next, patients were randomized to the drug or the placebo condition. For four consecutive visits the clinic collected counts of epileptic seizures in the two weeks before the visit. The data set contains the following variables: count of seizures, treatment indicator, visit number, dummy for visit #4, log of age, log of baseline count. All predictors are grand mean centered. The data come from the GLLAMM homepage at: www.gllamm.org/books, used in Chapter 7 on count data.

CHAPTER 8: MULTILEVEL SURVIVAL ANALYSIS

First Sex Data

This is a data set from Singer and Willett's book on longitudinal data analysis (2003), from a study by Capaldi, Crosby and Stoolmiller (1996). A sample of 180 middle-school boys were tracked from the 7th through the 12th grade, with the outcome measure being when they had sex for the first time. At the end, 54 boys (30 percent) were still virgins. These observations are censored. File *firstsex* is used as an example of (single-level) survival data in Chapter 8. There is one dichotomous predictor variable, which is whether there has been a parental transition (0 if the boy lived with his biological parents before the data collection began).

Sibling Divorce

This involves multilevel survival data analyzed by Dronkers and Hox (2006). The data are from the National Social Science Family Survey of Australia of 1989–1990. In this survey detailed information was collected, including the educational attainment of respondents,

their social and economic background, such as parental education and occupational status of the father, parental family size and family form, and other relevant characteristics of 4513 men and women in Australia. The respondent also answered all these questions about his or her parents and siblings. The respondents gave information about at most three siblings, even if there were more siblings in the family. All sibling variables were coded in the same way as the respondents, and all data were combined in a file with respondents or siblings as the unit of analysis. In that new file, respondents and siblings from the same family had the same values for their parental characteristics, but had different values for their child characteristics. The data file contains only those respondents or siblings that were married or had been married, and gave no missing values. File: *sibdiv*.

CHAPTER 9: CROSS-CLASSIFIED MULTILEVEL MODELS

Pupcross Data

This data file is used to demonstrate the cross-classified data with pupils nested within both primary and secondary schools. These are simulated data, where 1000 pupils attended 100 primary and subsequently 30 secondary schools. There is no complete nesting structure; the pupils are nested within the cross-classification of primary and secondary schools. The file *pupcross* contains the secondary school achievement score, which is the outcome variable, and the explanatory pupil-level variables, gender (0 = boy, 1 = girl) and SES. School-level explanatory variables are the denomination of the primary and the secondary school (0 = no, 1 = yes). These data are used for the example of a cross-classified analysis in Chapter 8.

Sociometric Scores Data

The sociometric data are simulated data, intended to demonstrate a data structure where the cross-classification is at the lowest level, with an added group structure because there are several groups. The story is that in small groups all members are asked to rate each other. Since the groups are of different sizes, the usual data file organized by case in *socscors* has many missing values. The data are rearranged in a data file called *soclong* for the multilevel analysis. In *soclong* each record is defined by the sender–receiver pairs, with explanatory variables age and sex defined separately for the sender and the receiver. The group variable ‘group size’ is added to this file.

CHAPTER 10: MULTIVARIATE MULTILEVEL REGRESSION MODELS

School Manager Data

The school manager data are from an educational research study (Krüger, 1994). In this study, male and female school managers from 98 schools were rated by 854 pupils. The

data are in file *manager*. These data are used to demonstrate the use of multilevel regression modeling for measuring context characteristics (here, the school manager's management style). The questions about the school manager are questions 5, 9, 12, 16, 21, and 25; in Chapter 10 of the book these are renumbered 1 ... 6. These data are used only to demonstrate the multilevel psychometric analyses in Chapter 9. They can also be analyzed using one of the multilevel factor analysis procedures outlined in Chapter 12. The data set also contains the pupils' and school manager's gender (1 = female, 2 = male), which is not used in the example. The remaining questions in the data set are all about various aspects of the school environment; a full multilevel exploratory factor analysis is a useful approach to these data.

CHAPTER 11: THE MULTILEVEL APPROACH TO META-ANALYSIS

Social Skills Meta-Analysis Data

The social skills meta-analysis data in file *meta20* contain the coded outcomes of 20 studies that investigate the effect of social skills training on social anxiety. All studies use an experimental group/control group design. Explanatory variables are the duration of the training in weeks, the reliability of the social anxiety measure used in each study (two values, taken from the official test manual), and the studies' sample size. The data are simulated.

Asthma and LRD Meta-Analysis Data

The asthma and LRD data are from Nam, Mengersen and Garthwaite (2003). The data are from a set of 59 studies that investigate the relationship between children's environmental exposure to smoking (ETS) and the child health outcomes of asthma and lower respiratory disease (LRD). Available are the logged odds ratio (LOR) for asthma and LRD, and their standard errors. Study-level variables are the average age of subjects, publication year, smoking (0 = parents, 1 = other in household), and covariate adjustment used (0 = no, 1 = yes).

There are two effect sizes, the logged odds ratio for asthma and lower respiratory disease (LRD). Only a few studies report both. Datafile: *AstLrd*.

CHAPTER 13: ASSUMPTIONS AND ROBUST ESTIMATION METHODS

Estrone Data

The estrone data are 16 independent measurements of the estrone level of five post-menopausal women (Fears et al., 1996). The data file *estronex* contains the data in the usual format; the file *estrlong* contains the data in the format used for multilevel analysis. Although the data structure suggests a temporal order in the measurements, there is none.

Before the analysis, the estrone levels are transformed by taking the natural logarithm of the measurements. The estrone data are used in Chapter 13 to illustrate the use of advanced estimation and testing methods on difficult data. The difficulty of the estrone data lies in the extremely small sample size and the small value of the variance components.

Good89 Data

The file *good89* (from Good, 1999, p. 89) contains the very small data set used to demonstrate the principles of bootstrapping in Chapter 13.

CHAPTER 14: MULTILEVEL FACTOR MODELS

Family IQ Data

The family IQ data are patterned to follow the results from a study of intelligence in large families (van Peet, 1992). They are the scores on six subscales from an intelligence test and are used in Chapter 14 to illustrate multilevel factor analysis. The file *FamilyIQ* contains the data from 275 children in 50 families. The data file contains the additional variables gender and parental IQs, which are not used in the analyses in this book. Datafile: *FamIQ*.

CHAPTER 15: MULTILEVEL PATH MODELS

GALO Data

The GALO data in file *galo* are from an educational study by Schijf and Dronkers (1991). They are data from 1377 pupils within 58 schools. We have the following pupil-level variables: father's occupational status, *focc*; father's education, *feduc*; mother's education, *meduc*; pupil sex, *sex*; the result of GALO school achievement test, *GALO*; and the teacher's advice about secondary education, *advice*. At the school level we have only one variable: the school's denomination, *denom*. Denomination is coded 1 = Protestant, 2 = nondenominational, 3 = Catholic (categories based on optimal scaling). The data file *galo* contains both complete and incomplete cases, and an indicator variable that specifies whether a specific case in the data file is complete or not.

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